

# CEC2017 method comparison based on empirical runtime distributions

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# Table of contents

## 1 CEC2017 Competition

Evaluation criteria

Results record

## 2 Performance Measures

Empirical runtime distributions

Example

## 3 Results

## CEC2017 bound constrained case

Test functions are minimization problems defined as following:

$$\text{Min } F_P(x), \quad x = [x_1, x_2, \dots, x_D]^D$$

**D:** Dimension = 10,30,50,100 **P:** Problem Number = 1,...,30

**Search range** =  $[-100, 100]^D$  **Budget:** f-evals =  $10000 * D$

**Initialization:** Uniform random initialization within the search space. Random seed is based on time.

**Global Optimum:**  $F_P(x^*) = 100 * P$

## CEC2017 results record

Function error value is defined as:

$$ERR_P = F_P(x^{best}) - F_P(x^*)$$

The accuracy of finding the optimum is  $10^{-8}$ :

$$ERR_P \leq 10^{-8} \implies ERR_P = 0$$

Tuning search method parameters for each problem or dimension is **not allowed**.

**Runs/problem:** 51

**Recorded ERR:** 14 error values are recorded for each problem for each run, after (0.01, 0.02, 0.03, 0.05, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1.0)\* $Budget_D$ .

## ECDF empirical runtime distributions

Runlength-based target quality indicator corresponds to the function  $P$  value to be reached, and is defined as:

$$I_P^t = F_P(x^*) + \Delta I_P^t$$

$$F_P(x^{best}) \leq \Delta I_P^t \leq F_P(x^{worst})$$

$$\frac{\Delta I_P^{t+1}}{\Delta I_P^t} = 10^{0.2}, \quad t \in T_P$$

The ratio between two neighboring  $\Delta I_P$  target precision values is  $10^{0.2}$ . The largest  $\Delta I_P$  value is the error value chosen such that the **worst algorithm** reaches the **first budget step**. Smallest  $\Delta I_P$  value is related to the **best algorithm** error value on the **last budget step**.

**Budget steps:** 14 moments on which error values are reported

ECDF performance assessment: [Link](#)

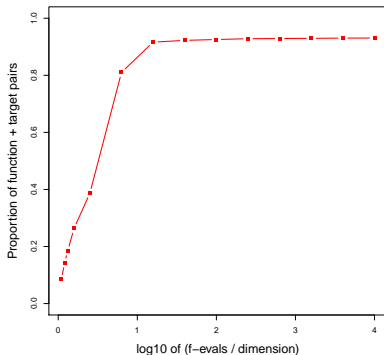
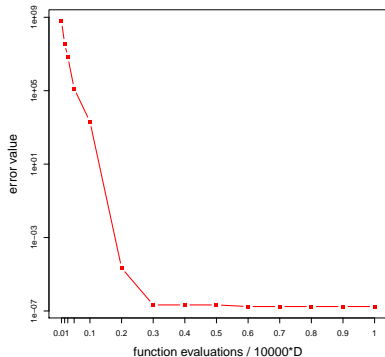
## ECDF empirical runtime distributions

ECDF plot displays the proportion of problems solved within a specified budget, where the budget is given on the x-axis. The y-axis shows the fraction of target quality indicators which have been reached. The fraction is defined as:

$$P_P(b) = \frac{\sum_{t=1}^{|T_P|} [ERR_P(b) \leq I_P^t]}{|T_P|}, \quad b \in \{1, \dots, 14\}$$

The  $P_P(b)$  ratio can be considered as **probability of achieving success** for a given budget  $b$ .

## ECDF plot example

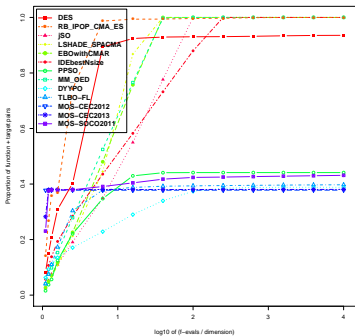


Convergence plot for a single run, ECDF plot aggregated for 51 runs, with 14 budget steps on which error for a single problem:  $P=1$ ,  $N=10$ . values have been reported.

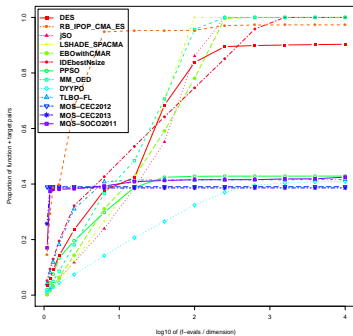
We can see in right plot, for example, that about **90 percent** of the problems were solved within  $10^2 * D = 10^3$  function evaluations.

# CEC2017 Function 1

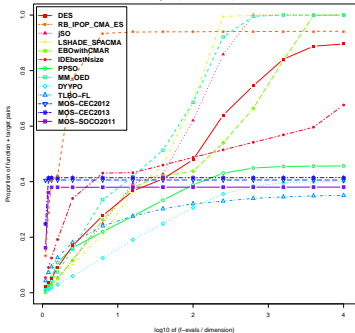
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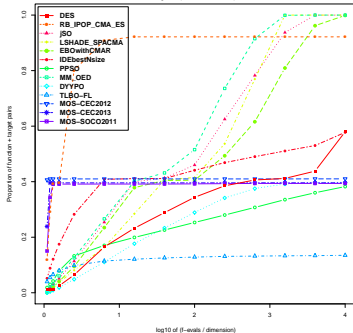
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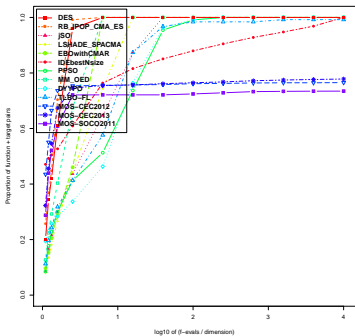
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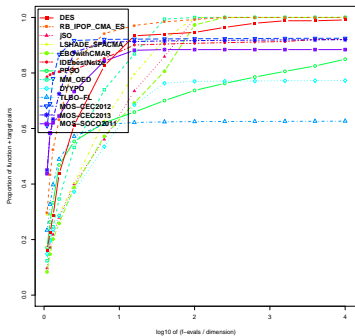


