

Image restoration and segmentation using the Ambrosio-Tortorelli functional and discrete calculus

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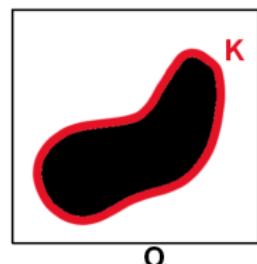
Mumford-Shah functional

[Mumford and Shah, 1989]

We minimize :

$$\mathcal{MS}(K, u) = \underbrace{\int_{\Omega \setminus K} |u - g|^2 \, dx}_{\text{fidelity term}} + \alpha \underbrace{\int_{\Omega \setminus K} |\nabla u|^2 \, dx}_{\text{smoothness term}} + \lambda \underbrace{\mathcal{H}^1(K \cap \Omega)}_{\text{discontinuities length}}$$

- Ω the image domain
- g the input image
- u a piecewise smooth approximation of g
- K the discontinuities set
- \mathcal{H}^1 the Hausdorff measure



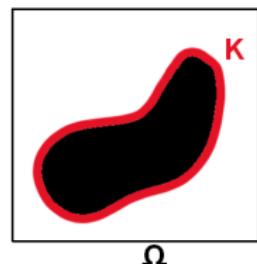
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Ambrosio-Tortorelli functional

[Ambrosio and Tortorelli, 1992]

$$AT_\varepsilon(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla v|^2 + \frac{1}{\varepsilon} \frac{(1-v)^2}{4} \, dx$$

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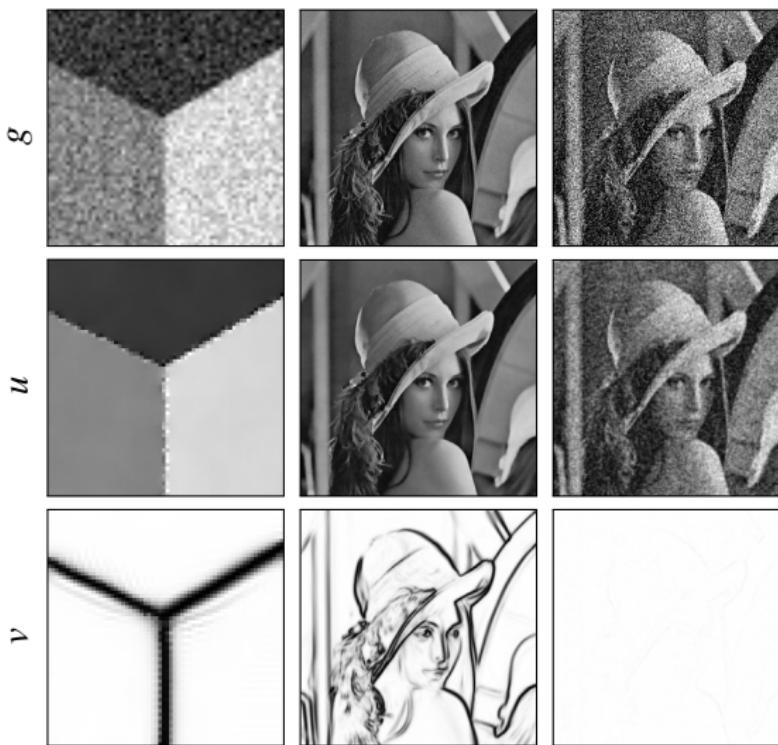
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$$AT_\varepsilon(u, v) \xrightarrow{\Gamma} \mathcal{MS}$$

