

Question 1 (10 points). Determine the values of h for which the following vectors are linearly dependent.

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -5 \\ 7 \\ 8 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ h \end{bmatrix}.$$

$$\left[\begin{array}{ccc|c} 1 & -5 & 1 & 0 \\ -1 & 7 & 1 & 0 \\ 3 & 8 & h & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & -5 & 1 & 0 \\ 0 & 2 & 2 & 0 \\ 0 & 23 & h-3 & 0 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|c} 1 & -5 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & h-26 & 0 \end{array} \right]$$

$$h = 26$$

Question 2 (12 points). Let

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 1 & 1 & -1 \\ 1 & 1 & 3 & 3 \\ -1 & -1 & 1 & 1 \end{bmatrix}$$

a. Reduce A to an Echelon form.

$$A \sim \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 2 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

b. Compute $\det(A)$. Is A invertible? **Hint:** Use Echelon form of A to compute $\det(A)$.

$$\det A = 1 \cdot 2 \cdot 2 \cdot 0 = 0$$

A is not invertible.

c. Let T be the linear transformation $T(\mathbf{x}) = A\mathbf{x}$. Is T one-to-one? Justify your answer.

T is not one-to-one because $A\vec{x} = \vec{0}$ has nontrivial solutions (the rightmost column in the echelon form gives a free variable).

d. Find a basis for column space $\text{Col}A$.

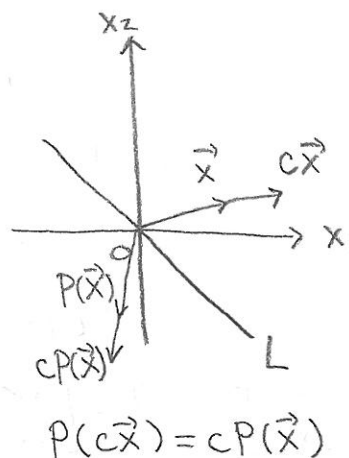
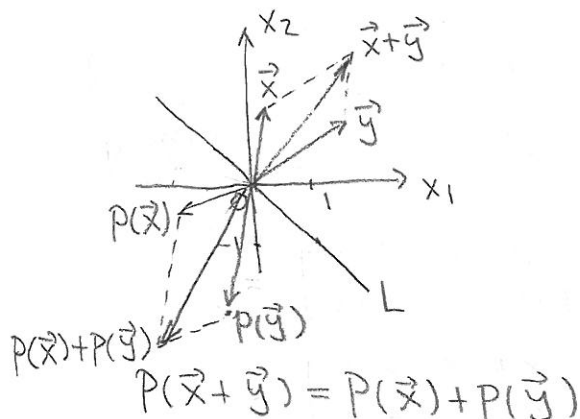
$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 3 \\ 1 \end{bmatrix} \right\} \quad \text{or} \quad \left\{ \begin{bmatrix} 1 \\ -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 3 \\ 1 \end{bmatrix} \right\}$$

Question 3 (10 points). Let $L = \text{Span}\left\{\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right\}$ be a line in \mathbb{R}^2 . Let $P : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the reflection about the line L ,

$$P(\mathbf{x}) = \mathbf{x} - 2\mathbf{x}^\perp$$

where $\mathbf{x}^\perp = \mathbf{x} - \text{proj}_L \mathbf{x}$

a. Show that P is a linear transformation.



b. Find the standard matrix for P .

$$\begin{bmatrix} P\begin{bmatrix} 1 \\ 0 \end{bmatrix} & P\begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

c. Find the eigenvalues and corresponding eigenvectors for the matrix in part b.

$$\det \begin{bmatrix} -\lambda & -1 \\ -1 & -\lambda \end{bmatrix} = \lambda^2 - 1 = 0 \Rightarrow \lambda = \pm 1$$

$$\underline{\lambda = 1} \quad \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\underline{\lambda = -1} \quad \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Question 4 (10 points). Suppose for the matrix A we know $\det(A - \lambda I) = \lambda^3(3 - \lambda)(4 + \lambda)(7 + \lambda)(18 - \lambda)$

a. Find all possible values of rank A .

Since the characteristic polynomial is of degree 7,

A is 7×7 .

Since the algebraic multiplicity of $\lambda = 3, -4, -7, 18$ is 1 each, these eigenvalues have 1-dimensional eigenspaces.

