

第12周高数互助课堂

15.1-15.4

多元函数判断极限存在性的方法

- 换元法
- 夹逼定理
- 举反例

判断极限 $\lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + y^6}{x^3 + y}$ 是否存在

令 $y = r \sin \theta, x = r \cos \theta$ 则

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + y^6}{x^3 + y}$$

$$= \lim_{r \rightarrow 0} \frac{r^5 \cos^5 \theta + r^6 \sin^6 \theta}{r^3 \cos^3 \theta + r \sin \theta} = \lim_{r \rightarrow 0} \frac{r^4 \cos^5 \theta + r^5 \sin^6 \theta}{r^2 \cos^3 \theta + \sin \theta}$$

$$\text{当 } \theta = 0, \text{ 原极限} = \lim_{x \rightarrow 0} \frac{x^5}{x^3} = \lim_{x \rightarrow 0} x^2 = 0$$

$$\text{当 } \theta \neq 0, \text{ 原极限} = \lim_{r \rightarrow 0} \frac{0}{\sin \theta} = 0$$

原极限=0?

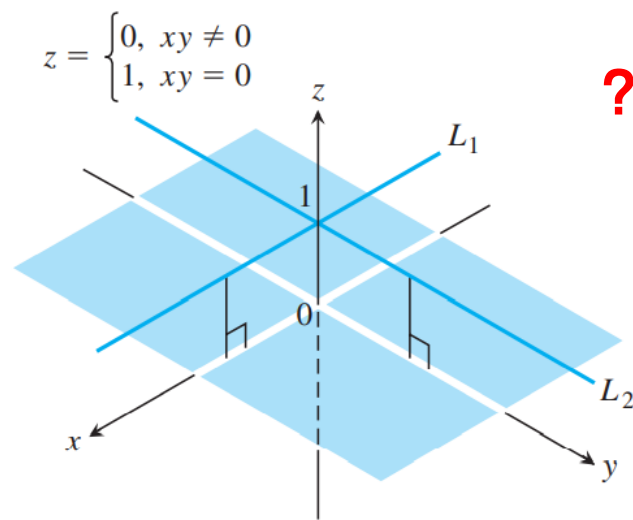
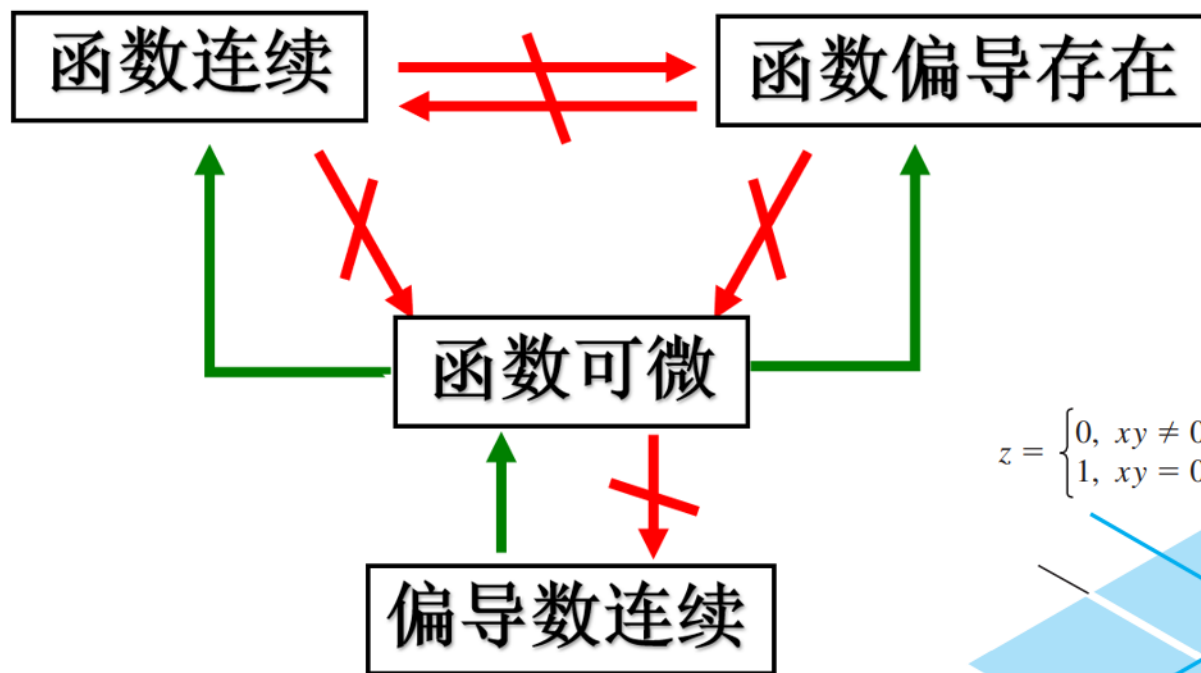
判断极限 $\lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + y^6}{x^3 + y}$ 是否存在

