Artificial Intelligence Nanodegree

Convolutional Neural Networks

Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the iPython Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to \n", "**File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this IPython notebook.

Why We're Here

In this notebook, you will make the first steps towards developing an algorithm that could be used as part of a mobile or web app. At the end of this project, your code will accept any user-supplied image as input. If a dog is detected in the image, it will provide an estimate of the dog's breed. If a human is detected, it will provide an estimate of the dog breed that is most resembling. The image below displays potential sample output of your finished project (... but we expect that each student's algorithm will behave differently!).



In this real-world setting, you will need to piece together a series of models to perform different tasks; for instance, the algorithm that detects humans in an image will be different from the CNN that infers dog breed. There are many points of possible failure, and no perfect algorithm exists. Your imperfect solution will nonetheless create a fun user experience!

The Road Ahead

We break the notebook into separate steps. Feel free to use the links below to navigate the notebook.

- Step 0: Import Datasets
- Step 1: Detect Humans
- Step 2: Detect Dogs
- Step 3: Create a CNN to Classify Dog Breeds (from Scratch)
- Step 4: Use a CNN to Classify Dog Breeds (using Transfer Learning)
- Step 5: Create a CNN to Classify Dog Breeds (using Transfer Learning)
- Step 6: Write your Algorithm
- Step 7: Test Your Algorithm

Step 0: Import Datasets

Import Dog Dataset

In the code cell below, we import a dataset of dog images. We populate a few variables through the use of the load files function from the scikit-learn library:

- train files, valid files, test files numpy arrays containing file paths to images
- train_targets, valid_targets, test_targets numpy arrays containing onehot-encoded classification labels

```
In [1]: from sklearn.datasets import load files
        from keras.utils import np utils
        import numpy as np
        from glob import glob
        # define function to load train, test, and validation datasets
        def load dataset(path):
            data = load files(path)
            dog files = np.array(data['filenames'])
            dog_targets = np_utils.to_categorical(np.array(data['target']), 133)
            return dog_files, dog_targets
        # load train, test, and validation datasets
        train files, train_targets = load_dataset('dogImages/train')
        valid files, valid targets = load dataset('dogImages/valid')
        test_files, test_targets = load_dataset('dogImages/test')
        # load list of dog names
        dog names = [item[20:-1] for item in sorted(glob("dogImages/train/*/"))]
        # print statistics about the dataset
        print('There are %d total dog categories.' % len(dog_names))
        print('There are %s total dog images.\n' % len(np.hstack([train_files, v
        alid_files, test_files])))
        print('There are %d training dog images.' % len(train files))
        print('There are %d validation dog images.' % len(valid_files))
        print('There are %d test dog images.'% len(test files))
```

```
There are 133 total dog categories.
There are 8351 total dog images.
There are 6680 training dog images.
There are 835 validation dog images.
There are 836 test dog images.
```

Using TensorFlow backend.

Import Human Dataset

In the code cell below, we import a dataset of human images, where the file paths are stored in the numpy array human files.

```
In [2]: import random
    random.seed(8675309)

# load filenames in shuffled human dataset
    human_files = np.array(glob("lfw/*/*"))
    random.shuffle(human_files)

# print statistics about the dataset
    print('There are %d total human images.' % len(human_files))
```

There are 13233 total human images.

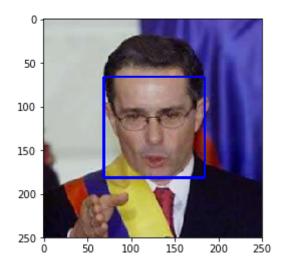
Step 1: Detect Humans

We use OpenCV's implementation of <u>Haar feature-based cascade classifiers</u> (http://docs.opencv.org/trunk/d7/d8b/tutorial_py_face_detection.html) to detect human faces in images. OpenCV provides many pre-trained face detectors, stored as XML files on https://github.com/opencv/opencv/tree/master/data/haarcascades). We have downloaded one of these detectors and stored it in the haarcascades directory.

