

CAD for VLSI

Modeling



Mixed Integer Linear Programming

- ❑ A mathematical programming such that:
 - The objective is a linear function
 - All constraints are linear functions
 - Some variables are real numbers and some are integers, i.e., "mixed integer"
- ❑ It is almost like a linear programming, except that some variables are integers

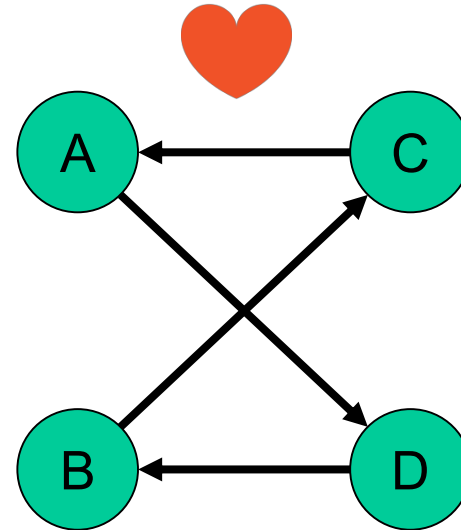
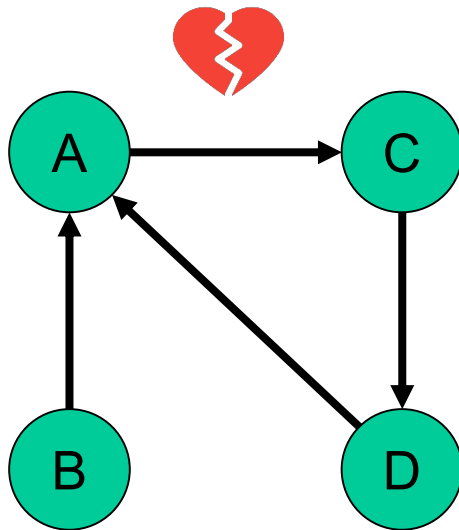
NP-C problem

Group Assignment Problem

- ❑ You are going to assign 4 persons into 2 groups
 - Everyone associates with only one group
 - Every group has at least one person
 - Dislike persons are not in the same group
 - Like overcomes dislike
 - Try your best to balance the group

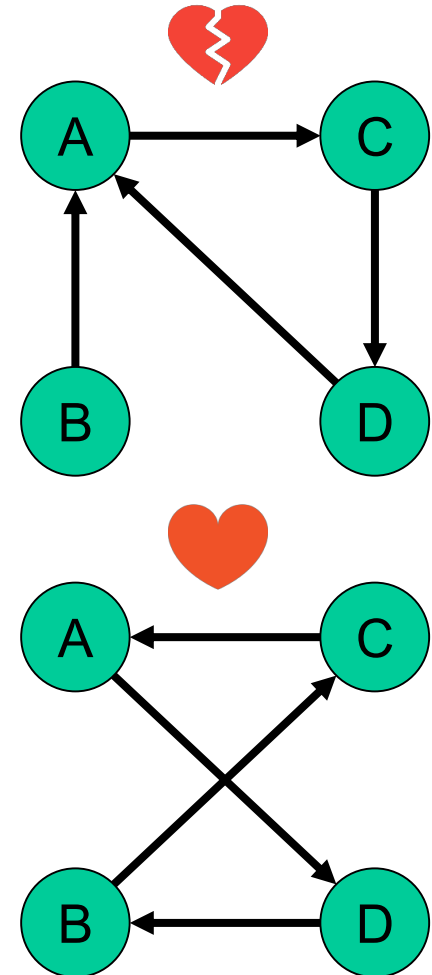
- ❑ Let's model this problem as an ILP/SAT problem!

Example of Group Assignment



ILP-based Formulation – 1

- ❑ Variable $a1$ and $a2$ are binary (0/1)
 - $a1 = 1$: A in group 1
 - $a2 = 1$: A in group 2
- ❑ Constraints:
 - Uniqueness constraint
 - Group constraint
 - Dislike constraint
- ❑ Objective:
 - Balanced group size



ILP-based Formulation – 2

❑ Variable $a1$ and $a2$ are binary (0/1)

- $a1 = 1$: A in group 1
- $a2 = 1$: A in group 2

❑ Constraints:

- Uniqueness constraint
- Group constraint
- Dislike constraint

❑ Objective:

- Balanced group size

Min

$$a1 + b1 + c1 + d1 - a2 - b2 - c2 - d2$$

Subject To

$$a1 + b1 + c1 + d1 - a2 - b2 - c2 - d2 \geq 0$$

$$a1 + a2 = 1$$

$$b1 + b2 = 1$$

$$c1 + c2 = 1$$

$$d1 + d2 = 1$$

$$a1 + b1 + c1 + d1 \geq 1$$

$$a2 + b2 + c2 + d2 \geq 1$$

$$b1 + a1 - c1 \leq 1$$

$$b2 + a2 - c2 \leq 1$$

$$a1 + c1 - d1 \leq 1$$

$$a2 + c2 - d2 \leq 1$$

$$c1 + d1 - a1 \leq 1$$

$$c2 + d2 - a2 \leq 1$$

$$d1 + a1 - b1 \leq 1$$

$$d2 + a2 - b2 \leq 1$$

Binary

$a1$

$b1$

$c1$

$d1$

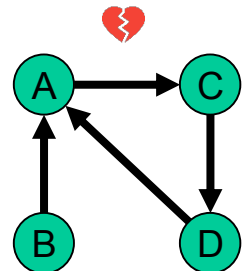
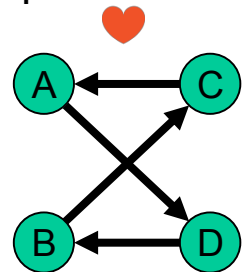
$a2$

$b2$

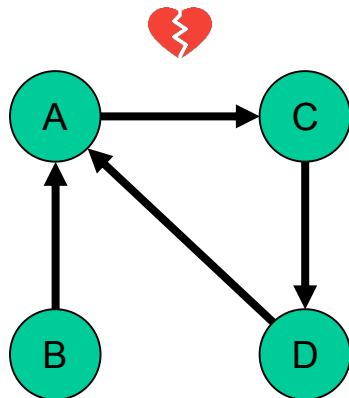
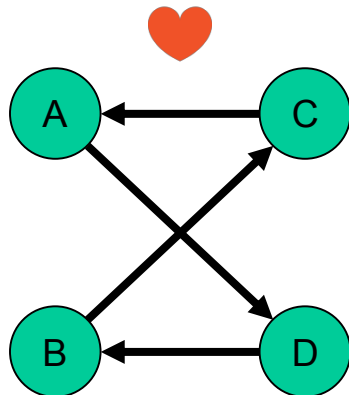
$c2$

$d2$

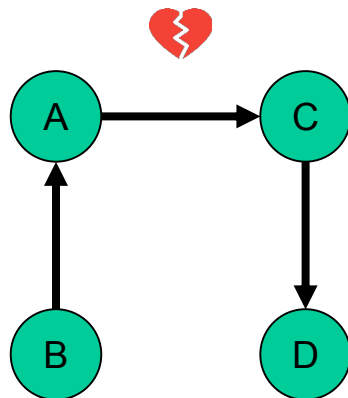
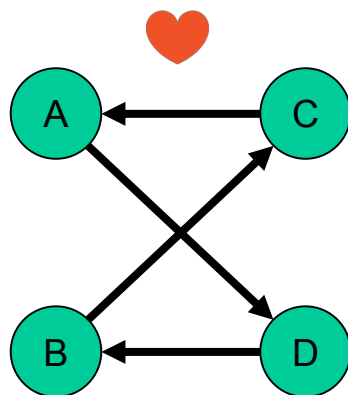
End