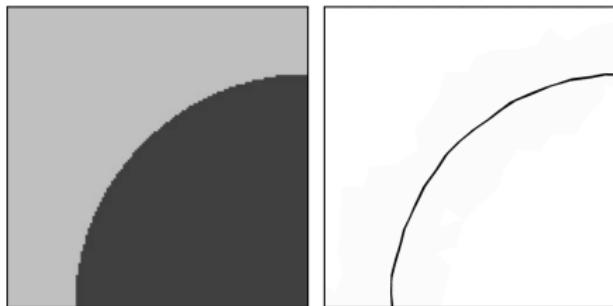


Finite differences implementation



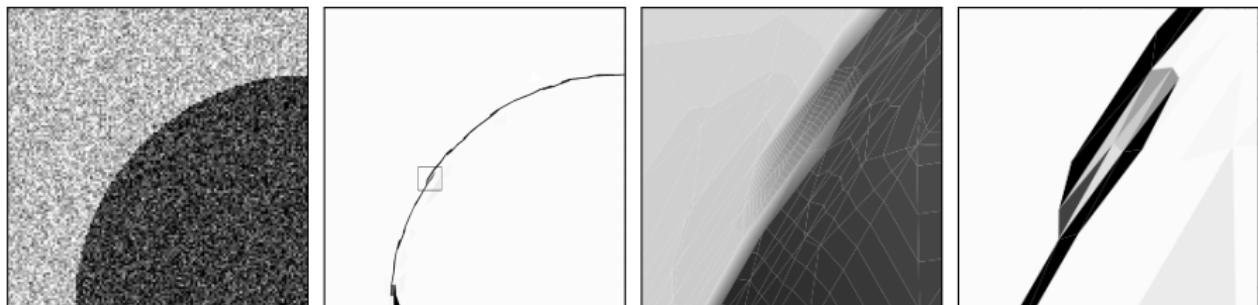
Finite elements implementation

- ▷ Proposed in [Bourdin and Chambolle, 2000]



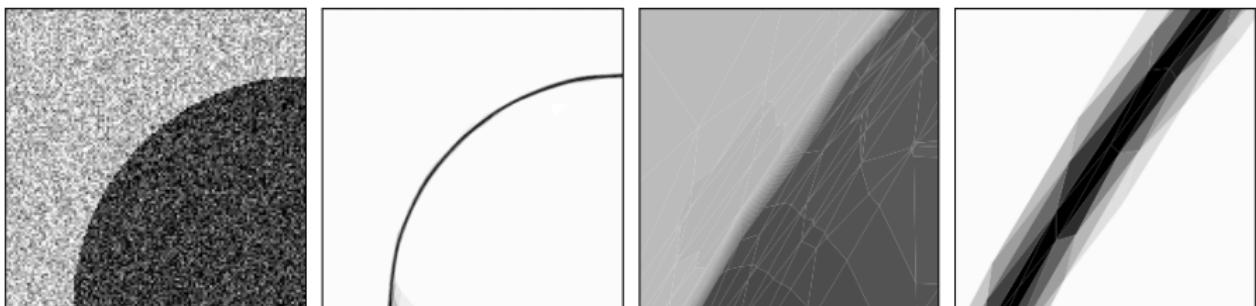
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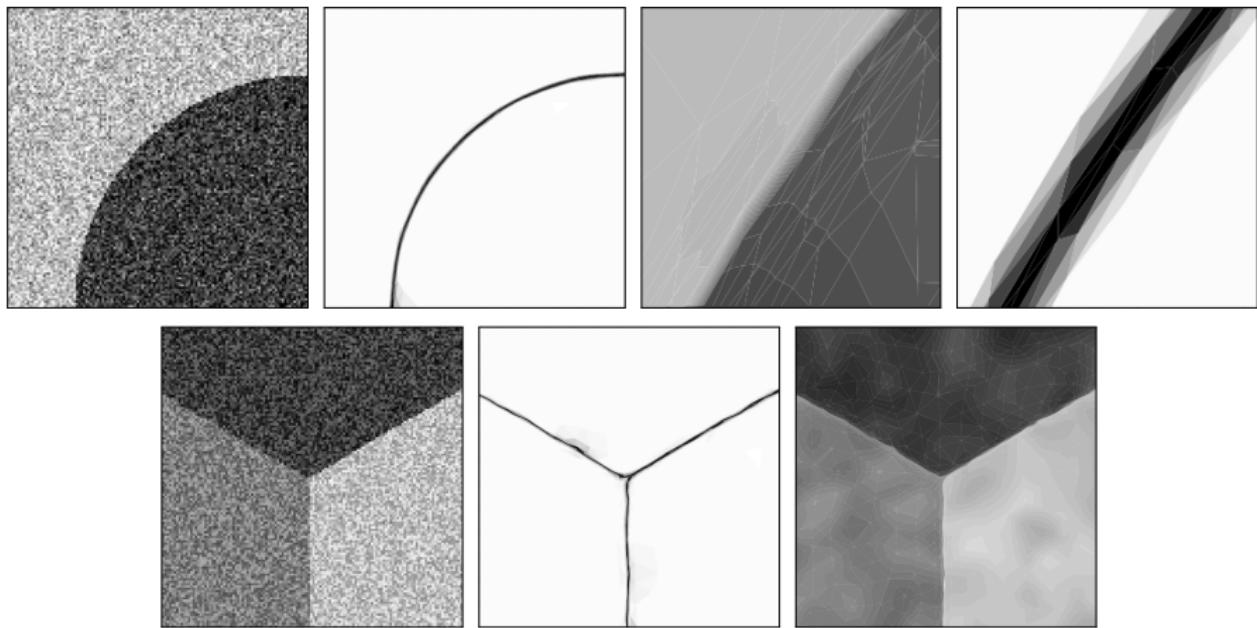
Finite elements implementation