$$\text{let } y = -x^3 + x^5,$$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + y^6}{x^3 + y} = \lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + (-x^3 + x^5)^6}{x^5} = 1$$

$$\text{let } y = 0, \lim_{(x,y) \rightarrow (0,0)} \frac{x^5 + y^6}{x^3 + y} = 0$$

The limit does not exist.



连续

定义 3 设二元函数 $f(P) = f(x, y)$ 的定义域为 D , $P_0(x_0, y_0)$ 为 D 的聚点, 且 $P_0 \in D$. 如果

$$\lim_{(x, y) \rightarrow (x_0, y_0)} f(x, y) = f(x_0, y_0),$$

则称函数 $f(x, y)$ 在点 $P_0(x_0, y_0)$ 连续.

DEFINITION A function $f(x, y)$ is **continuous at the point** (x_0, y_0) if

1. f is defined at (x_0, y_0) ,
2. $\lim_{(x, y) \rightarrow (x_0, y_0)} f(x, y)$ exists,
3. $\lim_{(x, y) \rightarrow (x_0, y_0)} f(x, y) = f(x_0, y_0)$.

A function is **continuous** if it is continuous at every point of its domain.

定义 设函数 $z = f(x, y)$ 在点 (x_0, y_0) 的某一邻域内有定义, 当 y 固定在 y_0 而 x 在 x_0 处有增量 Δx 时, 相应的函数有增量

$$f(x_0 + \Delta x, y_0) - f(x_0, y_0),$$

偏导存在

如果

$$\lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x, y_0) - f(x_0, y_0)}{\Delta x} \quad (1)$$

存在, 则称此极限为函数 $z = f(x, y)$ 在点 (x_0, y_0) 处对 x 的偏导数, 记作

$$\left. \frac{\partial z}{\partial x} \right|_{\substack{x=x_0 \\ y=y_0}}, \left. \frac{\partial f}{\partial x} \right|_{\substack{x=x_0 \\ y=y_0}}, z_x \Big|_{\substack{x=x_0 \\ y=y_0}} \quad \text{或} \quad f_x(x_0, y_0). \textcircled{1}$$

DEFINITION The **partial derivative of** $f(x, y)$ **with respect to** x **at the point** (x_0, y_0) is

$$\left. \frac{\partial f}{\partial x} \right|_{(x_0, y_0)} = \lim_{h \rightarrow 0} \frac{f(x_0 + h, y_0) - f(x_0, y_0)}{h},$$

provided the limit exists.

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定义 设函数 $z = f(x, y)$ 在点 (x, y) 的某邻域内有定义, 如果函数在点 (x, y) 的全增量

$$\Delta z = f(x + \Delta x, y + \Delta y) - f(x, y)$$

可表示为

$$\Delta z = A\Delta x + B\Delta y + o(\rho), \quad (2)$$

其中 A, B 不依赖于 $\Delta x, \Delta y$ 而仅与 x, y 有关, $\rho = \sqrt{(\Delta x)^2 + (\Delta y)^2}$, 则称函数 $z = f(x, y)$ 在点 (x, y) 可微分, 而 $A\Delta x + B\Delta y$ 称为函数 $z = f(x, y)$ 在点 (x, y) 的全微分, 记作 dz , 即

$$dz = A\Delta x + B\Delta y.$$

如果函数在区域 D 内各点处都可微分, 那么称这函数在 D 内可微分.

