	_		_																									
A:twoDMotion	A:cartSys	A:cartSysR	A:yAxisDir	A:startOrigin	DD:positionIX	DD:positionIY	DD:frequencyDD	DD:angFrequencyDD	DD:periodSHMDD	TM:acceleration	TM:velocity	TM:NewtonSecLawMot	TM:NewtonSecLawRotMot	GD:velocityIX	GD:velocityIY	GD:accelerationIX	GD:accelerationIY	GD:hForceOnPendulum	GD:vForceOnPendulum	GD:angFrequencyGD	GD:periodPend	IM:calOfAngularDisplacement	FR:inputValues	FR:verifyInptVals	FR:calcAngPos	FR:outputValues	NFR:correct	NFR:portable