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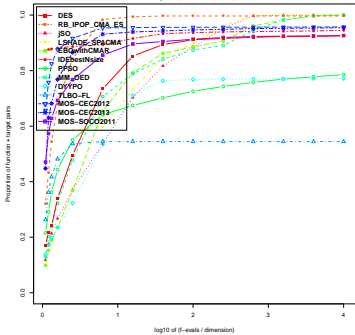
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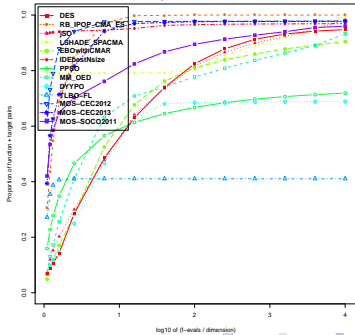
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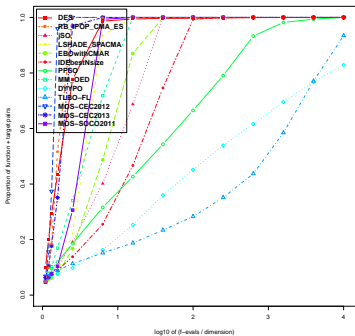


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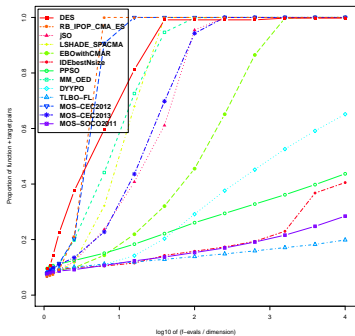


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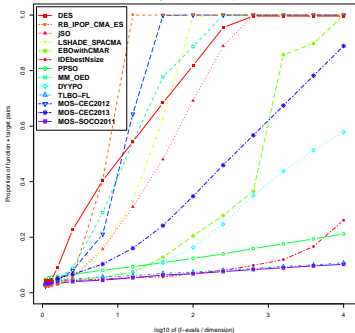
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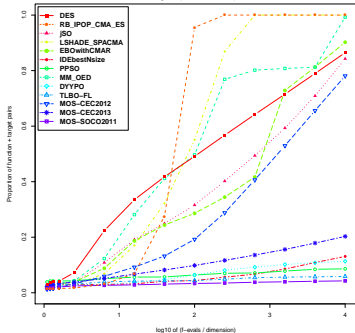
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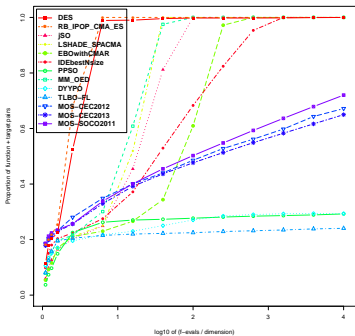


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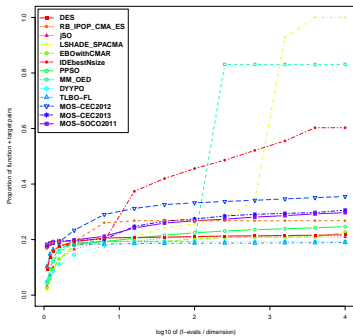


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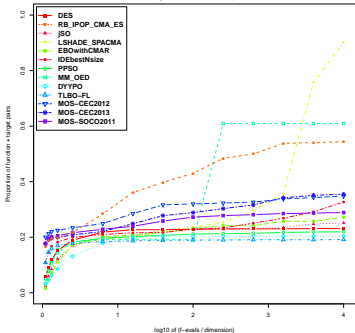
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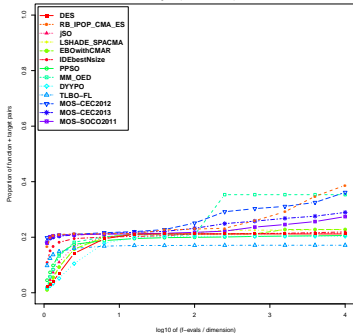
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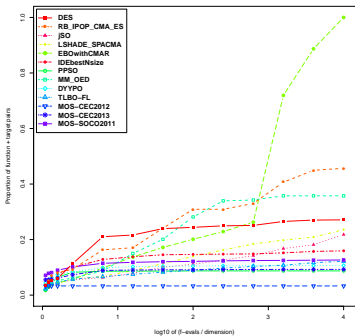


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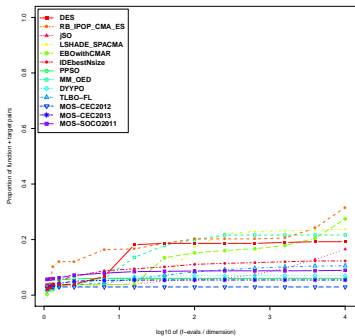


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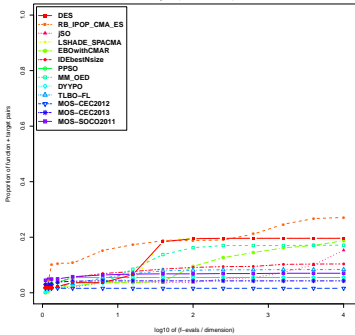
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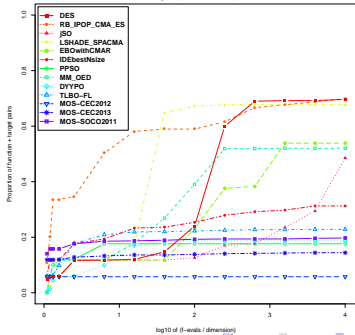
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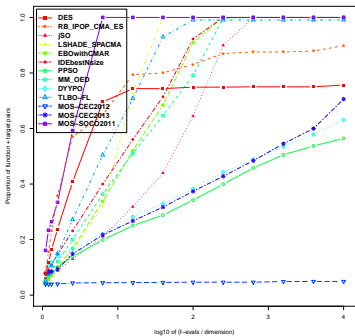


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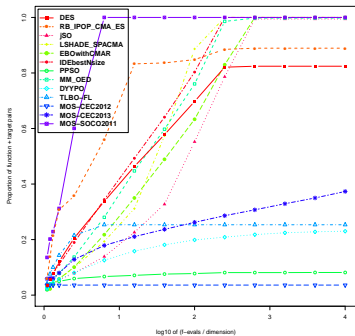