In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

In [3]: import cv2 import matplotlib.pyplot as plt %matplotlib inline # extract pre-trained face detector face cascade = cv2.CascadeClassifier('haarcascades/haarcascade frontalfa ce_alt.xml') # load color (BGR) image img = cv2.imread(human_files[3]) # convert BGR image to grayscale gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY) # find faces in image faces = face_cascade.detectMultiScale(gray) # print number of faces detected in the image print('Number of faces detected:', len(faces)) # get bounding box for each detected face for (x,y,w,h) in faces: # add bounding box to color image cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)# convert BGR image to RGB for plotting cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB) # display the image, along with bounding box plt.imshow(cv rgb) plt.show()

('Number of faces detected:', 1)



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [4]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

(IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face detector function.

- What percentage of the first 100 images in human files have a detected human face?
- What percentage of the first 100 images in dog files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer:

- 98% of the first 100 images in human files have a detected human face.
- 11% of the first 100 images in dog files have a detected human face.

Question 2: This algorithmic choice necessitates that we communicate to the user that we accept human images only when they provide a clear view of a face (otherwise, we risk having unneccessarily frustrated users!). In your opinion, is this a reasonable expectation to pose on the user? If not, can you think of a way to detect humans in images that does not necessitate an image with a clearly presented face?

Answer:

• In my opinion, it is not a reasonable expectation to pose on the user. There are methods that can detect humans in images that does not necessitate an image with a clearly presented face. As an example, Adam Geitgey presented a method to do so using face landmarks and embedding (measurements): https://medium.com/@ageitgey/machine-learning-is-fun-part-4-modern-face-recognition-with-deep-learning-c3cffc121d78)

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on each of the datasets.

```
In [6]: ## (Optional) TODO: Report the performance of another
## face detection algorithm on the LFW dataset
### Feel free to use as many code cells as needed.
```

Step 2: Detect Dogs

In this section, we use a pre-trained ResNet-50

(http://ethereon.github.io/netscope/#/gist/db945b393d40bfa26006) model to detect dogs in images. Our first line of code downloads the ResNet-50 model, along with weights that have been trained on ImageNet (http://www.image-net.org/), a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a). Given an image, this pre-trained ResNet-50 model returns a prediction (derived from the available categories in ImageNet) for the object that is contained in the image.

```
In [7]: from keras.applications.resnet50 import ResNet50
# define ResNet50 model
ResNet50_model = ResNet50(weights='imagenet')
```

Pre-process the Data

When using TensorFlow as backend, Keras CNNs require a 4D array (which we'll also refer to as a 4D tensor) as input, with shape

(nb samples, rows, columns, channels),

where nb_samples corresponds to the total number of images (or samples), and rows, columns, and channels correspond to the number of rows, columns, and channels for each image, respectively.

The path_to_tensor function below takes a string-valued file path to a color image as input and returns a 4D tensor suitable for supplying to a Keras CNN. The function first loads the image and resizes it to a square image that is 224×224 pixels. Next, the image is converted to an array, which is then resized to a 4D tensor. In this case, since we are working with color images, each image has three channels. Likewise, since we are processing a single image (or sample), the returned tensor will always have shape

The paths_to_tensor function takes a numpy array of string-valued image paths as input and returns a 4D tensor with shape

```
(nb_samples, 224, 224, 3).
```

Here, nb_samples is the number of samples, or number of images, in the supplied array of image paths. It is best to think of nb_samples as the number of 3D tensors (where each 3D tensor corresponds to a different image) in your dataset!

```
In [8]: from keras.preprocessing import image
    from tqdm import tqdm

def path_to_tensor(img_path):
        # loads RGB image as PIL.Image.Image type
        img = image.load_img(img_path, target_size=(224, 224))
        # convert PIL.Image.Image type to 3D tensor with shape (224, 224, 3)
        x = image.img_to_array(img)
        # convert 3D tensor to 4D tensor with shape (1, 224, 224, 3) and ret
    urn 4D tensor
    return np.expand_dims(x, axis=0)

def paths_to_tensor(img_paths):
    list_of_tensors = [path_to_tensor(img_path) for img_path in tqdm(img_paths)]
    return np.vstack(list_of_tensors)
```

Making Predictions with ResNet-50

Getting the 4D tensor ready for ResNet-50, and for any other pre-trained model in Keras, requires some additional processing. First, the RGB image is converted to BGR by reordering the channels. All pre-trained models have the additional normalization step that the mean pixel (expressed in RGB as [103.939, 116.779, 123.68] and calculated from all pixels in all images in ImageNet) must be subtracted from every pixel in each image. This is implemented in the imported function preprocess_input. If you're curious, you can check the code for preprocess_input here (https://github.com/fchollet/keras/blob/master/keras/applications/imagenet_utils.py).