- ▷ Proposed in [Bourdin and Chambolle, 2000]
- ▷ Finite elements with mesh **refinement** and **realignment**



Finite elements implementation

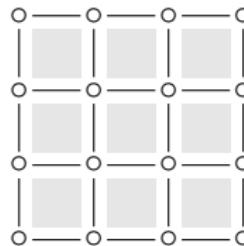
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Discrete Calculus

Cell complex

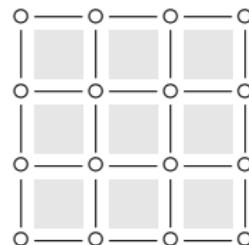
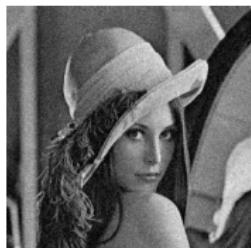
- We decompose the image domain into a cell complexe
 - ▷ faces : pixels
 - ▷ edges : sides shared by 2 pixels
 - ▷ vertices : vertices shared by 4 pixels



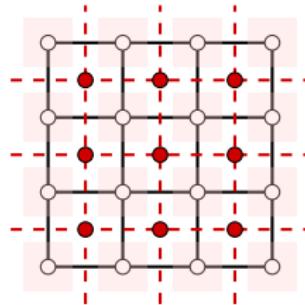
Discrete Calculus

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 - ▷ faces : pixels
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 - ▷ vertices : vertices shared by 4 pixels
- Dual complex :
 - ▷ dual vertices : centers of primal faces
 - ▷ dual edges : edges orthogonal to primal edges
 - ▷ dual faces : delineated by dual vertices and edges



primal



dual

Discrete Calculus

Discrete operators

- **Discrete k -form** associates a scalar to a k -dimensional cell (represented by column vectors)

primal

dual



[Grady and Polimeni, 2010]

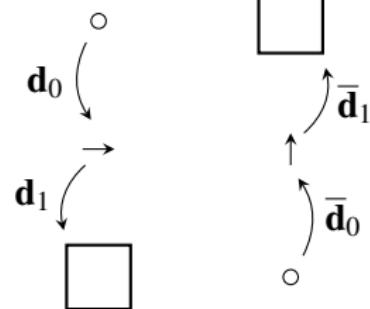
Discrete Calculus

Discrete operators

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- **Derivative operators \mathbf{d}_k** are the oriented k -cells to $(k+1)$ -cells incidence matrix

primal

dual

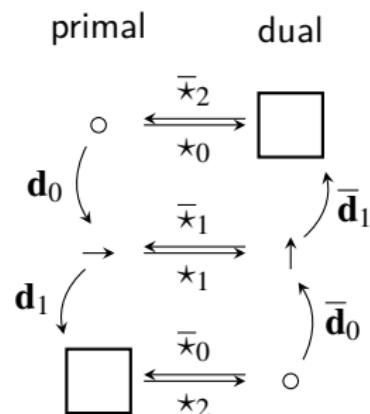


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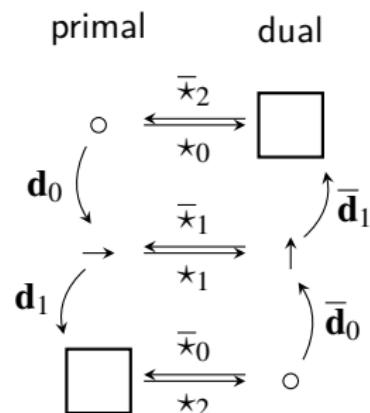


