

Introduction to Computer Vision HW02

- Generating Hybrid Image -

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Part 1.1

```
def boxfilter(n):
    assert n%2 == 1, "Dimesion must be odd"
    return np.ones((n,n))/(n**2)
```

```
boxfilter(3)
>> array([[0.11111111, 0.11111111, 0.11111111],
          [0.11111111, 0.11111111, 0.11111111],
          [0.11111111, 0.11111111, 0.11111111]])
```

```
boxfilter(4)
>> -----
AssertionError
Traceback (most recent call last)
<ipython-input-43-5870f78beb34> in <module> ----> 1 boxfilter(4)
<ipython-input-42-5fc975c6d216> in boxfilter(n)
      3 # If n is odd, create n * n size array filled with 1. And divide it with
sum of array, in this case , n**2.
      4 def boxfilter(n):
----> 5 assert n%2 == 1, "Dimesion must be odd" 6 return np.ones((n,n))/(n**2)
```

AssertionError: Dimesion must be odd

[illegible]

Part 1.2

```
def gauss1d(sigma):
    d = math.ceil(sigma*6)//2*2+1
    g1 = np.exp(-(np.arange(d)-d//2)**2/(2*sigma**2))
    return g1/np.sum(g1)

gauss1d(0.3)
>> array([0.00383626, 0.99232748, 0.00383626])

gauss1d(0.5)
>> array([0.10650698, 0.78698604, 0.10650698])

gauss1d(1)
>> array([0.00443305, 0.05400558, 0.24203623, 0.39905028, 0.24203623,
          0.05400558, 0.00443305])

gauss1d(2)
>> array([0.0022182 , 0.00877313, 0.02702316, 0.06482519, 0.12110939,
          0.17621312, 0.19967563, 0.17621312, 0.12110939, 0.06482519,
          0.02702316, 0.00877313, 0.0022182 ])
```

Part 1.3

```
def gauss2d(sigma):
    return np.outer(gauss1d(sigma), gauss1d(sigma))

gauss2d(0.5)
>> array([[0.01134374, 0.08381951, 0.01134374],
          [0.08381951, 0.61934703, 0.08381951],
          [0.01134374, 0.08381951, 0.01134374]])

gauss2d(1)
>> array([[1.96519161e-05, 2.39409349e-04, 1.07295826e-03, 1.76900911e-03,
          1.07295826e-03, 2.39409349e-04, 1.96519161e-05],
          [2.39409349e-04, 2.91660295e-03, 1.30713076e-02, 2.15509428e-02,
          1.30713076e-02, 2.91660295e-03, 2.39409349e-04],
          [1.07295826e-03, 1.30713076e-02, 5.85815363e-02, 9.65846250e-02,
          5.85815363e-02, 1.30713076e-02, 1.07295826e-03],
          [1.76900911e-03, 2.15509428e-02, 9.65846250e-02, 1.59241126e-01,
          9.65846250e-02, 2.15509428e-02, 1.76900911e-03],
          [1.07295826e-03, 1.30713076e-02, 5.85815363e-02, 9.65846250e-02,
          5.85815363e-02, 1.30713076e-02, 1.07295826e-03],
          [2.39409349e-04, 2.91660295e-03, 1.30713076e-02, 2.15509428e-02,
          1.30713076e-02, 2.91660295e-03, 2.39409349e-04],
          [1.96519161e-05, 2.39409349e-04, 1.07295826e-03, 1.76900911e-03,
          1.07295826e-03, 2.39409349e-04, 1.96519161e-05]])
```

Part 1.4.a : python 소스코드 참조(line 124)

Part 1.4.b: python 소스코드 참조(line 152)

Part 1.4.c, d

```
dogIm = Image.open('2b_dog.bmp')
dogIm = dogIm.convert('L')
dogImArray = np.asarray(dogIm)
dogImGaussArray = gaussconvolve2d(dogImArray, 3)
dogImGaussArray = dogImGaussArray.astype('uint8')
dogImGauss = Image.fromarray(dogImGaussArray)
dogImGauss.save('dog_gaussian.bmp', 'PNG')
dogIm.show()
dogImGauss.show()
```

