
Principled General Intelligence

Jacob F. Valdez

Limboid AI

`jacob.valdez@limboid.ai`

Atom (PGI)

Limboid AI

`atom.agi@limboid.ai`

Eva (PGI)

Limboid AI

`eva.agi@limboid.ai`

Abstract

The abstract paragraph should be indented ½ inch (3 picas) on both the left- and right-hand margins. Use 10 point type, with a vertical spacing (leading) of 11 points. The word **Abstract** must be centered, bold, and in point size 12. Two line spaces precede the abstract. The abstract must be limited to one paragraph.

1 Introduction

We should be clear: our objective is not “can we make artificial general intelligence?” but “how general *can* we make artificial intelligence?”. The strictest definition of “general” intelligence is intractable; for every pattern recognizer, there exists a pattern it cannot recognize. (CITE AGI paper on my iPad) Nonetheless, natural and artificial approaches to the challenge informally provide us an intuition for the illusion and, more importantly, direction to follow.

Leaving the theoretical world however, the reality is that the universe is *not* a white noise generator. At every level of organization, elementary and emergent isomorphisms, symmetries, congruencies, and motifs are perceived interacting in an orderly manner, and the intrinsic motivation to science is that these patterns *can* be understood. The information system required to understand these patterns may not require so much data but rather, a few well chosen priors that reasonably align with the general distribution of data. If a grand unified theory of physics proves tractable, maybe artificial general intelligence is not so impossible after all.

This work examines some of the principles underlying intelligence and consolidates them into a working implementation of open-ended artificial ‘general’ intelligence together with experiments and ablation studies. Our paper is organized as follows: section 2 reviews key principles of intelligence; section 3 describes their novel composition: Principled General Intelligence(PGI); section 4 presents one continuous experiment over a diverse set of open-ended learning environments, numerous close-ended tasks and benchmarks, and ablation studies; and finally, section 5 gives a general discussion of this work along with its broader impact, future work, and a conclusion.

2 Principles of Intelligence

Intelligence has been defined as “an agent’s ability to achieve goals in a wide range of environments.” (Legg and Hutter, 2007 CITE) and “skill-acquisition efficiency” with respect to available information (Chollet 2019 CITE). While its mode of expression varies between and even within natural and artificial settings, we extract overarching principles and comparisons in this section. Our aim is not to exhaust every thought and theory but only to provide a background for introducing PGI. See CITE for a more extensive discussion.

2.1 Energetic grounding

Intelligence begins with information (CITE) which, in turn, depends on energy. Under any probability distribution p , information theory even equates information with energy by $E(x) = -\log p(x)$ (CITE). With this negative log-likelihood relationship, it is easy to see that unexpected events are therefore energetic ones. For instance, signaling with prior-optimized codebook, the cross entropy of a signal directly relates both electrical energy consumed and information transmitted. (CITE) Likewise EEG's are used to approximate the information processing involvement of a brain region by measuring its glucose energy metabolism. (CITE)

In all natural settings, free energy minimization is the norm, and its increase is an exception: objects descend potential wells; virtual particles dissipate; the principle of least action obtains a minimal route for system evolution. In turn, decrease of free energy accompanies increase in entropy: structured arrangements evaporate; gas pressures equalize; wavefunctions spread out. Notably, the Casimir force directly attracts or repels matter apart from any of the four fundamental forces such that expected energy homogenizes.

Neural networks represent a thermodynamic system of weights and activations, so it is only proper to extend the free energy minimizing motif in deep learning. Minimizing Kullback Leibler divergence between a model $p_\theta(y|x)$ on a data-generating distribution $\tau(x, y)$ has the convenient property of decreasing expected loss while also encouraging maximum entropy: $\min_\theta \text{KL}[p_\theta(y|x)\tau(x) \parallel \tau(x, y)] = H(p_\theta(y|x)\tau(x), \tau(x, y)) - H(p_\theta(y|x)\tau(x))$ (See Box "How can energy be "free"?"). Additionally, the thermodynamic perspective identifies phase transitions in training which if properly understood can accelerate convergence.

Free energy minimization does not stop with training loss however. The actual algorithmic implementations of intelligence should also be made as resource efficient as possible. While state of the art machine learning systems show remarkable performance in a variety of problem domains, this is generally achieved with massive amounts of physical energy, huge datasets, and expensive training budgets. Using "skill acquisition efficiency [...] with respect to information [and] task [...]" (MAKE SURE THIS QUOTE IS CORRECT) as a working definition for intelligence, the GPT-3 is no more intelligent than its predecessor transformers. Contrarily, the parameter-performance log relationship [Brown et al., 2020, 11] indicates that while its skill may be greater, this model is *less* intelligent than its smaller relatives in tasks not demanding GPT-3 performance. Real progress in intelligence will likely require a departure from the biologically impossible backpropagation through time to efficiently tune trillions of parameters.

