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## IYGB - N1456 PAPER C - QUESTION 1

START BY FINDING  $\vec{AB}$

$$\vec{AB} = \underline{b} - \underline{a} = (17\hat{i} - 5\hat{j}) - (2\hat{i} + 5\hat{j}) = 15\hat{i} - 10\hat{j}$$

FIND THE WORK DONE (IN OR OUT) BY THE FRCF

$$\begin{aligned} W &= \underline{F} \cdot \underline{s} = (2.6\hat{i} - 0.1\hat{j}) \cdot (15\hat{i} - 10\hat{j}) \\ &= 39 + 1 = 40 \text{ J} \end{aligned}$$

BY ENERGY

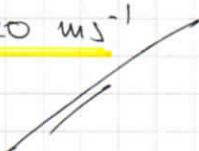
WORK IN = GAIN IN KINETIC ENERGY

$$40 = \frac{1}{2} m v^2$$

$$40 = \frac{1}{2} \times 0.2 \times v^2$$

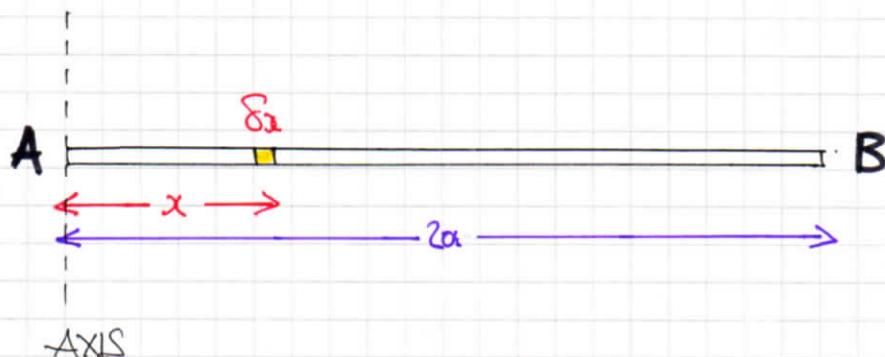
$$v^2 = 400$$

$$v = \underline{20 \text{ ms}^{-1}}$$



## IYGB-M45G PAPER C - QUESTION 2

LOOKING AT THE DIAGRAM BELOW



IF THE MASS OF THE ROD IS  $m$ , THEN  $\rho = \frac{m}{2a}$

(MASS PER UNIT LENGTH)

- ① THE MASS OF INFINITESIMAL LENGTH  $\delta x$  IS  $\rho \delta x$
- ② THE MOMENT OF INERTIA OF THE "INFINITESIMAL" ABOUT THE AXIS THROUGH A IS

$$(\rho \delta x) x^2$$

- ③ SUMMING UP ALL THESE MOMENTS OF INERTIA FROM A TO B AND TAKING UNITS

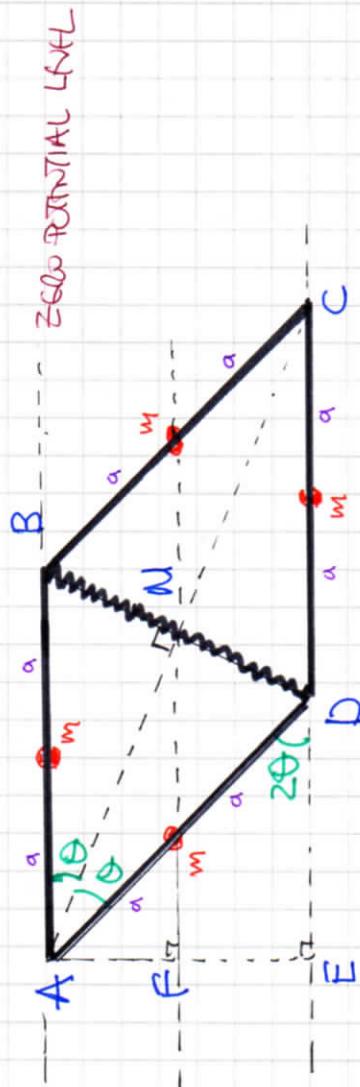
$$I = \int_{x=0}^{x=2a} \rho x^2 dx = \left[ \frac{1}{3} \rho x^3 \right]_{x=0}^{x=2a} = \frac{1}{3} \rho (8a^3) - 0$$

$$= \frac{1}{3} \left( \frac{m}{2a} \right) (8a^3) = \underline{\underline{\frac{4}{3} m a^2}}$$

As required

## YGB - M1SS PART C - QUESTION 3

START WITH A DETAILED DIAGRAM



TAKING THE LEVEL OF AB AS THE ZERO

GRAVITATIONAL POTENTIAL LEVEL

$$V_G(0) = -mg |AF| \times 2 - mg |AE|$$

(Level AD, BC)

$$V_G(\theta) = -2mg (\alpha \sin 2\theta) - mg (2a \sin 2\theta)$$

$$V_G(\theta) = -4mg \sin 2\theta$$

ELECTRIC POTENTIAL ENERGY NEXT

- $|BM| = |AB| \sin \theta = 2a \sin \theta$

- $|BD| = 2|BM| = 4a \sin \theta$

- $|AD| \sin 2\theta = 2a \sin 2\theta$

- $|FE| = \frac{1}{2} |AE| = a \sin 2\theta$

$$V_E(0) = \frac{mg}{2a} x^2$$

$$V_E(\theta) = \frac{mg}{2a} [BD(-a)]^2$$

$$V_E(\theta) = \frac{mg}{2a} [4a \sin \theta - a]^2$$

$$V_E(\theta) = \frac{1}{2} mg a (4 \sin \theta - 1)^2$$

## IXGB - N1456 PARC C - POSITION 3

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TOTAL POTENTIAL ENERGY is a function of  $\theta$ , is given by

$$V(\theta) = \frac{1}{2}mg\alpha(4\sin\theta - 1)^2 - 4mg\alpha\sin 2\theta + \text{constant}$$

LOOKING FOR EQUILIBRIUM POSITIONS

$$V'(\theta) = 4mg\alpha(4\sin\theta - 1)\cos\theta - 8mg\alpha\cos 2\theta$$

$$V'(\theta) = 4mg\alpha [ (4\sin\theta - 1)\cos\theta - 2\cos 2\theta ]$$

$$V'(\theta) = 4mg\alpha [ 4\sin\theta\cos\theta - \cos\theta - 2\cos 2\theta ]$$

$$V'(\theta) = 4mg\alpha [ 2\sin 2\theta - \cos\theta - 2\cos 2\theta ]$$

SOLVING FOR ZERO

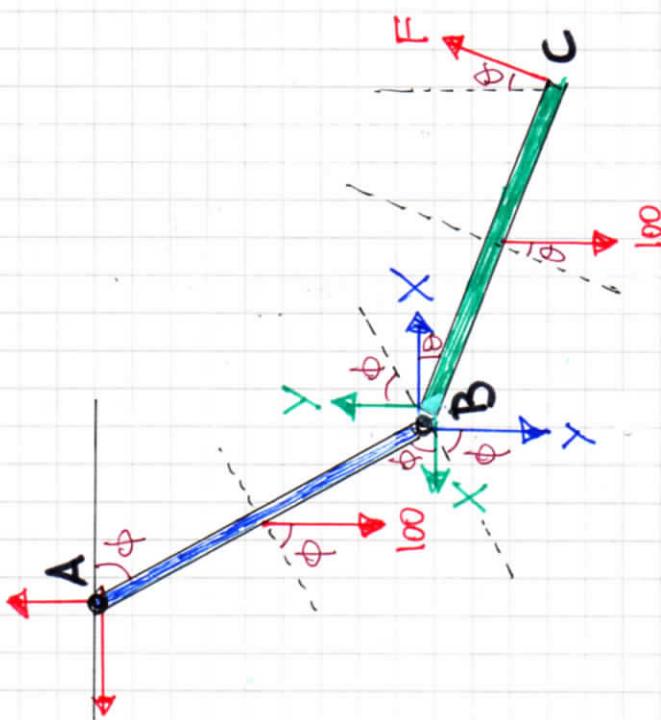
$$0 = 4mg\alpha ( 2\sin 2\theta - \cos\theta - 2\cos 2\theta )$$

$$2\sin 2\theta - \cos\theta - 2\cos 2\theta = 0$$

~~as required~~

## IYGB - M15C PAPER C - QUESTION 4

STARTING WITH A DETAILED DIAGRAM



a)