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DEFINITION A function $z = f(x, y)$ is **differentiable at** (x_0, y_0) if $f_x(x_0, y_0)$ and $f_y(x_0, y_0)$ exist and Δz satisfies an equation of the form

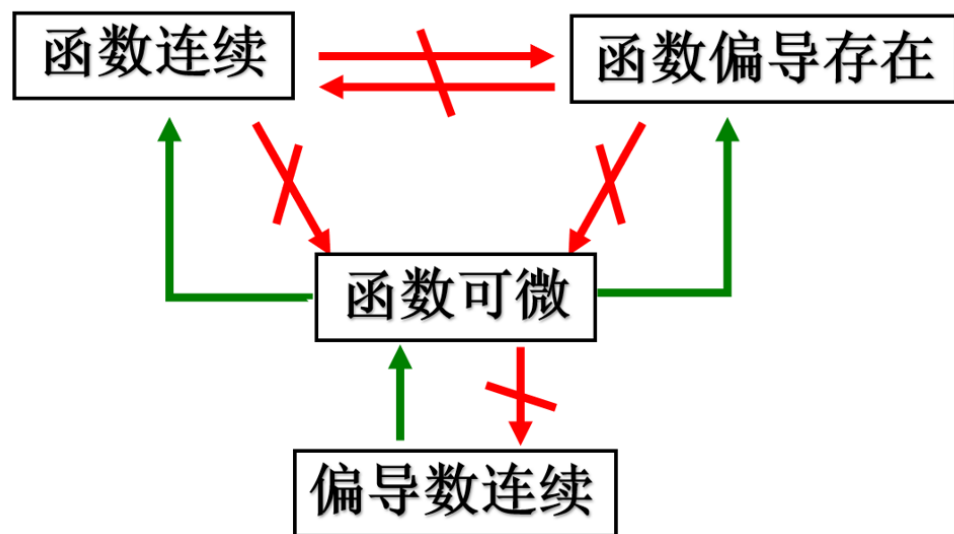
$$\Delta z = f_x(x_0, y_0)\Delta x + f_y(x_0, y_0)\Delta y + \epsilon_1\Delta x + \epsilon_2\Delta y$$

in which each of $\epsilon_1, \epsilon_2 \rightarrow 0$ as both $\Delta x, \Delta y \rightarrow 0$. We call f **differentiable** if it is differentiable at every point in its domain, and say that its graph is a **smooth surface**.

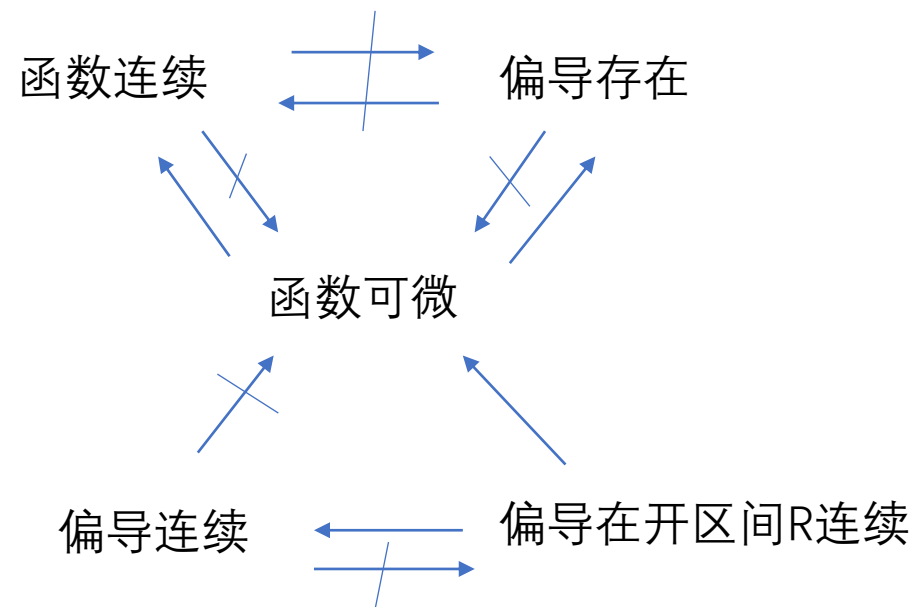
可微

COROLLARY OF THEOREM 3 If the partial derivatives f_x and f_y of a function $f(x, y)$ are continuous throughout an open region R , then f is differentiable at every point of R .

