

Jade Wilkins  
112450816

## Homework 0

This report provides an outlook on using Matlab to explore color-based segmentation and the counting of objects. During the first assignment, I used functions such as `medfilt2` to take away noise on the image. In order to count the number of objects I utilized the image processing functions such as `im2bw` to create a B&W version of the original image and `bwlabel` to distinguish objects. I used LAB functions in combination with functions already mentioned in order to find objects based on color.

### 3.1 Denoise Image

The first thing I did to approach this assignment was to smooth out the image. I did this by first separating out the red, green, and blue color planes of the pin image. Then I applied `medfilt2` to each to each individual color plane. Then I compiled all the filtered image layers into a new image file “filtPins” (figure 1).



Figure 1

### 3.2 Finding the total number of colored objects

My approach to counting the total number of pins is based on the “*Color Segmentation with Live Image Acquisition*” video provide to us via piazza. First, I converted the filtered image of the pins into a doubly precise version of the image. Then I extracted the color threshold from each of the color layers. After that, I converted every color layer to B&W using `im2bw`. Then using `imcomplement`, I compiled all three layers together to make a complete B&W image of the pins (figure 2). Next, I used morphological operation `imfill` to fill in all the empty holes in the image (figure 3). Once that was complete, I used `bwlabel` to find all the individual objects in the image. Then I printed the number of pins by displaying the `numlabels` variable from the matrix provided by `bwlabel`. In addition, I placed a red box around all the pins using `regionprops` bounding box and the `rectangle` function (figure 4).

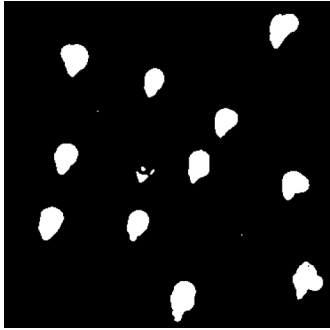


Figure 2

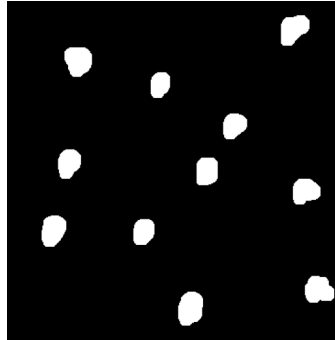


Figure 3

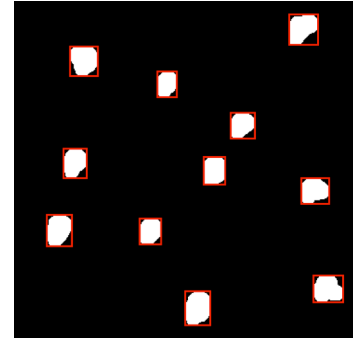


Figure 4

### 3.3 Finding Individual colored objects

My approach to finding individual colored objects is based on the “*Color Segmentation with Live Image Acquisition*” video provide to us via piazza. In order to compare the colors of the objects I first found the median color of all the pins. By constructing a for loop and finding the median color across all three-color planes. At the end of the loop I re concatenate all the color planes to see the median value of all the color pins (figure 5). Then I used `ginput(1)` in order to select the colored pin I would want to use to find pins of the same color. Then stored the color of the pin I had just selected. Next, I converted the RGB space to LAB color space using the `makecform` and `applycform` commands. Next I found similarly colored objects by finding the Euclidean distance between the color values using the hypotenuse formula. Then I stored information about the objects that were close in color into a separate variable (figure 6). Then I converted that variable into B&W in order to label all objects (figure 7). Then using `regionprops` with bounding box I created a for loop that placed colored boxed around each of the objects of matching color. I repeated this process three more times for the other colors (figure 8).



Figure 5



Figure 6

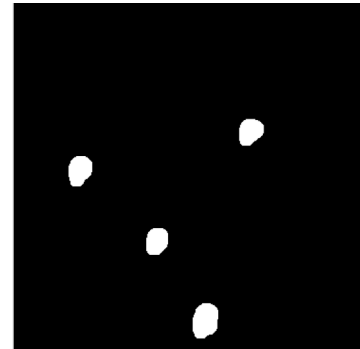


Figure 7

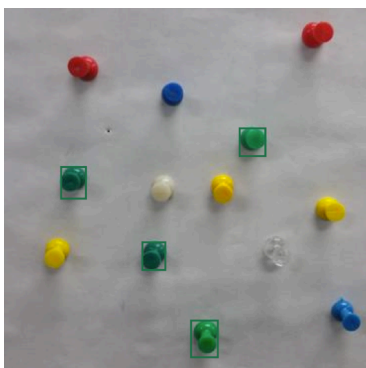


Figure 8

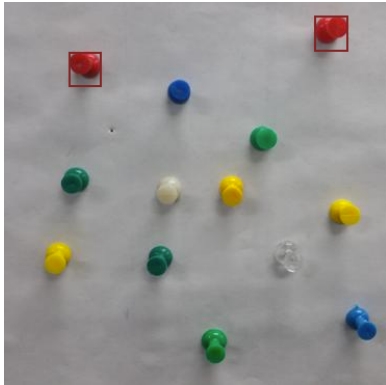


Figure 9

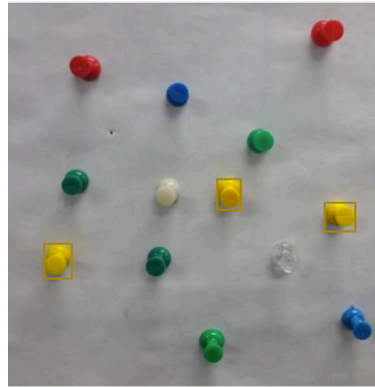


Figure 10

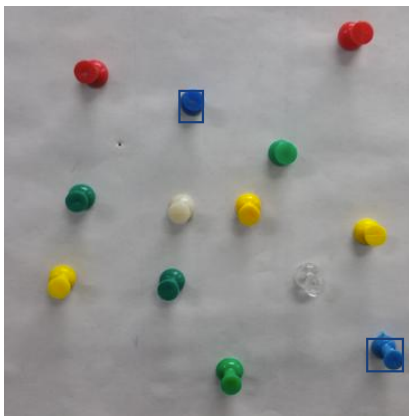


Figure 11