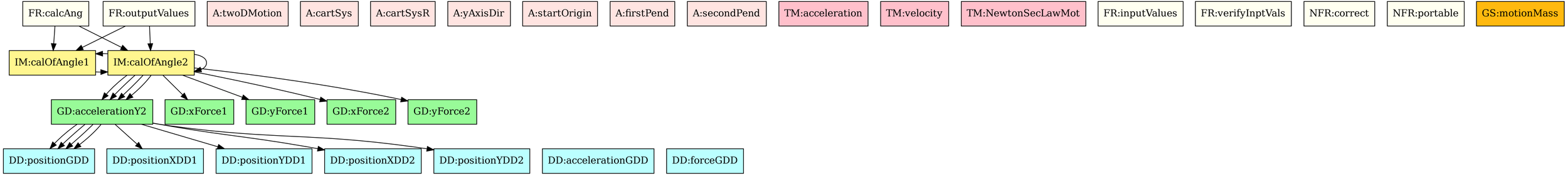
FR:calcAng
FR:outputValues
A:twoDMotion
A:cartSys
A:cartSysR
A:yAxisDir
A:startOrigin
A:firstPend
A:secondPend
TM:acceleration
TM:velocity
TM:NewtonSecLawMot
FR:inputValues
FR:verifyInptVals
NFR:correct
NFR:portable
GS:motionMass
IM:calOfAngle1
IM:calOfAngle2
GD:accelerationY2
GD:xForce1
GD:yForce1
GD:xForce2
GD:yForce2
DD:positionGDD
DD:positionXDD1
DD:positionYDD1
DD:positionXDD2
DD:positionYDD2
DD:accelerationGDD
DD:forceGDD