Lab Assignment

Imports, Functions and Variables

```
import time
import numpy as np
import scipy.io as sci
import matplotlib.pyplot as plt
import sounddevice as sd
#Variable Declaration
color='g'
#Defining a generic function for plotting
def plot(f_t, t, newGraph=True, figsize=(12.0, 6.0), title='', functionLabel='', xLabel='t', yLabel='f(t)'):
    global color
   if newGraph:
       plt.figure(figsize=figsize)
       color='g'
   #Configure Colour
   if color == 'g' and newGraph==False:
   elif color == 'r' and newGraph==False:
   elif color == 'y' and newGraph==False:
       color='b'
   elif color == 'b' and newGraph==False:
       color='o'
   elif color == 'o' and newGraph==False:
     color='p'
   #Configurable titles/ Labels
   plt.plot(t, f_t, color=color, label=functionLabel)
    if title !=''
       plt.title(title)
   if xLabel !='':
       plt.xlabel(xLabel)
   if yLabel !='':
       plt.ylabel(yLabel)
   plt.grid(True)
   plt.legend()
   plt.tight_layout()
```

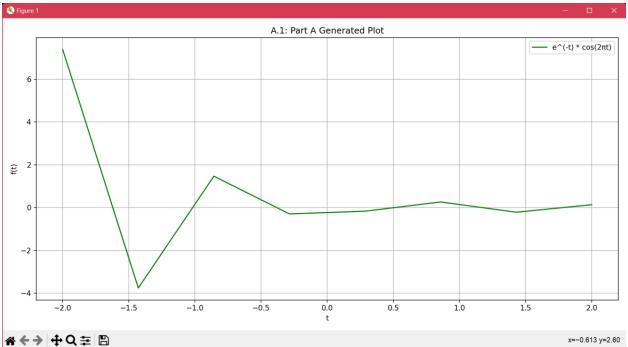
A. Anonymous functions and plotting continuous functions.

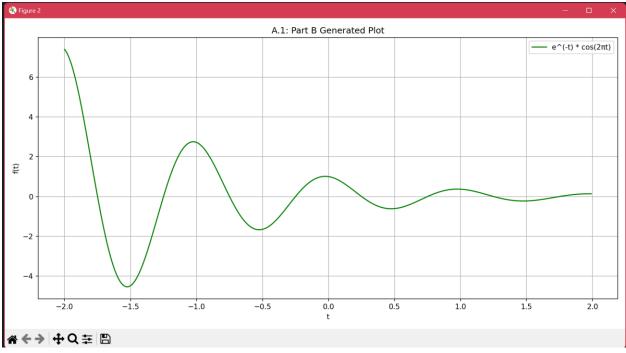
Problem A.1

Code:

```
# Problem A.1:
# Figure 1.46: Plotting f(t) = e^(-t) * cos(2πt)
t = np.linspace(-2, 2, 8)
f_t = np.exp(-t) * np.cos(2 * np.pi * t)
plot(f_t, t, title='A.1: Part A Generated Plot', functionLabel='e^(-t) * cos(2πt)')

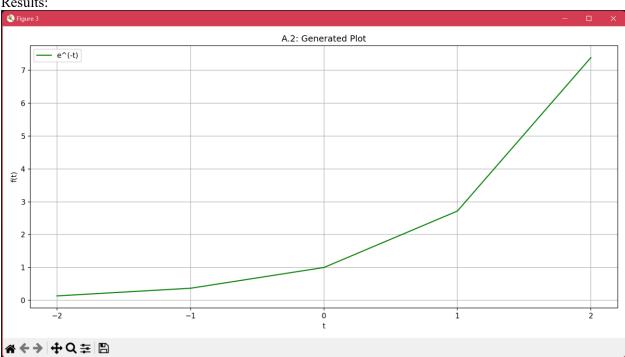
# Figure 1.47: Additional Points
t = np.arange(-2, 2, 0.01)
f_t = np.exp(-t) * np.cos(2 * np.pi * t)
plot(f_t, t, title='A.1: Part B Generated Plot', functionLabel='e^(-t) * cos(2πt)')
```





Code:

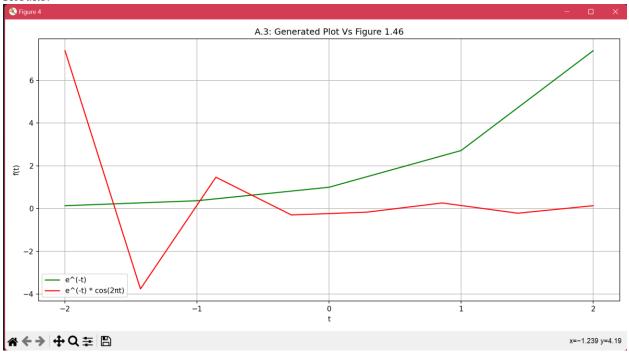
```
# Problem A.2:
t = np.linspace(-2, 2, 5) You, last week • The Start ...
f_t = np.exp(t)
plot(f_t, t, title='A.2: Generated Plot', functionLabel='e^(-t)')
plt.xticks(np.arange(-2, 2.01, 1))
```