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方向导数 (标量)

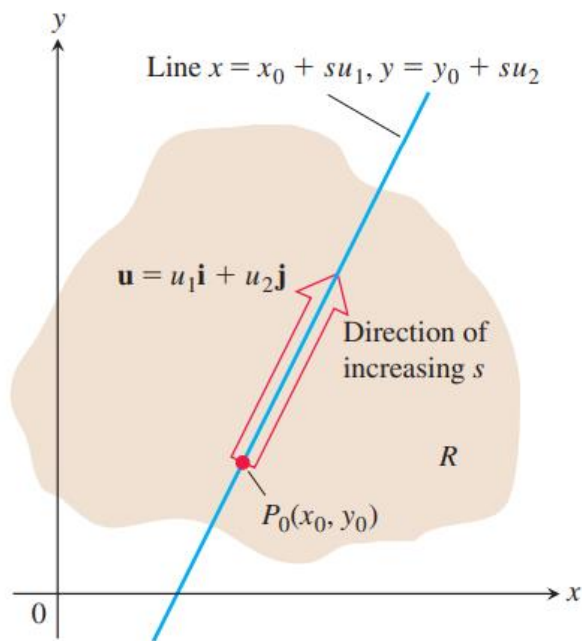
大小: 函数在 P_0 点沿 \vec{u} 方向的变化率

定义:

DEFINITION The **derivative of f at $P_0(x_0, y_0)$ in the direction of the unit vector $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j}$** is the number

$$\left(\frac{df}{ds}\right)_{\mathbf{u}, P_0} = \lim_{s \rightarrow 0} \frac{f(x_0 + su_1, y_0 + su_2) - f(x_0, y_0)}{s}, \quad (1)$$

provided the limit exists.



梯度 (矢量)

方向: 函数增长最快的方向

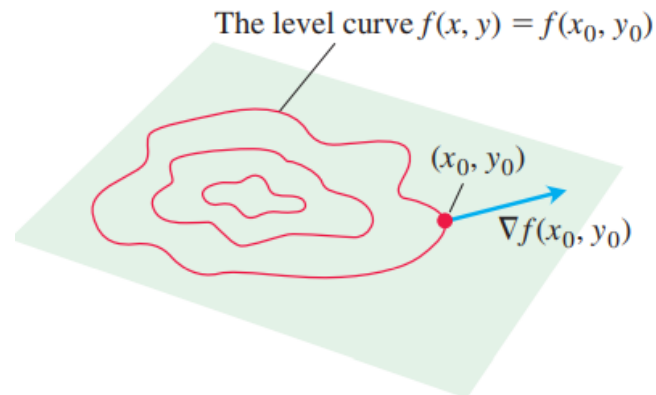
大小: 方向导数的最大值

定义:

DEFINITION The **gradient vector (gradient)** of $f(x, y)$ at a point $P_0(x_0, y_0)$ is the vector

$$\nabla f = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j}$$

obtained by evaluating the partial derivatives of f at P_0 .



DEFINITION The **derivative of f at $P_0(x_0, y_0)$ in the direction of the unit vector $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j}$** is the number


$$\left(\frac{df}{ds}\right)_{\mathbf{u}, P_0} = \lim_{s \rightarrow 0} \frac{f(x_0 + su_1, y_0 + su_2) - f(x_0, y_0)}{s}, \quad (1)$$

provided the limit exists.

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obtained by evaluating the partial derivatives of f at P_0 .



THEOREM 9—The Directional Derivative Is a Dot Product If $f(x, y)$ is differentiable in an open region containing $P_0(x_0, y_0)$, then

$$\left(\frac{df}{ds}\right)_{\mathbf{u}, P_0} = (\nabla f)_{P_0} \cdot \mathbf{u}, \quad (4)$$

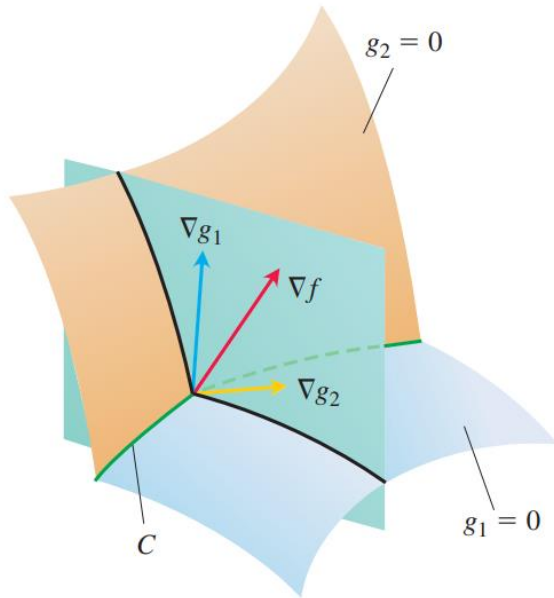
the dot product of the gradient ∇f at P_0 and \mathbf{u} . In brief, $D_{\mathbf{u}}f = \nabla f \cdot \mathbf{u}$.

