

# Artificial neural networks and backpropagation

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- 2 Artificial neuron
- 3 Artificial neural networks
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# Artificial neural networks and deep learning history

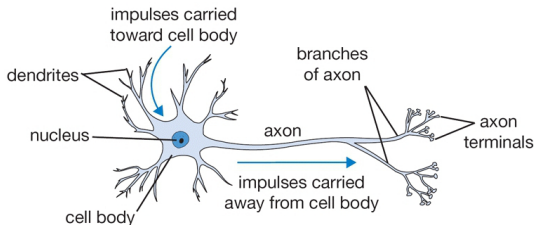
For a very complete state of the art on deep learning, see the overview by Schmidhuber [Schmidhuber, 2015].

- 1958: Rosenblatt's perceptron [Rosenblatt, 1958]
- 1980's: the backpropagation algorithm (see, for example, the work of Le Cun [LeCun, 1985])
- 2006-: CNN implementations using Graphical Processing Units (GPU): up to a 50 speed-up factor.
- 2011-: super-human performances [Cireşan et al., 2011]
- 2012: Imagenet image classification won by a CNN [Krizhevsky et al., 2012].

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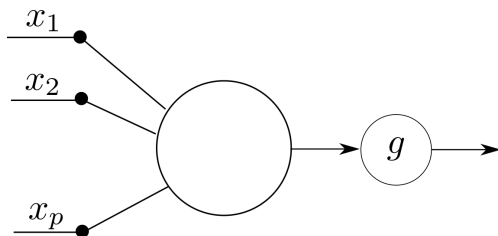
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# Neuron



- The human brain contains 100 billion ( $10^{11}$ ) neurons
- A human neuron can have several thousand dendrites
- The neuron sends a signal through its axon if during a given interval of time the net input signal (sum on excitatory and inhibitory signals received through its dendrites) is larger than a threshold.

# Artificial neuron

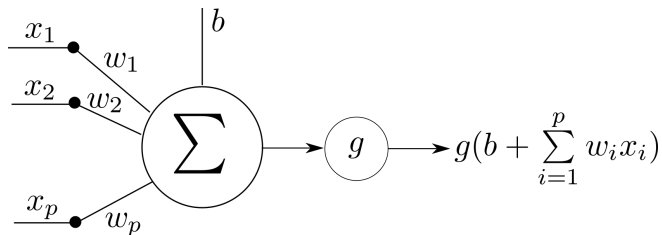


## General principle

An artificial neuron takes  $p$  inputs  $\{x_i\}_{1 \leq i \leq p}$ , combines them to obtain a single value, and applies an **activation function**  $g$  to the result.

- The first artificial neuron model was proposed by [McCulloch and Pitts, 1943]
- Input and output signals were binary
- Input dendrites could be inhibitory or excitatory

# Modern artificial neuron



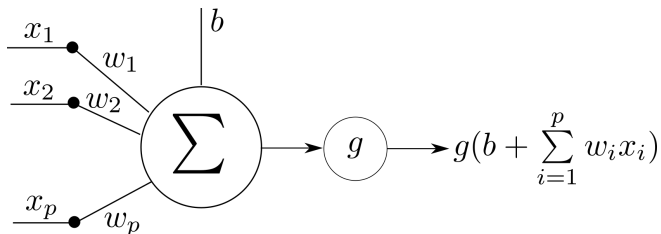
- The neuron computes a linear combination of the **inputs**  $x_i$ 
  - The **weights**  $w_i$  are multiplied with the inputs
  - The **bias**  $b$  can be interpreted as a threshold on the sum
- The **activation function**  $g$  somehow decides, depending on its input, if a signal (the neuron's **activation**) is produced



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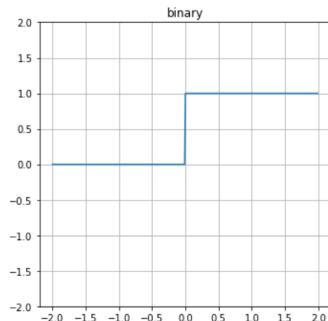
# The role of the activation function



