

# Reliable Software - Assignment 1

Joergen Aleksander Fagervik

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## **1 General**

## **2 Task 1**

### **2.1 Code**

```

int x = 10;
int y = 0;

active proctype t1() {
    do
        :: x != y -> x = x - 1; y = y + 1;
    od
}

active proctype t2() {
    do
        :: x == y -> atomic { x = 7; y = 3; }
    od
}

init {run t1(); run t2();}

```

## **3 Task 2**

### **3.1 Code**

```

int x = 0;

proctype P() {
    int k;
    int N = 5;

    int local_x;

    for (k: 1..N) {
        local_x = x; /* LOAD */
        local_x++; /* INCREMENT */
        x = local_x; /* STORE */
    }
}

proctype check() {
    if
    :: (_nr_pr == 1) -> printf("x is %d\n", x); assert (x == 3);
    fi
}

init {
    run P(); run P(); run P();

    run check();
}

```

## **4 Task 3**

### **4.1 Code**

```

#define N 3 // Number of people
#define B_MIN 0
#define B_MAX 4

#define NUMM 300

byte PERSON1 = 0;
byte PERSON2 = 1;
byte PERSON3 = 2;

chan c1 = [NUMM] of {int};
chan c2 = [NUMM] of {int};
chan c3 = [NUMM] of {int};

byte a1 = 5, a2 = 6, a3 = 7;

byte b[N]; // Lower bounds b[i] for each person
byte d[N]; // Candidate dates d[i] for each person
byte f[N]; // Earliest available dates f[i] for each person

// MAIN IDEA: RECEIVE TO YOUR OWN IDS CHANNEL, SEND TO NEXT

active proctype P1(byte id) {
    byte prev_date;

    d[id] = 0;
    f[id] = 0;

    do
    :: true ->
        d[id] = f[id];

        c2 ! d[id];

        c1 ? prev_date;

    if
    :: prev_date > d[id] -> d[id] = prev_date;
    :: else -> skip;
    fi;

    f[id] = (d[id] - b[id] + a1);

    if
    :: f[id] <= prev_date -> break;
    :: else -> skip;

```

```

        fi;
    od;
}

active proctype P2(byte id) {
    byte prev_date;

    d[id] = 0;
    f[id] = 0;

    do
    :: true ->
        d[id] = f[id];

        c3 ! d[id];

        c2 ? prev_date;

        if
        :: prev_date > d[id] -> d[id] = prev_date;
        :: else -> skip;
        fi;

        f[id] = (d[id] - b[id] + a2);

        if
        :: f[id] <= prev_date -> break;
        :: else -> skip;
        fi;
    od;
}

active proctype P3(byte id) {
    byte prev_date;

    d[id] = 0;
    f[id] = 0;

    do
    :: true ->
        d[id] = f[id];

        c1 ! d[id];

        c3 ? prev_date;

```



```

    if
    :: prev_date > d[id] -> d[id] = prev_date;
    :: else -> skip;
    fi;

    f[id] = (d[id] - b[id] + a3);

    if
    :: f[id] <= prev_date -> break;
    :: else -> skip;
    fi;
od;
}

init {
    // Initialize lower bounds b[i] and intervals a[i]
    byte b1, b2, b3;

    // Loop through possible values of b1, b2, and b3
    for (b1: B_MIN..B_MAX) {
    for (b2: B_MIN..B_MAX) {
    for (b3: B_MIN..B_MAX) {

        // Initialize lower bounds and intervals for each person
        b[0] = b1; b[1] = b2; b[2] = b3;

        run P1(PERSON1);
        run P2(PERSON2);
        run P3(PERSON3);

        // TODO: Fix this loop
        do
        :: _nr_pr > 1 -> 0;
        :: else -> break;
        od;

        // Print the largest possible meeting date and the corresponding lower bo
        if
        :: d[0] > d[1] && d[0] > d[2] -> printf("Largest meeting date: %d, -b1: %d", d[0], b1);
        :: d[1] > d[0] && d[1] > d[2] -> printf("Largest meeting date: %d, -b1: %d", d[1], b1);
        :: d[2] > d[0] && d[2] > d[1] -> printf("Largest meeting date: %d, -b1: %d", d[2], b1);
        :: else -> skip;
        fi;
    }
}
}
}

```

}

## **5 Task 4**

### **5.1 Code**

```

mtype = {p,v}; // P for Wait, V for signal

chan S = [0] of {mtype};

byte N = 0;

proctype semaphore(byte n) {
    N = n;
    do
        :: N > 0 ->
            S ? p;
            N--;
        :: N == 0 ->
            S ? v;
            N++;
    od
}

active[5] proctype c() {
    do
        :: S ! p;
            printf("%d-bien-here!\n", _pid);
            S ! v;
    od
}

active proctype check() {
    assert (N >= 0);
}

init {
    byte n = 3;
    run semaphore(n);

    // run check();

    /*bit i;
    for (i: 1..5) {
        run c();
    }/
}

```

## **6 Task 5**

### **6.1 Code**

```

mtype = { p, v }; // P for Wait, V for signal

chan S = [0] of {mtype};

// TODO: Impl chan1
chan C = [5] of {int};

byte N = 0;

proctype semaphore(byte n) {
    N = n;
    do
        :: N > 0 ->
            S ? p;
            N--;
        :: N == 0 ->
            S ? v;
            N++;
    od
}

active[5] proctype c() {
    do
        :: S ! p;
        printf("%d-bien-here!\n", _pid);
        S ! v;
    od
}

active proctype check() {
    assert (N >= 0);
}

init {
    byte n = 3;
    run semaphore(n);

    // run check();

    /*bit i;
    for (i: 1..5) {
        run c();
    }/
}

```