TAKING MOMENTS OF BC ABOUT B

$$\Rightarrow F \times 2 = 100 \cos \theta \times 1 \\ \Rightarrow 2F = 100 \times \frac{4}{5} \\ \Rightarrow F = 40 \text{ N}$$

b)

DRAWING FORCES ON THE ROD BC (GREEN BRACES)

$$(4) : Y + F \sin \theta = 100 \\ Y + 40 \times \frac{4}{5} = 100 \\ Y = 68 \text{ N}$$

$$X = 40 \times \frac{4}{5} \\ X = 24 \text{ N}$$

c)

TAKING MOMENTS OF AB ABOUT A (BLUE FORCES)

$$100 \cos \theta \times 1 + Y \cos \theta \times 2 = X \sin \theta \times 2 \\ \Rightarrow 100 \cos \theta + 136 \cos \theta = 48 \sin \theta \\ \Rightarrow 236 \cos \theta = 48 \sin \theta \\ \Rightarrow \frac{\sin \theta}{\cos \theta} = \frac{236}{48} \\ \Rightarrow \tan \theta = \frac{59}{12} \\ \Rightarrow \theta \approx 78.5^\circ$$

$$\tan \theta = \frac{3}{4} \quad \sin \theta = \frac{3}{5}, \cos \theta = \frac{4}{5}$$

LET WITHOUT LOSS OF GENERALITY  $|AB| = |BC| = 2$

## IYGB - M1SG PAPER C - QUESTIONS

a) STARTING WITH THE USUAL MOMENTUM / IMPULSE DIAGRAM



BY THE IMPULSE MOMENTUM PRINCIPLE

$$\Rightarrow -mg\delta t = [(m + \delta m)(v + \delta v) + (-\delta m)(v - u)] - [mv]$$

$$\Rightarrow -mg\delta t = \cancel{mv} + m\delta v + v\delta m + \delta m\delta v - \cancel{v\delta m} + u\delta m - \cancel{mv}$$

$$\Rightarrow -mg\delta t = m\delta v + u\delta m + \delta m\delta v$$

$$\Rightarrow -mg = m \frac{\delta v}{\delta t} + u \frac{\delta m}{\delta t} + \frac{\delta m \delta v}{\delta t}$$

TAKING UNITS AND REARRANGE FOR THE ACCELERATION

$$\Rightarrow -mg = m \frac{dv}{dt} + u \frac{dm}{dt}$$

$$\Rightarrow \frac{dv}{dt} = -g - \frac{u}{m} \frac{dm}{dt}$$

NEXT, AS THE EJECTION RATE OF THE FUEL IS CONSTANT

$$\Rightarrow \frac{dm}{dt} = -\gamma, \text{ SUBJECT TO } t=0 \\ m=M$$

$$\Rightarrow m = M - \gamma t$$

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## NYGB - M4SG PAPER C - QUESTION 5

COMBINING THE LAST TWO EXPRESSIONS

$$\Rightarrow \frac{dv}{dt} = -g - \frac{u\lambda}{M-\lambda t} \quad (\cancel{2})$$

$$\Rightarrow \frac{dv}{dt} = \frac{u\lambda}{M-\lambda t} - g$$

FINALLY FOR IMMEDIATE LIFT OFF  $\frac{dv}{dt} > 0$ , AT  $t=0$

$$\Rightarrow \frac{u\lambda}{M} - g > 0$$

$$\Rightarrow u\lambda - gM > 0$$

$$\Rightarrow u\lambda > Mg$$

$$\Rightarrow \lambda > \frac{Mg}{u}$$

~~AS REQUIRED~~

b) SOLVING THE O.D.E BY DIRECT INTEGRATION - FIRST

WE REQUIRE TO FIND THE TIME WHEN  $m = \frac{3}{4}M$

$$\Rightarrow m = M - \lambda t$$

$$\Rightarrow \frac{3}{4}M = M - \left(\frac{3Mg}{u}\right)t$$

$$\Rightarrow \frac{3Mg}{u}t = \frac{1}{4}M$$

$$\Rightarrow t = \frac{u}{12g}$$

SOLVING THE O.D.E, SUBJECT TO  $t=0, v=0$ ,

$$\Rightarrow \int dv = \left( \frac{u\lambda}{M-\lambda t} - g \right) dt$$

$$\Rightarrow \int dv = \left( \frac{u \frac{3Mg}{u}}{M - \frac{3Mg}{u}t} - g \right) dt$$

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## IYGB-M456 PAPER C - QUESTIONS

$$\Rightarrow l \, dv = \left( \frac{3Mg}{u - \frac{3Mgt}{u}} - g \right) dt$$

$$\Rightarrow l \, dv = \left( \frac{\frac{3g}{t} - \frac{3gt}{u}}{1 - \frac{3gt}{u}} - g \right) dt$$

$$\Rightarrow l \, dv = \left( \frac{\frac{3ug}{u - 3gt}}{1 - \frac{3gt}{u}} - g \right) dt$$

$$\Rightarrow \int_{v=0}^V l \, dv = \int_{t=0}^{t=\frac{u}{12g}} \frac{\frac{3ug}{u - 3gt}}{1 - \frac{3gt}{u}} - g \, dt$$

$$\Rightarrow [v]_0^V = \left[ \frac{3ug}{-3g} \ln|u - 3gt| - gt \right]_{t=0}^{t=\frac{u}{12g}}$$

$$\Rightarrow v = \left[ -u \ln|u - 3gt| - gt \right]_{t=0}^{t=\frac{u}{12g}}$$

$$\Rightarrow v = \left[ u \ln|u - 3gt| + gt \right]_{t=\frac{u}{12g}}^{t=0}$$

$$\Rightarrow v = \left[ u \ln u \right] - \left[ u \ln \left| u - 3g \left( \frac{u}{12g} \right) \right| + g \left( \frac{u}{12g} \right) \right]$$

$$\Rightarrow v = u \ln u - u \ln \left( \frac{3}{4}u \right) - \frac{1}{12}u$$

$$\Rightarrow v = u \ln \left( \frac{u}{\frac{3}{4}u} \right) - \frac{1}{12}u$$

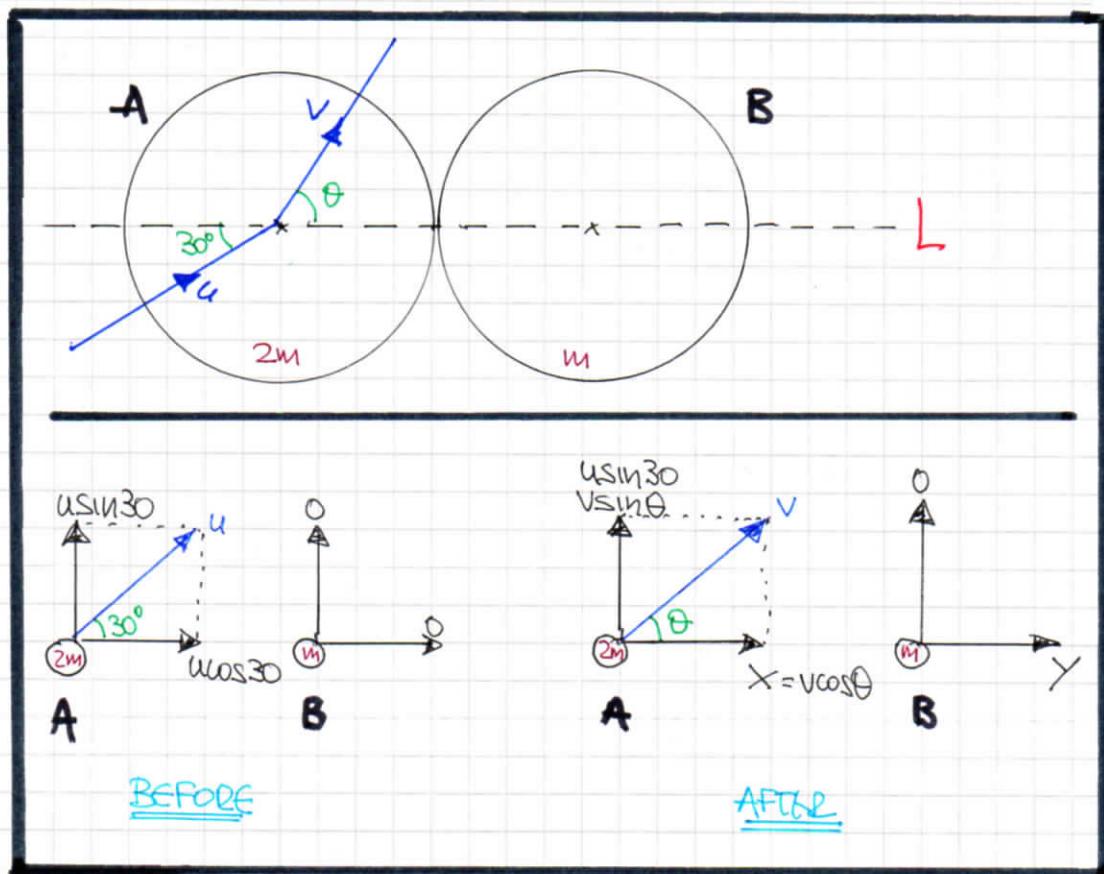
$$\Rightarrow v = u \ln \frac{4}{3} - \frac{1}{12}u$$