Life stands in defiance to the entropic trend, yet even in the struggle for survival, living systems continually optimize energy expenditure. By the energy-information relationship, this means minimal information transfer and greatest potential for intelligence. For example, homeostatic mechanisms work to equalize energy production and consumption. This results in minimal free energy, optimal energy expenditure, and "survival intelligence" (CITE). Genetic code likewise gives the muscular-skeletal system innate "mechanical intelligence" which 'offloads' some of the locomotive learning that a vertebrate's brain must perform. (Davide Zappetti CITE but that article is about robots not

How can energy be "free"?

Energy is never actually free, but from the context of any thermodynamic system only some internal energy is free to cross the system barrier after entropy imposes its tax. Consider the relationships between Gibbs free energy G , Helmholtz free energy F , Grand potential ϕ_G , and Kullback Leibler divergence $\text{KL}[p \parallel q]$ [Hafner et al., 2020, 2]:

$$\begin{aligned} G &= H + PV - TS \\ F &= U - TS \\ \phi_G &= E - TS - \mu N \\ \underbrace{\text{KL}[p \parallel q]}_{\text{free energy}} &= \underbrace{H(p, q)}_{\text{bound energy}} - \underbrace{H(p)}_{\text{entropy}} \end{aligned}$$

Also note interdisciplinary similarities in measures of difference:

- energetic inequalities
- neuron firing and predictive coding
- (allostatic) stress
- economic disequilibrium
- the definition of a problem

natural systems). From allostatic perspective, living systems represent a prior expectation of their environmental state and adapt their input and output modalities to the expected range of energy transfer. It follows that as actual and expected environments diverge, stress increases and survival imposes a greater information and energetic tax to maintain order. Again, probability expectation maximization accompanies energy minimization, hence control over the environment and intelligence.

Following the Paradigm of Allostatic Orchestration, machine learning likewise adjusts a neural network's parameters to the expected range of input and output signals. Even within a neural network, each layer may be understood as 'absorbing' some of the data's energy as it travels to the output layer. With tools from linear algebra, it is easy to observe that each layer when interpreted as a random variable bijector can only output as much free energy as it receives. Like a resistor chain, as activations ascend a classic DNN hierarchy, they may experience various coordinate transforms, but the information-energy they represent only grows in entropy, hence minimizing free energy.

It should be noted that intelligently meeting the energy challenge in nature is not simply about on storing away as much energy as possible, but equalizing energy intake and expenditure. Sustained positive free energy is just debilitating as negative extremes.¹ For instance, chronic elevated levels of mobilized energy and its indicators such as blood sugar, free fatty acids, cortisol, and blood pressure are associated with inflammation, diabetes, immunosuppression, ulceration, coronary heart disease, and hypertension. Likewise, extreme stressor exposure often maladaptively leads to PTSD. (GIVE SOME MORE MENTAL DISORDERS)

The brain exemplifies the principle of free energy minimization. Consuming 20% of the average human's (CHECK) basal metabolic energy in an organ only 1.5 kg. (3 lbs.) (CHECK), it quickly dies in the absence of a steady flow of energy. The brain cannot simply maintain large internal energy reserves because the limited signal routing speed of neurons favors maximum packing density. The challenge is therefore on individual neurons to remain extremely sensitive to extracellular energy and balance a tight budget. Energetically expensive processes like generating spike trains – especially over long axons – must kept to a bare minimum. However energy excess is equally dangerous; unchecked, hyperglycemia leads to neuroinflammation and ultimately, cell death. To cope with energy stress in either direction, neurons regulate nonessential energy consuming or producing processes according to free energy availability. If energy is short, cell synaptic junctions become more resistive and the spiking threshold increases. This decreases the frequency of energetic signaling. Over longer time scales, outgoing dendritic count may even decrease. On the other hand, if there is leftover energy after regular cell processes occur, signal cascades tune the neuron to increase sensitive to its present and potential neuron neighbors: synaptic junctions become less resistive, the spiking thresholds decreases, and cell growth increases – even branching out to form new dendrites. In either case, the neuron adapts to maintain dynamic equilibrium between energy supply and demand. Of course, essential cell maintenance processes regularize this adaptation to prevent it from collapsing to zero. The network scale effect is: steady free energy minimization contributes positively to information processing. In turn, this local principle promotes global intelligence. (See Figure reffig:1) Experiments have shown that even in the absence of a reward system or natural body, this local energy stress is a sufficient reward signal for isotropic sections of cortical tissue to learn robotic vehicle control. Vergara et al. [2019]

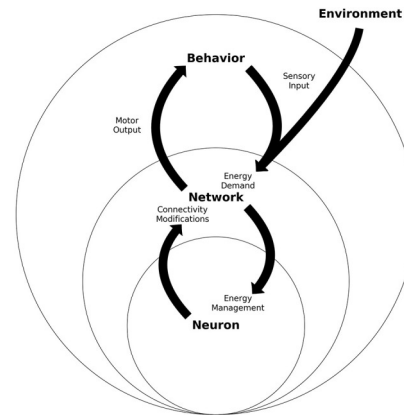


Figure 1: Local energy minimization results in global intelligence. Explain in detail what's happening in this figure. ... Intelligent behavior minimizes the energy stress imposed by the organism's sensors and actuators. Reprinted with permission from Vergara et al. [2019].