- The initial idea behind the activation function is that it works somehow as a gate
- If its input is “high enough”, then the neuron is activated, i.e. a signal (other than zero) is produced
- It can be interpreted as a source of abstraction: information considered as unimportant is ignored

## Activation: binary

$$g(x) = \begin{cases} 1, & \text{if } x > 0 \\ 0, & \text{otherwise} \end{cases}$$

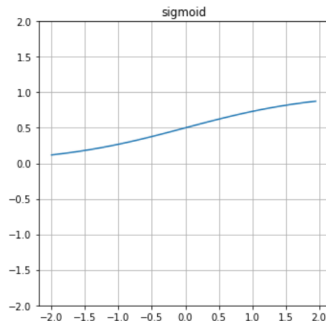


### Remarks

- Biologically inspired
- + Simple to compute
- + High abstraction
  - Gradient nil except on one point
- In practice, almost never used

## Activation: sigmoid

$$g(x) = \frac{1}{1 + e^{-x}}$$

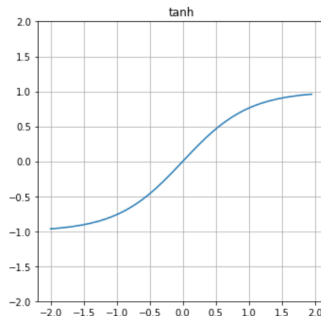


### Remarks

- + Similar to binary activation, but with usable gradient
- However, gradient tends to zero when input is far from zero
- More computationally intensive

## Activation: hyperbolic tangent

$$g(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

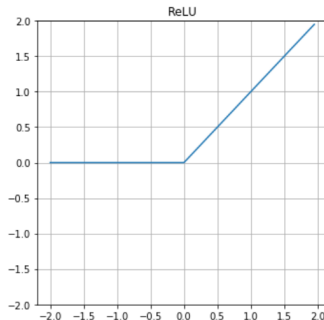


### Remarks

- Similar to sigmoid

# Activation: rectified linear unit

$$g(x) = \begin{cases} x, & \text{if } x > 0 \\ 0, & \text{otherwise} \end{cases}$$



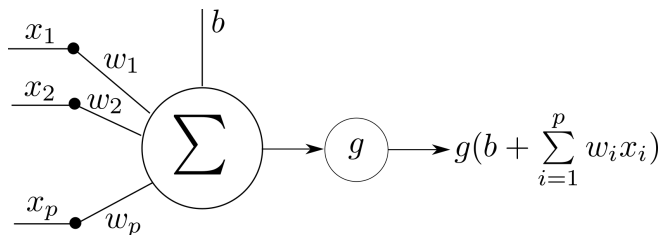
## Remarks

- + Usable gradient when activated
- + Fast to compute
- + High abstraction

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# What can an artificial neuron compute?

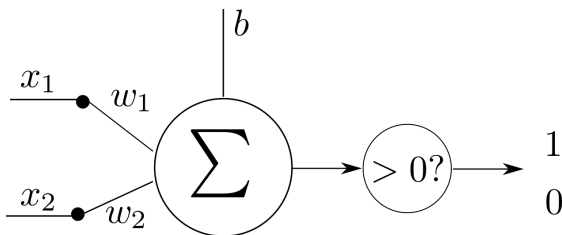


In  $\mathbb{R}^p$ ,  $b + \sum_{i=1}^p w_i x_i = 0$  corresponds to a hyperplane. For a given point  $\mathbf{x} = \{x_0, \dots, x_p\}$ , decisions are made according to the side of the hyperplane it belongs to.