Now that we have a way to format our image for supplying to ResNet-50, we are now ready to use the model to extract the predictions. This is accomplished with the predict method, which returns an array whose i-th entry is the model's predicted probability that the image belongs to the i-th ImageNet category. This is implemented in the ResNet50_predict_labels function below.

By taking the argmax of the predicted probability vector, we obtain an integer corresponding to the model's predicted object class, which we can identify with an object category through the use of this <u>dictionary</u> (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a).

```
In [9]: from keras.applications.resnet50 import preprocess_input, decode_predict
ions

def ResNet50_predict_labels(img_path):
    # returns prediction vector for image located at img_path
    img = preprocess_input(path_to_tensor(img_path))
    return np.argmax(ResNet50_model.predict(img))
```

Write a Dog Detector

While looking at the <u>dictionary (https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a)</u>, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained ResNet-50 model, we need only check if the ResNet50_predict_labels function above returns a value between 151 and 268 (inclusive).

We use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

```
In [10]: ### returns "True" if a dog is detected in the image stored at img_path
    def dog_detector(img_path):
        prediction = ResNet50_predict_labels(img_path)
        return ((prediction <= 268) & (prediction >= 151))
```

(IMPLEMENTATION) Assess the Dog Detector

Question 3: Use the code cell below to test the performance of your dog detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?

Answer:

- 2% of the images in human files short have a detected dog.
- What 100% of the images in dog files short have a detected dog.

```
In [11]: ### TODO: Test the performance of the dog_detector function
    ### on the images in human_files_short and dog_files_short.
    are_human_faces = [dog_detector(f) for f in human_files_short]
    are_dog_faces = [dog_detector(f) for f in dog_files_short]

human_dog_faces = filter(lambda x: x == True, are_human_faces)
    dog_faces = filter(lambda x: x == True, are_dog_faces)

print('Percentage of human faces detected as dog faces:', len(human_dog_faces) / 100.0)

print('Percentage of dog faces detected as dog faces:', len(dog_faces) / 100.0)
```

```
('Percentage of human faces detected as dog faces:', 0.02)
('Percentage of dog faces detected as dog faces:', 1.0)
```

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 1%. In Step 5 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

Be careful with adding too many trainable layers! More parameters means longer training, which means you are more likely to need a GPU to accelerate the training process. Thankfully, Keras provides a handy estimate of the time that each epoch is likely to take; you can extrapolate this estimate to figure out how long it will take for your algorithm to train.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have great difficulty in distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

Curly-Coated Retriever	American Water Spaniel

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.

Yellow Labrador	Chocolate Labrador	Black Labrador

We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

Pre-process the Data

We rescale the images by dividing every pixel in every image by 255.

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
model.summary()
```

We have imported some Python modules to get you started, but feel free to import as many modules as you need. If you end up getting stuck, here's a hint that specifies a model that trains relatively fast on CPU and attains >1% test accuracy in 5 epochs:



Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. If you chose to use the hinted architecture above, describe why you think that CNN architecture should work well for the image classification task.

Answer:

I chose to use the hinted architecture above. This CNN architecture should work well for the image classification task for the following reasons.

First Conv2D is used to create convolutional layers to make use of the space locality. Specifically, by using kernel windows of minimum size 2 by 2, each neuron in a feature map in a given convolutional layer is connected only to neurons located in a 2 by 2 window in the previous layer.

The number of filters (e.g., 16, 32, 64) is increased layer by layer to capture more and more higher-level features.

The max polling layer is added inbetween convolutional layers to subsample the input image in order to tolerate small image shift (location invariance), reduce the conputational load, memory usage, and the number of learning parameters.

Finally a regular feedforward neural network (consisting of fully connected layer with softmax) is added to make final decision.