The Method of Lagrange Multipliers

Suppose that $f(x, y, z)$ and $g(x, y, z)$ are differentiable and $\nabla g \neq \mathbf{0}$ when $g(x, y, z) = 0$. To find the local maximum and minimum values of f subject to the constraint $g(x, y, z) = 0$ (if these exist), find the values of x, y, z , and λ that simultaneously satisfy the equations

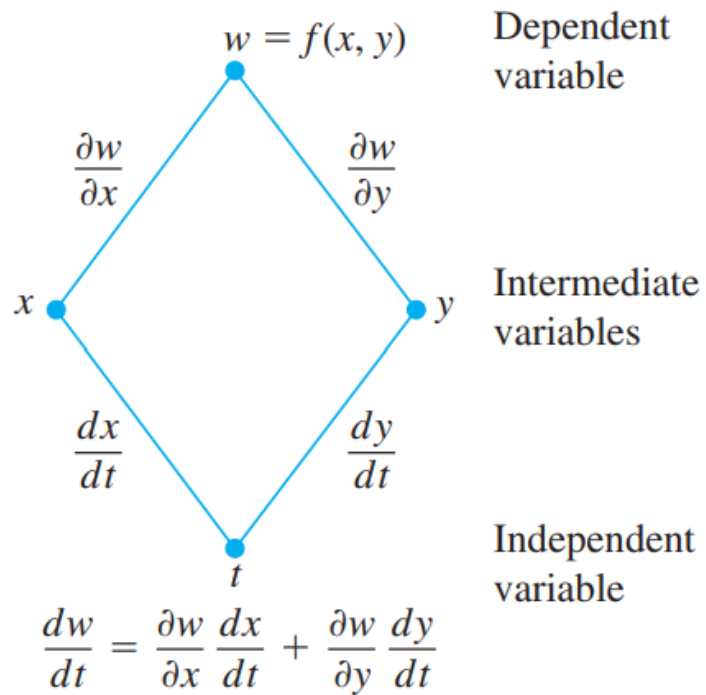
$$\nabla f = \lambda \nabla g \quad \text{and} \quad g(x, y, z) = 0. \quad (1)$$

For functions of two independent variables, the condition is similar, but without the variable z .



$$\nabla f = \lambda \nabla g_1 + \mu \nabla g_2, \quad g_1(x, y, z) = 0, \quad g_2(x, y, z) = 0$$

Chain Rule

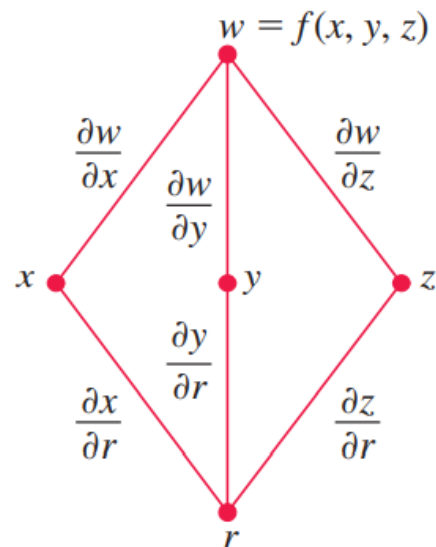


THEOREM 5—Chain Rule For Functions of One Independent Variable and Two Intermediate Variables If $w = f(x, y)$ is differentiable and if $x = x(t)$, $y = y(t)$ are differentiable functions of t , then the composite $w = f(x(t), y(t))$ is a differentiable function of t and