$$\Rightarrow v = \underline{\underline{\left( \ln \frac{4}{3} - \frac{1}{12} \right) u}}$$

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## IYGB - M456 PAPER C - QUESTION 6

a) STARTING WITH A VISUAL DIAGRAM FOR THE COLLISION



BY CONSERVATION OF MOMENTUM ALONG L

$$\Rightarrow 2m u \cos 30 + 0 = 2m X + m Y$$

$$\Rightarrow 2X + Y = 2u \cos 30^\circ$$

$$\Rightarrow \boxed{2X + Y = \sqrt{3}u}$$

BY RESTITUTION ALONG

$$\Rightarrow \frac{Y - X}{u \cos 30} = e$$

$$\Rightarrow -X + Y = e u \cos 30^\circ$$

$$\Rightarrow -X + Y = \frac{\sqrt{3}}{2} eu$$

$$\Rightarrow \boxed{-2X + 2Y = \sqrt{3}eu}$$

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## IYGB - M4SG PAPER C - QUESTION 6

SOLVING THE EQUATIONS YIELDS BY ADDITION

$$\Rightarrow 3Y = \sqrt{3}u + \sqrt{3}eu$$

$$\Rightarrow 3Y = \sqrt{3}u(1+e)$$

$$\Rightarrow Y = \frac{\sqrt{3}}{3}u(1+e)$$

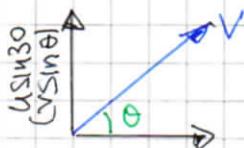
AND  $X = Y - \frac{\sqrt{3}}{2}eu$

$$\Rightarrow X = \frac{\sqrt{3}}{3}u(1+e) - \frac{\sqrt{3}}{2}eu = \frac{\sqrt{3}}{3}u + \frac{\sqrt{3}}{3}eu - \frac{\sqrt{3}}{2}eu$$

$$\Rightarrow X = \frac{\sqrt{3}}{3}u - \frac{\sqrt{3}}{6}eu$$

$$\Rightarrow X = \frac{\sqrt{3}}{6}u(2-e)$$

SPEED OF A — NO MOTION IN EXCERCE  $\perp$  TO L



$$X = \frac{1}{6}\sqrt{3}u(2-e)$$

$$|V|^2 = (usin30)^2 + X^2$$

$$|V|^2 = \frac{1}{4}u^2 + \frac{1}{12}u^2(2-e)^2$$

$$|V|^2 = \frac{1}{12}u^2 [3 + (2-e)^2]$$

$$|V|^2 = \frac{1}{12}u^2 [e^2 - 4e + 7]$$

$$|V| = u \sqrt{\frac{e^2 - 4e + 7}{12}}$$

SPEED OF B

SIMPLY FOUND ABOVE AS THE PERPENDICULAR TO L  
COMPONENT IS ZERO

$$|V_B| = \frac{1}{3}\sqrt{3}u(1+e)$$

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## NYGB - M456 PAPER C - QUESTION 6

b) K.E. BEFORE THE COLLISION

$$\frac{1}{2}(2m)u^2 = mu^2$$

K.E. AFTER THE COLLISION

$$\begin{aligned} & \frac{1}{2}(2m)v_A^2 + \frac{1}{2}mv^2 \\ &= m\left(\frac{u(e^2-4e+7)}{12}\right) + \frac{1}{2}m\left(\frac{u^2}{3}(1+e)^2\right) \\ &= \frac{mu^2}{12}(e^2-4e+7) + \frac{mu^2}{6}(e^2+2e+1) \\ &= \frac{mu^2}{12}[e^2-4e+7 + 2e^2+2e+2] \\ &= \frac{mu^2}{12}[3e^2+9] \\ &= \frac{1}{4}mu^2(e^2+3) \end{aligned}$$

FINALLY WE HAVE

$$\Rightarrow \frac{\frac{1}{4}mu^2(e^2+3)}{mu^2} = \frac{4}{5} \quad \leftarrow \text{"20% lost"}$$

$$\Rightarrow \frac{1}{4}(e^2+3) = \frac{4}{5}$$

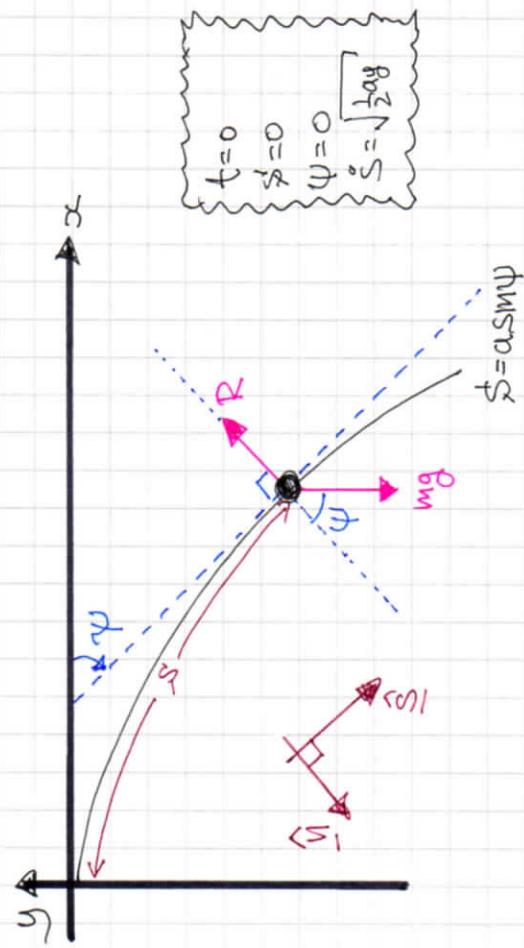
$$\Rightarrow e^2+3 = \frac{16}{5}$$

$$\Rightarrow e^2 = \underline{\underline{\frac{1}{5}}}$$

As Required

# NYGB - M4SC PAGE C - QUESTION 7

a) START BY PUTTING ALL INFO INTO A DIAGRAM



$$\Rightarrow \frac{1}{2} \frac{d}{dt} (\dot{s}^2) = g \left( \frac{\dot{s}}{a} \right) \quad \leftarrow \text{EQUATION OF MOTION}$$

$$\Rightarrow \frac{d}{dt} \left( \frac{\dot{s}^2}{2} \right) = \frac{2g}{a} \dot{s}$$

$$\Rightarrow \left[ \frac{\dot{s}^2}{2} \right]_0^t = \int \frac{2g}{a} \dot{s} \, ds$$

$$\Rightarrow \dot{s} = \sqrt{2g} \quad \text{at } t=0$$

$$\Rightarrow v^2 - \frac{1}{2} a g = \left[ \frac{2g}{a} s^2 \right]_0^s$$

$$\Rightarrow v^2 - \frac{1}{2} a g = \frac{2g}{a} s^2$$

$$\Rightarrow v^2 = \frac{2g}{a} s^2 + \frac{1}{2} a g$$

LOOKING NEXT AT THE NORMAL DIRECTION ( $\hat{n}$ )

