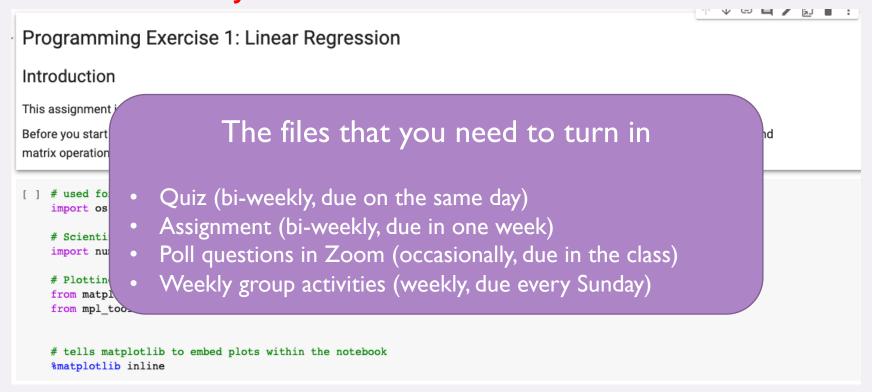
LECTURE 5

SPRING 2021
APPLIED MACHINE LEARNING
CIHANG XIE

EXERCISES

Google Colab Exercises (distributed during the lecture)

NO NEED TO SUBMIT! JUST TO HELP YOU UNDERSTAND LECTURE



GROUP ACTIVITIES

ALL groups have submitted the files

https://piazza.com/class/kmmw9butjod4ay?cid=13

- Please read notes & exercises from other groups
- Week 3 (lecture 4-5)



TODAY

- Review of Gradient Descent Algorithm
- Choosing Learning Rate lpha
- Basis Functions

LINEAR REGRESSION

GRADIENT DESCENT

- Initialize θ
- Repeat until convergence

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial Cost(\theta)}{\partial \theta_j}$$
 (simultaneous update for $\theta_0, \theta_1, \dots, \theta_d$)

• For linear regression:

$$\frac{\partial Cost(\theta)}{\partial \theta_j} = \frac{\partial}{\partial \theta_j} \frac{1}{2n} \sum_{i=1}^n \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

With
$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + ... + \theta_d x_d = \sum_{j=0}^{d} \theta_j x_j$$

GRADIENT DESCENT

$$\begin{split} \frac{\partial Cost(\theta)}{\partial \theta_j} &= \frac{\partial}{\partial \theta_j} \frac{1}{2n} \sum_{i=1}^n \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2 \\ &= \frac{1}{2n} \qquad \frac{\partial}{\partial \theta_j} \sum_{i=1}^n \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2 \qquad \text{Scalar multiple rule} \\ &= \frac{1}{2n} \sum_{i=1}^n \qquad \frac{\partial}{\partial \theta_j} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2 \qquad \text{Sum rule} \\ &= \frac{1}{2n} \sum_{i=1}^n \qquad 2 \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \quad \frac{\partial}{\partial \theta_j} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) \qquad \text{Power rule} \\ &= \frac{1}{n} \sum_{i=1}^n \left(\sum_{k=0}^d \theta_k x_k^{(i)} - y^{(i)} \right) \qquad \frac{\partial}{\partial \theta_j} \left(\sum_{k=0}^d \theta_k x_k^{(i)} - y^{(i)} \right) \\ &= \frac{1}{n} \sum_{i=1}^n \left(\sum_{k=0}^d \theta_k x_k^{(i)} - y^{(i)} \right) x_j^{(i)} \end{split}$$

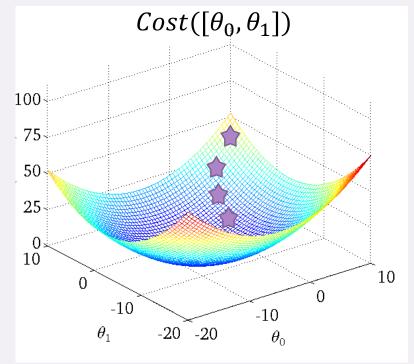
GRADIENT DESCENT

- Initialize θ
- Repeat until convergence

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial Cost(\theta)}{\partial \theta_i}$$

(simultaneous update for θ_0 , θ_1 , ..., θ_d)

IN-CLASS QUIZ - WHICH ONE IS CORRECT?



Left:

$$\begin{aligned} & \text{Temp0} \leftarrow \theta_0 - \alpha \frac{\partial Cost \left(\theta_0, \theta_1\right)}{\partial \theta_0} \\ & \text{Temp1} \leftarrow \theta_1 - \alpha \frac{\partial Cost \left(\theta_0, \theta_1\right)}{\partial \theta_1} \\ & \theta_0 \leftarrow \text{Temp0} \\ & \theta_1 \leftarrow \text{Temp1} \end{aligned}$$

Right:

