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- (a) (5) Write all required setup code such that all of the pins are inputs. Do not assume any bits have known values at power-on.

```
GPIOPinWrite(CtrlStat, 0x02); // enable port by setting pin high
GPIOPinWrite(DIR, 0x00); // 0 is input
```

- (b) (15) Let there be an empty array of 10 1-byte values declared as `uint8_t stuff[10]`. Write a polling loop that waits for individual bytes to arrive on the interface and then puts them into sequential slots in the array.

volatile uint8\_t i=0;

```
while(i < 10)
{
    int8_t flagVal = GPIOPinRead(CtrlStat, GPIO_PIN_3); // check if in
    while(0x04 != flagVal)
    {
        flagVal = GPIOPinRead(CtrlStat, GPIO_PIN_3); // keep until something is
    }
    stuff[i] = GPIOPinRead(DATA, 0x11111111); // store incoming byte in array
    i++; // increment array storage location
}
return 0;
```

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- (c) (15) Write a complete ISR to replace your polling loop. Do not worry about any additional initializations or any interrupt enables (global or specific). Only write the complete ISR.

```
void IntGPIO(void)
{
    if(i < 10)
    {
        stuff[i] = GPIOPinRead(DATA, 0x11111111); // store incoming byte in array
        i++; // increment array slot
    }
    GPIOPinWrite(INTCTL, 0x01); // clear interrupt flag
}
return;
```

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