When the activation function is binary, we obtain a **perceptron**

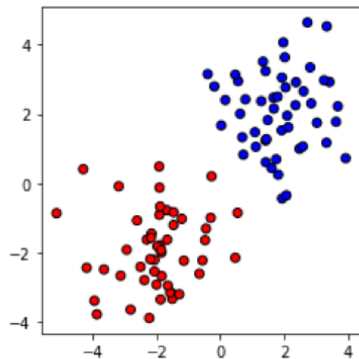


## Example of what we can do with a neuron

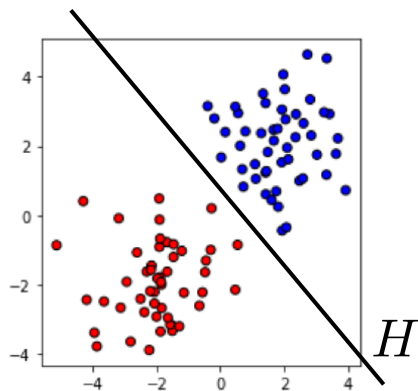


- $p = 2$  : 2 dimensional inputs (can be represented on a screen!)
- Activation: binary
- Classification problem

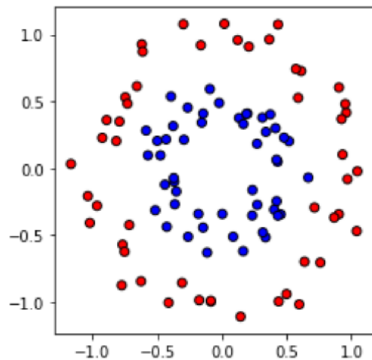
# Gaussian clouds



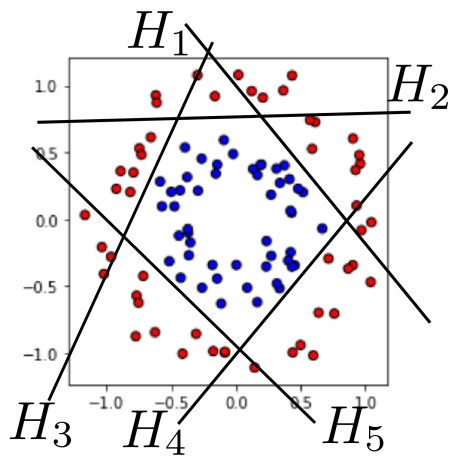
## Gaussian clouds



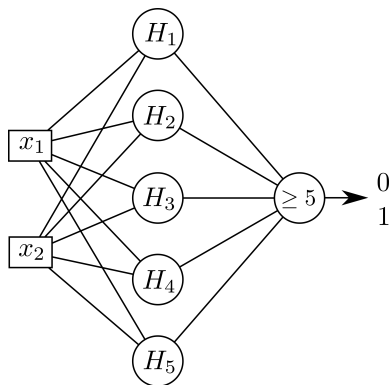
# Circles



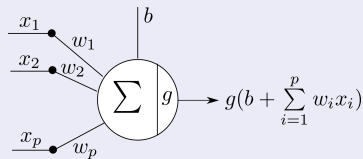
# Circles



# Solution



## Artificial neuron compact representation



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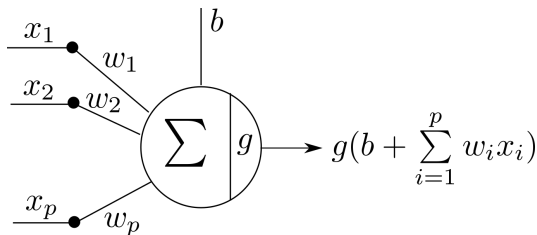
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# Notations



We will often use:

$$\mathbf{W} = (w_1, \dots, w_p)^T$$

$$\mathbf{x} = (x_1, \dots, x_p)^T$$

Therefore, we can simply write:

$$g(b + \sum_{i=1}^p w_i x_i) = g(b + \mathbf{W}^T \mathbf{x})$$

# Neural network (NN)

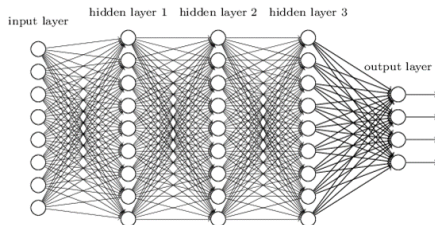
## Definitions

- An (artificial) neural network is a directed graph, where:
  - the nodes are artificial neurons and
  - the edges are connections between the neurons.
- The **input layer** is the set of neurons without incoming edges.
- The **output layer** is the set of neurons without outgoing edges.