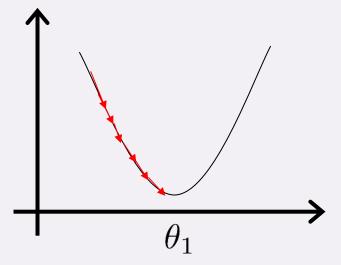
$$\begin{aligned} & \text{Temp0} \leftarrow \theta_0 - \alpha \frac{\partial Cost \ (\theta_0, \theta_1)}{\partial \theta_0} \\ & \theta_0 \leftarrow \text{Temp0} \\ & \text{Temp1} \leftarrow \theta_1 - \alpha \frac{\partial Cost \ (\theta_0, \theta_1)}{\partial \theta_1} \\ & \theta_1 \leftarrow \text{Temp1} \end{aligned}$$

CHOOSE α

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial Cost(\theta)}{\partial \theta_j}$$

(simultaneous update for θ_0 , θ_1 , ..., θ_d)

Learning rate



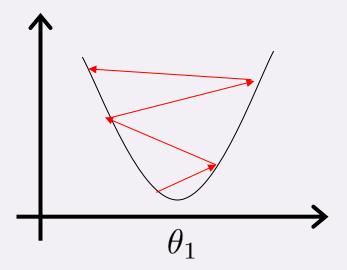
If α is too small, gradient descent can be very slow.

CHOOSE α

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial Cost(\theta)}{\partial \theta_j}$$

(simultaneous update for $\theta_0, \theta_1, \dots, \theta_d$)

Learning rate



minimum. It may fail to converge, or even diverge.

If α is too large, gradient

descent can overshoot the

CHOOSE α

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial Cost(\theta)}{\partial \theta_j}$$
 (simultaneous update for $\theta_0, \theta_1, \dots, \theta_d$)

Learning rate

For certain functions $Cost(\theta)$, we can theoretically guarantee the convergence of gradient descent by choosing a appropriate α

If interested, please read machine learning course at UBC: lecture 4, starting from page 9 https://www.cs.ubc.ca/~schmidtm/Courses/540-W18/L4.pdf

EXTENDING LINEAR REGRESSION TO MORE COMPLEX MODELS

- The inputs X for linear regression can be:
 - Original quantitative inputs
 - Transformation of quantitative inputs (log, exp, square, etc.)
 - Polynomial transformation (example: $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3$)
 - Interactions between variables (example: $x_3 = x_1 \times x_2$)

• This allows use of linear regression techniques to fit non-linear datasets.

LINEAR BASIS FUNCTION MODEL

Generally,

$$h_{\theta}(x) = \sum_{j=0}^{d} \theta_{j} \phi_{j}(x)$$

• Typically, $\phi_0(x) = 1$ so that θ_0 acts as a bias.

Basis Function

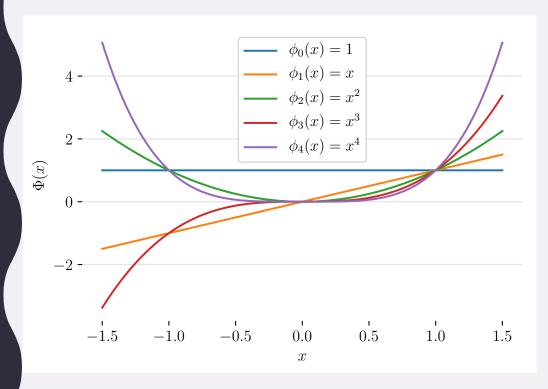
• In the simplest case, we can use linear basis function:

$$\phi_j(x) = x_j$$

• Polynomial basis function: $\phi_j(x) = x^j$

• Gaussian basis function:
$$\phi_j(x) = e^{-\frac{\left(x - \mu_j\right)^2}{2s^2}}$$

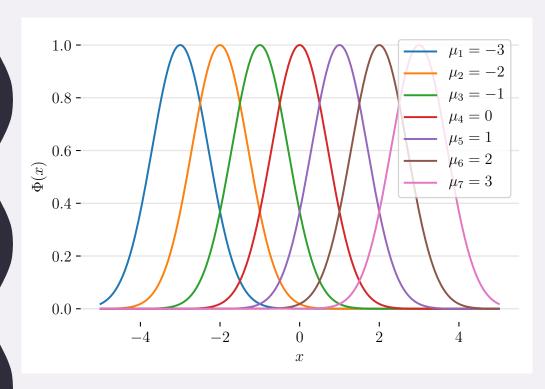
EXAMPLE - POLYNOMIAL BASIS FUNCTION



(a) Polynomial basis out to degree 4.

$$y = \theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3 + \theta_4 x^4 = \sum_{j=0}^{\infty} \theta_j x^j$$

EXAMPLE - GAUSSIAN BASIS FUNCTION



(a) Examples of Gaussian-type radial basis functions.

$$y = \theta_0 + \theta_1 e^{-\frac{(x-\mu_1)^2}{2s^2}} + \dots + \theta_7 e^{-\frac{(x-\mu_7)^2}{2s^2}}$$

EXERCISE

HTTPS://COLAB.RESEARCH.GOOGLE.C OM/DRIVE/IVIFN_VBCFAXXAPHZW-WUGJRRGXGLFVFQ?USP=SHARING

QUESTIONSP

HW1 (DUE 4/20)





HW₁

Due Apr 20 at 11:59pm | 60 pts



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