$$\Rightarrow m \frac{\dot{s}^2}{\rho} = m g \cos \psi - R$$

WITHOUT IT GRAVITY,  $R=0$

$$\Rightarrow m \frac{\dot{s}^2}{\rho} = m g \cos \psi$$

$$\Rightarrow \dot{s}^2 = g \rho \cos \psi$$

USING ABOVE EXPRESSION FOR  $\dot{s}^2 = v^2$

CONNECT/PREPARE THE USUAL AUXILIARIES

$$\bullet \dot{s} = a \sin \psi \Rightarrow \rho = \frac{ds}{d\psi} = a \cos \psi$$

$$\bullet \alpha = \ddot{s} \frac{1}{\rho} + \frac{\dot{s}^2}{\rho^2}$$

LOOKING AT THE TANGENTIAL MOTION ( $\hat{t}$ )

$$\Rightarrow m \ddot{s} = m g \sin \psi$$

$$\Rightarrow \ddot{s} = g \sin \psi$$

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## YGB - M4SC PAGE C - QUESTION 7

$$\Rightarrow \frac{g}{a} s^2 + \frac{1}{2} a g = g (\cos \psi) \cos \psi$$

$$\Rightarrow \frac{s^2}{a} + \frac{1}{2} a = \cos^2 \psi$$

$$\Rightarrow 2s^2 + a^2 = 2a^2 \cos^2 \psi$$

$$\Rightarrow 2s^2 + a^2 = 2a^2(1 - \sin^2 \psi)$$

$$\Rightarrow 2s^2 + a^2 = 2a^2 \left(1 - \left(\frac{s}{a}\right)^2\right)$$

$$\Rightarrow 2s^2 + a^2 = 2a^2 \left(1 - \frac{s^2}{a^2}\right)$$

$$\Rightarrow 2s^2 + a^2 = 2a^2 - 2s^2$$

$$\Rightarrow 4s^2 = a^2$$

$$\Rightarrow s^2 = \frac{1}{4} a^2$$

$$\Rightarrow s = \frac{1}{2} a$$

b) firstly we have

$$\text{AC } \dot{s} = \frac{1}{2} a \Rightarrow \frac{1}{2} a = a \sin \psi$$

$$\Rightarrow \sin \psi = \frac{1}{6}$$

NORMAL ACCELERATION ( $\ddot{s}$ ) IS SIMPLE SIN.

$$\Rightarrow \ddot{s} = g \sin \psi \quad (\text{FROM FORMULA})$$

$$\Rightarrow \ddot{s} = g \times \sin \frac{\pi}{6}$$

$$\Rightarrow \ddot{s} = \frac{1}{2} g$$

TANGENTIAL ACCELERATION IS

$$\Rightarrow \ddot{s} = \frac{\ddot{s}^2}{r} = \frac{\frac{g}{a} s^2 + \frac{1}{2} a g}{a \cos \psi}$$

$$\Rightarrow \ddot{s} = \frac{\frac{g}{a} \left(\frac{1}{2} a\right)^2 + \frac{1}{2} a g}{a \cos \frac{\pi}{6}} = \frac{\frac{3}{4} a g}{a \sqrt{\frac{3}{2}}} = \frac{\sqrt{3}}{2} g$$

HENCE THE MAGNITUDE OF THE ACCELERATION  
CAN BE FOUND AS

$$\sqrt{\left(\frac{1}{2} g\right)^2 + \left(\frac{\sqrt{3}}{2} g\right)^2} = \sqrt{\frac{1}{4} g^2 + \frac{3}{4} g^2} = g$$

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## IYGB - M456 PAPER C - QUESTION 8

$$F_1 = (3a+1)\underline{i} + 3\underline{j} \quad \text{AT} \quad A(1,2)$$

$$F_2 = (a-10)\underline{i} - 2\underline{j} \quad \text{AT} \quad B(2,0)$$

$$F_3 = \underline{i} + (1-a)\underline{j} \quad \text{AT} \quad C(4,-1)$$

- a) IF THE SYSTEM IS TO REDUCE TO A COUPLE ABOUT O

$$F_1 + F_2 + F_3 = (0,0)$$

$$(3a+1, 3) + (a-10, -2) + (1, 1-a) = (0,0)$$

$$(4a-8, 2-a) = (0,0)$$

THIS IS INDEED POSSIBLE IF  $a=2$

FINDING THE MOMENT ABOUT O, WITH  $a=2$

$$\begin{vmatrix} 1 & \underline{j} & \underline{k} \\ 1 & 2 & 0 \\ 7 & 3 & 0 \end{vmatrix} + \begin{vmatrix} 1 & \underline{j} & \underline{k} \\ 2 & 0 & 0 \\ -8 & -2 & 0 \end{vmatrix} + \begin{vmatrix} 1 & \underline{j} & \underline{k} \\ 4 & -1 & 0 \\ 1 & -1 & 0 \end{vmatrix}$$

$$= [0, 0, 3-14] + [0, 0, -4] + [0, 0, -4+1]$$

$$= [0, 0, -11] + [0, 0, -4] + [0, 0, -3]$$

$$= [0, 0, -18]$$

HENCE, A MAGNITUDE OF 18 Nm, ANTICLOCKWISE

## IYGB - M1456 PAPER C - QUESTION 8

b) Now find the moment of the forces about O, in terms of  $a$

$$\underline{G}_o = \begin{vmatrix} i & j & k \\ 1 & 2 & 0 \\ 3a+1 & 3 & 0 \end{vmatrix} + \begin{vmatrix} i & j & k \\ 2 & 0 & 0 \\ a-10 & -2 & 0 \end{vmatrix} + \begin{vmatrix} i & j & k \\ 4 & -1 & 0 \\ 1 & 1-a & 0 \end{vmatrix}$$

$$\underline{G}_o = (0, 0, 3-6a-2) + (0, 0, -4) + (0, 0, 4-4a+1)$$

$$\underline{G}_o = (0, 0, 1-6a) + (0, 0, -4) + (0, 0, 5-4a)$$

$$\underline{G}_o = (0, 0, 2-10a)$$

This yields zero moment if  $a = \frac{1}{5}$

THM  $\underline{F}_1 + \underline{F}_2 + \underline{F}_3 = (4a-8, 2-a) \leftarrow$  from earlier

$$= \left( -\frac{36}{5}, \frac{9}{5} \right)$$

THE LINE PASSES THROUGH THE ORIGIN (ZERO MOMENT ABOUT O)

$$y = mx + \cancel{c}$$

$$m = \frac{\frac{9}{5} - 0}{-\frac{36}{5} - 0} = -\frac{1}{4}$$

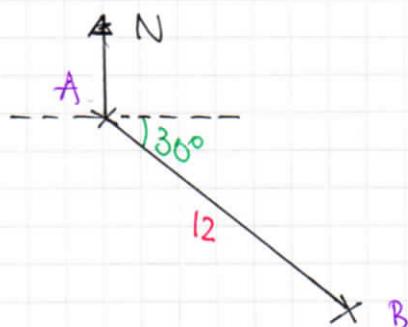
∴ REDUCES TO  $\underline{F} = -\frac{36}{5}\underline{i} + \frac{9}{5}\underline{j}$ , WHICH ACTS

ALONG THE LINE  $y = -\frac{1}{4}x$

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## IYGB - M4SG PAPER C - QUESTION 9