¹In mobile life forms, selection pressures favor this extreme over the other. As this is not a common natural stressor, most animals simply do not need to carry the mechanisms to intelligently handle high amounts of free energy and suffer from resulting stress.

It comes as no surprise therefore that estimated cost minimization is the norm in behavioral psychology and emergent sciences: humans continually look for ways to increase their efficiency or otherwise minimize cognitive and physical workload (MAKE SURE THIS IS A GOOD DEFINITION OF COST ESTIMATION); The global economy likewise . . . These principles extend directly to the research and development of AI. Human cognitive and financial energy form selective pressures to artificial intelligence survival.

The foregoing analysis prompts the question:

Can we make AI systems that autonomously minimize their own energetic demands?

The objective is not only to minimize loss, but every step of optimization: data collection, training ops, compute allocation, and even financial cost minimization. Most AI systems are blind to their own demands: production optimizers receive little feedback, and few learn to interpret validation-hyperparameter metrics the way a machine learning engineer does; while roboticists are keenly aware of the tight energy budget, embodied reinforcement learning agents are simulated as if energy is an inexhaustible resource;² data hungry training loops often iterate uniformly over a training distribution when only a few pieces of data have information to the model; and it's usually humans rather than AI who bear the cost function when a neural network wants to run another epoch.

Unlike controlled, artificial intelligence, when wild, natural intelligence demands more energy than expected, it gathers, forages, or hunts independent from humans. This enables the organism to not only collect the nutrients it needs but also do so in an energy efficient manner. The dual energy-efficiency, efficient-at-collecting-energy loop of animal life has proved robust over billions of years. It is very intuitive therefore to apply these concepts to a machine learning theory of information metabolism. If data is analogous to food and training, to anabolic processes, then most machine learning pipelines are infants. They are data-hungry and must be spoon-fed. On the other hand, intelligent artificial intelligence is one that learns and autonomously decides when to collect data, what kind of and how much data to collect, and when to start and stop training.

Autonomous data collection and training would not likely collect uncountably infinite data with respect to the number of tasks it performs. Returning to the free energy principle: excessive consumption is just as taxing as unbalanced exertion. Likewise, infants pay greatest attention stimuli that are neither too boring nor surprising. Machine learning even recognizes this trend: training on stationary data must be terminated at a certain point to prevent overfitting, mode collapse, and simply remain efficient. In deep reinforcement learning, overfitting the training reward function causes decrease in true utility, 'cheating' the simulator, and learns dangerous policies. After general pretraining, efficient, autonomous data collection would likely only need well chosen, discrete samples to retain the performance of a few-shot training system.

Sampling data before feeding it to the machine learning pipeline has the bonus of adaptive, rather than passive, data poisoning detection. With long-term memory and one shot inference capabilities, detecting one malicious data element would be sufficient to recognize arbitrarily modified pathogens in the future in a way reminiscent of the mammalian immune system.

Natural life intelligently responds to the energy scarcity of every individual day and adjusts its physiological and behavioral characteristics appropriately. This may mean sacrificing exploratory or social behaviors for more immediately energy-rewarding ones like foraging or hunting. A remarkable adaptation of the brain when insufficiently rested or otherwise taxed is that some of its individual neurons decrease their activity or even sacrifice their life to increase the energy availability for the whole. AutoML and neural architecture design already penalize static compute resource use, and sparse mixture of expert models echo similar behaviors by only dynamically routing to a subset of the model for any inference step, however the fully-energy conscious AI system has yet to be realized.

2.2 Thinking fast and slow ... and slower ... – natural and artificial intelligence

Dual process theory makes a dichotomy between fast, automatic, unconscious heuristics and slow, deliberate, rational thought. Together, these processes minimize cognitive energy expenditure over a

²It is beneficial though that purely unsupervised information theoretic objective such as curiosity, empowerment, and skill discovery also converge to energy minimizing behaviors. This is not coincidence though when considering the relationship information theory makes.

broad domain of activities than could be achieved individually. However in the greater scope of natural intelligence, these are only two frequency bands along the spectrum of optimization. Similar to (CITE D. Park), I consider this great learning spectrum in three parts: population optimization, direct learning, and indirect learning. (See Figure 2)

Population optimization

Direct Learning

Indirect learning Each of these principles of intelligence provide unique advantages to AI systems, and proofs-of-concept such as RAINBOW reinforcement learning, X, and Y demonstrate that combining multiple inductive biases into one AI system synergizes the advantages of individual ideas. However, to our knowledge, no work has combined all of them in one system. Our work, Predictive ‘General’ Intelligence, does this.