The algebraic multiplicity of $\lambda = 0$ equals 3, and thus the corresponding eigenspace can be of dimension 1, 2 or 3.

dim=1 $A\vec{x} = \vec{0}$ has 1 free variable, rank $A = 7 - 1 = 6$

dim=2 $A\vec{x} = \vec{0}$ has 2 free variables, rank $A = 7 - 2 = 5$

dim=3 $A\vec{x} = \vec{0}$ has 3 free variables, rank $A = 7 - 3 = 4$

examples
 $\begin{bmatrix} 0 & 0 & 0 & 3 & -4 & -7 & 18 \\ 0 & 0 & 0 & 3 & -4 & -7 & 18 \\ 0 & 0 & 0 & 3 & -4 & -7 & 18 \end{bmatrix}$

b. Answer the same question as in part a. under the further assumption that A is diagonalizable.

Since A is diagonalizable, it must be the last case above (geometric multiplicity = algebraic multiplicity = 3).

$$\text{rank } A = 4$$

Question 5 (10 points). Let

$$A = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

a. Find the eigenvalues of A .

$$\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 1 & 1 \\ 1 & 2-\lambda & 1 \\ 1 & 1 & 2-\lambda \end{vmatrix}$$

$$= (2-\lambda) \begin{vmatrix} 2-\lambda & 1 \\ 1 & 2-\lambda \end{vmatrix} - 1 \cdot \begin{vmatrix} 1 & 1 \\ 1 & 2-\lambda \end{vmatrix} + 1 \cdot \begin{vmatrix} 1 & 2-\lambda \\ 1 & 1 \end{vmatrix}$$

$$= (2-\lambda)(\lambda^2 - 4\lambda + 3) - (1-\lambda) + (\lambda-1)$$

$$= (2-\lambda)(\lambda-1)(\lambda-3) + 2(\lambda-1)$$

$$= (\lambda-1)(-\lambda^2 + 5\lambda - 4) = -(\lambda-1)^2(\lambda-4) \Rightarrow \lambda=1 \text{ or } \lambda=4$$

b. Is A diagonalizable? If so find an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$.

$$\underline{\lambda=1} \quad A - \lambda I = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \vec{v} = \begin{bmatrix} -s-t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\underline{\lambda=4} \quad A - \lambda I = \begin{bmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & -2 \\ 1 & -2 & 1 \\ -2 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & -2 \\ 0 & -3 & 3 \\ 0 & 3 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \vec{v} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

A is diagonalizable, $AP = PD$ with $P = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

c. Compute P^{-1} in part b.

$$\begin{aligned} & \left[\begin{array}{ccc|ccc} -1 & -1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 1 & -1 & -1 & 0 & 0 \\ 0 & -1 & 2 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 \end{array} \right] \\ & \sim \left[\begin{array}{ccc|ccc} 1 & 1 & -1 & -1 & 0 & 0 \\ 0 & 1 & -2 & -1 & -1 & 0 \\ 0 & 0 & 3 & 1 & 1 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 1 & -1 & -1 & 0 & 0 \\ 0 & 1 & -2 & -1 & -1 & 0 \\ 0 & 0 & 1 & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{array} \right] \\ & \sim \left[\begin{array}{ccc|ccc} 1 & 1 & 0 & -\frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 0 & -\frac{1}{3} & -\frac{1}{3} & \frac{2}{3} \\ 0 & 0 & 1 & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -\frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ 0 & 1 & 0 & -\frac{1}{3} & -\frac{1}{3} & \frac{2}{3} \\ 0 & 0 & 1 & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{array} \right] \Rightarrow P^{-1} = \begin{bmatrix} -\frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & -\frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \end{aligned}$$

Question 6 (10 points). Find an orthonormal basis for $\text{Col } A$, where

$$A = \begin{bmatrix} 0 & 2 & 3 \\ 1 & 2 & 0 \\ 0 & 2 & 3 \\ 1 & 2 & 0 \end{bmatrix}$$

$\vec{a}_1 \quad \vec{a}_2 \quad \vec{a}_3$

$$\vec{v}_1 = \vec{a}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{v}_2 = \vec{a}_2 - \frac{\vec{a}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1$$

$$= \begin{bmatrix} 2 \\ 2 \\ 2 \\ 2 \end{bmatrix} - \frac{4}{2} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 0 \\ 2 \\ 0 \end{bmatrix}$$

$$\vec{v}_3 = \vec{a}_3 - \frac{\vec{a}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{a}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

$$= \begin{bmatrix} 3 \\ 0 \\ 3 \\ 0 \end{bmatrix} - 0 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} - \frac{12}{8} \begin{bmatrix} 2 \\ 0 \\ 2 \\ 0 \end{bmatrix} = \vec{0}$$

Thus an orthogonal basis for $\text{Col } A$ is $\{\vec{v}_1, \vec{v}_2\}$

and the corresponding orthonormal basis is $\left\{ \begin{bmatrix} 0 \\ 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ 1/\sqrt{2} \\ 0 \end{bmatrix} \right\}$

Question 7 (10 points). Given vectors

$$\mathbf{a} = \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix},$$

find the orthogonal projection of \mathbf{a} onto $\text{Span}\{\mathbf{b}, \mathbf{c}\}$.