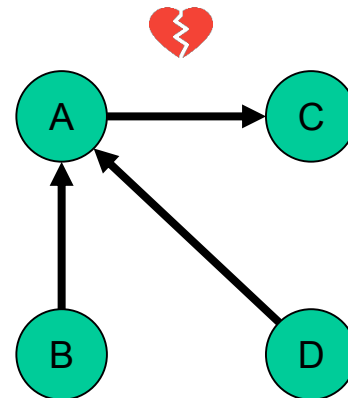
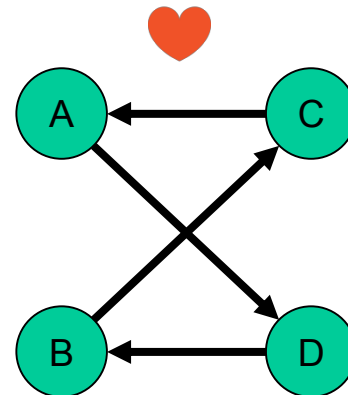
ILP-based Formulation – 3



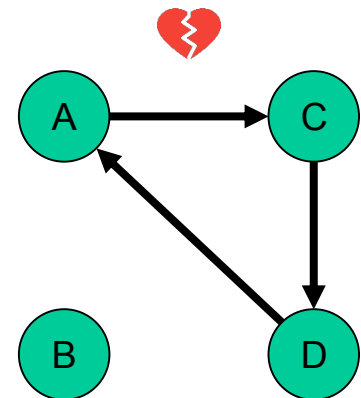
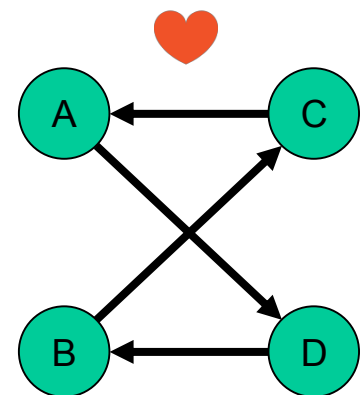
No solution



{A, D} {B, C}



{B, C, D} {A}



{A, B, D} {C}

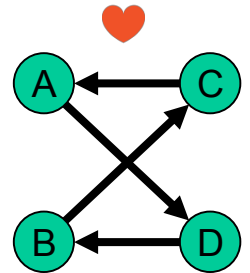
SAT-based Formulation

- Given 4 persons and 2 groups
 - $a1 = T$: A in group 1
 - $a2 = T$: A in group 2
- Constraints:
 - Uniqueness constraint
 - Group constraint
 - Dislike constraint
- Objective:
 - Any feasible solution is OK.

$a_1 \rightarrow 1$
 $b_1 \rightarrow 2$
 $c_1 \rightarrow 3$
 $d_1 \rightarrow 4$

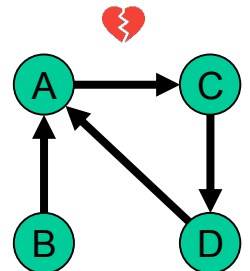
 $a_2 \rightarrow 5$
 $b_2 \rightarrow 6$
 $c_2 \rightarrow 7$
 $d_2 \rightarrow 8$

p cnf 8 18
 c uniqueness constraint
 1 5 0
 -1 -5 0
 2 6 0
 -2 -6 0
 3 7 0
 -3 -7 0
 4 8 0
 -4 -8 0



c group constraint
 1 2 3 4 0
 5 6 7 8 0

c dislike constraint
 -2 -1 3 0
 -6 -5 7 0
 -1 -3 4 0
 -5 -7 8 0
 -3 -4 1 0
 -7 -8 5 0
 -4 -1 2 0
 -8 -5 6 0



Circuit Models

- ❑ Circuit model
 - Abstraction
 - Representation of relevant features only

- ❑ Unambiguously transferring the design information
 - Humans to humans
 - Humans to CAD tools

Model Classifications

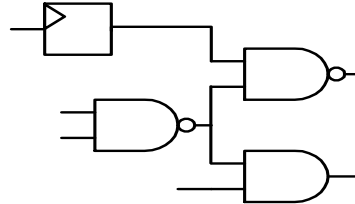
- ❑ Abstraction levels
 - Architectural
 - Logic
 - Geometrical
- ❑ Views
 - Behavioral
 - Structural
 - Physical
- ❑ Media
 - Language
 - Diagram
 - Mathematical model

Abstraction Levels

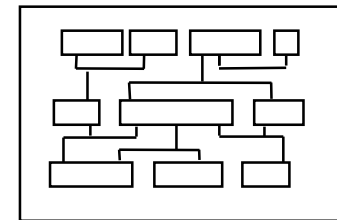
Architectural level

...
PC = PC + 1;
FETCH(PC);
DECODE(INST);
...