# Feed-forward neural networks

## Definition

- A feed-forward neural networks is a NN without cycles
- A neuron belongs to layer  $q$  if the longest path in the graph between the input layer and the neuron is of length  $q$ .
- Any layers other than input and output layers are called **hidden layers**



(from <http://www.jtoy.net>)

# Feed-forward neural networks

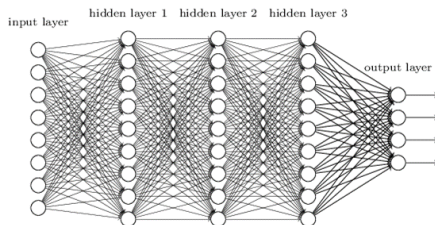
In the following of this course, except when otherwise specified, all NNs will be feed-forward. Indeed, this is the preferred type of NN for image processing.

## What about other architectures?

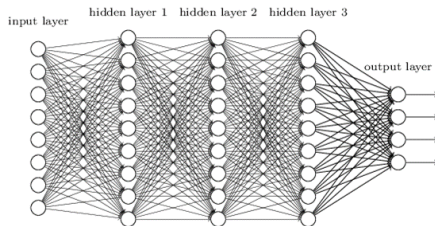
- Recurrent neural networks (RNN)
- Long short-term memory networks (LSTM)
- More powerful than feed-forward NNs
- More biologically realistic
- Complex dynamics; more difficult to train
- Mainly used for processing temporal data

# Fully-connected network

- A layer is said to be fully-connected if each of its neurons is connected to all the neurons of the previous and following layers
- A NN is said to be fully connected if all its hidden layers are fully connected

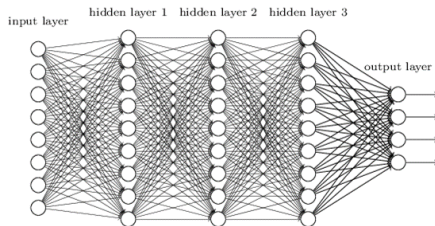


# Number of parameters



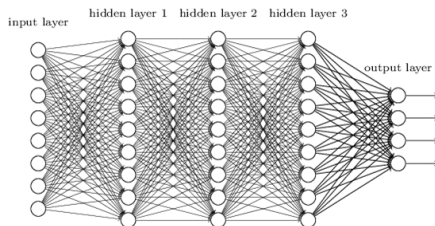
- How many parameters does the above network contain?

# Number of parameters



- How many parameters does the above network contain?
- First hidden layer:

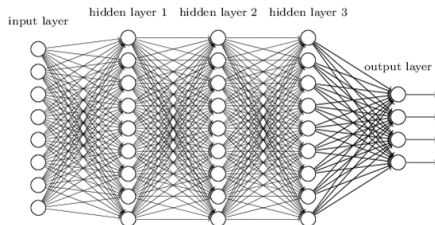
# Number of parameters



- How many parameters does the above network contain?
- First hidden layer:
- $9 \text{ neurons} \times 8 \text{ neurons in the previous layer} + 9 \text{ biases} = 81$

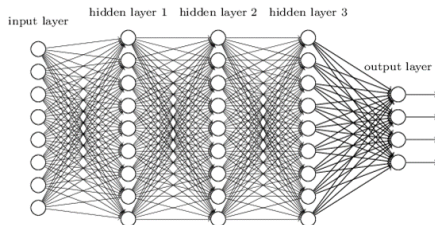


# Number of parameters



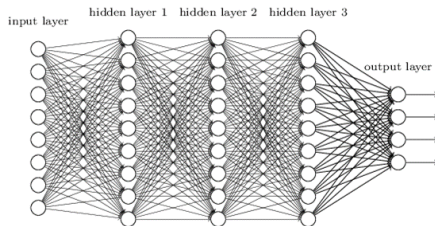
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- Second and third layers:  $9 \times 9 + 9 = 90$