```
In [13]: from keras.layers import Conv2D, MaxPooling2D, GlobalAveragePooling2D
         from keras.layers import Dropout, Flatten, Dense
         from keras.models import Sequential
         num_dog_classes = 133 # 133 bod breeds
         model = Sequential()
         ### TODO: Define your architecture.
         model.add(Conv2D(16, kernel_size=(2, 2), strides=(2, 2),
                          activation='relu',
                          input_shape=(224, 224, 3)))
         model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
         model.add(Conv2D(32, (2, 2), activation='relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Conv2D(64, (2, 2), activation='relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(GlobalAveragePooling2D())
         model.add(Dense(num_dog_classes, activation='softmax'))
         model.summary()
```

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 112, 112, 16)	208
max_pooling2d_2 (MaxPooling2	(None, 56, 56, 16)	0
conv2d_2 (Conv2D)	(None, 55, 55, 32)	2080
max_pooling2d_3 (MaxPooling2	(None, 27, 27, 32)	0
conv2d_3 (Conv2D)	(None, 26, 26, 64)	8256
max_pooling2d_4 (MaxPooling2	(None, 13, 13, 64)	0
global_average_pooling2d_1 ((None, 64)	0
dense_1 (Dense)	(None, 133)	8645
Total params: 19,189 Trainable params: 19,189 Non-trainable params: 0		======

Compile the Model

```
In [14]: model.compile(optimizer='rmsprop', loss='categorical crossentropy', metr
         ics=['accuracy'])
```

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to <u>augment the training data (https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html)</u>, but this is not a requirement.

```
In [15]: from keras.callbacks import ModelCheckpoint
      ### TODO: specify the number of epochs that you would like to use to tra
      in the model.
      epochs = 5
      ### Do NOT modify the code below this line.
      checkpointer = ModelCheckpoint(filepath='saved models/weights.best.from_
      scratch.hdf5',
                            verbose=1, save_best_only=True)
      model.fit(train tensors, train targets,
             validation data=(valid tensors, valid targets),
             epochs=epochs, batch_size=20, callbacks=[checkpointer], verbos
      e=1)
      Train on 6680 samples, validate on 835 samples
      Epoch 1/5
      cc: 0.0104Epoch 00000: val loss improved from inf to 4.86219, saving mo
      del to saved models/weights.best.from scratch.hdf5
      6680/6680 [=============] - 30s - loss: 4.8831 - acc:
      0.0103 - val_loss: 4.8622 - val_acc: 0.0168
      Epoch 2/5
      cc: 0.0137Epoch 00001: val loss improved from 4.86219 to 4.82290, savin
      g model to saved models/weights.best.from scratch.hdf5
      0.0136 - val loss: 4.8229 - val acc: 0.0120
      Epoch 3/5
      cc: 0.0182Epoch 00002: val loss improved from 4.82290 to 4.77668, savin
      g model to saved models/weights.best.from scratch.hdf5
      0.0181 - val_loss: 4.7767 - val_acc: 0.0180
      Epoch 4/5
      cc: 0.0225Epoch 00003: val_loss improved from 4.77668 to 4.76083, savin
      g model to saved models/weights.best.from scratch.hdf5
      0.0225 - val_loss: 4.7608 - val_acc: 0.0144
      Epoch 5/5
      cc: 0.0227Epoch 00004: val loss improved from 4.76083 to 4.73775, savin
      g model to saved models/weights.best.from scratch.hdf5
      0.0229 - val_loss: 4.7377 - val_acc: 0.0156
```

Out[15]: <keras.callbacks.History at 0x125e02250>

Load the Model with the Best Validation Loss

```
In [16]: model.load_weights('saved_models/weights.best.from_scratch.hdf5')
```

Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 1%.

Step 4: Use a CNN to Classify Dog Breeds

To reduce training time without sacrificing accuracy, we show you how to train a CNN using transfer learning. In the following step, you will get a chance to use transfer learning to train your own CNN.

Obtain Bottleneck Features

```
In [18]: bottleneck_features = np.load('bottleneck_features/DogVGG16Data.npz')
    train_VGG16 = bottleneck_features['train']
    valid_VGG16 = bottleneck_features['valid']
    test_VGG16 = bottleneck_features['test']
```

Model Architecture

The model uses the the pre-trained VGG-16 model as a fixed feature extractor, where the last convolutional output of VGG-16 is fed as input to our model. We only add a global average pooling layer and a fully connected layer, where the latter contains one node for each dog category and is equipped with a softmax.