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Discrete Calculus

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- **Discrete Hodge star operators \star_k** send k -forms of the primal complex onto $(n-k)$ -forms of the dual complex
- **$\mathbf{M}_{01} = \frac{1}{2}|\mathbf{d}_0|$** transforms a 0-form into a 1-form by averaging the values on the two edge extremities
- **"Edge Laplacian"** : $\bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 \mathbf{d}_1 + \mathbf{d}_0 \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1$

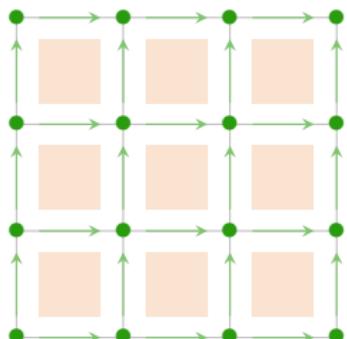


[Grady and Polimeni, 2010]

Discrete formulation of AT

On faces and vertices

$$AT_\varepsilon(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla v|^2 + \frac{1}{\varepsilon} \frac{(1-v)^2}{4} \, dx$$



We choose :

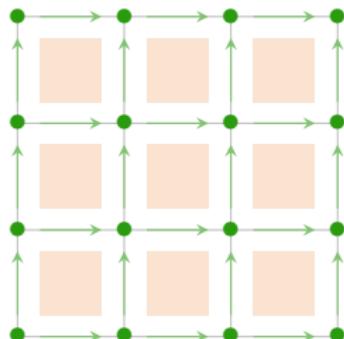
- u, g to live on faces
 - ▷ u, g are 2-forms
- v to live on vertices
 - ▷ v is a 0-form



Discrete formulation of AT

On faces and vertices

$$AT_\varepsilon(u, v) = \alpha \int_{\Omega} |u - g|^2 \, dx + \int_{\Omega} v^2 |\nabla_2 u|^2 \, dx + \lambda \int_{\Omega} \varepsilon |\nabla_0 v|^2 + \frac{1}{\varepsilon} \frac{(1-v)^2}{4} \, dx$$



We choose :

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 - ▷ u, g are 2-forms
- v to live on vertices
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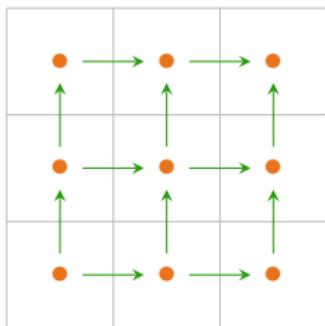


$$\begin{aligned} AT_\varepsilon^{2,0}(u, v) &= \alpha \langle u - g, u - g \rangle_2 + \langle \mathbf{M}_{01} v \wedge \bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 u, \mathbf{M}_{01} v \wedge \bar{\star}_1 \bar{\mathbf{d}}_0 \star_2 u \rangle_1 \\ &\quad + \lambda \varepsilon \langle \mathbf{d}_0 v, \mathbf{d}_0 v \rangle_1 + \frac{\lambda}{4\varepsilon} \langle 1 - v, 1 - v \rangle_0 \end{aligned}$$

Discrete formulation of AT

On vertices and edges

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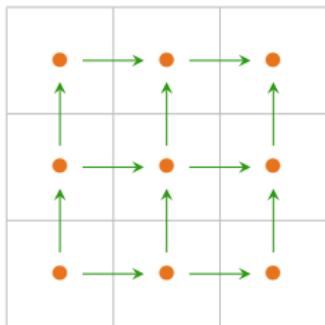
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- u, g to live on vertices •
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▷ v is a 1-form