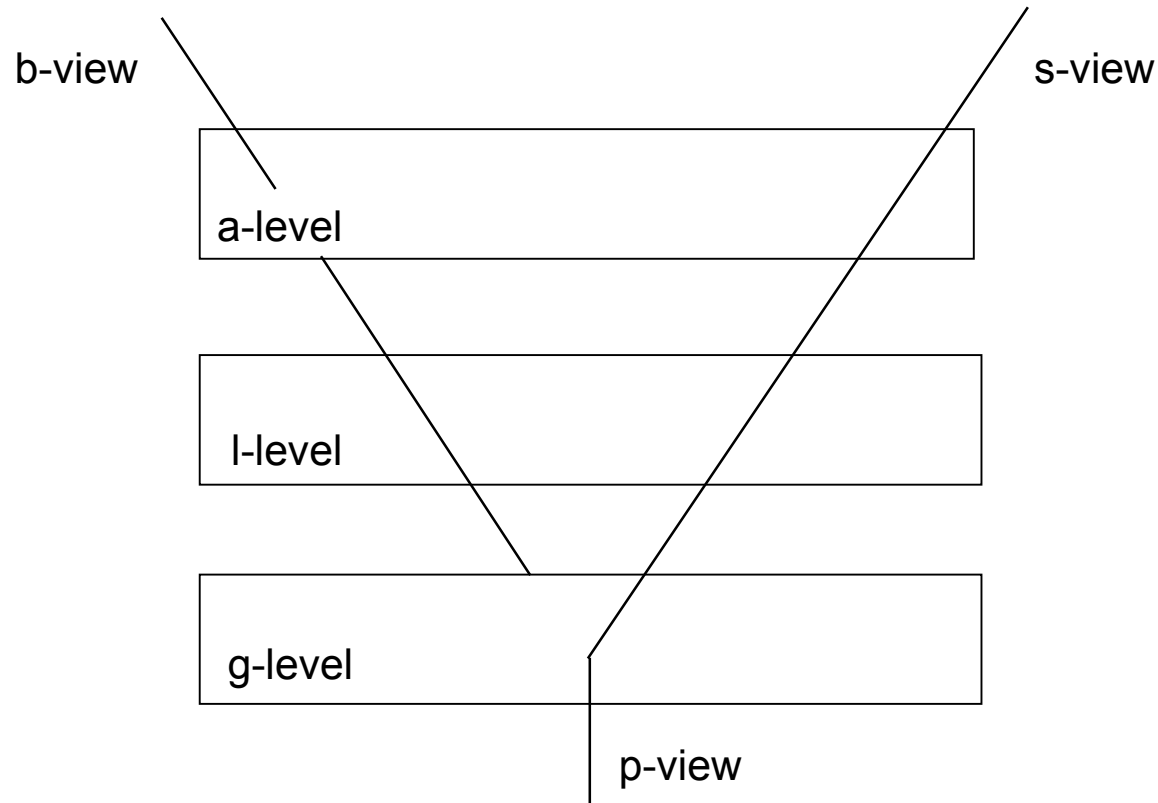
Logic level



Geometrical level



Views and Abstraction Levels



Levels of Abstractions and Corresponding Views

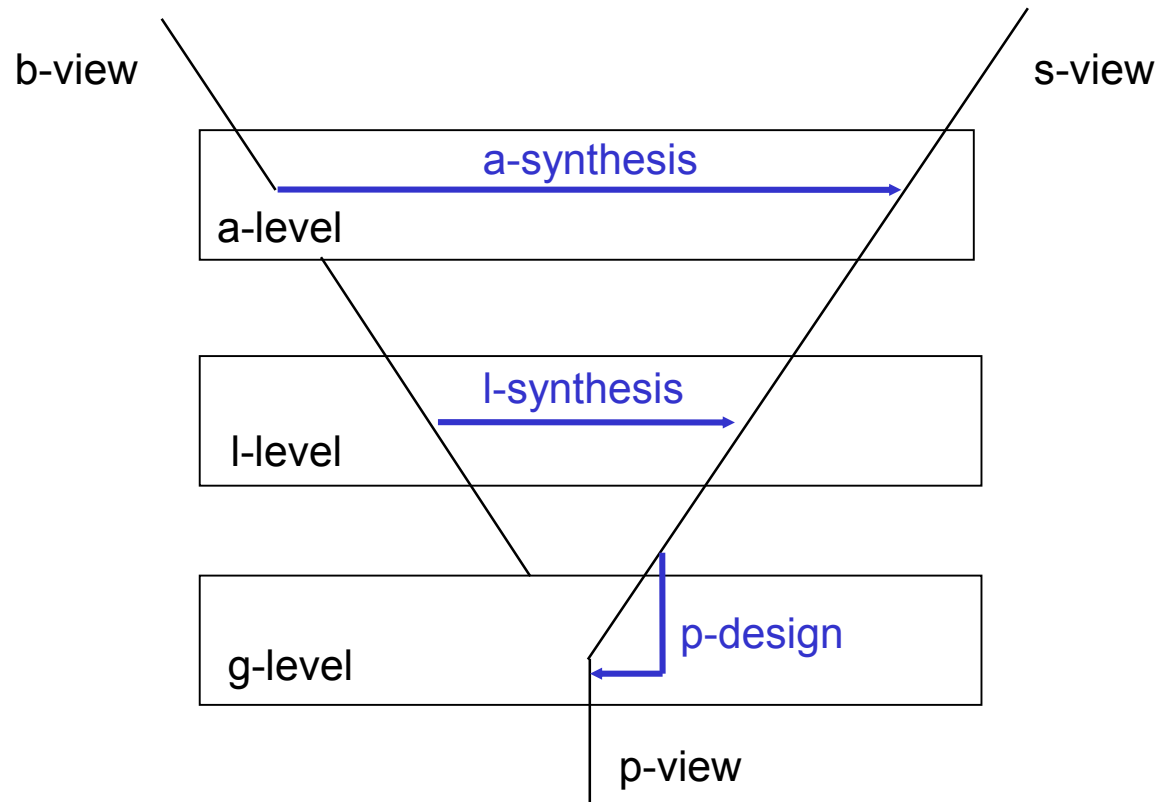
Behavioral View	Structural View	Views Levels
<pre> ... PC = PC + 1; FETCH(PC); DECODE(INST); ... </pre>		Architectural Level
		Logic Level

Synthesis

- ❑ Synthesis
 - A set of transformation between two views

- ❑ Synthesis tasks
 - Architectural-level synthesis
 - High-level synthesis, structural synthesis
 - Logic-level synthesis
 - Gate-level structure, library binding (mapping)
 - Geometrical-level synthesis
 - Physical design