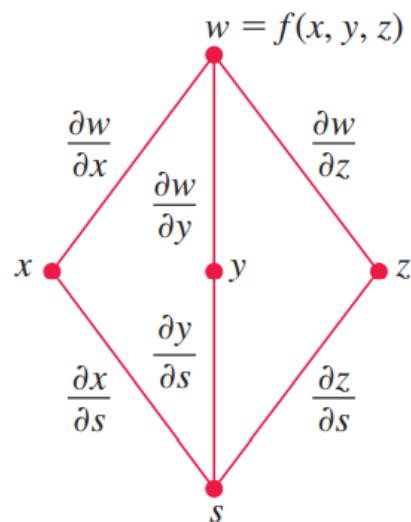
$$\frac{dw}{dt} = f_x(x(t), y(t)) \cdot x'(t) + f_y(x(t), y(t)) \cdot y'(t),$$

or

$$\frac{dw}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}.$$



$$\frac{\partial w}{\partial r} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial r} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial r}$$



$$\frac{\partial w}{\partial s} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial s}$$

THEOREM 7—Chain Rule for Two Independent Variables and Three Intermediate Variables Suppose that $w = f(x, y, z)$, $x = g(r, s)$, $y = h(r, s)$, and $z = k(r, s)$. If all four functions are differentiable, then w has partial derivatives with respect to r and s , given by the formulas

$$\frac{\partial w}{\partial r} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial r} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial r}$$

$$\frac{\partial w}{\partial s} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial w}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial s}.$$

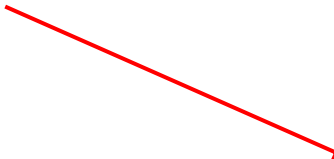
Summary of Max-Min Tests

The extreme values of $f(x, y)$ can occur only at

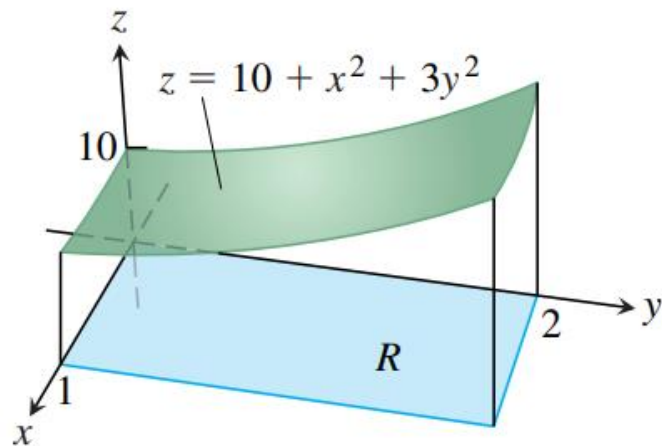
- i) **boundary points** of the domain of f
- ii) **critical points** (interior points where $f_x = f_y = 0$ or points where f_x or f_y fails to exist).

If the first- and second-order partial derivatives of f are continuous throughout a disk centered at a point (a, b) and $f_x(a, b) = f_y(a, b) = 0$, the nature of $f(a, b)$ can be tested with the **Second Derivative Test**:

- i) $f_{xx} < 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$ at $(a, b) \Rightarrow$ **local maximum**
- ii) $f_{xx} > 0$ and $f_{xx}f_{yy} - f_{xy}^2 > 0$ at $(a, b) \Rightarrow$ **local minimum**
- iii) $f_{xx}f_{yy} - f_{xy}^2 < 0$ at $(a, b) \Rightarrow$ **saddle point**
- iv) $f_{xx}f_{yy} - f_{xy}^2 = 0$ at $(a, b) \Rightarrow$ **test is inconclusive**

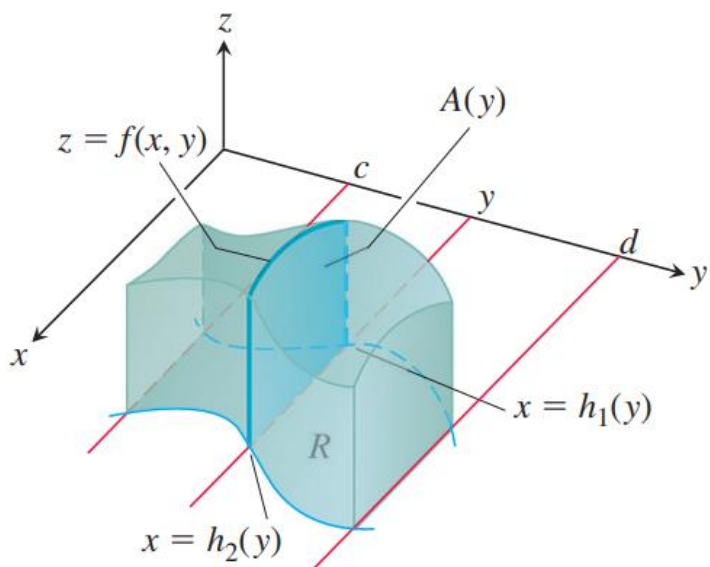

$$f_{xx}f_{yy} - f_{xy}^2 = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{xy} & f_{yy} \end{vmatrix}.$$