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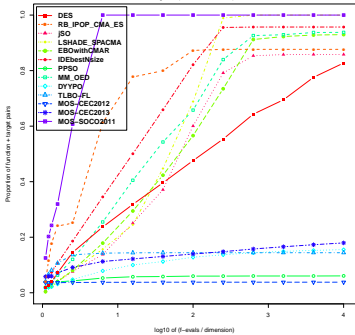
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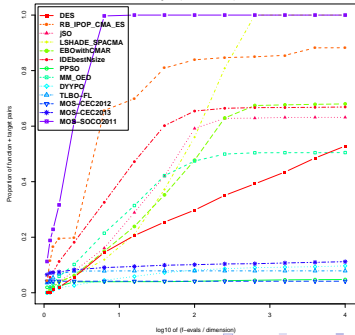
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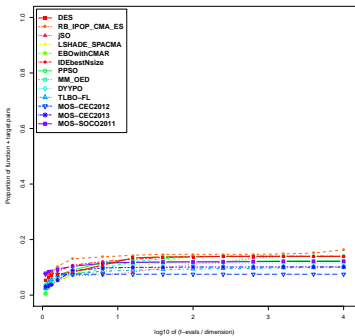


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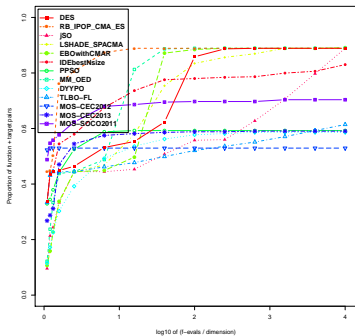


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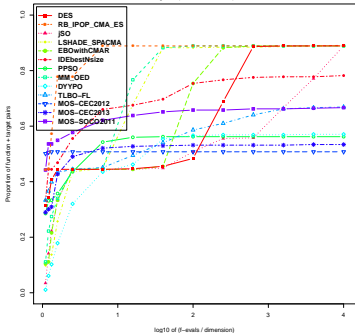
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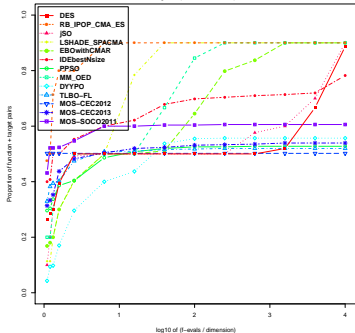
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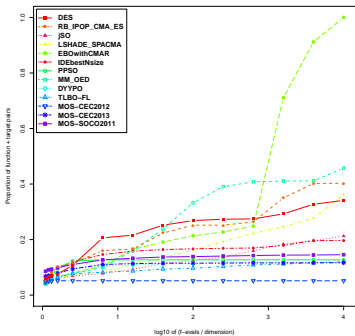


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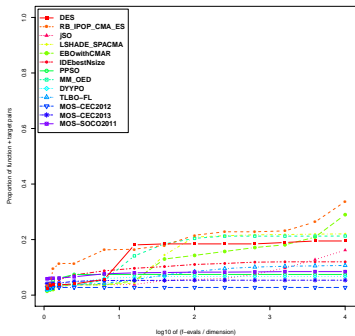


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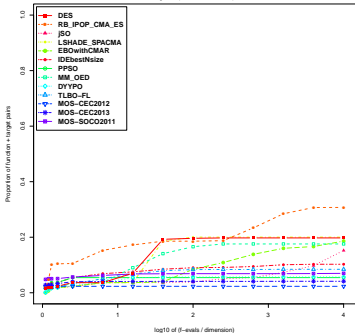
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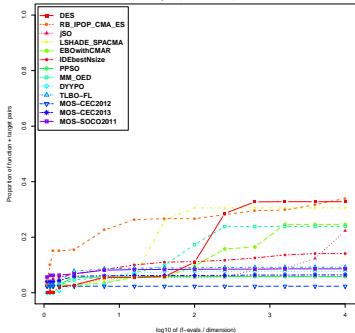
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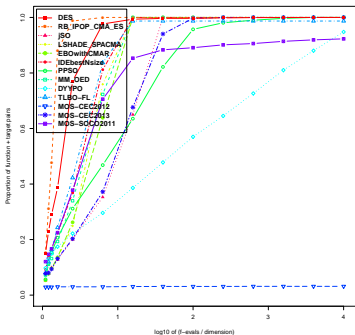


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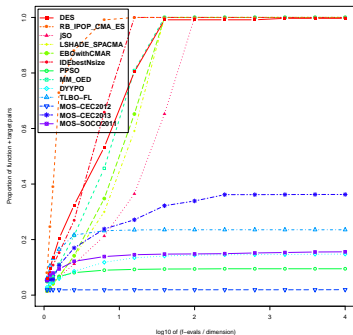


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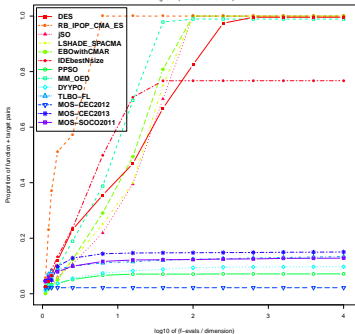
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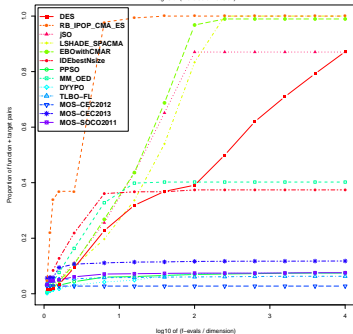
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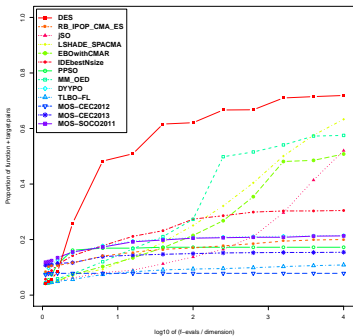
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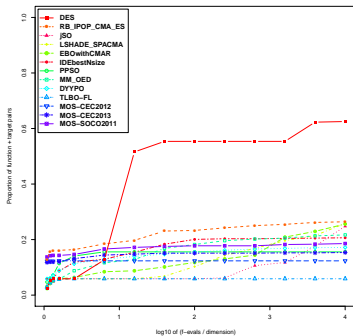