```
In [19]: VGG16_model = Sequential()
    VGG16_model.add(GlobalAveragePooling2D(input_shape=train_VGG16.shape[1
    :]))
    VGG16_model.add(Dense(133, activation='softmax'))
    VGG16_model.summary()
```

Layer (type)	Output	Shape	Param #
global_average_pooling2d_2 ((None,	512)	0
dense_2 (Dense)	(None,	133)	68229
Total params: 68,229 Trainable params: 68,229 Non-trainable params: 0			

Compile the Model

```
In [20]: VGG16_model.compile(loss='categorical_crossentropy', optimizer='rmsprop'
, metrics=['accuracy'])
```

Train the Model

```
Train on 6680 samples, validate on 835 samples
Epoch 1/20
acc: 0.1027Epoch 00000: val_loss improved from inf to 11.33329, saving
model to saved models/weights.best.VGG16.hdf5
6680/6680 [============= ] - 1s - loss: 12.7765 - acc:
0.1079 - val_loss: 11.3333 - val_acc: 0.1940
Epoch 2/20
acc: 0.2547Epoch 00001: val_loss improved from 11.33329 to 10.69640, sa
ving model to saved models/weights.best.VGG16.hdf5
0.2557 - val_loss: 10.6964 - val_acc: 0.2695
Epoch 3/20
acc: 0.3108Epoch 00002: val_loss improved from 10.69640 to 10.45481, sa
ving model to saved models/weights.best.VGG16.hdf5
0.3103 - val_loss: 10.4548 - val_acc: 0.2934
Epoch 4/20
cc: 0.3452Epoch 00003: val_loss improved from 10.45481 to 10.08614, sav
ing model to saved models/weights.best.VGG16.hdf5
0.3455 - val_loss: 10.0861 - val_acc: 0.3018
Epoch 5/20
cc: 0.3714Epoch 00004: val loss improved from 10.08614 to 10.05534, sav
ing model to saved models/weights.best.VGG16.hdf5
0.3707 - val_loss: 10.0553 - val_acc: 0.3102
Epoch 6/20
cc: 0.3930Epoch 00005: val loss improved from 10.05534 to 9.79394, savi
ng model to saved models/weights.best.VGG16.hdf5
0.3933 - val loss: 9.7939 - val acc: 0.3257
Epoch 7/20
cc: 0.4116Epoch 00006: val loss improved from 9.79394 to 9.68047, savin
g model to saved models/weights.best.VGG16.hdf5
0.4111 - val_loss: 9.6805 - val_acc: 0.3401
Epoch 8/20
cc: 0.4174Epoch 00007: val loss improved from 9.68047 to 9.61918, savin
g model to saved models/weights.best.VGG16.hdf5
0.4184 - val loss: 9.6192 - val acc: 0.3473
Epoch 9/20
cc: 0.4267Epoch 00008: val loss improved from 9.61918 to 9.55098, savin
g model to saved models/weights.best.VGG16.hdf5
0.4256 - val_loss: 9.5510 - val_acc: 0.3521
Epoch 10/20
```

```
cc: 0.4322Epoch 00009: val loss improved from 9.55098 to 9.43496, savin
g model to saved models/weights.best.VGG16.hdf5
0.4322 - val_loss: 9.4350 - val_acc: 0.3353
Epoch 11/20
cc: 0.4438Epoch 00010: val loss improved from 9.43496 to 9.30237, savin
g model to saved models/weights.best.VGG16.hdf5
0.4446 - val loss: 9.3024 - val acc: 0.3581
Epoch 12/20
cc: 0.4585Epoch 00011: val loss improved from 9.30237 to 9.17087, savin
g model to saved models/weights.best.VGG16.hdf5
0.4600 - val_loss: 9.1709 - val_acc: 0.3665
Epoch 13/20
cc: 0.4655Epoch 00012: val_loss improved from 9.17087 to 9.10368, savin
g model to saved models/weights.best.VGG16.hdf5
6680/6680 [=============] - 0s - loss: 8.4060 - acc:
0.4660 - val_loss: 9.1037 - val_acc: 0.3725
Epoch 14/20
cc: 0.4742Epoch 00013: val_loss improved from 9.10368 to 8.96492, savin
g model to saved models/weights.best.VGG16.hdf5
0.4740 - val_loss: 8.9649 - val_acc: 0.3820
Epoch 15/20
cc: 0.4835Epoch 00014: val_loss improved from 8.96492 to 8.84272, savin
g model to saved models/weights.best.VGG16.hdf5
0.4831 - val loss: 8.8427 - val acc: 0.3904
Epoch 16/20
cc: 0.4858Epoch 00015: val_loss did not improve
0.4847 - val loss: 8.8515 - val acc: 0.3832
Epoch 17/20
cc: 0.4942Epoch 00016: val loss improved from 8.84272 to 8.66475, savin
g model to saved models/weights.best.VGG16.hdf5
0.4934 - val_loss: 8.6647 - val_acc: 0.3952
Epoch 18/20
cc: 0.5035- ETA: 0s - loss: 7.7712Epoch 00017: val loss did not improve
0.5030 - val_loss: 8.6809 - val_acc: 0.4036
Epoch 19/20
cc: 0.5061Epoch 00018: val loss did not improve
0.5063 - val_loss: 8.6996 - val_acc: 0.3988
Epoch 20/20
6460/6680 [=======
             ===========>.] - ETA: 0s - loss: 7.9133 - a
```

