

Simulating quantum circuits with non-Clifford noise

Brandin Farris, Daley McMahon, Jad Soucar, Peter Ye

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Institute for Pure and Applied Mathematics
& NASA Ames Research Center

Industry Mentors: Dr. Namit Anand, Dr. Jeffrey Marshall
Academic Mentor: Zhuoyang Ye

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Background

What is a quantum computer?

Input State

$$|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$$

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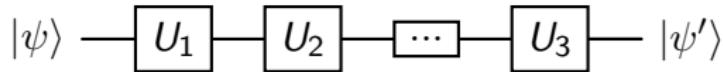
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The problem with classical simulations of quantum circuits

$$|\psi\rangle = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$$

$$|\psi\rangle \otimes |\phi\rangle = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_4 \end{bmatrix}$$

$$|\psi\rangle \otimes |\phi\rangle \otimes |\lambda\rangle = \begin{bmatrix} \alpha_1 \\ \vdots \\ \vdots \\ \alpha_8 \end{bmatrix}$$

- State grows exponentially, 2^n for n qubits.
- The current state of the art allows for the classical simulation of a 54-qubit system (Pednault et al 2019)

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$$C_i \in \mathcal{C} := \langle CX = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}, H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}, P = \begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix} \rangle$$

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$$|s_i\rangle \in \mathcal{S} := \{s \mid \exists C_i \in \mathcal{C} \text{ s.t } s = C_i |0\rangle\}$$

The Noise Problem

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Simulate a Noise Channel

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K_i is Non-Unitary!

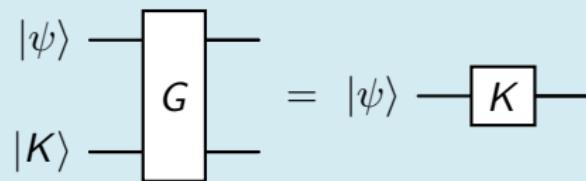
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Resource States & Gadgets



$$\text{s.t } G \in \mathcal{C} \text{ & } |K\rangle \in \mathcal{S}$$

K-Gadget

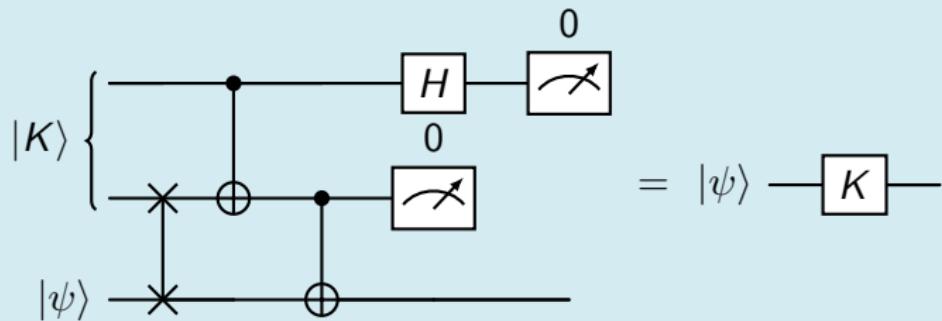
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$$\mathsf{K} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mapsto (a \quad c \quad b \quad d)$$

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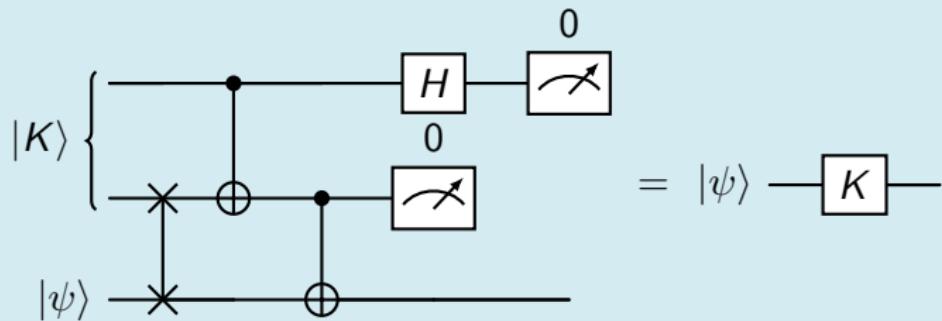
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$$|K\rangle = \sum_{i=1}^4 c_i |s_i\rangle, \quad |s_i\rangle \in \mathcal{S} \implies 4^c \# \text{ of states}$$

