

Math 415. Exam 1. September 28, 2017

Full Name: _____

Net ID: _____

Discussion Section: _____

- There are 18 problems worth 5 points each.
 - You must not communicate with other students.
 - No books, notes, calculators, or electronic devices allowed.
 - This is a 70 minute exam.
 - Do not turn this page until instructed to.
 - Fill in the answers on the scantron form provided. Also circle your answers on the exam itself.
 - Hand in both the exam and the scantron.
 - On the scantron make sure you bubble in **your name, your UIN and your NetID**.
 - There are several different versions of this exam.
 - Please double check that you correctly bubbled in your answer on the scantron. It is the answer on the scantron that counts!
 - Good luck!
-

Fill in the following information on the scantron form:

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95. D

96. C

1. (5 points) Consider the following multiplication of two 3×3 -matrices, where the question marks represent unknown coefficients:

$$\begin{bmatrix} 9 & 8 & 6 \\ ? & 9 & ? \\ ? & 3 & 1 \end{bmatrix} \begin{bmatrix} 8 & 1 & 4 \\ 2 & ? & ? \\ 3 & 3 & ? \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix}.$$

With the information given, only one coefficient in the matrix on the right hand side can be calculated. Which one is it?

- (A) $\star c_{11}$
 - (B) c_{31}
 - (C) c_{21}
 - (D) c_{12}
 - (E) None of the other answers.
-

Solution. Only the first row of the first matrix and the first column of the second matrix are fully determined. Thus we can only compute c_{11} , which is $9 \cdot 8 + 8 \cdot 2 + 6 \cdot 3$.

2. (5 points) Let \mathbf{a}, \mathbf{b} be non-zero vectors in \mathbb{R}^3 , where \mathbf{a} is not a scalar multiple of \mathbf{b} . Which of the following is a description of the set $\text{span}(\mathbf{a}, \mathbf{b})$?

- (A) It is \mathbb{R}^2 .
 - (B) It is a line in \mathbb{R}^3 through the origin.
 - (C) It is the union of two lines in \mathbb{R}^3 .
 - (D) ★ It is a plane in \mathbb{R}^3 through the origin.
 - (E) None of the other answers.
-

Solution. If the two vectors are not scalar multiples of each other, \mathbf{b} is not in the line spanned by \mathbf{a} in \mathbb{R}^3 . So the two vectors span a subspace which is a plane (2-dimensional)

and the origin is a point on that plane, because $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ is a scalar multiple of either vector.

Note that while $\text{span}(\mathbf{a}, \mathbf{b})$ is 2-dimensional, it is not \mathbb{R}^2 . Because vectors in \mathbb{R}^2 have just two entries, but vectors in $\text{span}(\mathbf{a}, \mathbf{b})$ have three entries.

3. (5 points) Let $\mathbf{a}_1, \mathbf{a}_2$ and \mathbf{b} be three vectors in \mathbb{R}^3 and suppose \mathbf{b} is in $\text{span}(\mathbf{a}_1, \mathbf{a}_2)$. Consider the matrix $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{b}]$, that is the matrix whose first column is \mathbf{a}_1 , whose second column is \mathbf{a}_2 and whose third column is \mathbf{b} . Which of the following statements is true?

(A) A is row equivalent to $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

(B) None of the other answers.

(C) $\star A$ has at most 2 pivots.

(D) A is invertible.

Solution. In order for \mathbf{b} to be in $\text{span}(\mathbf{a}_1, \mathbf{a}_2)$, the linear system with the augmented matrix $[\mathbf{a}_1 \ \mathbf{a}_2 \ | \ \mathbf{b}]$ has to be consistent. Thus $[\mathbf{a}_1 \ \mathbf{a}_2 \ | \ \mathbf{b}]$ can not have 3 pivots. Thus A can not have three pivots.

4. (5 points) For which values of b is the matrix $\begin{bmatrix} 1 & b \\ 2 & 2b \end{bmatrix}$ invertible?