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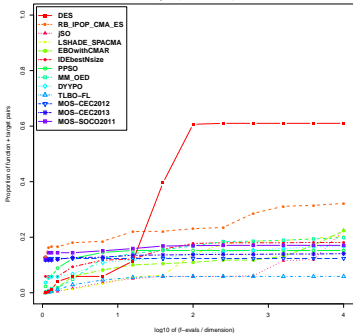
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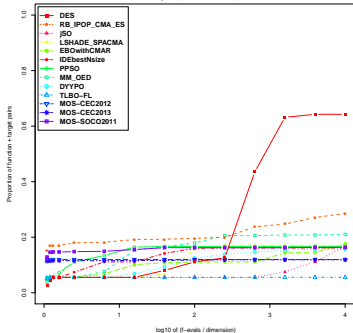
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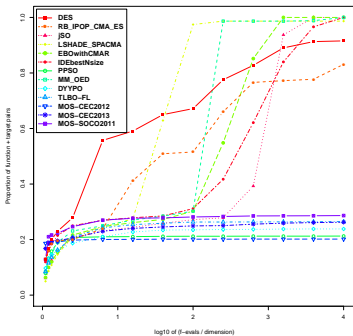


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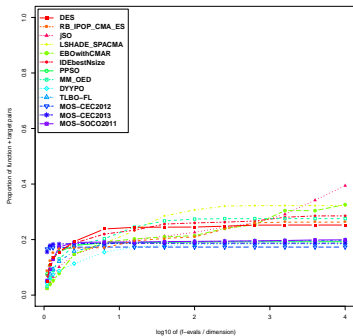


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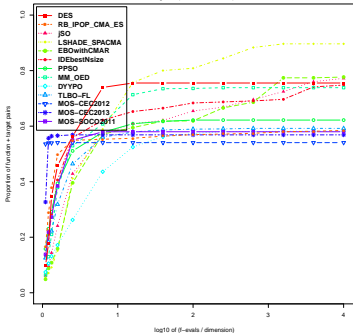
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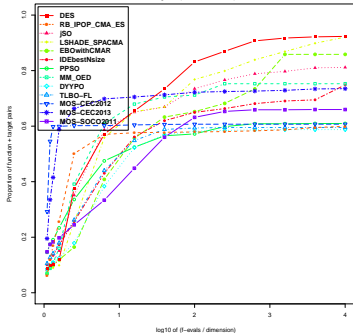
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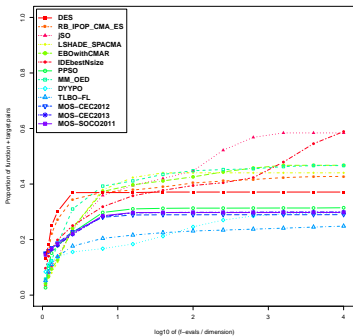


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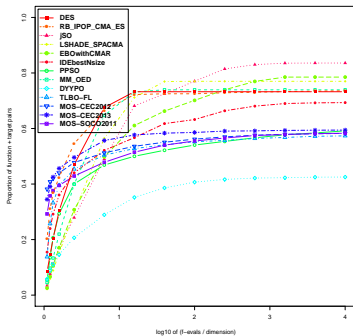


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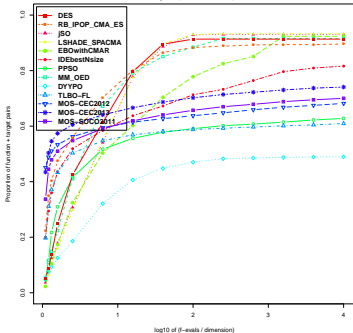
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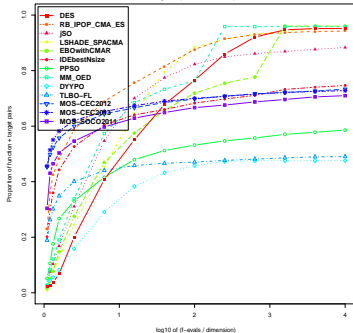
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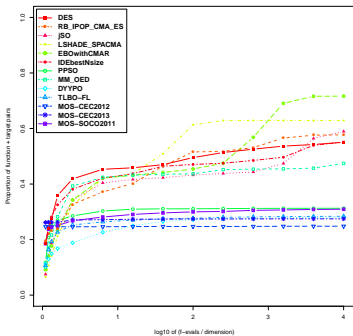


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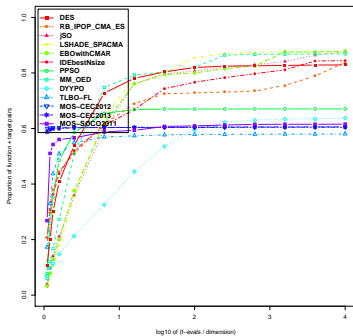


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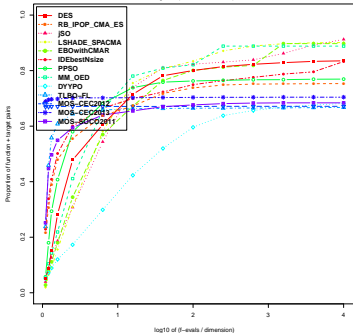
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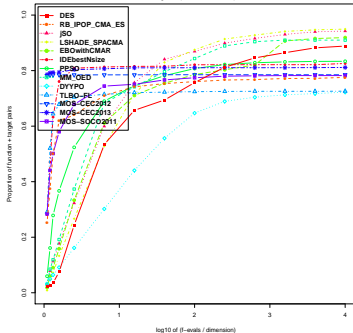
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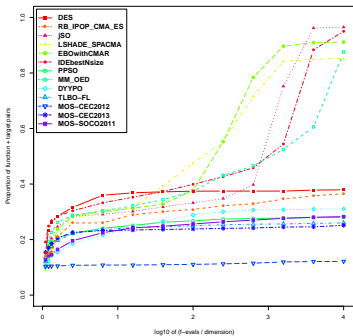


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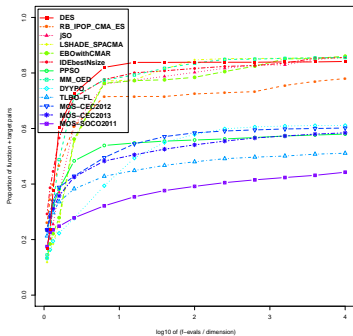


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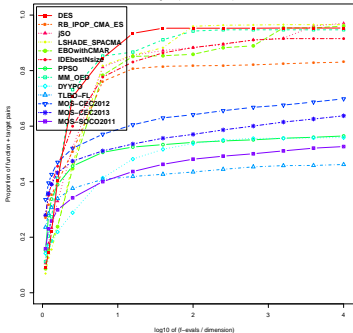
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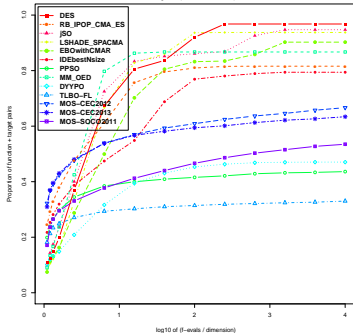
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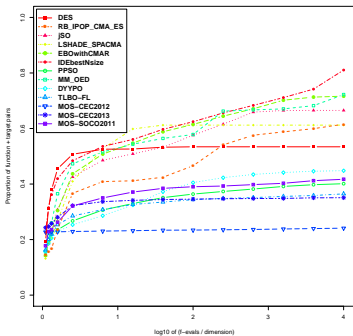