# Number of parameters



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- First hidden layer:
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- Second and third layers:  $9 \times 9 + 9 = 90$
- Output layer:  $4 \times 9 + 4$

# Number of parameters



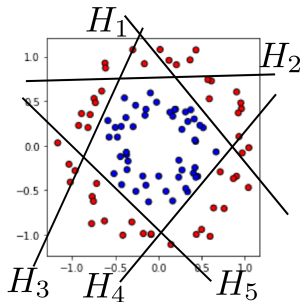
- How many parameters does the above network contain?
- First hidden layer:
  - 9 neurons  $\times$  8 neurons in the previous layer + 9 biases = 81
- Second and third layers:  $9 \times 9 + 9 = 90$
- Output layer:  $4 \times 9 + 4$
- Total: 305 parameters

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# Universal approximation theorem

- We have previously seen that a neuron can be used as a linear classifier and that combining several of them one can build complex classifiers
- We will see that this observation can be generalized



# Universal approximation theorem

Let  $f$  be a continuous real-valued function of  $[0, 1]^p$  ( $p \in \mathbb{N}^*$ ) and  $\epsilon$  a strictly positive real. Let  $g$  be a non-constant, increasing, bounded real function.

Then there exist an integer  $n$ , real vectors  $\{\mathbf{W}_i\}_{1 \leq n}$  of  $\mathbb{R}^p$ , and reals  $\{b_i\}_{1 \leq n}$  and  $\{v_i\}_{1 \leq n}$  such that for all  $\mathbf{x}$  in  $[0, 1]^p$ :

$$\left| f(\mathbf{x}) - \sum_{i=1}^n v_i g(\mathbf{W}_i^T \mathbf{x} + b_i) \right| < \epsilon$$

A first version of this theorem, using sigmoidal activation functions, was proposed by [CYBENKO, 1989]. The version above was demonstrated by [Hornik, 1991].

# Universal approximation theorem: what does it mean?

$$\left| f(\mathbf{x}) - \sum_{i=1}^n v_i g(\mathbf{W}_i^T \mathbf{x} + b_i) \right| < \epsilon$$

This means that function  $f$  can be approximated with a neural network containing:

- an input layer of size  $p$ ;
- a hidden layer containing  $n$  neurons with activation function  $g$ , weights  $\mathbf{W}_i$  and biases  $b_i$ ;
- an output layer containing a single neuron, with weights  $v_i$  (and an identity activation function).

# Universal approximation theorem in practice

- The number of neurons increases very rapidly with the complexity of the function
- Empirical evidence has shown that multi-layer architectures give better results



# Universal approximation theorem in practice

- The number of neurons increases very rapidly with the complexity of the function
- Empirical evidence has shown that multi-layer architectures give better results

A NN can potentially have a lot of parameters. How can we set them?

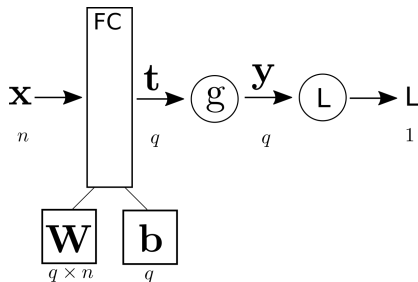
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# Introduction

- We have seen that NNs have a lot of potential
- However, how can the parameters be set?
  - Weights
  - Biases

