Potential Aviation Use Cases of Autonomy

- Simplified Vehicle Operations / Unified Flight Controls [1]
- > Automatic aircraft safety systems (e.g., Auto-GCAS, Garmin Autonomi-Autoland) [1]
- In-time Aviation Safety Management Systems [4]
- Proactive / Preemptive maintenance planning [4]
- Digital flight operations (automated operator-responsible separation capabilities) [3]
- Flight deck digital assistance (e.g., Digital Co-pilot) [1]
- Reduce crew civil passenger air transport [1]
- > Beyond Visual Line of Sight Operations by Unmanned Aircraft Uncontrolled airspace [1]
- Unmanned Aircraft Operations Remotely Piloted Controlled Airspace [1]
- Multi-aircraft operations (m:N) Shifting from Remotely Piloted to Remotely Managed flights [3]
- > High-Altitude Long Endurance (HALE) aka HAPS [1]
- Automated flight management for unmanned aircraft contingencies (e.g., lost c2 link) [3]

Uniquely Military

- Loyal Wingman [2]
- Collaborative mission management for multiple agents [2]
- ISR to find objects without direct supervision and pre-programmed flight paths. [2]
- Forward area small package resupply (e.g. think of zipline) [2]
- Collaborative platforms as a force multiplier for many mission types. [2]

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Proposed Breakouts For Transformational Engineering Workshop on Aviation Use Cases

1. Commercial Flight Operations

- Facilitator: Lesley Weitz or Craig Wanke (MITRE)
- Discussion Capture: Fred Wieland (Mosaic ATM)

2. Military Flight Operations

- Facilitator: Jim Paunicka (Boeing)
- Discussion Capture: David Maroney (MITRE)

3. Airspace and Operational Control

- Facilitator: Andy Lacher (NASA LaRC)
- Discussion Capture: Alex Cundiff (NASA LaRC)

Support Functions (safety data analytics, maintenance, training, etc.)

- Facilitator: Louis Alvarez (MIT-Lincoln Lab)
- Discussion Capture: Nipa Phojanamongkolkij (NASA-LaRC)

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Flight Deck Digital Assistance

- Key Stakeholder(s): OEMs, Avionics Manufacturers, Commercial Operators, Defense Operators, General Aviation, Regulators
- Short Description: The use of a variety of decision aids both integrated and non-integrated (e.g., Electronic Flight Bags) that assist flight crews with performance of their tasks which will reduce cognitive workload, catch errors, and improve decision-making (e.g., speed of decisions, expansion of options considered) resulting in increased safety and efficiency of flight operations. Could include memory aids/reminders, anticipatory information retrieval, monitors/alerts, calculators, warnings, etc. leveraging intuitive interfaces including voice recognition.
- Main Assumptions: Appropriate information can be stored, and voice recognition capabilities can meet performance requirements.
- Driving Needs/Requirements: Voice recognition, real-time connectivity to necessary information, integration with aircraft telemetry and systems information, processing power
- Dynamic Requirements:
- Related Metrics: Cognitive workload reduction, Improvements in the quality of decisions (how much safer are the decisions), Error reductions
- References:

Kevin Burns, Craig Bonaceto, Steven Estes, John Helleberg; Evaluating the Operational Safety of a Digital Copilot; Cognitive Assistance in Government and Public Sector Applications AAAI Technical Report FS-17-02; <a href="https://html.ncbi.nlm.nc