Synthesis Tasks



Gajski's Y-chart

BEHAVIORAL DOMAIN

Systems
Algorithms
Register transfers
Logic
Transfer functions

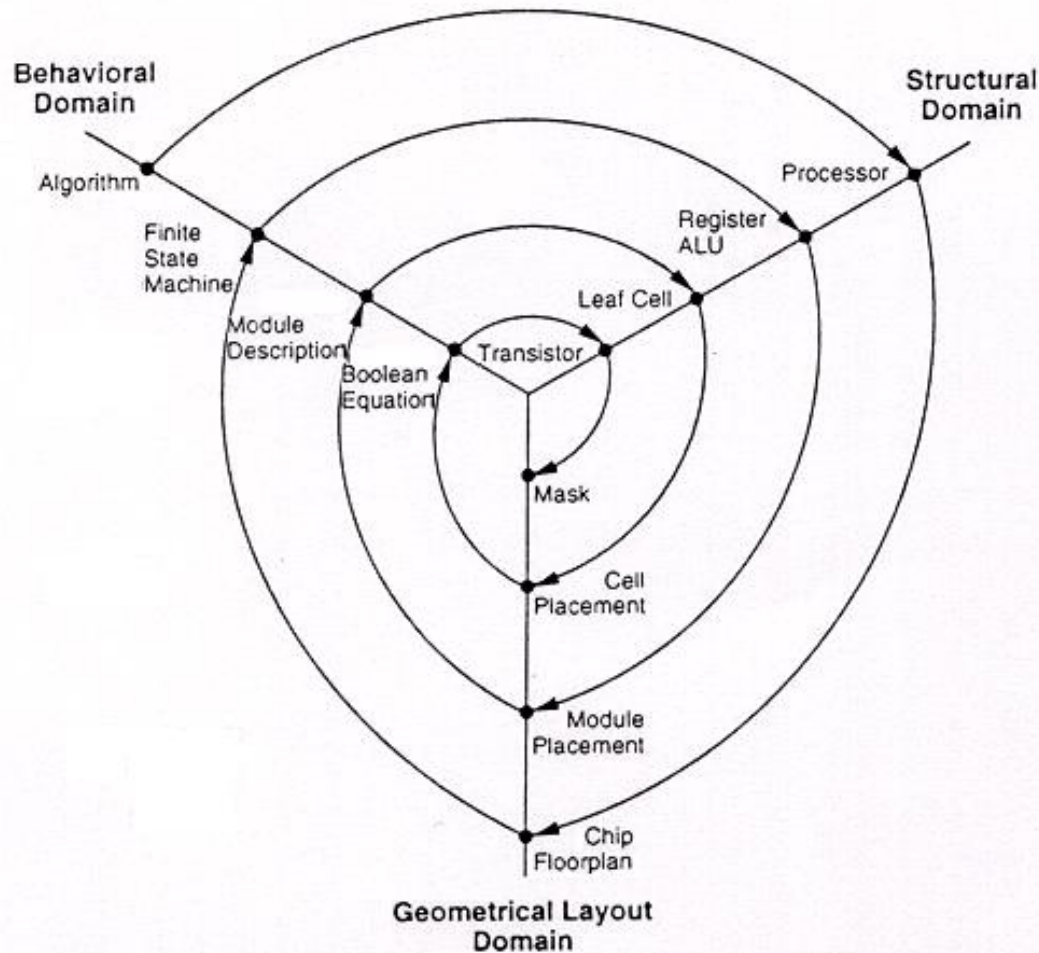
STRUCTURAL DOMAIN

Processors
ALU's, RAM, etc.
Gates, flip-flops, etc.
Transistors

Transistor layout
Cell layout
Module layout
Floor plans
Physical partitions

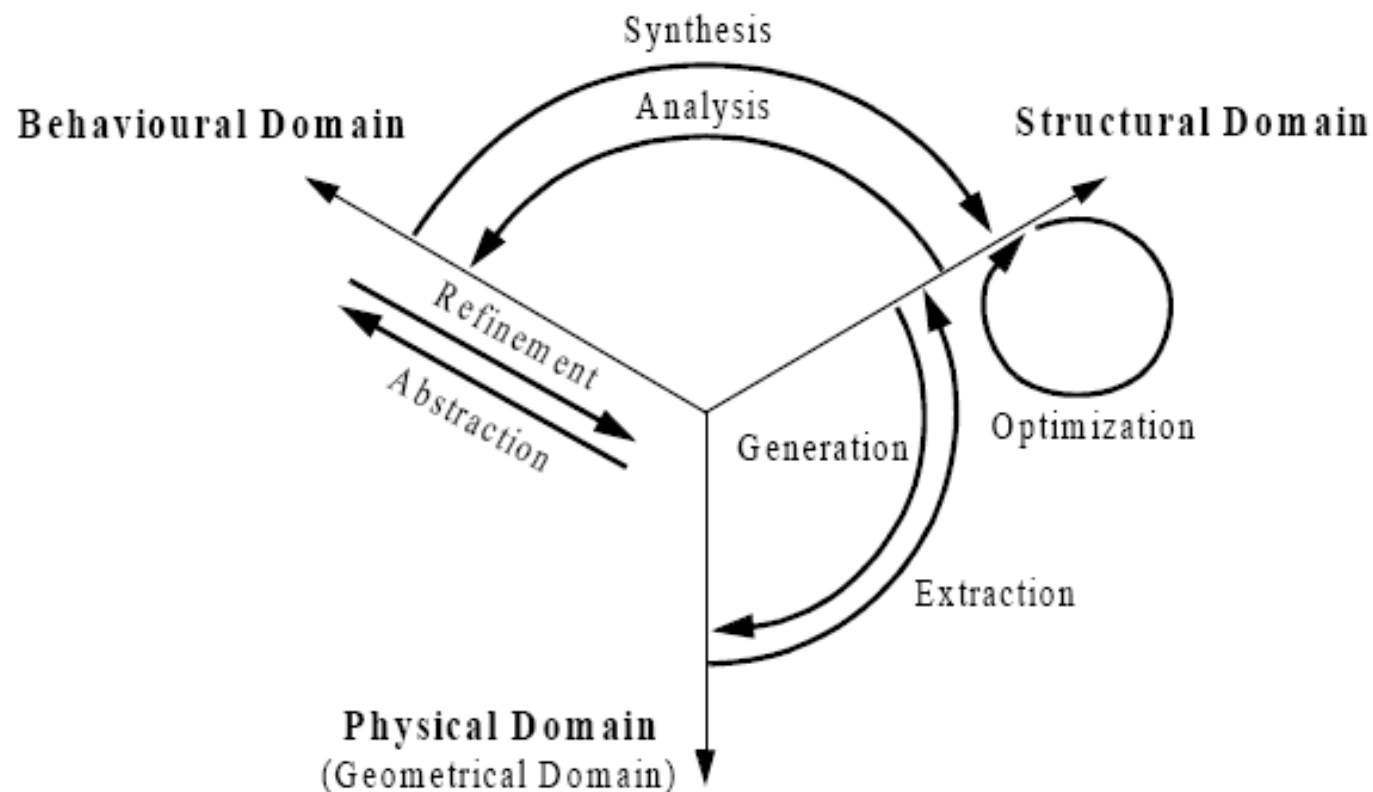
PHYSICAL DOMAIN

Y-chart Domain Mapping

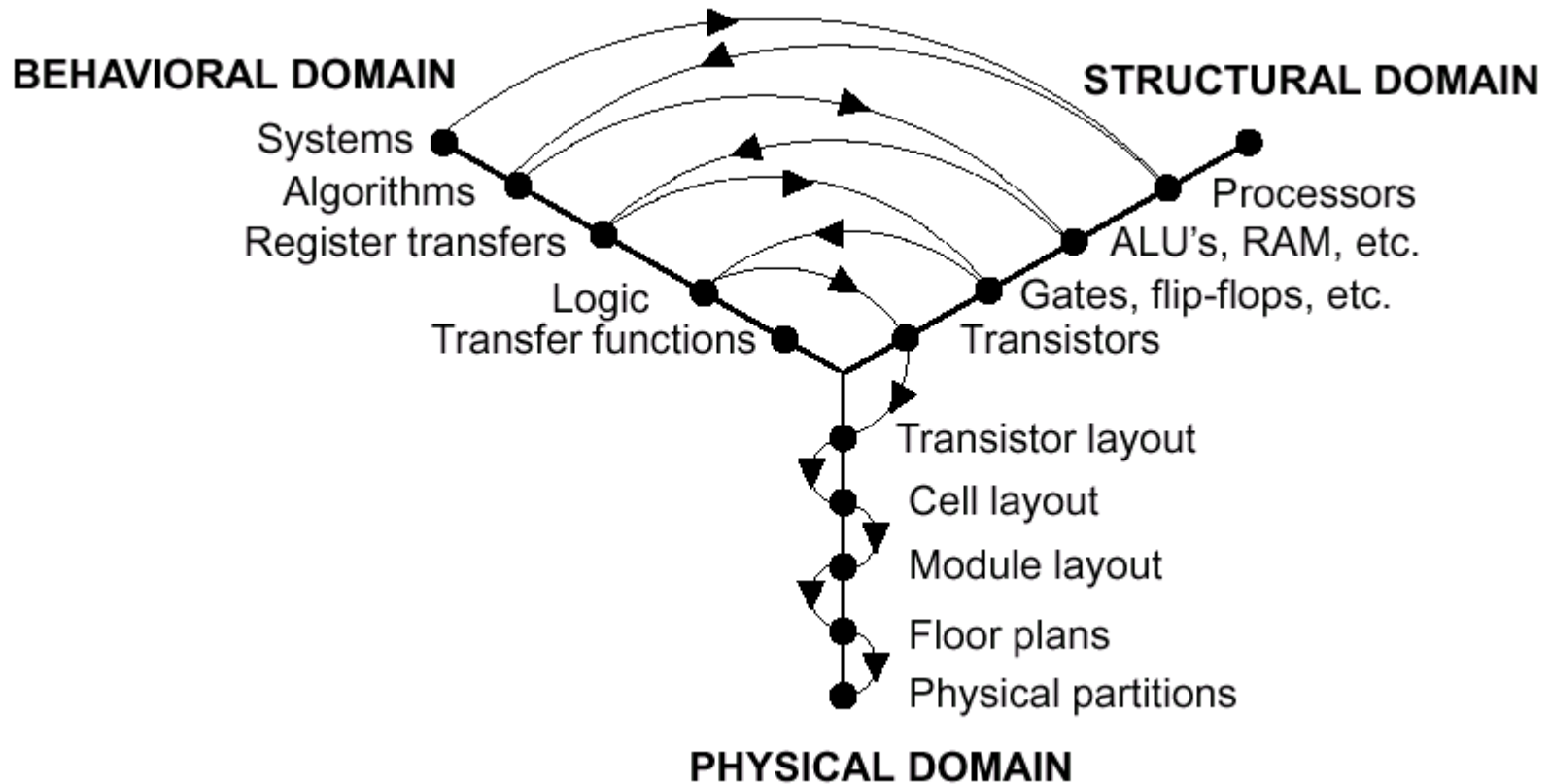


Y-transformations

Y-transformations



Top-down Design



Levels Revealed

Levels revealed

Hierarchy level	Abstraction	Supporting tools
System	space-time behavior as instruction, timing & pin assignment specifications	flow-charts, diagrams, high-level languages
Architecture	global organization of functional entities	HDLs, floor-planning block diagrams for clock cycle and area estimation
Register transfer	binding data flow functional modules and microinstructions	synthesis, simulation, verification, test analysis, resource use evaluation
Functional modules	primitive operations and control methods	libraries, module generators, schematic entry, test
Logic	Boolean function of gate circuits	Schematic entry, synthesis and simulation, verification, PLA tools
Switch	electrical properties of transistor circuits	RC extraction, timing verification, electrical analysis