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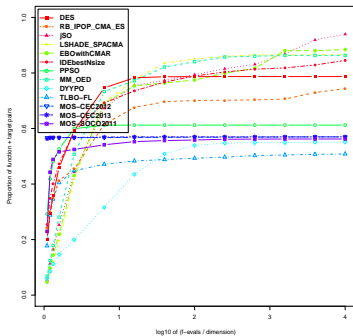


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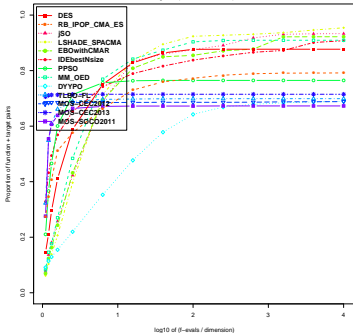
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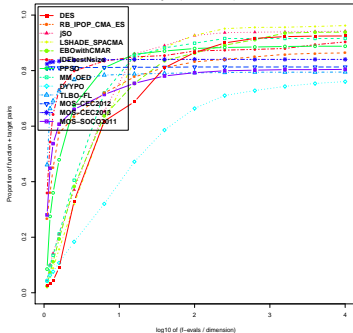
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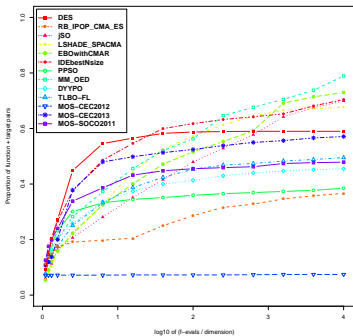


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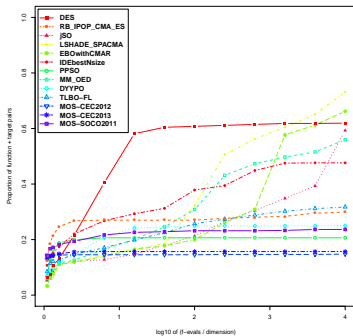


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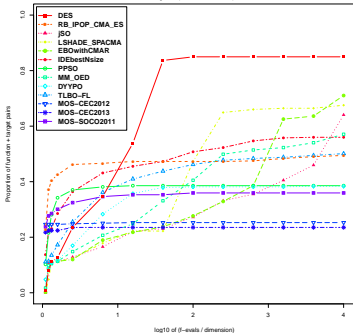
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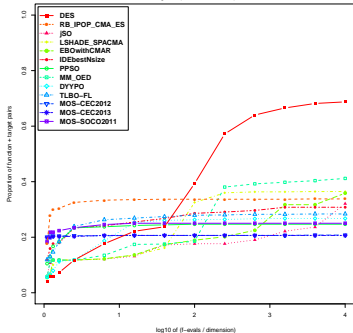
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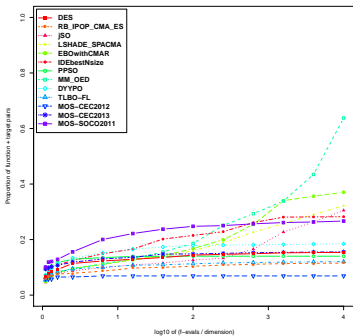


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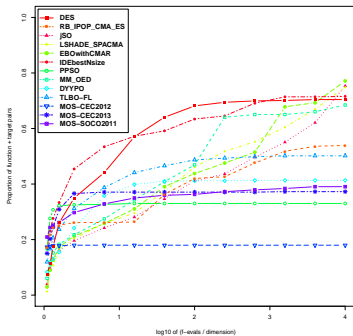


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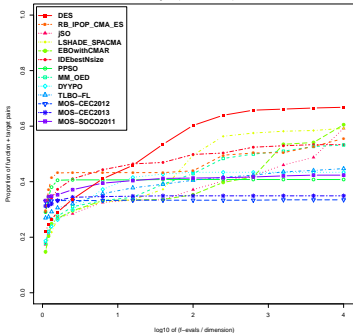
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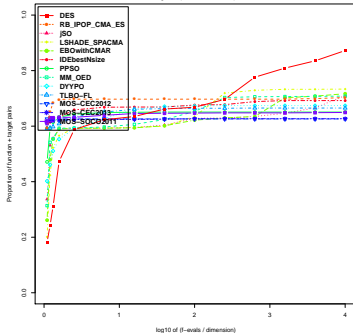
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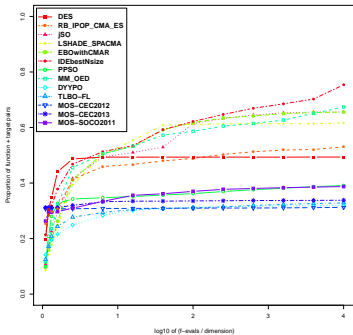
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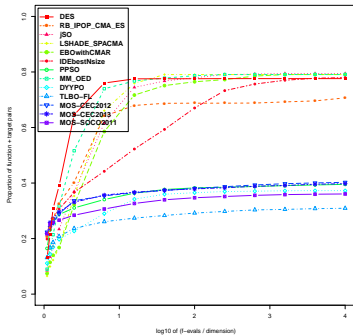


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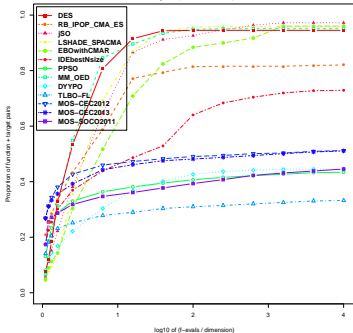
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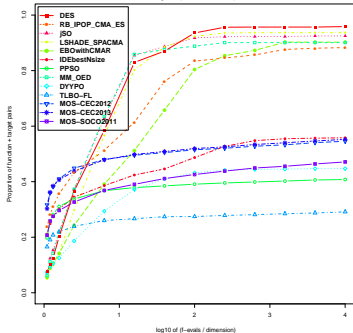
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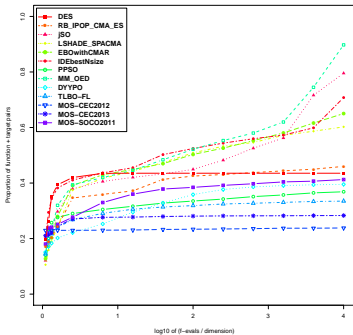