- (A) For any number b different from 1.
 - (B) ★ For no number b .
 - (C) None of the other answers.
 - (D) For any number b .
 - (E) For any number b different from 0.
-

Solution. This matrix is not invertible for any choice of b , as $1 * 2b - b * 2 = 0$.

5. (5 points) Let A be a 3×3 matrix and $\mathbf{b} \in \mathbb{R}^3$. Consider the following statements:

I. The row reduced echelon form of A is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

II. If the linear system $A\mathbf{x} = \mathbf{b}$ has a solution, then it has a unique solution.

Which one of these statements is always true?

- (A) Statement I only.
 - (B) Statement II only.
 - (C) Statement I and Statement II.
 - (D) ★ Neither of Statements I or II.
-

Solution. We do not know how many pivots the matrix A has. Both of these statements are true only when the matrix A has exactly 3 pivots.

6. (5 points) Let

$$\mathbf{w} = \begin{bmatrix} 1 \\ h \\ h \end{bmatrix}, \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

For which values of h is \mathbf{w} a linear combination of \mathbf{v}_1 and \mathbf{v}_2 ?

- (A) Only when $h = -1$.
 - (B) ★ Only when $h = 1$.
 - (C) For no value of h .
 - (D) None of the other answers.
-

Solution. We have to determine when the following system of equations is consistent:

$$\left[\begin{array}{cc|c} 1 & 1 & 1 \\ 1 & 2 & h \\ 1 & 3 & h \end{array} \right] \xrightarrow{R2 \rightarrow R2 - R1} \left[\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & h-1 \\ 1 & 3 & h \end{array} \right] \xrightarrow{R3 \rightarrow R3 - R1} \left[\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & h-1 \\ 0 & 2 & h-1 \end{array} \right]$$
$$\xrightarrow{R3 \rightarrow R3 - 2R2} \left[\begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & h-1 \\ 0 & 0 & -h+1 \end{array} \right]$$

The system is consistent if and only if $-h + 1 = 0$, i.e., $h = 1$.

7. (5 points) The matrix $A = \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix}$ is reduced to the identity matrix $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ using the following row operations (in the given order):

- (1) $R_2 \leftrightarrow R_4$.
- (2) $R_2 \rightarrow R_2 + 2R_1$,

What is A^{-1} ?

(A) $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{bmatrix}$

(B) $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ -2 & 1 & 0 & 0 \end{bmatrix}$

(C) ★ $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$

(D) None of the other answers.

(E) $\begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$

Solution. Let $E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ be the elementary matrix corresponding to $R2 \rightarrow R2+2R1$, and $E_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$ be the elementary matrix corresponding to $R2 \leftrightarrow R4$.

Then $E_2E_1A = I$. Thus E_2E_1 is the inverse of A . Thus

$$A^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

8. (5 points) Let $A = \begin{bmatrix} 1 & -1 & 3 & 4 \\ 0 & 2 & -2 & 1 \\ 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 5 \end{bmatrix}$. Which one of the following statements is true?

- (A) ★ There is $\mathbf{b} \in \mathbb{R}^4$ such that $A\mathbf{x} = \mathbf{b}$ is inconsistent.
 - (B) A is invertible.
 - (C) None of the other answers.
 - (D) $A\mathbf{x} = \mathbf{0}$ has exactly one solution.
 - (E) A does not have an LU decomposition.
-

Solution. Since an echelon form of A is $\begin{bmatrix} 1 & -1 & 3 & 4 \\ 0 & 2 & -2 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ there are free variables, thus

the system $A\mathbf{x} = \mathbf{b}$ cannot have only one solution. The vector $\mathbf{b} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -1 \end{bmatrix}$ makes the system inconsistent. Since the number of pivots is strictly less than 4, A is noninvertible. Since A is upper triangular $A = IA$ is a valid LU decomposition.

9. (5 points) Let A be an $m \times n$ matrix. Which one of the following statements is true?