# Backpropagation through a fully connected layer



Setup:

$$n, q \in \mathbb{N}^*$$

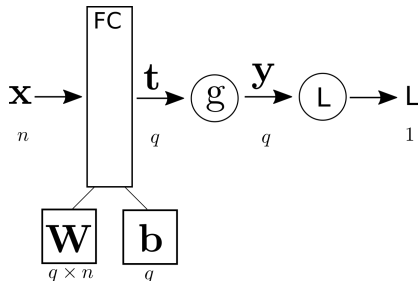
$$\mathbf{x} \in \mathbb{R}^n$$

$$\mathbf{W} \in \mathbb{R}^q \times \mathbb{R}^n$$

$$\mathbf{b}, \mathbf{t}, \mathbf{y} \in \mathbb{R}^q$$

$$L \in \mathbb{R}$$

# Backpropagation through a fully connected layer



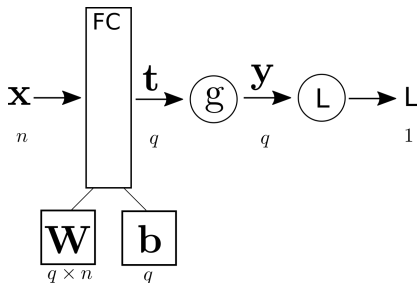
Local gradients:

Forward pass:

$$\begin{aligned}\mathbf{t} &= \mathbf{W}\mathbf{x} + \mathbf{b} \\ \mathbf{y} &= g(\mathbf{W}\mathbf{x} + \mathbf{b}) \\ L &= L(\mathbf{y})\end{aligned}$$

$$\begin{aligned}\frac{\partial \mathbf{t}}{\partial \mathbf{W}} &= \mathbf{x}^t \\ \frac{\partial \mathbf{t}}{\partial \mathbf{b}} &= \mathbf{1} \\ \frac{\partial \mathbf{y}}{\partial \mathbf{t}} &= g'\end{aligned}$$

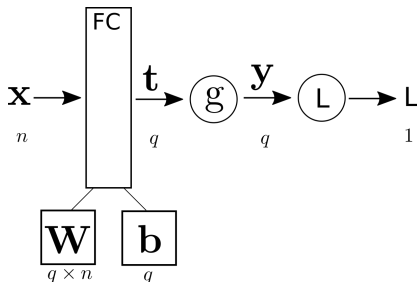
## Backpropagation through a fully connected layer



Backpropagation:

$$\begin{aligned}\frac{\partial L}{\partial \mathbf{t}} &= \frac{\partial L}{\partial \mathbf{y}} \cdot \frac{\partial \mathbf{y}}{\partial \mathbf{t}} \\ &= \frac{\partial L}{\partial \mathbf{y}} \odot g'(\mathbf{t})\end{aligned}$$

# Backpropagation through a fully connected layer



Backpropagation:

$$\begin{aligned}\frac{\partial L}{\partial \mathbf{W}} &= \frac{\partial L}{\partial \mathbf{t}} \cdot \frac{\partial \mathbf{t}}{\partial \mathbf{W}} \\ &= \frac{\partial L}{\partial \mathbf{y}} \odot \mathbf{g}'(\mathbf{t}) \cdot \mathbf{x}^t\end{aligned}\qquad \frac{\partial L}{\partial \mathbf{b}} = \frac{\partial L}{\partial \mathbf{y}} \odot \mathbf{g}'(\mathbf{t})$$

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# The triggering factor to the success of neural networks

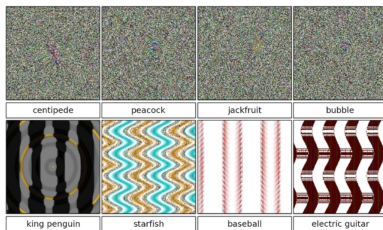
- Appropriate architectures: graphical processing units (GPUs)
- Optimized software
- Large annotated databases

# Practical considerations

For a deep-learning solution to work, you need:

- A lot of annotated data
- A lot of fiddling (different architectures; hyper-parameters)
- GPUs, at least from training

Deep learning can produce astonishing results  
[Nguyen et al., 2015]...



# The web giants

- Google, Facebook, Microsoft, Amazon etc. are actively investing in deep-learning
- Competition is intense
- Most of them are sharing their deep learning libraries

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