### INITIAL CONFIGURATION



### VELOCITY TRIANGLE

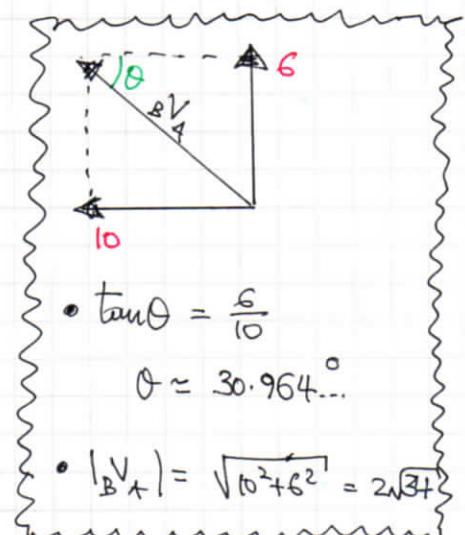
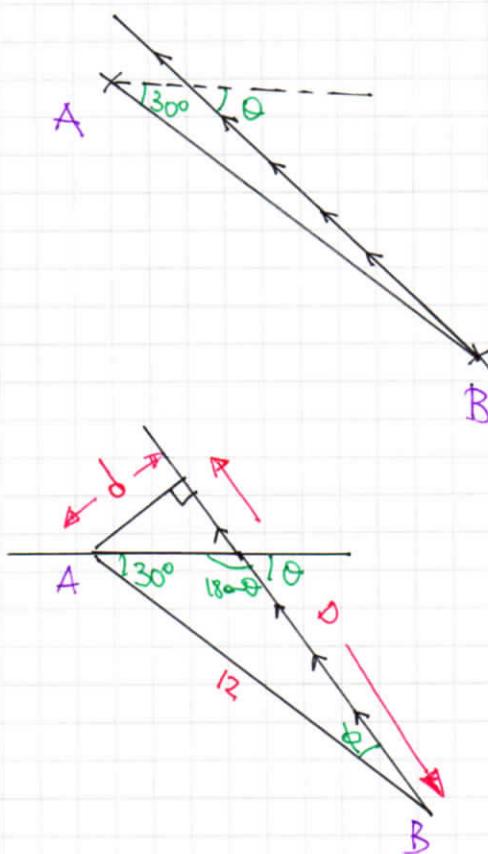
$$\underline{v}_{BA} = \underline{v}_B - \underline{v}_A$$

$$(\underline{v}_B = \underline{v}_A + \underline{v}_{BA})$$

$$\underline{v}_{BA} = (-3\hat{i} + 9\hat{j}) - (7\hat{i} + 3\hat{j})$$

$$\underline{v}_{BA} = -10\hat{i} + 6\hat{j}$$

### FIXING A, AN OBSERVER ON A SEEKS THE FOLLOWING



### SPLIT DISTANCE d is

$$d = 12 \sin \phi$$

$$d = 12 \sin(0.96375^\circ)$$

$$d \approx 0.2018 \dots \text{ km}$$

$$d \approx 202 \text{ m}$$

$$\begin{cases} \phi + 30 + 180 - \theta = 180 \\ \phi = \theta - 30 \\ \phi = 0.96375^\circ \end{cases}$$

## IYGB - M456 PAPER C - QUESTION 9

- $D = 12 \cos \phi = 12 \cos(0.96375\ldots) = 11.9983024\ldots \text{ km}$

- COVERED AT  $2\sqrt{34} \text{ km h}^{-1}$  WE OBTAIN

$$\frac{11.9983024\ldots}{2\sqrt{34}} \approx 1.0288\ldots \text{ HOUR}$$

$$\approx 1 \text{ HOUR } - 2 \text{ MINUTES}$$

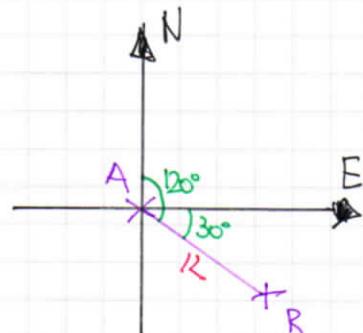
$$\approx \cancel{13 : 02}$$

### ALTERNATIVE BY VECTORS

- TAKE THE POSITION OF "A" AT NOON, TO BE THE ORIGIN  $\rightarrow$  THE POSITION VECTOR OF "B" AT NOON WILL BE

$$\underline{r}_B = \left( 12 \cos 30 \right) \hat{i} - \left( 12 \sin 30 \right) \hat{j}$$

$6\sqrt{3} \hat{i}$        $6 \hat{j}$



- THE POSITION VECTORS OF THE TWO SHIPS,  $t$  HOURS AFTER NOON, IS

$$\underline{r}_A = (0,0) + (7,3)t = (7t, 3t)$$

$$\underline{r}_B = (6\sqrt{3}, -6) + (-3, 4)t = (6\sqrt{3} - 3t, 4t - 6)$$

- THE POSITION VECTOR OF B, RELATIVE TO A IS GIVEN BY

$$\underline{r}_B - \underline{r}_A = (6\sqrt{3} - 10t, 4t - 6)$$

## IYGB - M1456 PAPER C - QUESTION 9

- THE DISTANCE BETWEEN THE SHIPS AT TIME  $t$

$$d = |\vec{r}_B - \vec{r}_A|$$

$$d = |6\sqrt{3} - 10t, 6t - 6|$$

$$d = \sqrt{(6\sqrt{3} - 10t)^2 + (6t - 6)^2}$$

$$d = \sqrt{108 - 120\sqrt{3}t + 100t^2 + 36t^2 - 72t + 36}$$

$$d = \sqrt{136t^2 - (72 + 120\sqrt{3})t + 144}$$

$$d^2 = 136t^2 - 24(3 + 5\sqrt{3})t + 144$$

- LET  $f(t) = 136t^2 - 24(3 + 5\sqrt{3})t + 144$   
BY COMPLETING THE SQUARE OR CANNES

$$f(t) = 272t - 24(3 + 5\sqrt{3})$$

- SOLVING FOR ZEROES

$$\begin{aligned} t &= \frac{24(3 + 5\sqrt{3})}{272} \approx 1.0288\dots \\ &\approx 1 \text{ HOUR } - 2 \text{ MINUTES} \\ &\approx \underline{\underline{13:02}} \end{aligned}$$

- AND TO FIND THE MINIMUM DISTANCE

$$d_{\min} = \sqrt{136(1.0288\dots)^2 - (72 + 120\sqrt{3})(1.0288\dots) + 144}$$

$$\approx 0.201839\dots \text{ km}$$

$$\approx \underline{\underline{202 \text{ m}}}$$

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## IYGB - M15G PAPER 2 - QUESTION 10

a)

$$F = \frac{25}{x^2} - \frac{50}{x^3}, x > 0$$

WORK BY  $F = -4$

$$\Rightarrow \int_1^k \frac{25}{x^2} - \frac{50}{x^3} dx = -4$$

$$\Rightarrow \left[ -\frac{25}{x} + \frac{25}{x^2} \right]_1^k = -4$$

$$\Rightarrow \left( -\frac{25}{k} + \frac{25}{k^2} \right) - \cancel{\left( -25 + 25 \right)} = -4 \quad \times k^2$$

$$\Rightarrow -25k + 25 = -4k^2$$

$$\Rightarrow 4k^2 - 25k + 25 = 0$$

$$\Rightarrow (4k - 5)(k - 5) = 0$$

$$\Rightarrow k = \begin{cases} 5 \\ \frac{5}{4} \end{cases}$$

b)

$$F = 0 \text{ YIELDS}$$

$$\frac{25}{x^2} - \frac{50}{x^3} = 0$$

$$25x - 50 = 0$$

$$x = 2$$

NEXT THE WORK FROM  $x=1$  TO  $x=2$

$$W = \int_1^2 \frac{25}{x^2} - \frac{50}{x^3} dx = \left[ -\frac{25}{x} + \frac{25}{x^2} \right]_1^2$$

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IYGB - M15G PAPER C - QUESTION 10

$$= \left( -\frac{25}{2} + \frac{25}{4} \right) - \cancel{\left( -25 + 25 \right)} = -\frac{25}{4} \quad (\text{it works})$$

By Energy

$$\Rightarrow KE_{x=1} - W_{out} = KE_{x=2}$$

$$\Rightarrow \frac{1}{2}mv^2 - \frac{25}{4} = \frac{1}{2}mv^2.$$

$$\Rightarrow \frac{1}{2}(0.5) \times 13^2 - \frac{25}{4} = \frac{1}{2}(0.5)v^2$$

$$\Rightarrow \frac{169}{4} - \frac{25}{4} = \frac{1}{4}v^2$$

$$\Rightarrow 169 - 25 = v^2$$

$$\Rightarrow v^2 = 144$$

$$\Rightarrow |v| = 12 \text{ ms}^{-1}$$

## IYGB - M456 PAPER C - QUESTION 11

$$r = k e^{\theta \omega t \alpha}$$

( $k, \alpha$  constants,  $0 < \alpha \leq \frac{\pi}{4}$ )