Layout	geometric constraints	layout editor/compactor, netlist extractor, DRC, placement and routing

Synthesis Levels and Tasks

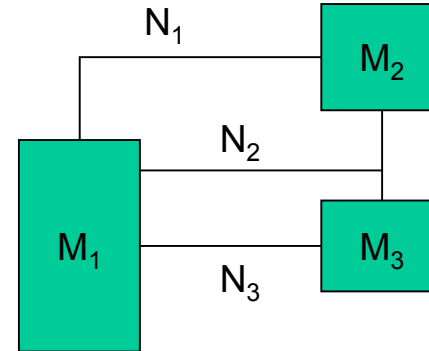
- ❑ System level synthesis
 - Clustering
 - Communication synthesis
- ❑ High-level synthesis
 - Resource or timing constrained scheduling
 - Resource allocation
 - Binding
- ❑ Register transfer level synthesis
 - Data-path synthesis
 - Controller synthesis
 - Logic-level synthesis
 - Logic minimization
 - Optimization, overhead removal
 - Library mapping
- ❑ Physical level synthesis
 - Placement
 - Routing

Abstract Models

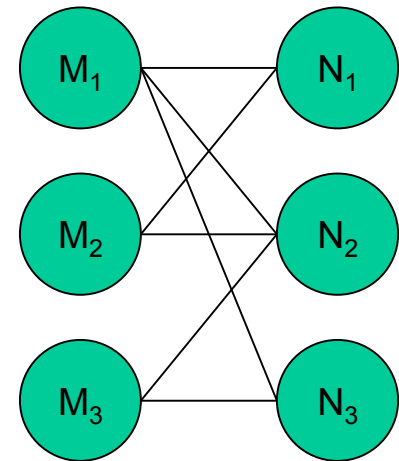
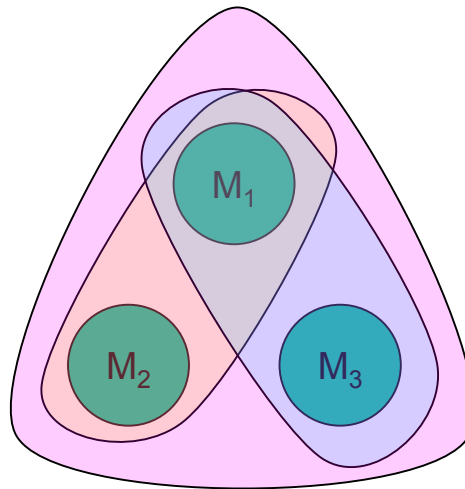
- ❑ Abstract models for different circuit views
 - Structure
 - Logic network
 - Combinational logic network
 - Sequential logic network
 - State diagram
 - Data-flow and Sequencing Graph

Abstract Models – Structure

- ❑ Module, net, pin
- ❑ Incidence matrix
- ❑ Hypergraph
- ❑ Bipartite graph

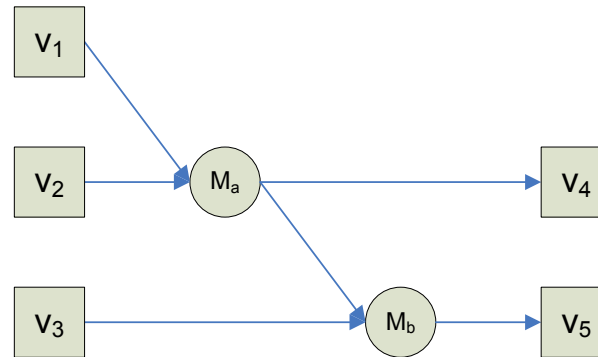


$$\begin{matrix} & N_1 & N_2 & N_3 \\ \begin{matrix} M_1 \\ M_2 \\ M_3 \end{matrix} & \begin{bmatrix} \mathbf{1} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} & \mathbf{1} & \mathbf{0} \\ \mathbf{0} & \mathbf{1} & \mathbf{1} \end{bmatrix} \end{matrix}$$