Rank 4 K-Gadget

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$$\begin{array}{ccccc} \psi \text{ ---} & \psi \text{ ---} & \psi \text{ ---} & \psi \text{ ---} & \psi \text{ ---} \\ s_1 \left\{ \begin{array}{c} \text{---} \\ \text{---} \end{array} \right. + s_2 \left\{ \begin{array}{c} \text{---} \\ \text{---} \end{array} \right. + s_3 \left\{ \begin{array}{c} \text{---} \\ \text{---} \end{array} \right. + s_4 \left\{ \begin{array}{c} \text{---} \\ \text{---} \end{array} \right. = K \left\{ \begin{array}{c} \text{---} \\ \text{---} \end{array} \right. \end{array}$$

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Theorem - Extent Bound on Kraus Resource State

Given an arbitrary contraction operator $K \in \mathbb{R}^{2 \times 2}$, the associated column-wise flattened vector has stabilizer decomposition

$$|K\rangle = \sum_i^r c_i |s_i\rangle, \quad |s_i\rangle \in \mathcal{S} \text{ such that}$$

$$\sum_i^r |c_i| \leq 1.268$$

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The small extent and numerical simulations indicate that most Kraus operators can be reasonably represented by a **rank 2** stabilizer decomposition!

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$$|K\rangle = \sum^2 c_i |s_i\rangle$$

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K-gadget Compression

So we choose 2 stabilizer states $|\tilde{0}\rangle$ and $|\tilde{1}\rangle$ to serve as our basis

$$|K\rangle = \left(\frac{|\tilde{0}\rangle + \alpha |\tilde{1}\rangle}{\beta} \right)$$

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$$|K\rangle^{\otimes c} = \left(\frac{|\tilde{0}\rangle + \alpha |\tilde{1}\rangle}{\beta} \right)^{\otimes c} = \frac{1}{\sqrt{K(\mathbb{F}_2^c)}} \sum_{x \in \mathbb{F}_2^c} \alpha^{|x|} |\tilde{x}_1 \tilde{x}_2 \dots \tilde{x}_t\rangle$$

$$K(\mathcal{L}) = \sum_{x,y \in \mathcal{L}} \nu^{|x+y|} \alpha^{|x|+|y|}, \text{ with } \nu = \langle \tilde{0} | \tilde{1} \rangle$$

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$$|K^{\otimes c}\rangle \approx |\mathcal{L}\rangle = \frac{1}{\sqrt{K(\mathcal{L})}} \sum_{x \in \mathcal{L}} \alpha^{|x|} |\tilde{x}_1 \tilde{x}_2 \dots \tilde{x}_t\rangle$$

Approximation Error

$$\delta(\mathcal{L}) = 1 - |\langle K^{\otimes c} | \mathcal{L} \rangle|^2$$

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Outstanding Questions

- How do we choose $|\tilde{0}\rangle$ and $|\tilde{1}\rangle$?

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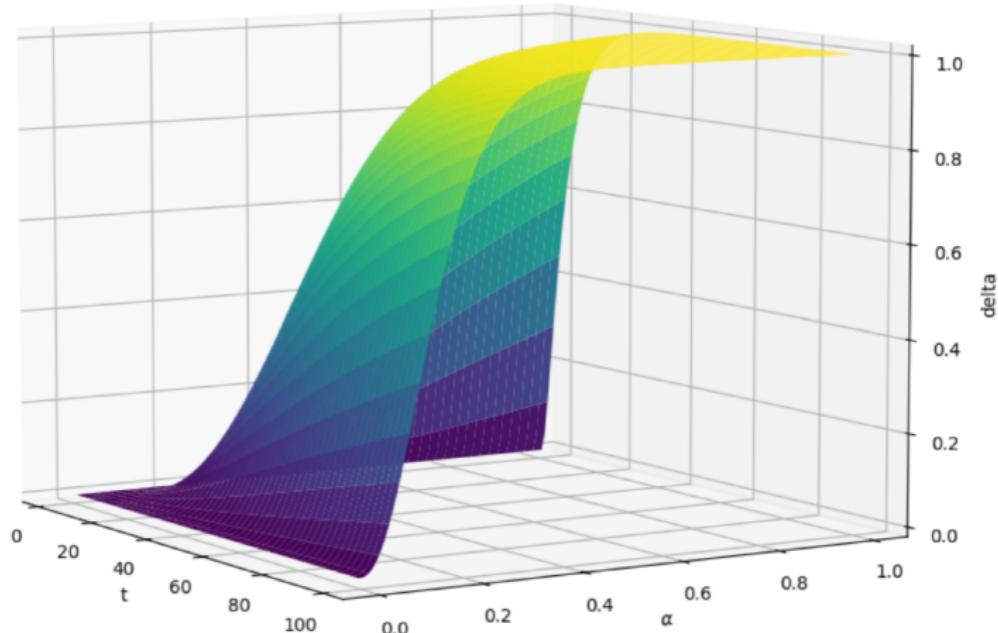
Such that the elements of \mathcal{L} have small hamming weights