CONSTANT ANGULAR VELOCITY

$$\dot{\theta} = \omega$$

$$\ddot{\theta} = 0$$

DIFFERENTIATE THE EQUATION OF THE PATH TO OBTAIN  $\dot{r}$  &  $\ddot{r}$

$$\Rightarrow r = k e^{\theta \omega t \alpha}$$

$$\Rightarrow \dot{r} = k e^{\theta \omega t \alpha} \times \dot{\theta} \omega t \alpha$$

$$\Rightarrow \dot{r} = r \omega \alpha t \alpha$$

$$\Rightarrow \ddot{r} = \dot{r} \omega \alpha t \alpha = (r \omega \alpha t \alpha) \omega \alpha t \alpha$$

$$\Rightarrow \ddot{r} = r \omega^2 \alpha t^2 \alpha$$

NOW THE ACCELERATION IN POLARIS IS GIVEN BY

$$\Rightarrow \ddot{r} = (\ddot{r} - r \dot{\theta}^2) \hat{r} + \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) \hat{\theta}$$

$$\Rightarrow \ddot{r} = (\ddot{r} - r \omega^2) \hat{r} + \frac{1}{r} \frac{d}{dt} (r^2 \omega) \hat{\theta}$$

$$\Rightarrow \ddot{r} = (\ddot{r} - r \omega^2) \hat{r} + 2\dot{r}\omega \hat{\theta}$$

$$\Rightarrow \ddot{r} = (r \omega^2 \alpha t^2 \alpha - \omega^2 r) \hat{r} + (2\omega^2 r \alpha t \alpha) \hat{\theta}$$

$$\Rightarrow \ddot{r} = r \omega^2 \left[ [ \omega^2 \alpha t^2 \alpha - 1 ] \hat{r} + [ 2\omega^2 r \alpha t \alpha ] \hat{\theta} \right]$$

NEXT THE MODULUS (MAGNITUDE OF ACCELERATION)

$$\Rightarrow |\ddot{r}| = \left| r \omega^2 \left[ ( \omega^2 \alpha t^2 \alpha - 1 ) \hat{r} + ( 2\omega^2 r \alpha t \alpha ) \hat{\theta} \right] \right|$$

$$\Rightarrow |\ddot{r}| = r \omega^2 \left[ ( \omega^2 \alpha t^2 \alpha - 1 )^2 + ( 2\omega^2 r \alpha t \alpha )^2 \right]^{\frac{1}{2}}$$

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## IYGB - M156 PAPER C - QUESTION 11

$$\Rightarrow |\ddot{r}| = rw^2 \left[ \omega t^4 - 2\omega t^2 + 1 + 4\omega t^2 \right]^{\frac{1}{2}}$$

$$\Rightarrow |\ddot{r}| = rw^2 \left[ \omega t^4 + 2\omega t^2 + 1 \right]^{\frac{1}{2}}$$

$$\Rightarrow |\ddot{r}| = rw^2 \sqrt{(\omega t^2 + 1)^2}$$

$$\Rightarrow |\ddot{r}| = rw^2 \cosec^2 \alpha$$

NEXT WE REQUIRE A VELOCITY EXPRESSION, TO GET THE SPEED

$$\Rightarrow v = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

$$\Rightarrow v = (rw\omega t) \hat{r} + rw \hat{\theta}$$

$$\Rightarrow |v| = |rw(\omega t \hat{r} + \hat{\theta})|$$

$$\Rightarrow |v| = rw \sqrt{\omega^2 t^2 + 1}$$

$$\Rightarrow |v| = rw \sqrt{\cosec^2 \alpha}$$

$$\Rightarrow |v| = rw \cosec \alpha$$

FINALLY WE OBTAIN

$$|\ddot{r}| = rw^2 \cosec^2 \alpha = \frac{1}{r} (r^2 w^2 \cosec^2 \alpha) = \frac{|v|^2}{r}$$

$$\therefore |\ddot{r}| = \frac{|v|^2}{r}$$

AS REQUIRED

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## NYGB - M456 PAPER C - QUESTION 12

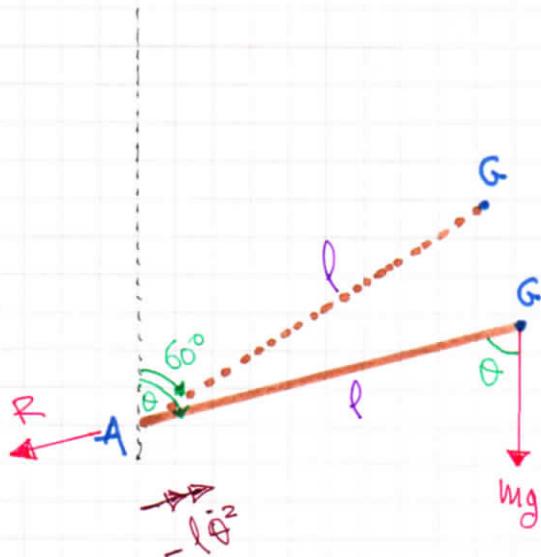
- a) STARTING WITH A DIAGRAM,  
WHERE G DENOTES THE MIDPOINT  
OF THE ROD

$$I_A = \frac{4}{3}ml^2$$

$$12ma^2 = \frac{4}{3}ml^2$$

$$l^2 = 9a^2$$

$$l = 3a$$



BY ENERGYES TAKING THE LEVEL OF "A" AS THE ZERO POTENTIAL LNTL

$$\Rightarrow P.E_{60^\circ} + \cancel{P.E}_{60^\circ} = K.E_\theta + P.E_\theta$$

$$\Rightarrow mg l \cos 60^\circ = \frac{1}{2} I \dot{\theta}^2 + mg l \cos \theta$$

$$\Rightarrow mg(3a) \times \frac{1}{2} = \frac{1}{2} (12ma^2) \dot{\theta}^2 + mg(3a) \cos \theta$$

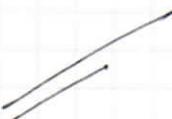
$$\Rightarrow \frac{3}{2} m g a = 4m a^2 \dot{\theta}^2 + 3m g a \cos \theta$$

$$\Rightarrow 3g = 8a \dot{\theta}^2 + 6g \cos \theta$$

$$\Rightarrow 8a \dot{\theta}^2 = 3g - 6g \cos \theta$$

$$\Rightarrow 8a \dot{\theta}^2 = 3g(1 - 2\cos \theta)$$

$$\Rightarrow \dot{\theta}^2 = \frac{3g}{8a} (1 - 2\cos \theta)$$



IYGB - M456 PAPER C - QUESTION 12

b) LOOKING IN THE RADIAL DIRECTION

$\Rightarrow$  "  $m\ddot{r}$  = RESULTANT FORCE "

$$\Rightarrow m(-3a\dot{\theta}^2) = -R - mg \cos \theta$$

$$\Rightarrow R = 3ma\dot{\theta}^2 - mg \cos \theta$$

$$\Rightarrow R = 3ma \left( \frac{3g}{8a} (1 - 2\omega_0 \theta) \right) - mg \cos \theta$$

$$\Rightarrow R = \frac{9}{8}mg(1 - 2\omega_0 \theta) - mg \cos \theta$$

$$\Rightarrow R = \frac{1}{8}mg(9 - 18\omega_0 \theta - 8 \cos \theta)$$

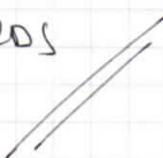
$$\Rightarrow R = \frac{1}{8}mg(9 - 26 \cos \theta)$$

HENCE THE REQUIRED COMPONENT IS

$\frac{1}{8}mg(9 - 26 \cos \theta)$ , RADIALLY INWARDS

OR

$\frac{1}{8}mg(26 \cos \theta - 9)$ , RADIALLY OUTWARDS



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## 1Y6B - M456 PAPER C - QUESTION 13

a)

SOLVING THE DIFFERENTIAL EQUATION

$$\Rightarrow m\ddot{x} = mg - kmv$$

$$\Rightarrow \ddot{x} = g - kv$$

$$\Rightarrow v \frac{dv}{dx} = g - kv$$

$$\Rightarrow \frac{1}{g-kv} dv = 1 dx.$$

$$\Rightarrow \frac{-kv}{g-kv} dv = -k dx$$

$$\Rightarrow \int_{v=0}^v \frac{-kv}{g-kv} dv = \int_{x=0}^x -k dx$$

$$\Rightarrow \int_0^v \frac{(g-kv)-g}{g-kv} dv = \int_0^x -k dx$$

$$\Rightarrow \int_0^v 1 - \frac{g}{g-kv} dv = \int_0^x -k dx$$

$$\Rightarrow \left[ v + \frac{g}{k} \ln|g-kv| \right]_0^v = \left[ -kx \right]_0^x$$