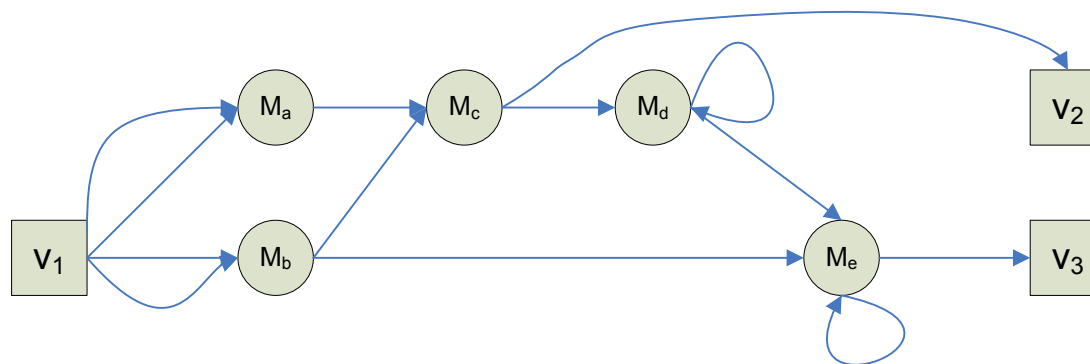


Abstract Models – Logic Network

❑ Combinational logic network



❑ Sequential logic network



Abstract Models – State Diagram

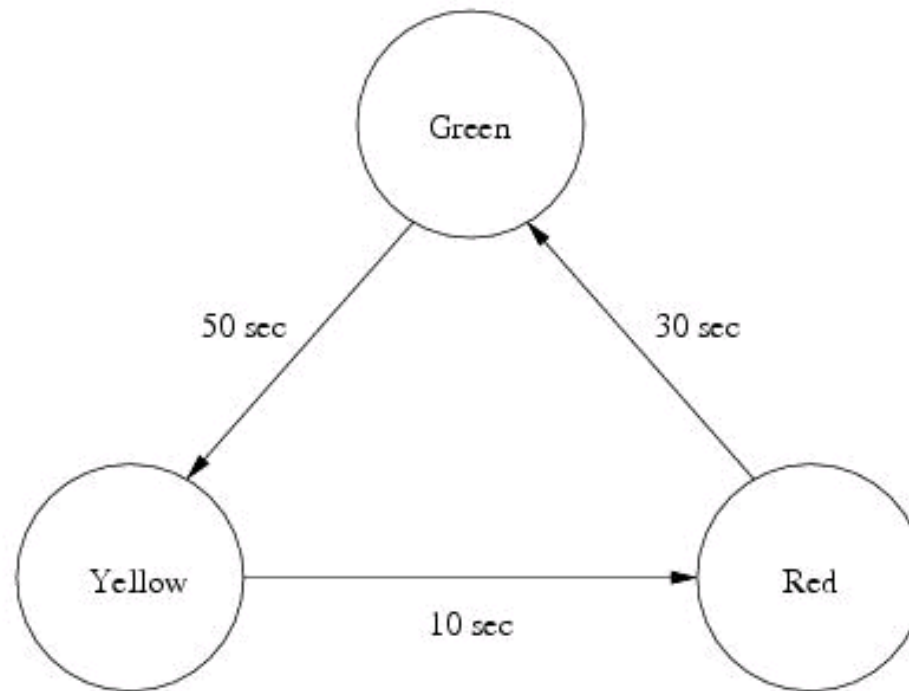
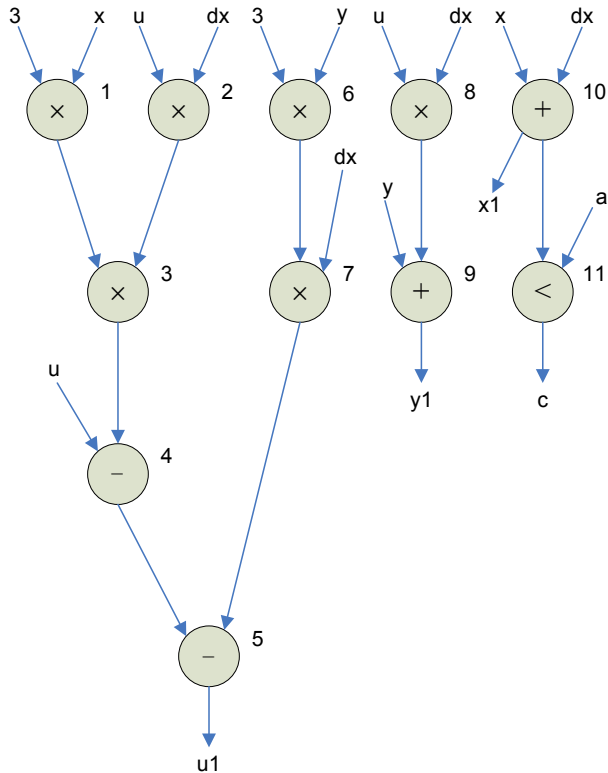
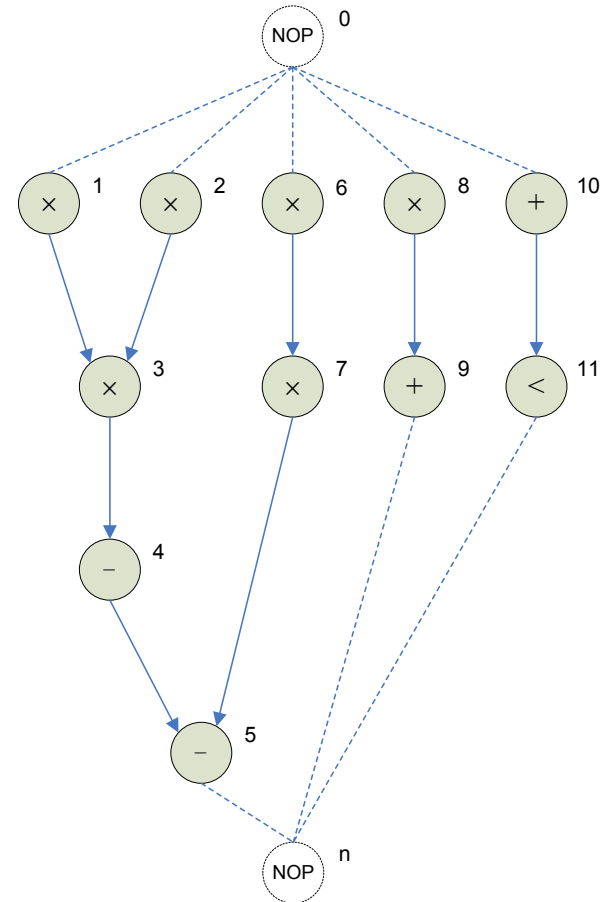


Figure 1: traffic light

Abstract Models – Data-flow and Sequencing Graph



Data-flow Graph



Sequencing Graph

Hardware Description Language

- ❑ Recent trend for circuit specification
 - Hardware description language (HDL)
 - Verilog, VHDL
 - Similar to write a software program

- ❑ Concise HDL models are preferable for representing
 - Flow
 - State
 - Logic diagram