Choose \mathcal{L} to be the basis of \mathbb{F}_2^c

$$\mathcal{L} = \mathcal{B}_2^c \cup \vec{0}$$

Approximation Error

Using a Basis Compression



Approximation Error

α	$\delta = .0001$	$\delta = .001$	$\delta = .01$
$\alpha = .0001$	37782	225963	2038344
$\alpha = .0005$	3011	12167	85849
$\alpha = .001$	1075	3783	22714
$\alpha = .005$	107	302	1227
$\alpha = .01$	41	108	383
$\alpha = .05$	5	11	31
$\alpha = .1$	2	4	12

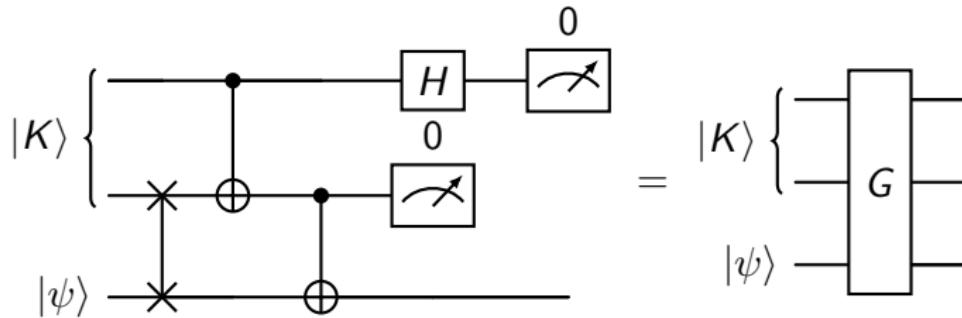
Table: Maximum t with $\nu = \frac{1}{\sqrt{2}}$

Summary

- ① Map K to a resource state $|K\rangle$
- ② Find stabilizer states that minimize α
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Example - Amplitude Dampening

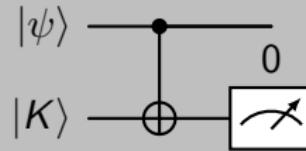
$$\xi_{AD} = \left\{ K_1 = \begin{bmatrix} 1 & 0 \\ 0 & \sqrt{1-p} \end{bmatrix}, K_2 = \begin{bmatrix} 0 & \sqrt{p} \\ 0 & 0 \end{bmatrix} \right\}$$

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$$K_1 \mapsto |K_1\rangle = (1 \quad \sqrt{1-p}) ,$$

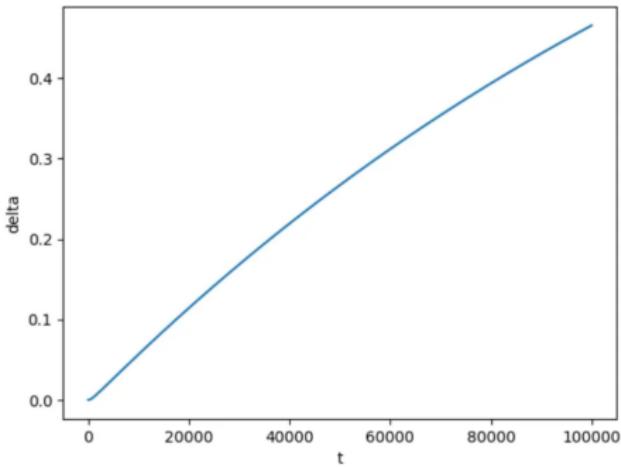


Simulations pt 3.

$$|K_1\rangle = \frac{|+\rangle + \alpha|0\rangle}{\beta}, \quad \alpha = \frac{1 - \sqrt{1-p}}{\sqrt{2(1-p)}}, \quad \beta = \sqrt{2(1-p)}$$

Choose \mathcal{L} to be the basis of \mathbb{F}_2^c

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Figure: $p = .01$

α	$\delta = .0001$	$\delta = .001$	$\delta = .01$
$\alpha = .003562$	173	505	2215

We can simulate 2215 applications of amplitude dampening within 99% fidelity using only 1.4GB of memory!

Acknowledgements



- ➊ We'd like to thank IPAM and the IPAM staff for hosting us this summer.
- ➋ NASA Ames Research Center for allowing us to visit their facility in Mountain View, CA.

Questions!