```
cc: 0.5060Epoch 00019: val loss did not improve
      0.5061 - val_loss: 8.7008 - val_acc: 0.3952
Out[21]: <keras.callbacks.History at 0x1264ac7d0>
```

Load the Model with the Best Validation Loss

```
In [22]: VGG16_model.load_weights('saved_models/weights.best.VGG16.hdf5')
```

Test the Model

Now, we can use the CNN to test how well it identifies breed within our test dataset of dog images. We print the test accuracy below.

```
In [23]: # get index of predicted dog breed for each image in test set
         VGG16 predictions = [np.argmax(VGG16_model.predict(np.expand_dims(featur
         e, axis=0))) for feature in test VGG16]
         # report test accuracy
         test accuracy = 100*np.sum(np.array(VGG16 predictions)==np.argmax(test t
         argets, axis=1))/len(VGG16 predictions)
         print('Test accuracy: %.4f%%' % test_accuracy)
```

Test accuracy: 41.0000%

Predict Dog Breed with the Model

```
In [24]: from extract bottleneck features import *
         def VGG16 predict breed(img path):
             # extract bottleneck features
             bottleneck feature = extract VGG16(path to tensor(img path))
             # obtain predicted vector
             predicted vector = VGG16 model.predict(bottleneck feature)
             # return dog breed that is predicted by the model
             return dog names[np.argmax(predicted vector)]
```

Step 5: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

In Step 4, we used transfer learning to create a CNN using VGG-16 bottleneck features. In this section, you must use the bottleneck features from a different pre-trained model. To make things easier for you, we have precomputed the features for all of the networks that are currently available in Keras:

- VGG-19 (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogVGG19Data.npz)
 bottleneck features
- ResNet-50 (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogResnet50Data.npz)
 bottleneck features
- Inception (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogInceptionV3Data.npz)
 bottleneck features
- Xception (https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogXceptionData.npz)
 bottleneck features

The files are encoded as such:

```
Dog{network}Data.npz
```

where {network}, in the above filename, can be one of VGG19, Resnet50, InceptionV3, or Xception. Pick one of the above architectures, download the corresponding bottleneck features, and store the downloaded file in the bottleneck features/ folder in the repository.

(IMPLEMENTATION) Obtain Bottleneck Features

In the code block below, extract the bottleneck features corresponding to the train, test, and validation sets by running the following:

```
bottleneck_features = np.load('bottleneck_features/Dog{network}Data.npz')
train_{network} = bottleneck_features['train']
valid_{network} = bottleneck_features['valid']
test_{network} = bottleneck_features['test']
```

```
In [25]: ### TODO: Obtain bottleneck features from another pre-trained CNN.
    bottleneck_features = np.load('bottleneck_features/DogResnet50Data.npz')
    train_Resnet50 = bottleneck_features['train']
    valid_Resnet50 = bottleneck_features['valid']
    test_Resnet50 = bottleneck_features['test']
```

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
<your model's name>.summary()
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer:

At the beginning the transfer learning is used to take the output of the trained Resnet50 model as input. Then a regular feedforward neural network (consisting of a global average pooling and a fully connected layer with softmax) is added to make final decision.