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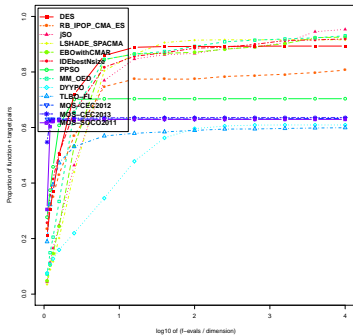


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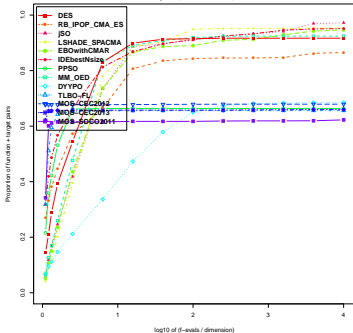
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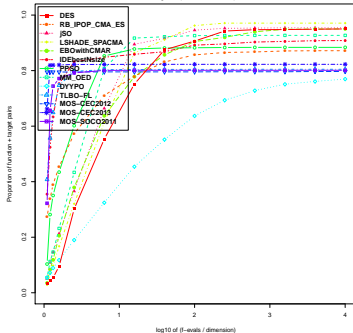
D=30



D=50

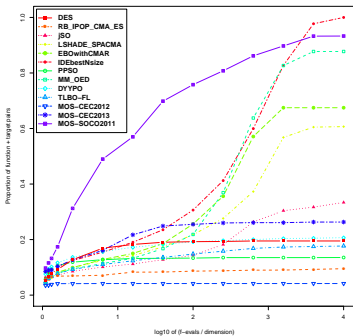


D=100

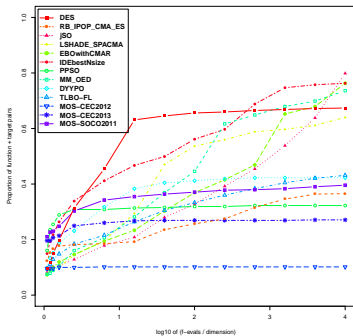


# CEC2017 Function 20

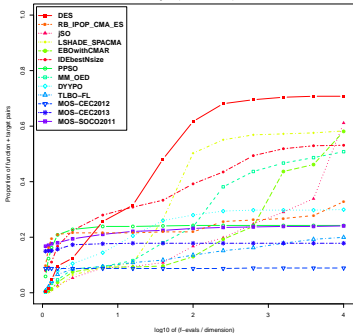
D=10



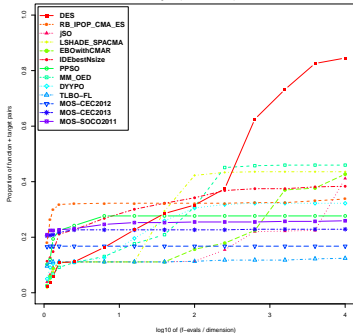
D=30



D=50

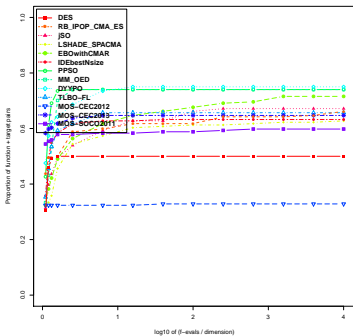


D=100

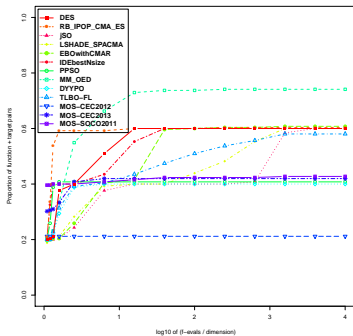


# CEC2017 Function 21

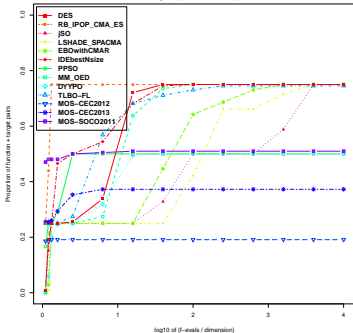
D=10



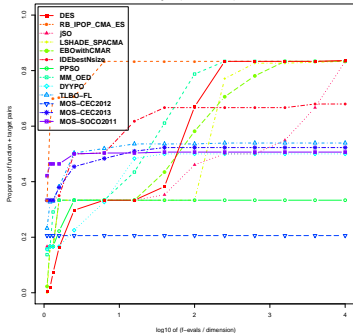
D=30



D=50

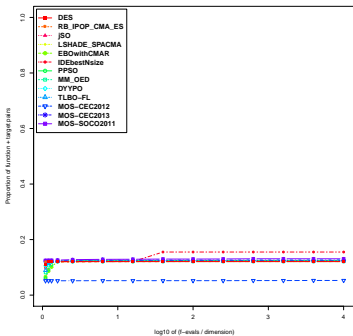


D=100

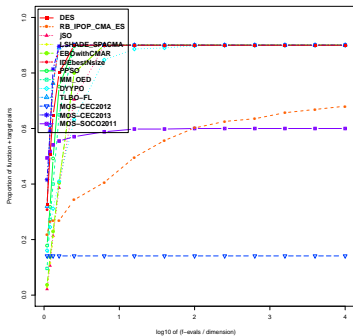


# CEC2017 Function 22

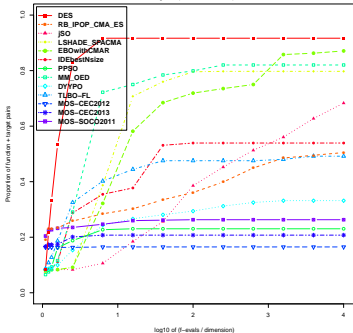