Code:

```
# Problem A.3:
# A.2 plot
t = np.linspace(-2, 2, 5)
f_t = np.exp(t)
plot(f_t, t, title='A.3: Generated Plot Vs Figure 1.46', functionLabel='e^(-t)')
plt.xticks(np.arange(-2, 2.01, 1))
# SuperImpose Figure 1.46 from A,1
t = np.linspace(-2, 2, 8)
f_t = np.exp(-t) * np.cos(2 * np.pi * t)
plot(f_t, t,newGraph=False, functionLabel='e^(-t) * cos(2πt)')
```

Results:

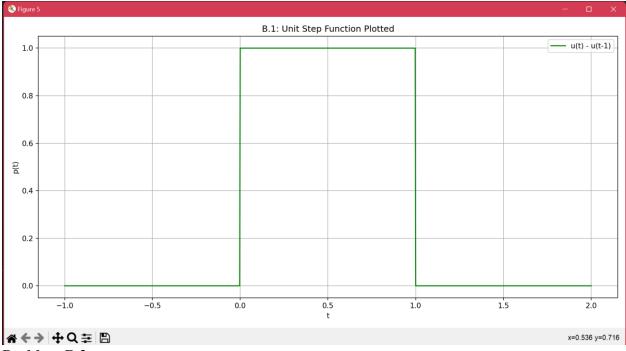


B. Time shifting and time scaling.

• Problem B.1

Code:

```
#Problem B.1:
t = np.linspace(-1, 2, 1000)
p_t = np.heaviside(t, 1) - np.heaviside(t - 1, 1)
plot(p_t, t, title='B.1: Unit Step Function Plotted', functionLabel='u(t) - u(t-1)', yLabel='p(t)')
```



Code:

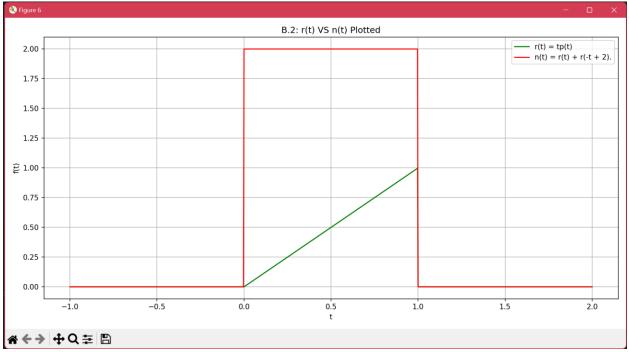
```
#Problem B.2: You, last week * Update lab1main.py ...

def r(t):
    return t * p_t

def n(t):
    return r(t) + r(-t + 2)

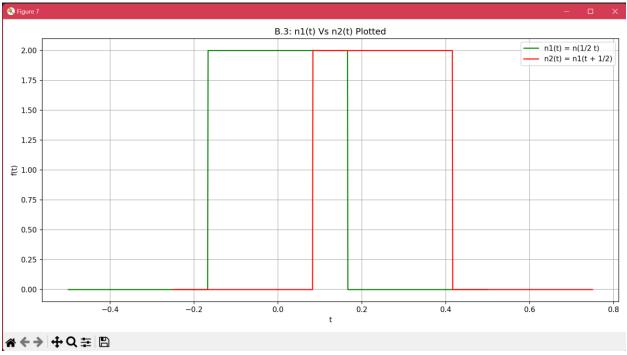
r_t = r(t)
    n_t = n(t)

plot(r_t, t, title='B.2: r(t) VS n(t) Plotted', functionLabel='r(t) = tp(t)', yLabel='r(t)/n(t)')
plot(n_t, t, newGraph=False, functionLabel= 'n(t) = r(t) + r(-t + 2).')
```