```
In [26]: ### TODO: Define your architecture.
Resnet50_model = Sequential()
Resnet50_model.add(GlobalAveragePooling2D(input_shape=train_Resnet50.sha
    pe[1:]))
Resnet50_model.add(Dense(133, activation='softmax'))
Resnet50_model.summary()
```

Layer (type)	Output	Shape	Param #
global_average_pooling2d_3 ((None,	2048)	0
dense_3 (Dense)	(None,	133)	272517
Total params: 272,517 Trainable params: 272,517 Non-trainable params: 0			

(IMPLEMENTATION) Compile the Model

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to <u>augment the training data (https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html)</u>, but this is not a requirement.

```
Train on 6680 samples, validate on 835 samples
Epoch 1/20
cc: 0.5934Epoch 00000: val_loss improved from inf to 0.79761, saving mo
del to saved models/weights.best.Resnet50.hdf5
6680/6680 [============= ] - 1s - loss: 1.6489 - acc:
0.5945 - val_loss: 0.7976 - val_acc: 0.7497
Epoch 2/20
cc: 0.8634Epoch 00001: val_loss improved from 0.79761 to 0.67594, savin
g model to saved models/weights.best.Resnet50.hdf5
0.8630 - val_loss: 0.6759 - val_acc: 0.7988
Epoch 3/20
cc: 0.9136Epoch 00002: val_loss did not improve
0.9129 - val loss: 0.6763 - val acc: 0.7988
Epoch 4/20
cc: 0.9495Epoch 00003: val loss did not improve
0.9496 - val loss: 0.6972 - val acc: 0.7880
Epoch 5/20
cc: 0.9605Epoch 00004: val_loss improved from 0.67594 to 0.67149, savin
g model to saved models/weights.best.Resnet50.hdf5
6680/6680 [=============] - 0s - loss: 0.1216 - acc:
0.9611 - val loss: 0.6715 - val acc: 0.8084
Epoch 6/20
cc: 0.9744Epoch 00005: val loss did not improve
0.9741 - val loss: 0.6933 - val acc: 0.8132
Epoch 7/20
cc: 0.9812Epoch 00006: val loss did not improve
0.9813 - val loss: 0.6821 - val acc: 0.8228
Epoch 8/20
cc: 0.9863Epoch 00007: val loss did not improve
0.9864 - val loss: 0.7217 - val acc: 0.8156
Epoch 9/20
cc: 0.9894Epoch 00008: val loss did not improve
0.9889 - val loss: 0.7789 - val acc: 0.8120
Epoch 10/20
cc: 0.9918Epoch 00009: val loss did not improve
0.9918 - val loss: 0.7538 - val acc: 0.8216
Epoch 11/20
cc: 0.9950Epoch 00010: val loss did not improve
```

```
0.9951 - val_loss: 0.7777 - val_acc: 0.8240
Epoch 12/20
cc: 0.9949Epoch 00011: val loss did not improve
0.9949 - val_loss: 0.7887 - val_acc: 0.8156
Epoch 13/20
cc: 0.9968Epoch 00012: val loss did not improve
0.9967 - val_loss: 0.8462 - val_acc: 0.8180
Epoch 14/20
cc: 0.9969Epoch 00013: val loss did not improve
0.9970 - val_loss: 0.8620 - val_acc: 0.8168
Epoch 15/20
cc: 0.9974Epoch 00014: val loss did not improve
6680/6680 [=============] - 1s - loss: 0.0103 - acc:
0.9972 - val_loss: 0.8373 - val_acc: 0.8287
Epoch 16/20
cc: 0.9977Epoch 00015: val_loss did not improve
0.9976 - val_loss: 0.8482 - val_acc: 0.8287
Epoch 17/20
cc: 0.9984Epoch 00016: val loss did not improve
0.9984 - val loss: 0.8629 - val acc: 0.8228
Epoch 18/20
cc: 0.9984Epoch 00017: val loss did not improve
0.9984 - val_loss: 0.9123 - val_acc: 0.8240
Epoch 19/20
cc: 0.9983Epoch 00018: val loss did not improve
0.9984 - val_loss: 0.9102 - val_acc: 0.8216
Epoch 20/20
cc: 0.9985Epoch 00019: val loss did not improve
0.9985 - val_loss: 0.9570 - val_acc: 0.8228
```

Out[28]: <keras.callbacks.History at 0x129693c10>

(IMPLEMENTATION) Load the Model with the Best Validation Loss

```
In [29]: ### TODO: Load the model weights with the best validation loss.
Resnet50_model.load_weights('saved_models/weights.best.Resnet50.hdf5')
```

(IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 60%.