- (A) ★ $A^T A$ is an $n \times n$ matrix.
 - (B) $A^T A$ is an $m \times n$ matrix.
 - (C) $A^T A$ is an $m \times m$ matrix.
 - (D) $A^T A$ is an $n \times m$ matrix.
 - (E) None of the other answers.
-

Solution. Since A^T is an $n \times m$ matrix and A is an $m \times n$ matrix , we know that $A^T A$ is an $n \times n$ matrix.

10. (5 points) Which of the following vectors does NOT belong to the set

$$\text{span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ 6 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 8 \\ 12 \\ 0 \end{bmatrix} \right) ?$$

(A) $\begin{bmatrix} 3 \\ 6 \\ 9 \\ 0 \end{bmatrix}$

(B) $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

(C) $\begin{bmatrix} 11 \\ 22 \\ 33 \\ 0 \end{bmatrix}$

(D) $\begin{bmatrix} 2 \\ 4 \\ 6 \\ 0 \end{bmatrix}$

(E) ★ $\begin{bmatrix} 5 \\ 10 \\ 20 \\ 0 \end{bmatrix}$

Solution. $\text{span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ 6 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 8 \\ 12 \\ 0 \end{bmatrix} \right) = \text{span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix} \right)$, so each vector in the set must be a scalar multiple of $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}$. Of the choices, only $\begin{bmatrix} 5 \\ 10 \\ 20 \\ 0 \end{bmatrix}$ is not.

11. (5 points) Which one of the following statements is FALSE?
- (A) If a system of linear equations has two different solutions, it must have infinitely many solutions.
 - (B) If A is invertible, the equation $A\mathbf{x} = \mathbf{b}$ has exactly one solution.
 - (C) Every matrix is row equivalent to a unique matrix in reduced row echelon form.
 - (D) ★ Every system of n linear equations in n variables has exactly one solution.
-

Solution. For a matrix A , its reduced echelon form is unique, so this option is true. There are $n \times n$ inconsistent linear systems, so this option is also false. The possibilities for a system of linear equations are “no solutions”, “exactly one solution” and “infinitely many solutions”. Thus if a system has at least 2 solutions, then it must in fact have infinitely many solutions, so this option is true. If A is invertible, the solution is unique and given by $\mathbf{x} = A^{-1}\mathbf{b}$, so this option is also true.

12. (5 points) Let $A = [\mathbf{a}_1 \ \mathbf{a}_2]$ be a 3×2 matrix and suppose that

$$A\mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \text{for } \mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \text{and } A\mathbf{y} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \text{for } \mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Then the following holds:

(A)

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = 1\mathbf{a}_1 + 1\mathbf{a}_2, \quad \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1\mathbf{a}_1 + 2\mathbf{a}_2$$

(B) None of the other answers.

(C) ★

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \mathbf{a}_1 + \mathbf{a}_2, \quad \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \mathbf{a}_1 + 2\mathbf{a}_2$$

(D)

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \mathbf{a}_1 + 2\mathbf{a}_2, \quad \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \mathbf{a}_1 + \mathbf{a}_2$$

(E)

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \mathbf{a}_1 + 0\mathbf{a}_2 + 3\mathbf{a}_3, \quad \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1\mathbf{a}_1 + 1\mathbf{a}_2 + 1\mathbf{a}_3$$

Solution. Matrix Multiplication is linear combination, so $A\mathbf{x} = x_1\mathbf{a}_1 + x_2\mathbf{a}_2$ for a 3×2 matrix.

13. (5 points) Let P be the 4×4 -permutation matrix that permutes the second row and the third row. Which of the following statements is true?

$$(A) P^7 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ and } (P^{-1})^9 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

$$(B) P^7 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ and } (P^{-1})^9 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

$$(C) P^7 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ and } (P^{-1})^9 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

(D) None of the other answers.

$$(E) \star P^7 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ and } (P^{-1})^9 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Solution. From class we know that $P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ and $P^{-1} = P$. Observe that $P^n = I_4$ whenever n is even, and $P^n = P$ whenever n is odd. Thus $P^7 = P$ and $(P^{-1})^9 = P^9 = P$.