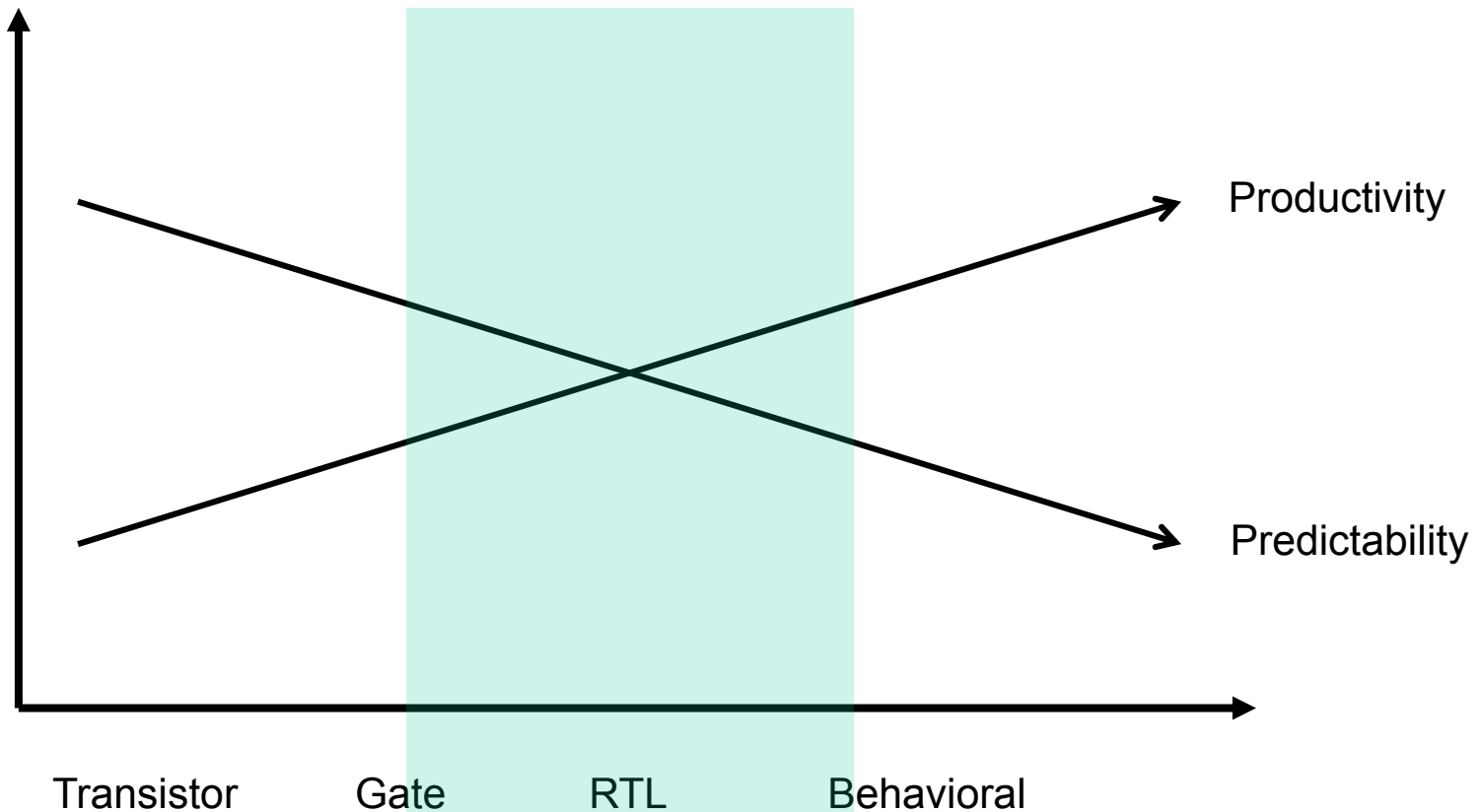
Hardware Description Language

- ❑ Structural description
 - Textual replacement for schematic
 - Hierarchical composition of modules from primitives
- ❑ Behavioral/functional description
 - Describe what module does, not how
 - Synthesis generates circuit for module

Miscellaneous HDLs

- ❑ Abel (circa 1983) - developed by Data-I/O
 - Targeted to programmable logic devices
 - Not good for much more than state machines
- ❑ ISP (circa 1977) - research project at CMU
 - Simulation, but no synthesis
- ❑ Verilog (circa 1985) - developed by Gateway (absorbed by Cadence)
 - Similar to Pascal and C
 - Delays is only interaction with simulator
 - Fairly efficient and easy to write
 - IEEE standard
- ❑ VHDL (circa 1987) - DoD sponsored standard
 - Similar to Ada (emphasis on re-use and maintainability)
 - Simulation semantics visible
 - Very general but verbose
 - IEEE standard

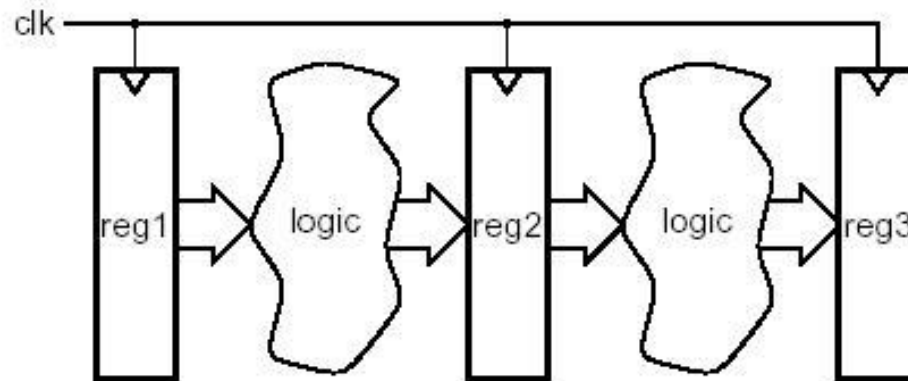
Productivity vs. Predictability



\therefore RTL is commonly used for circuit design

Register Transfer Level (RTL)

- ❑ A digital system is specified at the register transfer level (RTL) when it is specified by:
 - The set of registers
 - The operations performed on the data stored
 - The control that supervises the sequence of operations



Verilog

- ❑ Supports structural and behavioral descriptions
- ❑ Structural description
 - Explicit structure of the circuit
 - Ex: each logic gate instantiated and connected to others
- ❑ Behavioral description
 - Program describes input/output behavior
 - Many structural implementations could have same behavior
 - Ex: different implementation of one Boolean function (full-adder)

Verilog Descriptions

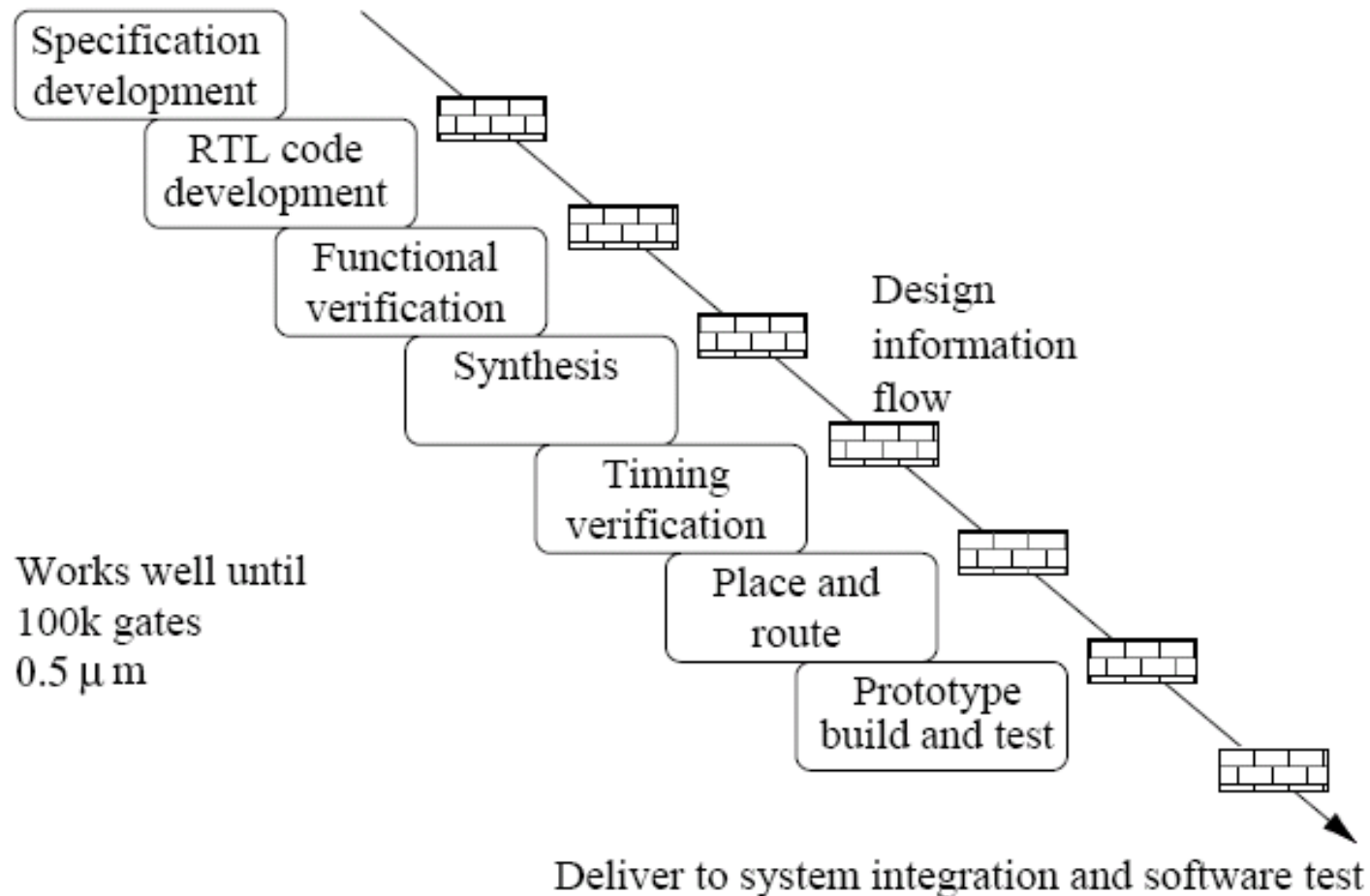
❑ Structural description

```
module HALF_ADDER (a, b, carry, sum);  
  input  a, b;  
  output carry, sum;  
  
  and  
    G1 (carry, a, b);  
  xor  
    G2 (sum, a, b);  
  
endmodule
```