>>

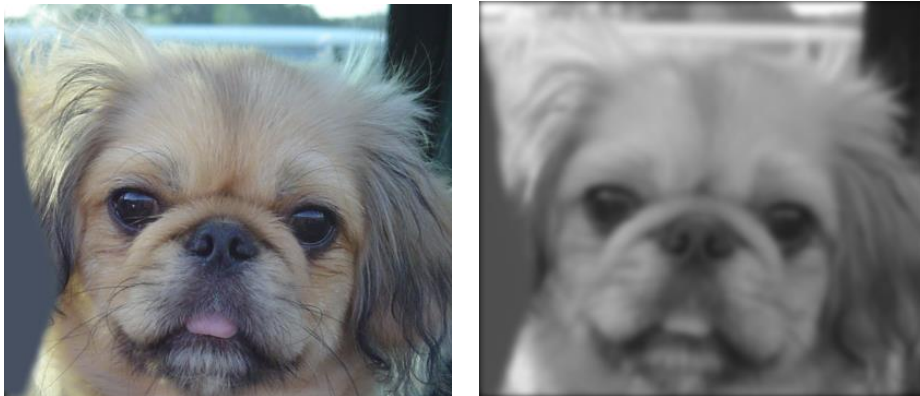


그림 1,2 -2b_dog.bmp, dog_gaussian.bmp

Part 2.1 (함수 imageFromChArray, colorLowPassChannels는 코드 참조; line 191~222)

```
dogIm = Image.open('2b_dog.bmp')
dogLowPassIm = imageFromChArray(colorLowPassChannels(dogIm, 3))
dogLowPassIm.show()
dogLowPassIm.save("dog_lowpass.bmp", "PNG")
```

>>

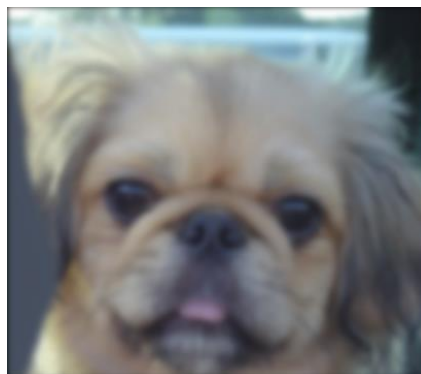


그림 3 - dog_lowpass.bmp

Part 2.2 (함수 colorHighPassChannels는 코드 참조; line 250~268)

```
catIm = Image.open('2a_cat.bmp')  
catHighPassIm = imageFromChArray(colorHighPassChannels(catIm, 3, 1))  
catHighPassIm.show()  
catHighPassIm.save("cat_highpass.bmp", "PNG")  
>>
```

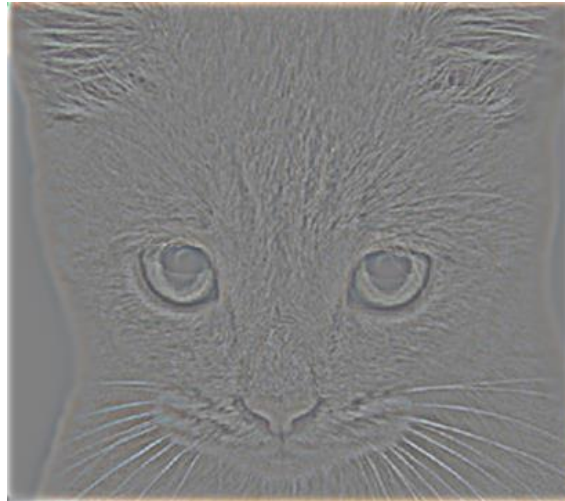


그림 4 - cat_highpass.bmp

Part 2.3 (함수 colorHybrid는 코드 참조; line 294~314)

```
catDogHybridIm = imageFromChArray(colorHybrid(dogIm, catIm, 3, 3))  
catDogHybridIm.show()  
catDogHybridIm.save("cat_dog_hybrid.bmp", "PNG")  
>>
```



그림 5 - cat_dog_hybrid.bmp