# Deep Contact

### Accelerating Rigid Simulation with Convolutional Networks

J. Wu

Department of Computer Science University of Copenhagen

Master Thesis Defense, 2018

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Deep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Deep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis



### Previous Work

- My first point.
- My second point.

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Deep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis

• Modeling Contact.

- Modeling Contact.
- Second item.

- Modeling Contact.
- Second item.
- Third item.

- Modeling Contact.
- Second item.
- Third item.
- Fourth item.

- Modeling Contact.
- Second item.
- Third item.
- Fourth item.
- Fifth item.

- Modeling Contact.
- Second item.
- Third item.
- Fourth item.
- Fifth item. Extra text in the fifth item.

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Oeep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis

In order to generate accessible data for CNN model, we transform every state into a set of grid images.

• It can make the simulation states be expressed by a set of matrixes, which can be accessible for deep neural networks.

In order to generate accessible data for CNN model, we transform every state into a set of grid images.

• It can make the simulation states be expressed by a set of matrixes, which can be accessible for deep neural networks.

•

Workflow

The whole workflow can be described as,

**9** Based on Smoothed Particle Hydrodynamics(SPH), map current state( $m, v_x, v_y, \omega, n_x$ ) to a image(the number of channel is 5.), which is called feature image.

#### Workflow

The whole workflow can be described as,

- **1** Based on Smoothed Particle Hydrodynamics(SPH), map current state( $m, v_x, v_y, \omega, n_x$ ) to a image(the number of channel is 5.), which is called feature image.
- The feature image will be used as input to a model(created by a convolutional neural network), then one image(the number of channels is 2) will be getting, which can be called label image.

#### Workflow

The whole workflow can be described as,

- **1** Based on Smoothed Particle Hydrodynamics(SPH), map current state( $m, v_x, v_y, \omega, n_x$ ) to a image(the number of channel is 5.), which is called feature image.
- The feature image will be used as input to a model(created by a convolutional neural network), then one image(the number of channels is 2) will be getting, which can be called label image.
- For all contacts positions, interpolated values will be gener- ated based on label image. Then, the values will be used as starting iterate values for contact force solver. In our hypoth- esis, the given starting values will speed up the solver to reach convergence.

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Oeep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis

# Smoothed Particle Hydrodynamics

**Fundamentals** 

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- 3 Deep Learning Model
  - CNN Architecture
  - Training Configuration
- 4 Results and Analysis

# Bilinear Interpolation

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Oeep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis

- Introduction
  - Previous Work
  - Thesis Overview
- Particles-Grid-Particles
  - Grid-Particle Method
  - Smoothed Particle Hydrodynamics
  - Bilinear Interpolation
- Oeep Learning Model
  - CNN Architecture
  - Training Configuration
- Results and Analysis



# **Blocks**

### Block Title

You can also highlight sections of your presentation in a block, with it's own title

#### Theorem

There are separate environments for theorems, examples, definitions and proofs.

### Example

Here is an example of an example block.

# Summary

- The first main message of your talk in one or two lines.
- The second main message of your talk in one or two lines.
- Perhaps a third message, but not more than that.
- Outlook
  - Something you haven't solved.
  - Something else you haven't solved.

# For Further Reading I



A. Author.

Handbook of Everything.

Some Press, 1990.



S. Someone.

On this and that.

Journal of This and That, 2(1):50–100, 2000.