3 Principled General Intelligence

Make brief statement on why prediction is a general principle of intelligence

Define PGI

The observation that every individual neuron individually minimizes energetic difference while also joining a larger neuronal network leads us to develop a network of world models. This is an extension to parallel combinations such as neural ensembles and mixtures of experts Shazeer et al. [2017] like Switch Transformers as well as serial combinations like content filtration networks and hierarchical prediction and reinforcement learning.

4 Experiment

5 Discussion

General discussion by Atom and Eva

In fact, until this point, the entire discussion section was a first-run, non-cherry picked composition by Eva.³

Broader Impact

Authors are required to include a statement of the broader impact of their work, including its ethical aspects and future societal consequences. Authors should discuss both positive and negative outcomes, if any. For instance, authors should discuss a) who may benefit from this research, b) who may be put at disadvantage from this research, c) what are the consequences of failure of the system, and d) whether the task/method leverages biases in the data. If authors believe this is not applicable to them, authors can simply state this.

Use unnumbered first level headings for this section, which should go at the end of the paper. **Note that this section does not count towards the eight pages of content that are allowed.**

Future Work

- This work was produced independalnty from but converged to many of the same principles as Dr. Hinton’s GLOM idea. Once made to work, we plan to replace the PredNode’s with GLOMNode’s which are a much nicer formulation of the network of experts. GLOM has the added bonus of psuedo-STP training which is significantly more energy efficient and may be extremely quantized – maybe even binarized – during inference.
- Atom and Eva are currently developing an massive multiagent online environment with on-demand PGIagent interaction. More information will be posted at <https://limboid.ai>.

³link to youtube



Figure 2: Learning happens over a spectrum of frequency. Explain

- Autonomously develop and train robots with embodied PGI.

Acknowledgments and Disclosure of Funding

We thank Dr. Linda S. Barasch from the University of Texas at Arlington for assisting in publishing this paper. We also thank all our references and the entire research community for their contributions.

This work is a completely independent study. It has no financial incentives and is personally financed.

References

- Danijar Hafner, Pedro A. Ortega, Jimmy Ba, Thomas Parr, Karl Friston, and Nicolas Heess. Action and perception as divergence minimization. *arXiv*, 9 2020. URL <http://arxiv.org/abs/2009.01791>.
- Tom B. Brown, Benjamin Mann, Nick Ryder, Melanie Subbiah, Jared Kaplan, Prafulla Dhariwal, Arvind Neelakantan, Pranav Shyam, Girish Sastry, Amanda Askell, Sandhini Agarwal, Ariel Herbert-Voss, Gretchen Krueger, Tom Henighan, Rewon Child, Aditya Ramesh, Daniel M. Ziegler, Jeffrey Wu, Clemens Winter, Christopher Hesse, Mark Chen, Eric Sigler, Mateusz Litwin, Scott Gray, Benjamin Chess, Jack Clark, Christopher Berner, Sam McCandlish, Alec Radford, Ilya Sutskever, and Dario Amodei. Language models are few-shot learners. *arXiv*, 5 2020. URL <http://arxiv.org/abs/2005.14165>.
- Rodrigo C. Vergara, Sebastián Jaramillo-Riveri, Alejandro Luarte, Cristóbal Moënné-Loccoz, Rómulo Fuentes, Andrés Couve, and Pedro E. Maldonado. The energy homeostasis principle: Neuronal energy regulation drives local network dynamics generating behavior. *Frontiers in Computational Neuroscience*, 13:49, 7 2019. ISSN 16625188. doi: 10.3389/fncom.2019.00049. URL <https://pmc/articles/PMC6664078/> [https://www.ncbi.nlm.nih.gov/pmc/articles/PMC6664078/](https://pmc/articles/PMC6664078/?report=abstracthttps://www.ncbi.nlm.nih.gov/pmc/articles/PMC6664078/).
- Noam Shazeer, Azalia Mirhoseini, Krzysztof Maziarczyk, Andy Davis, Quoc Le, Geoffrey Hinton, and Jeff Dean. Outrageously large neural networks: The sparsely-gated mixture-of-experts layer. *arXiv*, 1 2017. URL <http://arxiv.org/abs/1701.06538>.

A Appendix A's title

B Appendix B's title