D=10



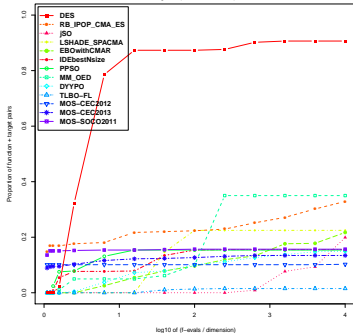
D=30



D=50

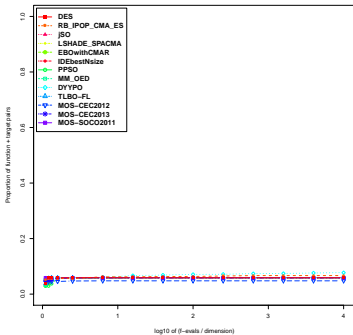


D=100

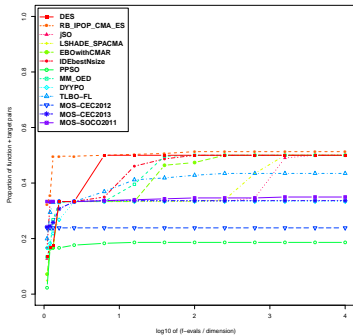


# CEC2017 Function 23

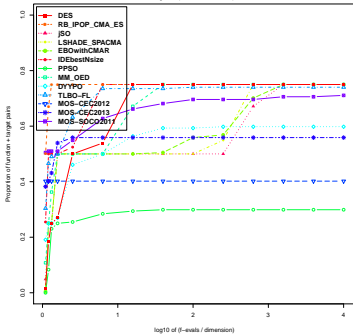
D=10



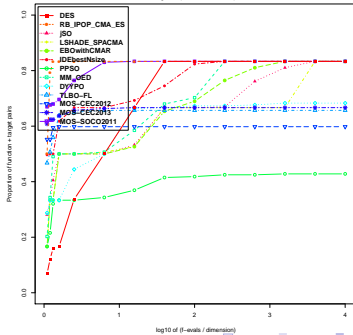
D=30



D=50

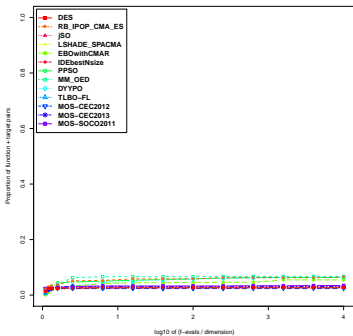


D=100

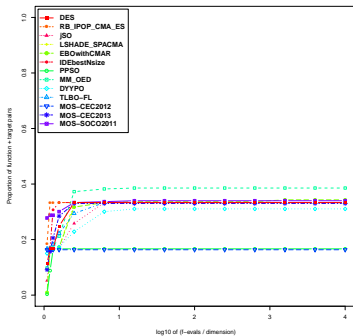


# CEC2017 Function 24

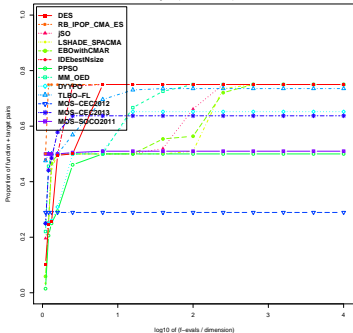
D=10



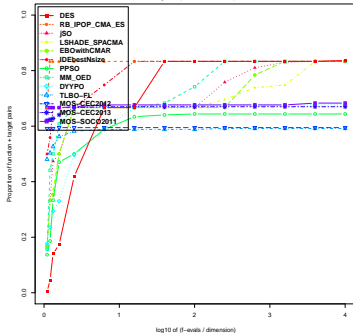
D=30



D=50

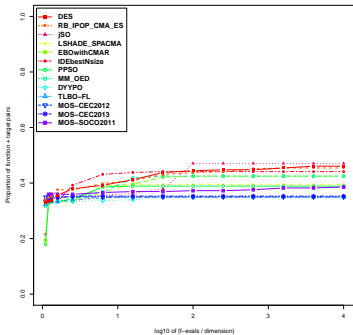


D=100

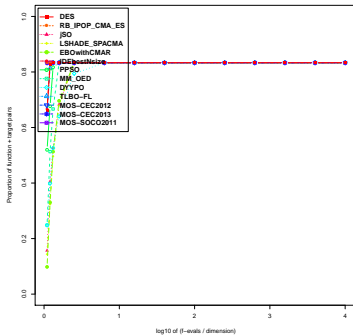


# CEC2017 Function 25

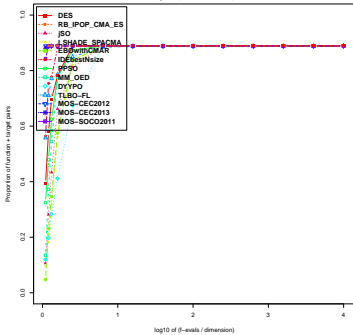
D=10



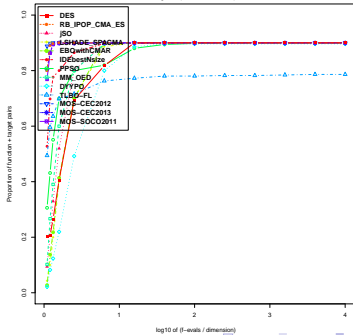
D=30



D=50



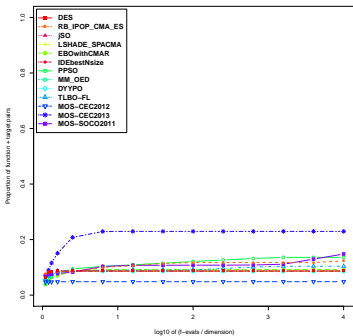
D=100



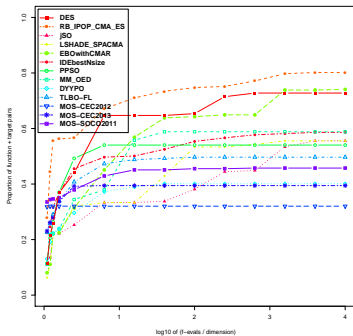


# CEC2017 Function 26

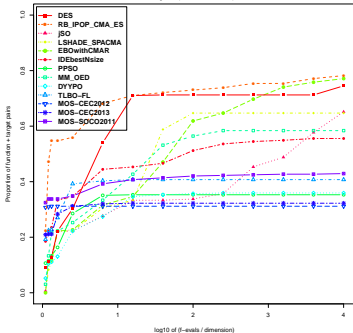
D=10