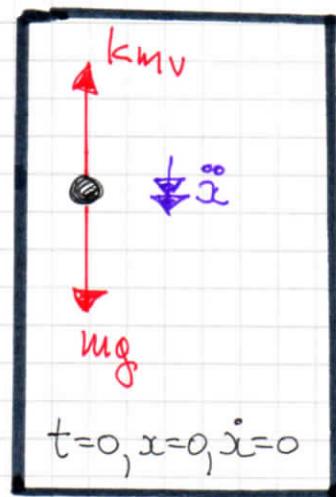
$$\Rightarrow \left[ v + \frac{g}{k} \ln|g-kv| \right] - \left[ \frac{g}{k} \ln g \right] = -kx - 0$$

$$\Rightarrow v + \frac{g}{k} \ln \left| \frac{g-kv}{g} \right| = -kx$$

$$\Rightarrow x = -\frac{1}{k}v - \frac{g}{k^2} \ln \left( \frac{g-kv}{g} \right)$$

$$\Rightarrow x = \frac{g}{k^2} \ln \left| \frac{g}{g-kv} \right| - \frac{v}{k}$$

AS REQUIRED



IYGB - MUSC PAPER C - QUESTION 13

b) LOOKING AT THE ORIGINAL O.D.E.

$$\ddot{x} = g - kv$$

INITIAL SPEED  $\Rightarrow \ddot{x} = 0$   
 $\Rightarrow V = \frac{g}{k}$

THUS WE HAVE IF  $v = \frac{1}{2}V = \frac{g}{2k}$

$$x = \frac{g}{k^2} \ln \left| \frac{g}{g-kv} \right| - \frac{v}{k}$$

$$x = \frac{g}{k^2} \ln \left| \frac{g}{g-k\frac{g}{2k}} \right| - \frac{\frac{g}{2k}}{k}$$

$$x = \frac{g}{k^2} \ln 2 - \frac{g}{2k^2}$$

$$x = \frac{g}{2k^2} [2 \ln 2 - 1]$$

$$x = \frac{1}{2g} \times \frac{g^2}{k^2} [\ln 4 - 1]$$

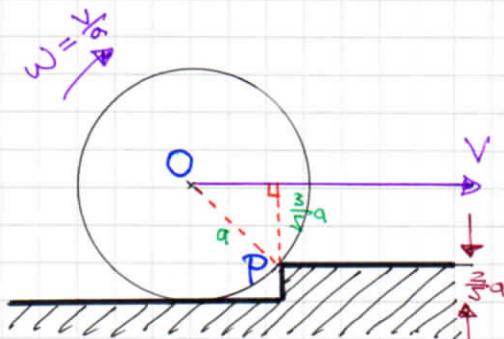
$$x = \frac{1}{2g} V^2 [\ln 4 - 1]$$

$$x = \frac{V^2}{2g} [-1 + \ln 4]$$

AS REQUIRED

# IYGB - M456 PAPER C - QUESTION 14

LOOKING AT THE DIAGRAM BELOW



MOMENT OF INERTIA OF THE SPHERE

$$I_o = \frac{2}{5}ma^2$$

$$I_p = \frac{2}{5}ma^2 + ma^2 = \frac{7}{5}ma^2$$

LET THE ANGULAR VELOCITY ABOUT P, BE Σ

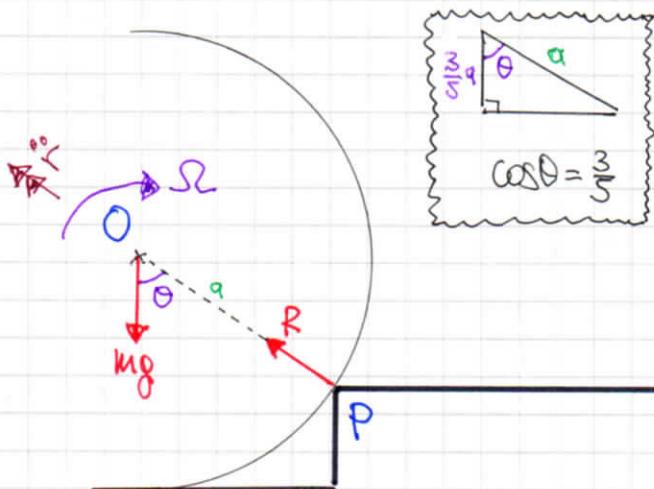
BY CONSERVATION OF MOMENTUM ABOUT P

$$\Rightarrow \underbrace{(I_o\omega) + (mV) \times \frac{3}{5}a}_{\text{JUST BEFORE IMPACT}} = \underbrace{I_p\Sigma}_{\text{AFTER IMPACT AT P}}$$

$$\Rightarrow \frac{2}{5}ma^2\omega + \frac{3}{5}mVa = \frac{7}{5}ma^2\Sigma$$

$$\Rightarrow 2a\omega + 3V = 7a\Sigma \quad \rightarrow \div \frac{1}{5}ma$$

NEXT WE CONSIDER THE INSTANT AFTER THE IMPACT



RADIALY, AS IT ROTATES AFTER P

$$\Rightarrow m\ddot{r} = R - mg\cos\theta$$

$$\Rightarrow m(-\Sigma^2 a) = R - mg\cos\theta$$

$$\Rightarrow R = mg\cos\theta - ma\Sigma^2$$

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## IYGB - M156 PAPER C - QUESTION 14

FOR ROTATION ABOUT P, R > 0

$$\Rightarrow \frac{3}{5}mg - ma\omega^2 > 0$$

$$\Rightarrow a\omega^2 < \frac{3}{5}g \quad \rightarrow \times 49a$$

$$\Rightarrow 49a^2\omega^2 < \frac{147}{5}ag$$

$$\Rightarrow (2aw + 3v)^2 < \frac{147}{5}ag$$

$$\Rightarrow (2av + 3v)^2 < \frac{147}{5}ag$$

$$\Rightarrow (5v)^2 < \frac{147}{5}ag$$

$$\Rightarrow 25v^2 < \frac{147}{5}ag$$

$$\Rightarrow v^2 < \frac{147}{125}ag$$

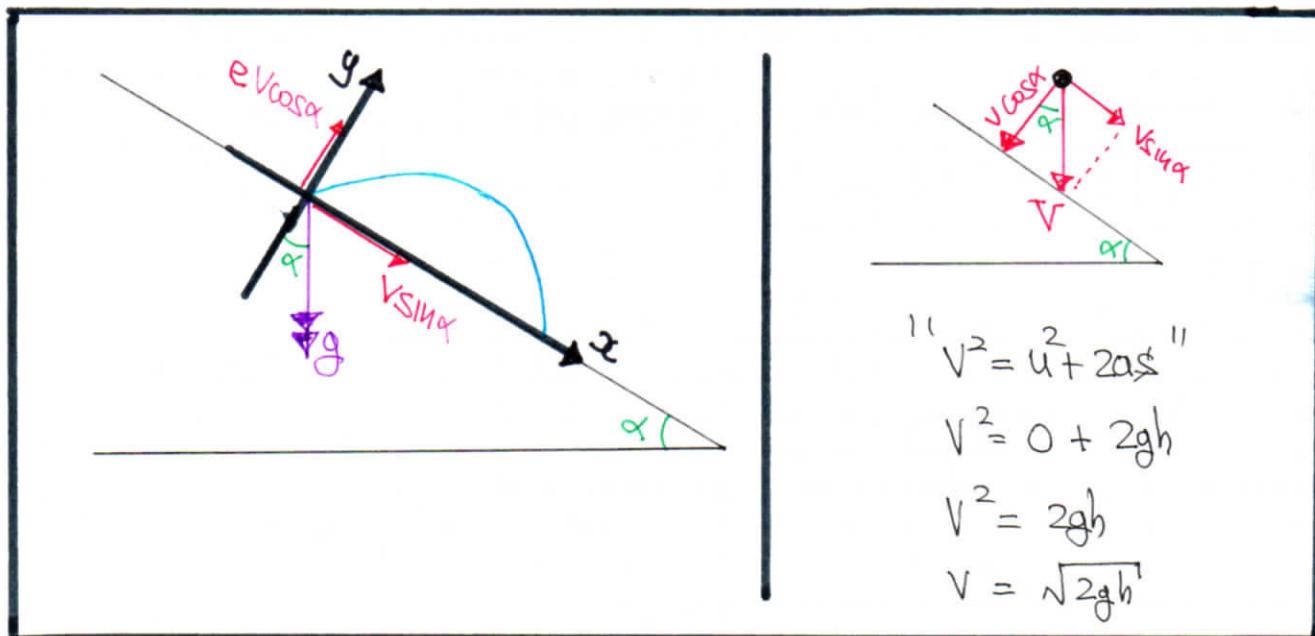
IN ORDER TO "CREATE"

$$7aw = 2aw + 3v$$

OBTAIN AND FAILURE

AS REQUIRED

## IYGB - M4SG PAPER C - QUESTION 15



- Start by computing the components of the velocity on impact, parallel & perpendicular to the plane (top right). — No momentum is exchanged parallel to the plane however perpendicular to the plane the "rebounding" velocity component is  $ev\cos\alpha$  (top left)