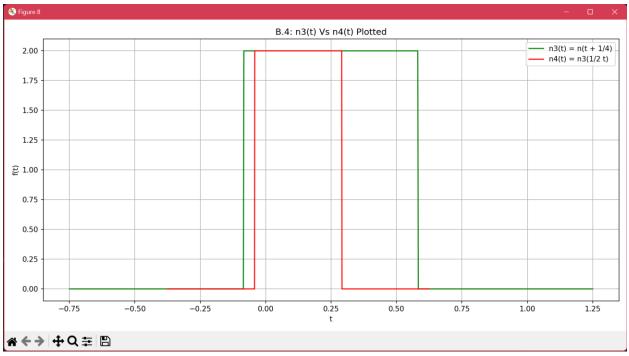
Code:

```
#Problem B.3:
#n1(t)
t = np.linspace(-1, 1, 1000)  # Reduce time values for n1 and n2
t = 0.5*t
n1_t = n(t)
plot(n1_t, t, title='B.3: n1(t) Vs n2(t) Plotted', functionLabel='n1(t) = n(1/2 t)', yLabel='n1(t)/n2(t)')
#n2(t)
t = np.linspace(-1, 1, 1000)
t = 0.5*(t + (1/2))
n2_t = n(t)  # Adjust the time values for n2
plot(n2_t, t, newGraph=False, functionLabel='n2(t) = n1(t + 1/2)')
```



Code:

```
#Problem B.4:
#n3(t)
t = np.linspace(-1, 1, 1000)
t = t+(1/4)
n3_t = n(t)
plot(n3_t, t, title='B.4: n3(t) Vs n4(t) Plotted', functionLabel='n3(t) = n(t + 1/4)', yLabel='n3(t)/n4(t)')
#n4(t)
t = np.linspace(-1, 1, 1000)
t = 1/2*(t + 1/4)
n4_t = n(t)
plot(n4_t, t, newGraph=False, functionLabel='n4(t) = n3(1/2 t)')
```



Code:

```
#Problem B.5:
#n2(t)
t = np.linspace(-1, 1, 1000)
t = 0.5*(t + (1/2))
n2_t = n(t)  # Adjust the time values for n2
plot(n2_t, t, title='B.5: n2(t) Vs n4(t) Plotted', functionLabel='n2(t) = n1(t + 1/2)', yLabel='n2(t)/n4(t)')
#n4(t)
t = np.linspace(-1, 1, 1000)
t = 1/2*(t + 1/4)
n4_t = n(t)
plot(n4_t, t, newGraph=False, functionLabel='n4(t) = n3(1/2 t)')
```

Results:



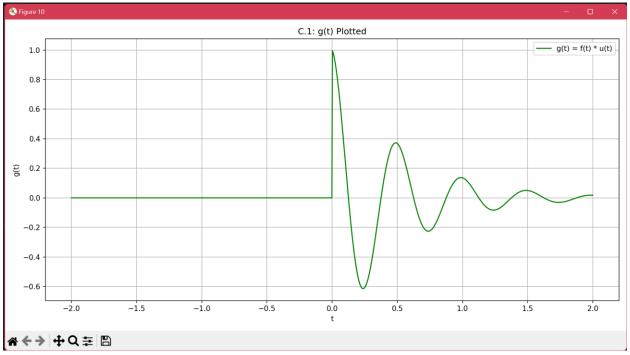
The unit step functions, share all qualities except that they are out of phase with one another.

C. Visualizing operations on the independent variable and algorithm vectorization.

• Problem C.1

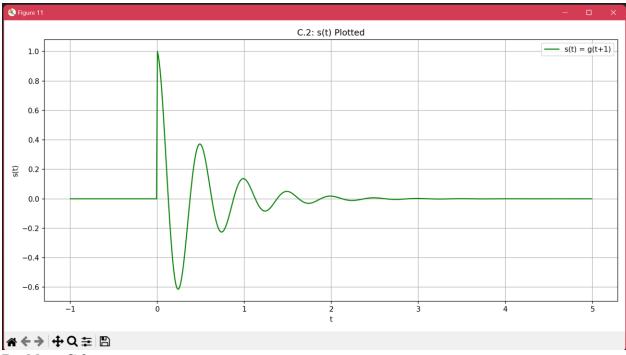
Code:

```
#Problem C.1 : g(t) = u(t) * f(t)
t = np.linspace(-2, 2, 1000)
f_t = np.exp(-2 * t) * np.cos(4 * np.pi * t)
u_t = np.heaviside(t, 1)
g_t = u_t * f_t
plot(g_t, t, title='C.1: g(t) Plotted', functionLabel= "g(t) = f(t) * u(t)", xLabel='t', yLabel='g(t)')
```



Code:

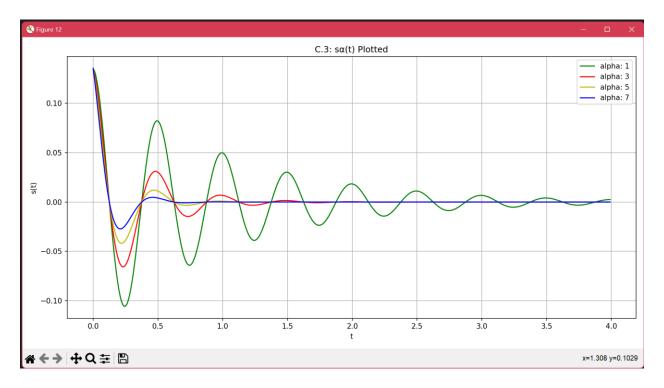
```
#Problem C.2: Plotting s(t)
t = np.arange(-2, 4, 0.01)
t = t + 1
f_t = np.exp(-2 * t) * np.cos(4 * np.pi * t)
u_t = np.heaviside(t, 1)
g_t = u_t * f_t
plot(g_t,t, title='C.2: s(t) Plotted', functionLabel= "s(t) = g(t+1)", xLabel='t', yLabel='s(t)')
```