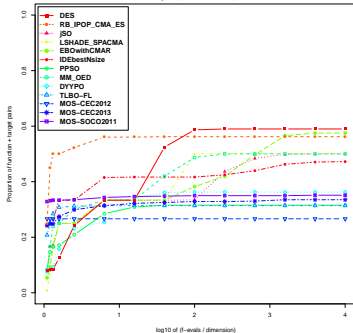
D=30



D=50

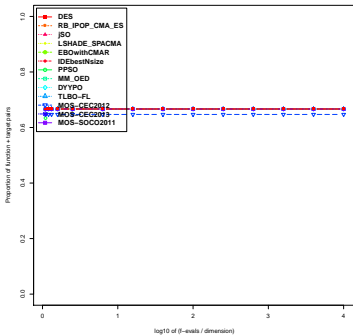


D=100

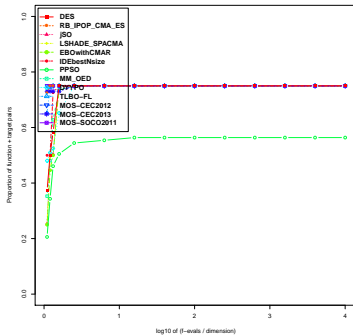


# CEC2017 Function 27

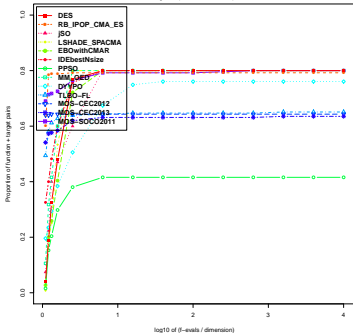
D=10



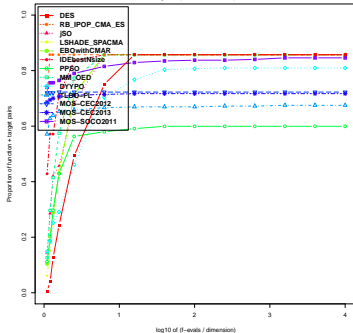
D=30



D=50

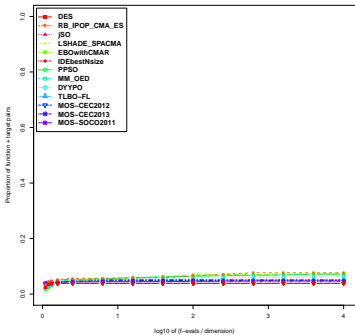


D=100

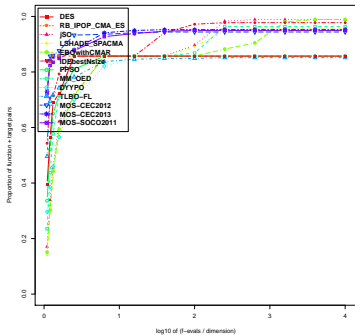


# CEC2017 Function 28

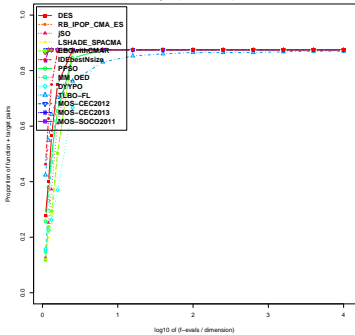
D=10



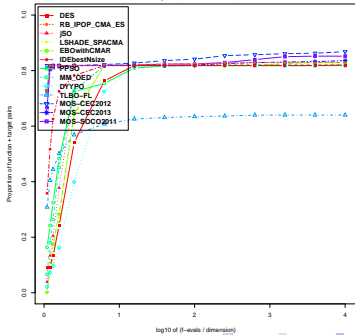
D=30



D=50

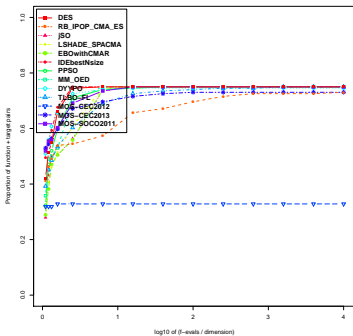


D=100

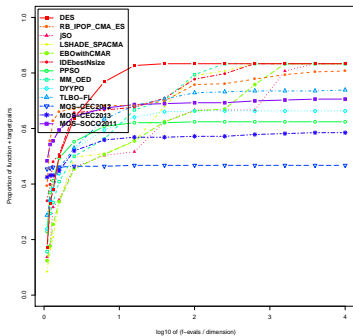


# CEC2017 Function 29

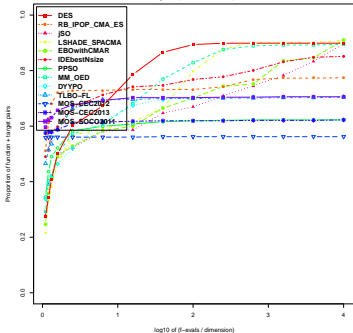
D=10



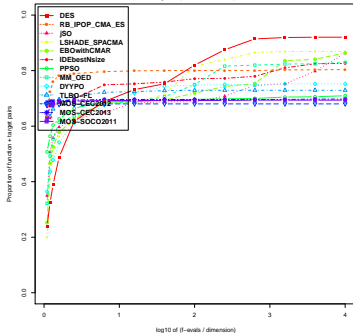
D=30



D=50

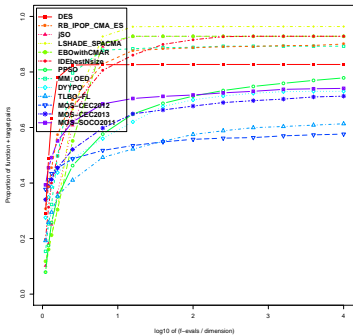


D=100

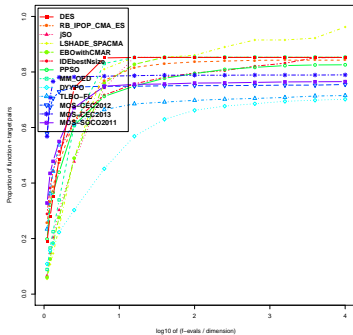


# CEC2017 Function 30

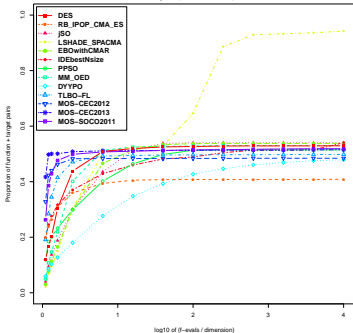
D=10



D=30



D=50



D=100