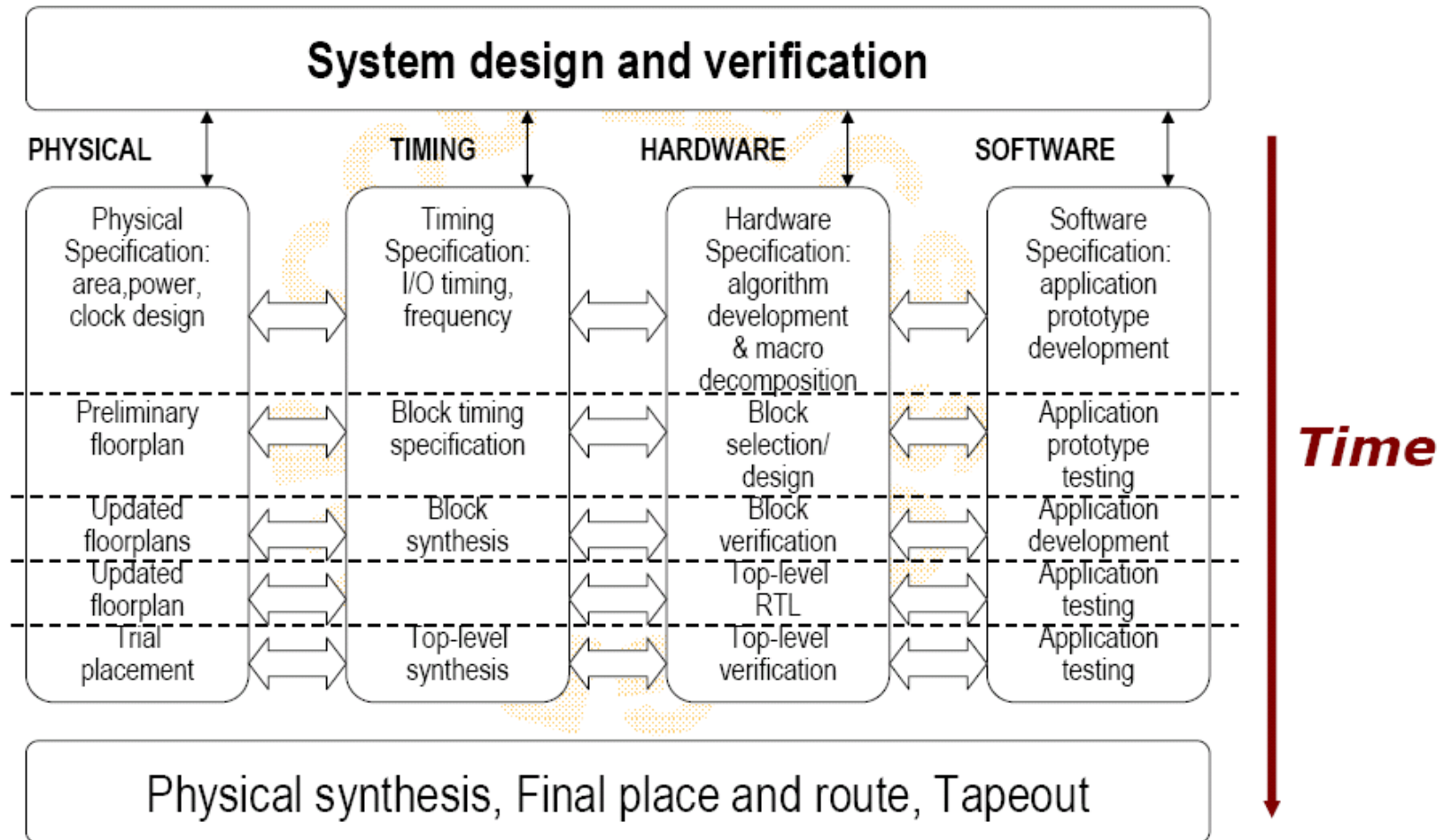
❑ Behavioral description

```
module HALF_ADDER (a, b, carry, sum);  
  input  a, b;  
  output carry, sum;  
  
  assign carry = a & b;  
  assign sum = a ^ b;  
  
endmodule
```

Traditional Waterfall Model



Spiral SOC Design Flow

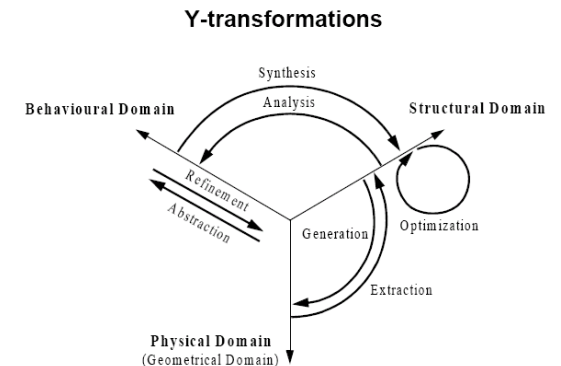
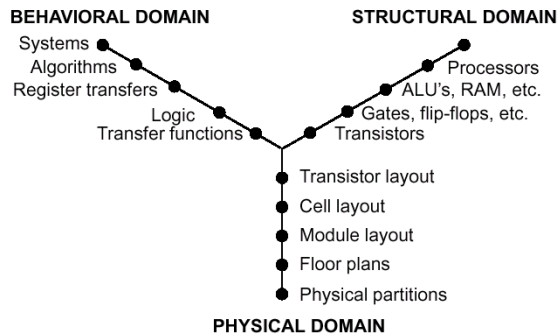


Spiral SOC Design Flow

- ❑ Characteristics
 - Parallel, concurrent development of hardware and software
 - Parallel verification and synthesis of modules
 - Floorplan, placement, and routing are included in the synthesis process
 - Modules developed only if a pre-designed hard or soft macro is not available – reusability
 - Planned iteration throughout
- ❑ The engineer are addressing all aspects of hardware and software design concurrently: functionality, timing, physical design, and verification

Waterfall vs. Spiral

- ❑ Traditional ASIC development follows so called waterfall model
 - Project transitions from phase to phase in step
 - Never returning to the activities of the previous phase
 - “Tossing” project over the wall from one team to the next
- ❑ However...
 - Complexity increases
 - Geometry shrinks
 - Time-to-market pressure increases
- ❑ In the spiral model, the design teams work on multiple aspects of the design simultaneously, incrementally improving in each area as the design converges on completion



Levels revealed

Hierarchy level	Abstraction	Supporting tools
System	space-time behavior as instruction, timing & pin assignment specifications	flow-charts, diagrams, high-level languages
Architecture	global organization of functional entities	HDLs, floor-planning block diagrams for clock cycle and area estimation
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