Code:

```
#Problem C.3: g(t) for different alpha values
t = np.arange(0, 4, 0.01)
u_t = np.heaviside(t, 1)
alpha = [1, 3, 5, 7]

newGraph = True
for i in range(0, 4):
    if(i > 0):
        newGraph = False
    f_t = np.exp(-2) * np.exp(-1 * alpha[i] * t) * np.cos(4 * np.pi * t)
    s_t = f_t * u_t
    functionLabel = "alpha: " + str(alpha[i])
    plot(s_t, t, newGraph=newGraph, title='C.3: sa(t) Plotted', functionLabel= functionLabel , xLabel='t', yLabel='s(t)')
```



D. Array indexing.

```
#Read MATLAB data file
data = sci.loadmat('lab1\ELE532_Lab1_Data.mat')

#Load data
A = data['A']
B = data['B']
x_audio = data['x_audio']
```

• Problem D.1

Code:

```
#Problem D.1 : Modifications to Array A
#(a) A(:)
a = A.flatten()
print("(a) Flattened A to 1D Array:")
print(a)
b_indexes = np.array([1, 3, 6])
b = A.flatten()[b_indexes]
print("\n(b) Extracted elements based on index:")
print(b)
c_mask = A >= 0.2
print("\n(c) Boolean mask for all elements >= 0.2:")
print(c_mask)
\#(d) A([A >= 0.2])
d = A[c_mask]
print("\n(d) Extracted elements where A >= 0.2:")
print(d)
#(e) A([ A >= 0.2 ]) = 0 You, now • Uncommitted changes
A[c_{mask}] = 0
print("\n(e) Setting elements >= 0.2 to 0:")
print(A)
```

```
The Length of the Matrix is 4 Cells
(a) Flattened A to 1D Array:
0.3426 0.7254 1.4897 0.8622 3.5784 -0.0631 1.409 0.3188 2.7694
 0.7147 1.4172]
(b) Extracted elements based on index:
[-1.3077 -0.205 3.0349]
(c) Boolean mask for all elements >= 0.2:
[[ True False False False]
 [ True False True False]
[False True True]
 [ True True False True]
[ True True True]]
(d) Extracted elements where A >= 0.2:
[0.5377 1.8339 3.0349 0.3426 0.7254 1.4897 0.8622 3.5784 1.409 0.3188
2.7694 0.7147 1.4172]
(e) Setting elements >= 0.2 to 0:
[[ 0.
       -1.3077 -1.3499 -0.205 ]
        -0.4336 0.
[ 0.
                    -0.1241]
 [-2.2588 0.
               0.
                       0.
 [ 0.
       0.
               -0.0631 0.
                            ]]
 [ 0.
         0.
               0.
                       0.
```

Code:

```
#Problem D.2
rows, cols = B.shape
#(a) Set values below 0.01 to zero
start = time.time()
for i in range(rows):
    for j in range(cols):
        if abs(B[i, j]) < 0.01:
            B[i, j] = 0
end = time.time()
nestedTime = end - start
#(b) Indexing approach
start = time.time()
B[B < 0.01] = 0
end = time.time()
IndexTime = end - start
#(c) Check execution time
print("\nNested Time: " + str(nestedTime) + "\nIndex Time: " + str(IndexTime) + "\n")
```

Nested Time: 0.020335674285888672 Index Time: 0.0004963874816894531

• Problem D.3

Code:

```
#Problem D.3
#Create a Copy of the data
audio_X = np.copy(x_audio)
#Threshold for compression
threshold = 0.1
#Initialize counter for zero-valued samples
zero_samples = 0
#Nested Loop to iterate through the array and apply the compression
for i in range(len(audio_X)):
    if abs(audio_X[i]) < threshold:</pre>
        audio_X[i] = 0
        zero samples += 1
#Print the number of zero-valued samples
print(f"\nNumber of zero-valued samples: {zero_samples}")
#Play the original audio
sd.play(x_audio, 8000)
sd.wait()
#Play the compressed audio
sd.play(audio X, 8000)
sd.wait()
#EOF CONTENT
#Display all plots
plt.show()
#End of code
```

```
Number of zero-valued samples: 12193
```