main

July 21, 2024

1 Question 8

Part A: Define Matrix A and SVD

```
[]: import numpy as np
     A = np.array([
         [1, 2, 3, 4],
         [4, 3, 2, 1],
         [1, 1, 1, 1],
         [0, 1, 2, 3],
         [1, 3, 2, 4]
     ])
     U, S, Vt = np.linalg.svd(A)
     print(f"U: {U}")
     print(f"S: {S}")
     print(f"Vt: {Vt}")
     Sigma = np.diag(S)
     print(f"Sigma: {Sigma}")
     Sigma_full = np.zeros((A.shape[0], A.shape[1]))
     Sigma_full[:Sigma.shape[0], :Sigma.shape[1]] = Sigma
     print(f"Sigma_full: {Sigma_full}")
    U: [[-5.57226401e-01 2.85816990e-01 -4.55858954e-01 5.61572987e-01
      -2.90922293e-01]
     [-4.59476939e-01 -8.42323299e-01 -1.12719724e-01 -2.02015835e-01
      -1.60798847e-01]
     [-2.03340668e-01 -1.11301262e-01 -1.13715736e-01 2.46490352e-01
       9.34117680e-01]
     [-3.53885733e-01 3.97118252e-01 -3.42143218e-01 -7.63588822e-01
       1.30123446e-01]
     [-5.58387984e-01 1.96746617e-01 8.05911675e-01 -8.32667268e-17
      -2.08166817e-17]]
    S: [9.58659829e+00 3.86203400e+00 1.08711850e+00 5.85762774e-16]
```

```
Vt: [[-0.32929958 -0.49290414 -0.48176851 -0.64537307]
     [-0.77628287 -0.27945872 0.06453409 0.56135824]
     [-0.19734915 \quad 0.65494147 \quad -0.71675271 \quad 0.13553791]
     Γ 0.5
                  -0.5
                              -0.5
                                            0.5
                                                      ]]
    Sigma: [[9.58659829e+00 0.00000000e+00 0.00000000e+00 0.0000000e+00]
     [0.00000000e+00 3.86203400e+00 0.0000000e+00 0.0000000e+00]
     [0.00000000e+00 0.00000000e+00 1.08711850e+00 0.00000000e+00]
     [0.00000000e+00 0.0000000e+00 0.0000000e+00 5.85762774e-16]]
    Sigma full: [[9.58659829e+00 0.00000000e+00 0.0000000e+00 0.0000000e+00]
     [0.00000000e+00 3.86203400e+00 0.0000000e+00 0.0000000e+00]
     [0.00000000e+00 0.0000000e+00 1.08711850e+00 0.0000000e+00]
     [0.00000000e+00 0.00000000e+00 0.0000000e+00 5.85762774e-16]
     [0.00000000e+00 0.00000000e+00 0.0000000e+00 0.0000000e+00]]
    Part B: Rank of A
[]: rank = np.linalg.matrix_rank(A)
     print(f"rank of A: {rank}")
    rank of A: 3
    Part C: Find Sigma dagger and U^T
[]: Sigma_pseudo_inv = np.linalg.pinv(Sigma_full)
     U_transpose = U.T
     print(f"Sigma_dagger: {Sigma_pseudo_inv}")
     print(f"U Transpose:: {U_transpose}")
    Sigma_dagger: [[0.10431229 0.
                                                                 0.
                                                                           ]
                                           0.
                                                      0.
                                                             ]
     ГО.
                 0.25893092 0.
                                        0.
                                                   0.
     ГО.
                 0.
                            0.91986293 0.
                                                   0.
                                                             ]
                                                             ]]
     ΓΟ.
                 0.
                            0.
                                        0.
                                                   0.
    U Transpose:: [[-5.57226401e-01 -4.59476939e-01 -2.03340668e-01 -3.53885733e-01
      -5.58387984e-01]
     [ 2.85816990e-01 -8.42323299e-01 -1.11301262e-01 3.97118252e-01
       1.96746617e-01]
     [-4.55858954e-01 -1.12719724e-01 -1.13715736e-01 -3.42143218e-01
       8.05911675e-01]
     [ 5.61572987e-01 -2.02015835e-01 2.46490352e-01 -7.63588822e-01
      -8.32667268e-17]
     [-2.90922293e-01 -1.60798847e-01 9.34117680e-01 1.30123446e-01
      -2.08166817e-17]]
    Part D: Psuedoinverse of A
[]: A_pseudo_inv = Vt.T @ Sigma_pseudo_inv @ U_transpose
     print(f"A_pseudo_inv: {A_pseudo_inv}")
    A_pseudo_inv: [[ 0.04444444 0.20555556 0.05
                                                         -0.00555556 -0.16666667]
     [-0.26666667 0.01666667 -0.05
                                          -0.21666667 0.5
                                                                  1
```

2 Part e: Verify moore-penrose conditions

```
[]: condition_1 = np.allclose(A @ A_pseudo_inv @ A, A)
    condition_2 = np.allclose(A_pseudo_inv @ A @ A_pseudo_inv, A_pseudo_inv)
    condition_3 = np.allclose((A @ A_pseudo_inv).T, A @ A_pseudo_inv)
    condition_4 = np.allclose((A_pseudo_inv @ A).T, A_pseudo_inv @ A)
    print(f"condition_1 (AA†A = A): {condition_1}")
    print(f"condition_2 (A†AA† = A†): {condition_2}")
    print(f"condition_3 ((AA†)T = AA†): {condition_3}")
    print(f"condition_4 ((A†A)T = A†A): {condition_4}")

condition_1 (AA†A = A): True
    condition_2 (A†AA† = A†): True
    condition_3 ((AA†)T = AA†): True
    condition_4 ((A†A)T = AA†): True
```