- Draw the equations of motion in the co-ordinate system shown in the above diagram

- $\ddot{x} = gs\sin\alpha$
- $\ddot{z} = gts\sin\alpha + V\sin\alpha$
- $z = \frac{1}{2}gt^2\sin\alpha + Vt\sin\alpha$

- $\ddot{y} = -g\cos\alpha$
- $\dot{y} = -gt\cos\alpha + ev\cos\alpha$
- $y = -\frac{1}{2}gt^2\cos\alpha + evt\cos\alpha$

- Determine the flight time to the "second" impact, i.e.  $y=0$

$$\Rightarrow 0 = -\frac{1}{2}gt^2\cos\alpha + evt\cos\alpha$$

$$\Rightarrow 0 = \frac{1}{2}t\cos\alpha [2ev - gt]$$

$$\Rightarrow t = \frac{2ev}{g} \quad (t \neq 0)$$

## IYGB - M456 PAPER C - QUESTION 15

- ② SUBSTITUTING INTO THE "x-equation" TO FIND THE REQUIRED DISTANCE d

$$d = \frac{1}{2}g\left(\frac{2ev}{g}\right)^2 \sin\alpha + v\left(\frac{2ev}{g}\right) \sin\alpha$$

$$d = \frac{2e^2v^2}{g} \sin\alpha + \frac{2ev^2}{g} \sin\alpha$$

$$d = \left(\frac{2ev^2}{g} \sin\alpha\right)(e+1)$$

$$d = \frac{2e}{g} \left(\frac{2gh}{g}\right) (\sin\alpha) (e+1)$$

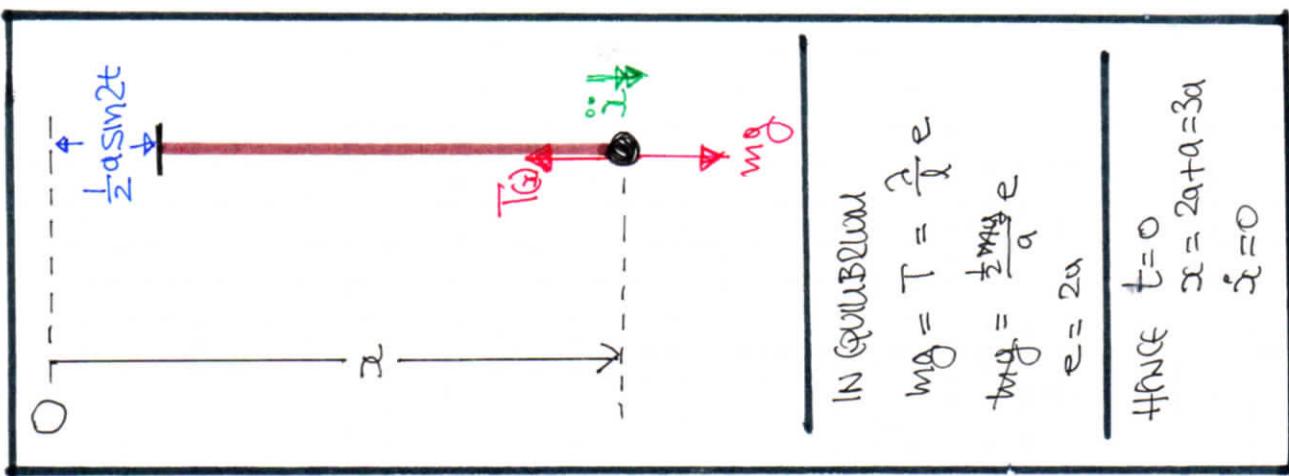
$$\cancel{d = 4eh(e+1) \sin\alpha}$$

$$\boxed{\begin{aligned} v &= \sqrt{2gh} \\ v^2 &= 2gh \end{aligned}}$$

# IYGB - M456 PAPER C - QUESTION 16

LOOKING AT THE DIAGRAM,  
FORM THE EQUATION OF MOTION

$$\begin{aligned}
 & \Rightarrow m\ddot{x} = mg - T \\
 & \Rightarrow m\ddot{x} = mg - \frac{2}{a}(x - a - \frac{1}{2}a\sin 2t) \\
 & \Rightarrow m\ddot{x} = mg - \frac{2mg}{a}(x - a - \frac{1}{2}a\sin 2t) \\
 & \Rightarrow \ddot{x} = g - \frac{2g}{2a}(x - a - \frac{1}{2}a\sin 2t) \\
 & \Rightarrow \ddot{x} = g - \frac{g}{2a}x + \frac{1}{2}g + \frac{1}{4}g\sin 2t \\
 & \Rightarrow \ddot{x} + \frac{g}{2a}\dot{x} = \frac{3}{2}g + \frac{1}{4}g\sin 2t \\
 & \Rightarrow \ddot{x} + \frac{g}{2a}\dot{x} = P\omega^2 + (Q\omega^2 - 4g)\sin 2t \\
 & \text{LET } \omega^2 = \frac{g}{2a} \Rightarrow g = 2a\omega^2 \\
 & \Rightarrow \ddot{x} + \omega^2 x = \frac{3}{2}(2a\omega^2) + \frac{1}{4}(2a\omega^2)\sin 2t \\
 & \Rightarrow \ddot{x} + \omega^2 x = 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t
 \end{aligned}$$



THE COMPLEMENTARY FUNCTION IS THE  
STANDARD S.H.M. SOLUTION

$$x = A\cos\omega t + B\sin\omega t$$

FOR PARTICULAR INTEGRAL WE TRY

$$\begin{aligned}
 x &= P + Q\sin\omega t \\
 \dot{x} &= -4Q\sin\omega t
 \end{aligned}$$

$$\begin{aligned}
 &\Rightarrow -4Q\sin\omega t + \omega^2(P + Q\sin\omega t) \\
 &\equiv 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t \\
 &\Rightarrow P\omega^2 + (Q\omega^2 - 4g)\sin 2t \\
 &\equiv P\omega^2 + 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t
 \end{aligned}$$

$$\begin{aligned}
 P &= 3a & \text{and} & Q(\omega^2 - 4) = \frac{1}{2}a\omega^2 \\
 Q &= \frac{a\omega^2}{2(\omega^2 - 4)}
 \end{aligned}$$

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## NGB - N4SE PAPER C - QUESTION 6

HENCE THE GENERAL SOLUTION IS GIVEN BY

$$x = A \cos \omega t + B \sin \omega t + 3a + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t$$

APPLY  $t=0$ ,  $x=3a$

$$3a = A + 3a$$

$$A=0$$

$$x = 3a + B \sin \omega t + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t$$

DIFFERENTIATE AND APPLY CONDITION  $t=0$ ,  $\dot{x}=0$

$$\dot{x} = B \omega \cos \omega t + \frac{a\omega^2}{\omega^2 - 4} \cos 2t$$

$$0 = B\omega + \frac{a\omega^2}{\omega^2 - 4}$$

$$B = -\frac{a\omega}{\omega^2 - 4}$$

$$x = 3a + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t - \frac{a\omega}{\omega^2 - 4} \sin \omega t$$

$$x = 3a + \frac{a\omega}{2(\omega^2 - 4)} [\omega \sin 2t - 2 \sin \omega t]$$