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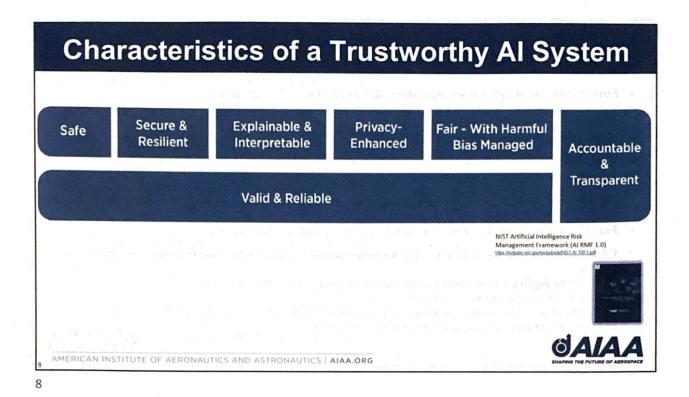
Multi-Aircraft Operations

- Key Stakeholder(s): New Entrants (Urban Air Mobility, Drone Delivery, Regional Air Mobility), Regulators
- > Short Description: Through the use of remote pilots of unmanned aircraft, it is now potentially possible for a single pilot to be responsible for multiple simultaneous operations. To improve economies of scale and to ensure reliable flight operations, many of the Advanced Air Mobility new entrants have a future vision where a small team of pilots (i.e., 'm') can be operating multiple simultaneous flights (i.e., 'N'). Often referred to as m:N operations.
- Main Assumptions: Automation can be reliable enough to increase the "neglect time" and enable human operators to be in an oversight / supervisory role and not be required to have situation awareness to assume direct control in the event of an off-nominal event.
- Driving Needs/Requirements: Automation is capable of appropriately responding to all nominal and off-nominal events
- Dynamic Requirements:
- Related Metrics: Cognitive workload, Neglect time, Effectiveness of decision-making for offnominal events
- References:

Boeing/Wisk; Concept of Operations for Uncrewed Urban Air Mobility; https://wisk.aero/wp-content/uploads/2022/09/Concept-of-Operations-for-Uncrewed-Urban-Air-Mobility.pdf

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Metric Classes for Human Machine Teaming

- Observability Human transparency into what automation is doing
- Predictability Human able to observe and understand intentions and activities of automation
- Attention Directing Automation is able to direct human attention appropriately
- Solution Space Exploration Ensures joint exploration of the appropriate solution space
- Adaptability Automation recognizes and adapts to unexpected situations
- Operator Directability Humans can direct and redirect automation priorities/activities
- Calibrated Trust Human is able to understand when and how much to depend on automation partner based upon demonstrated competency
- Common Ground Human's beliefs, assumptions and intentions are appropriately reflected in the automation
- Understandability/Simplicity Human is able to understand what the automation is doing by the information presented.

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https://www.mitre.org/sites /default/files/2021-11/prs-17-4208-human-machineteaming-systemsengineering-guide.pdf

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Another Thought on Metrics

- Functional -ilities Reliability, Availability, Accuracy, Trustworthiness, Resiliency
- Cyber-resistance How well the system handles cyber threats (data corruption, malicious or adversarial injection of bad training data, jamming, etc.)
- Temperament Measure of gradual failure with degraded function vs. abrupt failure and loss of function
- Human/machine teaming clear role for normal, degraded, off nominal.
- . Training level of skill required by the user and how to measure that "skill"
- Operational resiliency how well the autonomy adapts to mission changes, Operational Design Domain (ODD) changes. Flexibility in design and ops assumptions – narrow or broad ODD
- Fragility Brittleness How robust is the system in a real-world environment?
- Complexity of info feeding the function for proper behavior data for AI, sensors, corrections/changes to tasking
- **Portability/Agility** How easily can the system be deployed in different scenarios does it require a large re-work for small changes in mission/ODD, etc.?
- **Collaboration** How easily can the system be integrated with existing systems, tactics, cross-force collaboration, sharing of data, standard or unique protocols?

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Template for describing use cases

Title

- Key Stakeholder(s):
- Category: [Commercial Flight Operations; Military Flight Operations; Airspace and Operational Control; Support Functions]
- > Short Description:
- Main Assumptions:
- Driving Needs/Requirements:
- > Dynamic Requirements: Requirements that may change after deployment.
- > Related Metrics:
- > References:

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