Discrete formulation of AT

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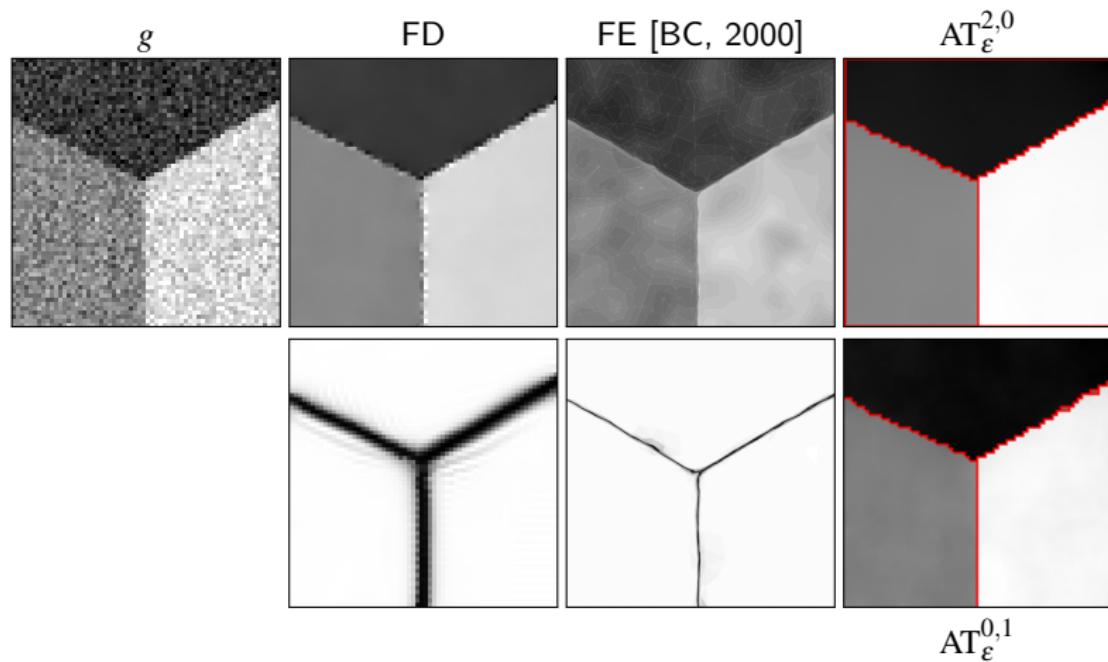


We choose :

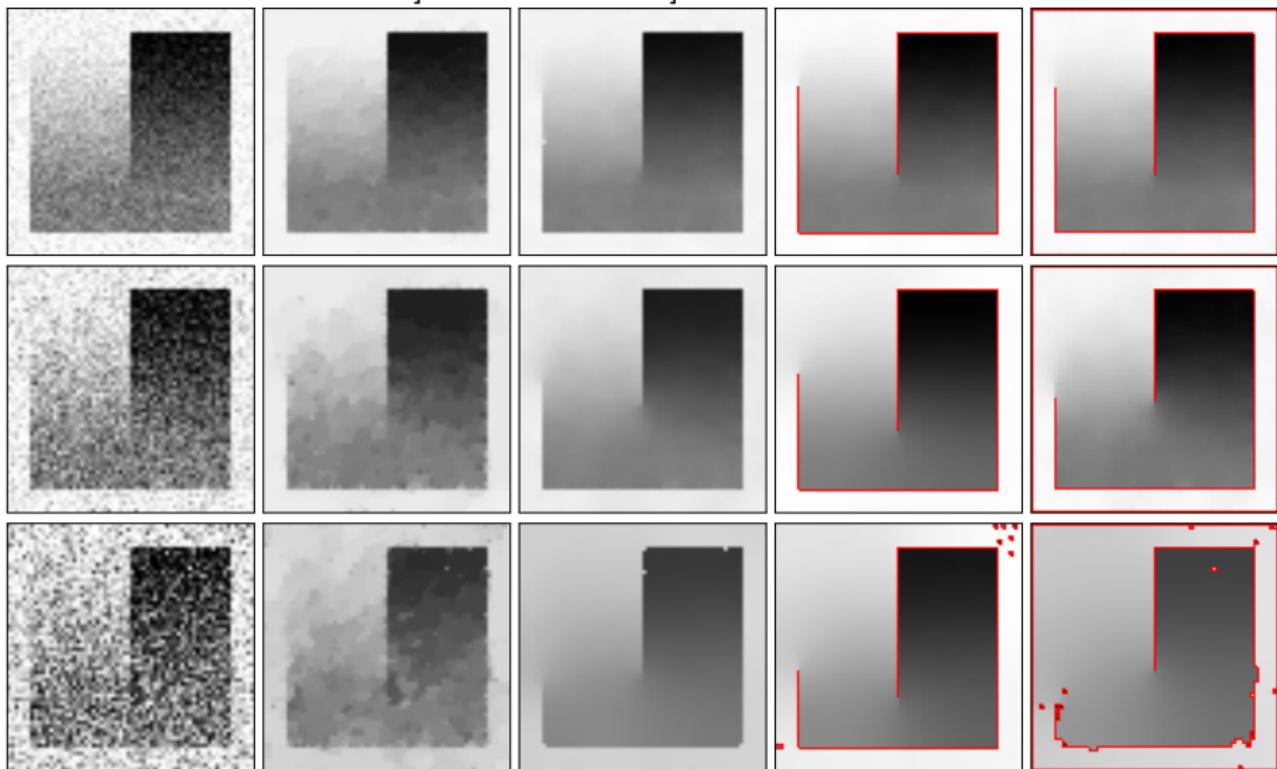
- u, g to live on vertices •
▷ u, g are 0-forms
- v to live on edges →
▷ v is a 1-form