14. (5 points) Find an explicit description of the null space of

$$A = \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

that is, find a minimal set of vectors $\mathbf{v}_1, \dots, \mathbf{v}_p$ such that $\text{Nul}(A) = \text{span}(\mathbf{v}_1, \dots, \mathbf{v}_p)$.

(A) None of the other answers.

(B) ★ $\begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}$

(C) $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$

(D) $\begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$

(E) $\begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}.$

Solution. $\text{Nul}(A)$ is the set of all solutions to the homogeneous equation

$$\begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

We identify x_1 , x_2 and x_4 as pivot variables and x_3 as the free variable. Thus we can write the general solution as

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_3 \\ -2x_3 \\ x_3 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}.$$

where $x_3 \in \mathbb{R}$ is free. We conclude that

$$\text{Nul}(A) = \text{span} \left(\begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} \right).$$

15. (5 points) Consider the following subsets of \mathbb{R}^2 :

$$W_1 = \left\{ \begin{bmatrix} a \\ a \end{bmatrix} : a \in \mathbb{R} \right\}, \quad W_2 = \left\{ \begin{bmatrix} a \\ b \end{bmatrix} : ab = 1 \right\}.$$

Then:

- (A) ★ Only W_1 is a subspace of \mathbb{R}^2 .
 - (B) Only W_2 is a subspace of \mathbb{R}^2 .
 - (C) Neither W_1 nor W_2 is a subspace of \mathbb{R}^2 .
 - (D) Both W_1 and W_2 are subspaces of \mathbb{R}^2 .
-

Solution. W_1 is a subspace, because $W_1 = \text{span}\left\{\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\}$. The second subset W_2 is not a subspace. Simply observe that the $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ is not in W_2 .

16. (5 points) Consider the following matrix

$$\begin{bmatrix} 1 & 1 & -1 & 0 \\ -2 & -2 & 2 & 0 \\ 2 & 2 & -2 & 0 \end{bmatrix}.$$

What is the number of pivot positions of this matrix?

- (A) 3
 - (B) 0
 - (C) None of the other answers.
 - (D) ★ 1
 - (E) 2
-

Solution.

$$A = \begin{bmatrix} 1 & 1 & -1 & 0 \\ -2 & -2 & 2 & 0 \\ 2 & 2 & -2 & 0 \end{bmatrix} \xrightarrow{R2 \rightarrow R2 + 2R1} \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 2 & 2 & -2 & 0 \end{bmatrix} \xrightarrow{R3 \rightarrow R3 - 2R1} \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

One pivot!

17. (5 points) Let

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 1 \\ 3 & 2 & 1 \end{bmatrix}.$$

Which of the following is the matrix L in an LU factorization of A ?

(A) $\star L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}.$

(B) $L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 1 & 1 \end{bmatrix}.$

(C) $L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix}.$

(D) $L = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & -1 & 1 \end{bmatrix}.$

(E) None of the other answers.

Solution.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 1 \\ 3 & 2 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 1 \\ 0 & -4 & -8 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 + R_2} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 1 \\ 0 & 0 & -1 \end{bmatrix},$$

where

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}, U = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 1 \\ 0 & 0 & -7 \end{bmatrix}, \text{ and } E_2 E_1 A = U$$

So

$$L = E_1^{-1} E_2^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}$$

18. (5 points) Let $D = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x^2 + y^2 \leq 1 \right\}$ denote the set of vectors in the unit disk of \mathbb{R}^2 . It can be shown that D is NOT a subspace of \mathbb{R}^2 . Which of the following tests does D fail to satisfy? (Select all that apply.)

- I. contains the zero vector
 - II. closed under vector addition
 - III. closed under scalar multiplication
- (A) III. only
(B) I., II., and III.
(C) II. only
(D) ★ II. and III. only
-

Solution. The zero vector $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ satisfies $0^2 + 0^2 \leq 1$. The vectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ each belong in D , but their sum $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ does not, as $1^2 + 1^2 > 1$. Finally, if we scale $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ by 2, then $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ does not belong in D since $2^2 + 0^2 > 1$.