Note that \vec{b} and \vec{c} are not orthogonal.

Find an orthogonal basis for $\text{Span}\{\vec{b}, \vec{c}\}$ by taking

$$\vec{v}_1 = \vec{b} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\vec{v}_2 = \vec{c} - \frac{\vec{c} \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

Then the orthogonal projection of \vec{a} can be computed as

$$\frac{\vec{a} \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 + \frac{\vec{a} \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

$$= \frac{4}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{3}{\frac{3}{2}} \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}$$

Question 8 (10 points). Suppose that a data set consists of points $(-2, 6)$, $(-1, 3)$, $(0, 0)$, $(1, 0)$ and $(2, 1)$ on the xy -plane. Determine the parabola

$$y = ax^2 + bx + c$$

that best models the relation between the x and y coordinates of these sample values. Hint: Compute a least-squares solution for $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{bmatrix} 4 & -2 & 1 \\ 1 & -1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 6 \\ 3 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

Set up the normal equations

$$A^T(\vec{b} - A\vec{x}) = \vec{0}$$

$$A^T A \vec{x} = A^T \vec{b}$$

$$\begin{bmatrix} 4 & 1 & 0 & 1 & 4 \\ -2 & -1 & 0 & 1 & 2 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 4 & -2 & 1 \\ 1 & -1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \\ 4 & 2 & 1 \end{bmatrix} \vec{x} = \begin{bmatrix} 4 & 1 & 0 & 1 & 4 \\ -2 & -1 & 0 & 1 & 2 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 6 \\ 3 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 34 & 0 & 10 \\ 0 & 10 & 0 \\ 10 & 0 & 5 \end{bmatrix} \vec{x} = \begin{bmatrix} 31 \\ -13 \\ 10 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 34 & 0 & 10 & 31 \\ 0 & 10 & 0 & -13 \\ 10 & 0 & 5 & 10 \end{array} \right] \sim \left[\begin{array}{ccc|c} 2 & 0 & 1 & 2 \\ 0 & 10 & 0 & -13 \\ 0 & 0 & -7 & -3 \end{array} \right] \Rightarrow \vec{x} = \begin{bmatrix} \frac{1}{2}(2 - \frac{3}{7}) \\ -\frac{13}{10} \\ \frac{3}{7} \end{bmatrix} = \begin{bmatrix} \frac{11}{14} \\ -\frac{13}{10} \\ \frac{3}{7} \end{bmatrix}$$

Thus the parabola is $y = \frac{11}{14}x^2 - \frac{13}{10}x + \frac{3}{7}$.

Question 9 (18 points). True or false? Justify your answer

- a. If \mathbf{v} and \mathbf{w} are two eigenvectors for the matrix A then $2\mathbf{v} + 3\mathbf{w}$ must also be an eigenvector for A .

False, if \vec{v} and \vec{w} belong to different eigenvalues.

Even better, let $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

- b. Every real 2×2 matrix with complex eigenvalues with non-zero imaginary part is similar to a matrix of rotation around the origin by some angle θ .

False, in general it is similar to the product of such a matrix and a diagonal matrix $\begin{bmatrix} c & 0 \\ 0 & c \end{bmatrix}$ (dilation).

- c. A linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$ is never onto.

True, $T\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $T\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ can span a subspace of \mathbb{R}^4 of dimension at most 2.

- d. A 4×4 real matrix always has at least one real eigenvalue.

False. Let $A = \left[\begin{array}{cc|cc} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & -2 \\ 0 & 0 & 2 & 0 \end{array} \right]$.

- e. If two $n \times n$ matrices A and B have the same characteristic polynomials then they are similar.

False. Let $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$.

- f. If A^3 is not invertible, neither is A .

True. Suppose A is invertible, with inverse A^{-1} .

Then $(A^{-1})^3$ would be the inverse of A^3 .