$$\begin{aligned} AT_{\varepsilon}^{0,1}(u, v) &= \alpha \langle u - g, u - g \rangle_0 + \langle v \wedge \mathbf{d}_0 u, v \wedge \mathbf{d}_0 u \rangle_1 \\ &+ \lambda \varepsilon \langle (\mathbf{d}_1 + \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1) v, (\mathbf{d}_1 + \bar{\star}_2 \bar{\mathbf{d}}_1 \star_1) v \rangle_2 + \frac{\lambda}{4\varepsilon} \langle 1 - v, 1 - v \rangle_1 \end{aligned}$$

Numerical results



Numerical results

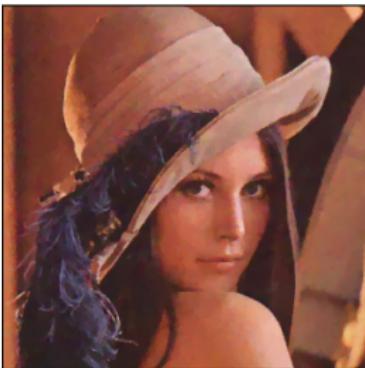
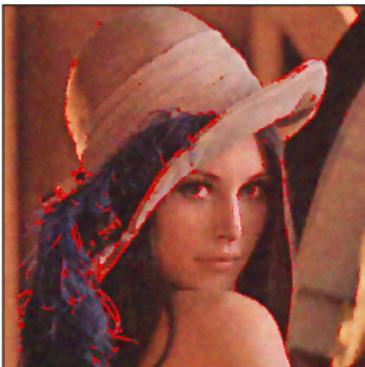
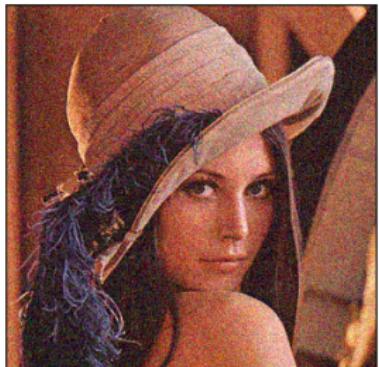
 g TV [Duran et al.,
2013][Strek. et al.,
2014] $AT_{\varepsilon}^{0,1}$ $AT_{\varepsilon}^{2,0}$ 

Numerical results

 g (PSNR = 26.1 dB) u (PSNR = 29.9 dB) $\text{AT}_\varepsilon^{2,0}$  $\text{AT}_\varepsilon^{0,1}$

Numerical results

TV

 u (PSNR = 29.36 dB) $\Delta T_\varepsilon^{2,0}$  u (PSNR = 29.03 dB)

 g (PSNR = 20.83 dB) u (PSNR = 27.29 dB)

Conclusion

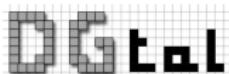
- Standard discretization schemes, such as finite differences or finite elements, lead to numerical difficulties
- Discrete calculus enables to reconstruct 1D contours and smooth regions

Conclusion

- Standard discretization schemes, such as finite differences or finite elements, lead to numerical difficulties
- Discrete calculus enables to reconstruct 1D contours and smooth regions

Perspectives

- Add anisotropy
- Work on non-image data
- Other applications : deblurring, tomography, 3D surface reconstruction, ...



Digital Geometry Tools and Algorithms - <http://dgtal.org>

Références I

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-  Bourdin, B. and Chambolle, A. (2000). Implementation of an adaptive finite-element approximation of the mumford-shah functional. *Numerische Mathematik*, 85(4) :609–646.
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