```
In [30]: ### TODO: Calculate classification accuracy on the test dataset.
# get index of predicted dog breed for each image in test set
Resnet50_predictions = [np.argmax(Resnet50_model.predict(np.expand_dims(feature, axis=0))) for feature in test_Resnet50]
# report test accuracy
test_accuracy = 100*np.sum(np.array(Resnet50_predictions)==np.argmax(test_targets, axis=1))/len(Resnet50_predictions)
print('Test accuracy: %.4f%%' % test_accuracy)
```

Test accuracy: 80.0000%

(IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

Similar to the analogous function in Step 5, your function should have three steps:

- 1. Extract the bottleneck features corresponding to the chosen CNN model.
- 2. Supply the bottleneck features as input to the model to return the predicted vector. Note that the argmax of this prediction vector gives the index of the predicted dog breed.
- 3. Use the dog names array defined in Step 0 of this notebook to return the corresponding breed.

The functions to extract the bottleneck features can be found in extract_bottleneck_features.py, and they have been imported in an earlier code cell. To obtain the bottleneck features corresponding to your chosen CNN architecture, you need to use the function

```
extract_{network}
```

where {network}, in the above filename, should be one of VGG19, Resnet50, InceptionV3, or Xception.

```
In [31]: ### TODO: Write a function that takes a path to an image as input
### and returns the dog breed that is predicted by the model.
from extract_bottleneck_features import *

def Resnet50_predict_breed(img_path):
    # extract bottleneck features
    bottleneck_feature = extract_Resnet50(path_to_tensor(img_path))
    # obtain predicted vector
    predicted_vector = Resnet50_model.predict(bottleneck_feature)
    # return dog breed that is predicted by the model
    return dog_names[np.argmax(predicted_vector)]
```

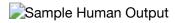
Step 6: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then,

- if a **dog** is detected in the image, return the predicted breed.
- if a **human** is detected in the image, return the resembling dog breed.
- if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and dog_detector functions developed above. You are **required** to use your CNN from Step 5 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!



(IMPLEMENTATION) Write your Algorithm

```
In [32]: ### TODO: Write your algorithm.
### Feel free to use as many code cells as needed.
from extract_bottleneck_features import *

def predict_breed(img_path):
    if dog_detector(img_path):
        # find out and print dog breed
        breed = Resnet50_predict_breed(img_path)
        print("Dog breed: ", breed)

elif face_detector(img_path):
    # find out and print dog breed
    breed = Resnet50_predict_breed(img_path)
        print("Hello, human, you are like a ", breed)

else:
    print("ERROR: neither human nor dog is detected!")
```

Step 7: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that **you** look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

(IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected:)? Or worse:(? Provide at least three possible points of improvement for your algorithm.

Answer:

The output is better than I expected. The following are three possible points of improvement to my algorithm:

- The first possible improvement is to provide visual feedback in conjunction with textual message. For example, if a human picture is predicted as a dog picture, in addition to the textual message, both of the given human picture and a sample image of the matched dog breed are displayed.
- The second possible improvement is to direct multiple human or dog faces from an image that contains multiple human faces or dog faces.
- The third possible improvement is to ditect both human faces and dog faces from an image that contains both human and dog faces.

```
In [33]: ## TODO: Execute your algorithm from Step 6 on
    ## at least 6 images on your computer.
    ## Feel free to use as many code cells as needed.
    predict_breed("dogImages/test/001.Affenpinscher/Affenpinscher_00003.jpg")

    ('Dog breed: ', 'Affenpinscher')

In [34]: predict_breed("dogImages/test/005.Alaskan_malamute/Alaskan_malamute_0030 9.jpg")

    ('Dog breed: ', 'Alaskan_malamute')

In [35]: predict_breed("dogImages/test/010.Anatolian_shepherd_dog/Anatolian_shepherd_dog_00661.jpg")

    ('Dog breed: ', 'Golden_retriever')

In [36]: predict_breed("dogImages/test/020.Belgian_malinois/Belgian_malinois_0140 7.jpg")

    ('Dog breed: ', 'Belgian_malinois')
```