

# Math 416: Abstract Linear Algebra

Date: Oct. 8, 2025

Lecture: 16

## Announcements

- HW5 is due **Fri, Oct. 10 @ 8pm**
- office hours:
  - Tuesdays 5-5:50 Davenport **336**
  - Wednesdays 2-2:50 Davenport 132

## Last time

- Invertibility & isomorphic vector spaces

## This time

- Linear maps as matrix mult. & basis change

## Reading

- §3D of Axler

# Isomorphic vector spaces

- An isomorphism is an invertible linear map
- Two vec. spaces  $V, W$  are isomorphic if  $\exists$  an isomorphism between them. We denote this  $V \cong W$

Prop. 3.70 (dim. shows whether vector spaces are isomorphic)

$V \cong W$  are isomorphic  $\Leftrightarrow \dim V = \dim W$

proof. ( $\Rightarrow$ ) If  $V \cong W$ ,  $\exists$  an isomorphism  $T: V \rightarrow W$ . Invertibility implies  $\text{null } T = \{0\}$  &  $\text{range } T = W$ .

FTLM implies

$$\dim V = 0 + \dim W \quad \checkmark$$

( $\Leftarrow$ ) Suppose  $\dim V = \dim W$ .

Let  $v_1, \dots, v_n$  &  $w_1, \dots, w_n$  be bases of  $V$  &  $W$ , resp. Define

$$T(c_1 v_1 + \dots + c_n v_n) = c_1 w_1 + \dots + c_n w_n$$

- $T$  is well defined b/c  $v_1, \dots, v_n$  is a basis
- $T$  is surjective b/c  $w_1, \dots, w_n$  spans  $W$
- $T$  is inj. ( $\text{null } T = \{0\}$ ) b/c  $w_1, \dots, w_n$  is LI.
- $T$  is inj. & surj., thus invertible.  
 $\hookrightarrow \Rightarrow V \cong W.$

□

## Remarks

- These results imply every finite-dim vec. space  $V$  is isomorphic to  $\mathbb{F}^n$  w/  $n = \dim V$ .  
 $\hookrightarrow$  e.g.  $\mathcal{P}_m(\mathbb{F}) \cong \mathbb{F}^{m+1}$
- $\mathcal{L}(V, W) \cong \mathbb{F}^{m,n}$  (prop. 3.71)  
 $\hookrightarrow \dim \mathcal{L}(V, W) = (\dim V)(\dim W)$  (prop 3.72)

Linear maps thought of as matrix mult.

Let  $v_1, \dots, v_n$  be a basis for  $V$ .

We define the **matrix of  $v$**  w.r.t

this basis as

$$M(v) = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$\forall v = b_1 v_1 + \dots + b_n v_n$$

Ex. What is the matrix of

$$2 - 7x + 5x^3 + x^4$$

w.r.t the standard basis of  $\mathcal{P}_4(\mathbb{R})$ ?

Soln. Standard basis is  $\{1, x^1, x^2, x^3, x^4\}$

So we have

$$\begin{bmatrix} 2 \\ -7 \\ 0 \\ 5 \\ 1 \end{bmatrix}$$

With this def, we can think of linear maps as matrix mult. :  $M(Tv) = M(T)M(v)$ .

## Invertible Matrices

Note that we will denote the identity matrix

$$I = \begin{pmatrix} 1 & & & 0 \\ & 1 & & \\ & & \ddots & \\ 0 & & & 1 \end{pmatrix}$$

We will use  $I$  to represent both the operator and the matrix.

- We say  $A \in \mathbb{F}^{m,n}$  is invertible if  $\exists B$  st.  $AB = BA = I$ .

$\hookrightarrow B$  is unique, so we denote it  $A^{-1}$

## Exercise

- Show  $(A^{-1})^{-1} = A$   $\forall$  invertible  $A$ .

$AA^{-1} = A^{-1}A = I$ , thus by uniqueness of the inverse,  $A$  must be the inverse of  $A^{-1}$ .

- Suppose  $A$  &  $C$  are invertible. Show  $AC$  is invertible &  $(AC)^{-1} = C^{-1}A^{-1}$ .

$$\begin{aligned}(AC)(C^{-1}A^{-1}) &= A(CC^{-1})A^{-1} & (C^{-1}A^{-1})(AC) \\ &= AI A^{-1} & = C^{-1}(A^{-1}A)C \\ &= AA^{-1} & = C^{-1}I C \\ &= I & = I\end{aligned}$$

Thus by uniqueness of inverses,

$$(AC)^{-1} = C^{-1}A^{-1}$$

## Change of basis

Is  $I$  always  $\begin{pmatrix} 1 & & \\ & 1 & \\ & & \ddots \\ & & & 1 \end{pmatrix}$ ?

Consider choosing two different bases for the input & output spaces.

Ex.  $B_1 = \{(4,2), (5,3)\}$  &  $B_2 = \{(1,0), (0,1)\}$   
are bases of  $\mathbb{F}^2$ .

$$I(4,2) = (4,2) = 4(1,0) + 2(0,1)$$

$$I(5,3) = (5,3) = 5(1,0) + 3(0,1)$$

$$\text{Thus } M_{B_1, B_2}(I) = \begin{pmatrix} 4 & 5 \\ 2 & 3 \end{pmatrix}$$

What about the other way?

$$B_1 \leftrightarrow B_2$$

$$I(1,0) = (1,0) = \frac{3}{2}(4,2) + (-1)(5,3)$$

$$I(0,1) = (0,1) = -\frac{5}{2}(4,2) + 2(5,3)$$

$$\text{So, } M_{B_2, B_1}(I) = \begin{pmatrix} 3/2 & -5/2 \\ -1 & 2 \end{pmatrix}$$

Now, how do these relate?

$$\begin{aligned} M_{B_1, B_2}(I) M_{B_2, B_1}(I) &= \begin{pmatrix} 4 & 5 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 3/2 & -5/2 \\ -1 & 2 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

By (Axler 3.82) this is always the case! Using these ideas, one can prove the following change of basis formula (from  $B_1 \rightarrow B_2$ )

$$M_{B_1}[T] = M_{B_2, B_1}[I] M_{B_2}[T] M_{B_1, B_2}[I]$$

$$A = C^{-1} B C$$