15.1-15.4



THEOREM 1—Fubini's Theorem (First Form) If $f(x, y)$ is continuous throughout the rectangular region $R: a \leq x \leq b, c \leq y \leq d$, then

$$\iint_R f(x, y) \, dA = \int_c^d \int_a^b f(x, y) \, dx \, dy = \int_a^b \int_c^d f(x, y) \, dy \, dx.$$



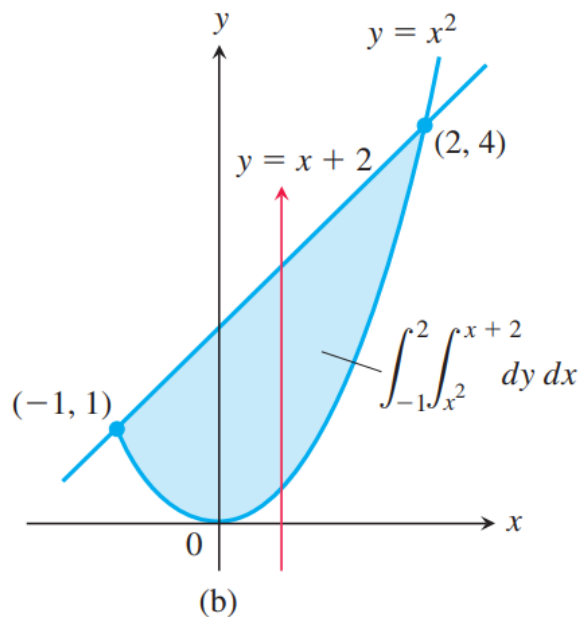
THEOREM 2—Fubini's Theorem (Stronger Form) Let $f(x, y)$ be continuous on a region R .

1. If R is defined by $a \leq x \leq b, g_1(x) \leq y \leq g_2(x)$, with g_1 and g_2 continuous on $[a, b]$, then

$$\iint_R f(x, y) \, dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x, y) \, dy \, dx.$$

2. If R is defined by $c \leq y \leq d, h_1(y) \leq x \leq h_2(y)$, with h_1 and h_2 continuous on $[c, d]$, then

$$\iint_R f(x, y) \, dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x, y) \, dx \, dy.$$



EXAMPLE 2 Find the area of the region R enclosed by the parabola $y = x^2$ and the line $y = x + 2$.

Solution If we divide R into the regions R_1 and R_2 shown in Figure 15.20a, we may calculate the area as

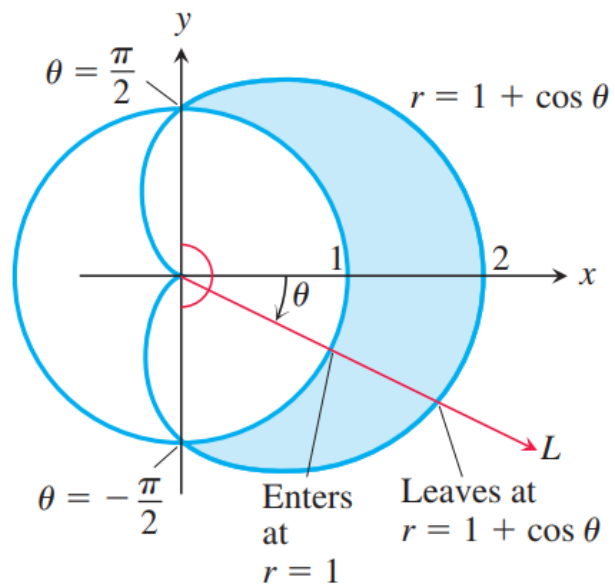
$$A = \iint_{R_1} dA + \iint_{R_2} dA = \int_0^1 \int_{-\sqrt{y}}^{\sqrt{y}} dx dy + \int_1^4 \int_{y-2}^{\sqrt{y}} dx dy.$$

On the other hand, reversing the order of integration (Figure 15.20b) gives

$$A = \int_{-1}^2 \int_{x^2}^{x+2} dy dx.$$

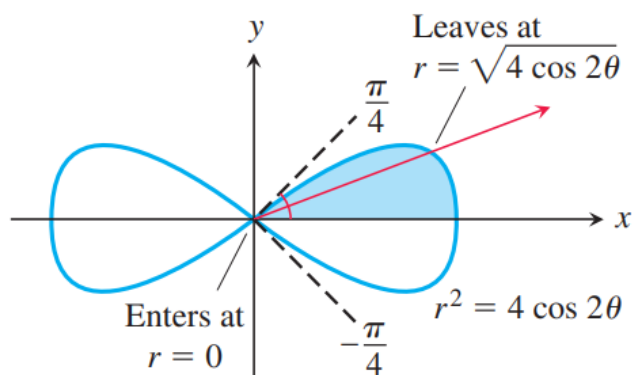
This second result, which requires only one integral, is simpler and is the only one we would bother to write down in practice. The area is

$$A = \int_{-1}^2 \left[y \right]_{x^2}^{x+2} dx = \int_{-1}^2 (x + 2 - x^2) dx = \left[\frac{x^2}{2} + 2x - \frac{x^3}{3} \right]_{-1}^2 = \frac{9}{2}. \quad \blacksquare$$



EXAMPLE 1 Find the limits of integration for integrating $f(r, \theta)$ over the region R that lies inside the cardioid $r = 1 + \cos \theta$ and outside the circle $r = 1$.

$$\int_{-\pi/2}^{\pi/2} \int_1^{1+\cos \theta} f(r, \theta) r \, dr \, d\theta.$$



EXAMPLE 2 Find the area enclosed by the lemniscate $r^2 = 4 \cos 2\theta$.

$$\begin{aligned} A &= 4 \int_0^{\pi/4} \int_0^{\sqrt{4 \cos 2\theta}} r \, dr \, d\theta = 4 \int_0^{\pi/4} \left[\frac{r^2}{2} \right]_{r=0}^{r=\sqrt{4 \cos 2\theta}} d\theta \\ &= 4 \int_0^{\pi/4} 2 \cos 2\theta \, d\theta = 4 \sin 2\theta \Big|_0^{\pi/4} = 4. \end{aligned}$$

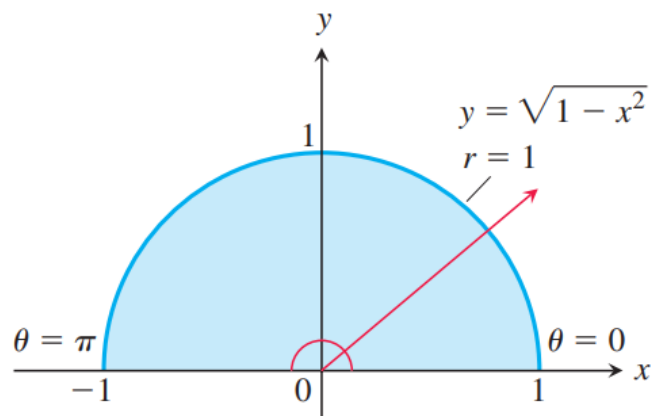
EXAMPLE 4 Evaluate the integral

$$\int_0^1 \int_0^{\sqrt{1-x^2}} (x^2 + y^2) dy dx.$$

Solution Integration with respect to y gives

$$\int_0^1 \left(x^2 \sqrt{1-x^2} + \frac{(1-x^2)^{3/2}}{3} \right) dx,$$

an integral difficult to evaluate without tables.



EXAMPLE 4 Evaluate the integral

$$\int_0^1 \int_0^{\sqrt{1-x^2}} (x^2 + y^2) dy dx.$$

$$\begin{aligned} \int_0^1 \int_0^{\sqrt{1-x^2}} (x^2 + y^2) dy dx &= \int_0^{\pi/2} \int_0^1 (r^2) r dr d\theta \\ &= \int_0^{\pi/2} \left[\frac{r^4}{4} \right]_{r=0}^{r=1} d\theta = \int_0^{\pi/2} \frac{1}{4} d\theta = \frac{\pi}{8}. \end{aligned}$$