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09
CE

Assignment - DAA

Q1. Write linear search pseudocode to search an element in a sorted array with minimum comparisons.

Python \rightarrow Function linear_search_sorted(arr, x):

n = length(arr)

i = 0

while i < n and arr[i] <= x:

if arr[i] == x:

return i

i = i + 1

return -1

Q2. Write Pseudo code for iterative and recursive insertion sort, Insertion sort is called online sorting. why? what about other sorting algorithms that has been discussed in lecture?

Iterative

Function insertion_sort(arr):

n = length(arr)

for i from 1 to n-1:

key = arr[i]

j = i-1

while j >= 0 and arr[j] > key:

arr[j+1] = arr[j]

j = j-1

arr[j+1] = key

return arr

Recursive

Function recursive_insertion_sort(arr, n)

if n <= 1:

return arr

recursive_insertion_sort(arr, n-1)

key = arr[n-1]

j = n-2

while j >= 0 and arr[j] > key:

arr[j+1] = arr[j]

j = j-1

arr[j+1] = key

return arr

Jai Kumar OY C.T
Other sorting algo. that have been discussed in lectures.

- Bubble sort: This algorithm repeatedly compares adjacent elements and swaps them if they are in the wrong order until the entire array is sorted.
- Selection Sort: This algorithm repeatedly selects the minimum element from the unsorted part of the array and swaps it with the first element of the unsorted part until the entire array is sorted.
- Merge sort: This algo divides the array into two halves recursively sort the two halves, and then merge the two sorted halves into a single sorted array.
- Quick sort: This sort algo picks an element as a pivot, partitions the array around the pivot, and then recursively sorts the two subarrays on either side of the pivot.

Q3. Complexity of all the sorting algo. that has been discussed in lecture.

1. Bubble sort

- W-case time complexity: $O(n^2)$
- B-case time complexity: $O(n)$
- Avg-case time complexity: $O(n^2)$
- Space complexity: $O(1)$

2. Selection Sort:

- W-case time complexity: $O(n^2)$
- B-case time complexity: $O(n^2)$
- Avg- time complexity: $O(n^2)$
- Space complexity: $O(1)$

3. Insertion sort:

- W-case time complexity: $O(n^2)$
- B-case time complexity: $O(n)$
- Avg-case time " : $O(n^2)$
- Space complexity: $O(1)$

4. Merge sort:

- W-case time complexity: $O(n \log n)$
- B-case time complexity: $O(n \log n)$
- Avg-case time " : $O(n \log n)$
- Space complexity: $O(n)$

5. Quick sort:

- W-case time complexity: $O(n^2)$
- B-case time " : $O(n \log n)$
- Avg-case time " : $O(n \log n)$
- Space complexity: $O(\log n)$

Jai Kumar

09
CE

Q4. Divide all the sorting algo into inplace/stable/online sorting.

Inplace

- Bubble sort
- Selection Sort
- Insertion sort
- Quick sort

Stable

- Insertion sort
- Merge sort

online

- Insertion sort

Q5. Write recursive/iterative pseudo code for binary search.
What is the time and space complexity of Linear and Binary Search (Recursive and Iterative).

Recursive Binary Search:

Function binarySearch(arr, left, right, x):

if right \geq left:

mid = left + (right - left) / 2

if arr[mid] == x:

return mid

elif arr[mid] > x:

return binarySearch(arr, left, mid - 1, x)

else:

return binarySearch(arr, mid + 1, right, x)

else:

return -1

Iterative Binary Search:

Jai Kumar

09

C E

Function binarySearch(arr, x):

left = 0

right = len(arr) - 1

while left <= right:

mid = left + (right - left) // 2

if arr[mid] == x:

return mid

elif arr[mid] > x:

right = mid - 1

else:

left = mid + 1

return -1

Linear Search

B-case time compl - $O(1)$

W- " " " - $O(n)$

space compl - $O(1)$

Binary

Recursive Binary

B-case time compl - $O(1)$

W- " " " - $O(\log n)$

space compl - $O(\log n)$

Iterative Binary

B-case time - $O(1)$

W- " " " - $O(\log n)$

space compl - $O(1)$

Q8. Which sorting is best for practical uses? Explain?

In general, there is no one-size-fits-all answer to which sorting algo is best for practical uses. However, some sorting algo are commonly used in practices because they have good average-case performance and are easy to implement and understand which includes

Jai Kumar 09 CE

Q6. Write recurrence relation for binary recursive search.

The recurrence relation for binary search is.

$$T(n) = T(n/2) + C$$

$T(n)$ represents the time complexity of searching for an element in an array of n elements using binary recursive search.

$n/2$ represent the size of the subproblem obtained by dividing the input array into two halves.

C represent the constant.

The base case for this recurrence relation is when the size of the subarray becomes 1 i.e., $T(1) = C$.

The recurrence relation can be solved using master Theorem. The master Theorem gives a time complexity of $O(\log n)$. Where n is the number of element in the array.

Q7. Find two indexes such that $A[i] + A[j] = K$ in minimum time complexity.

algo step 1: Initialize an empty hash table.

step 2: For each element $A[i]$ in the array:

a. calculate the diff. $K - A[i]$.

b. If the diff exists in the hash table, return the indices i and j such that $A[i] + A[j] = K$.

c. Otherwise add the current element $A[i]$ to hash table.

step 3: If no such indices are found, return null or an appropriate message indicating that the sum K cannot be obtained from any two elements of the array.

Q9. What do you mean by number of inversions in an array?

Task: Count the number of inversions in an array $arr[]$.

eg $\{7, 21, 31, 8, 10, 20, 6, 4, 5\}$ using merge sort.

(E) In an array of n distinct elements, an inversion is a pair of elements $(arr[i], arr[j])$ such that $i < j$ and $arr[i] > arr[j]$. In other words, it represents how far away an array is from being sorted in ascending order.

Code:

```
function mergeSort(arr, left, right) {
```

```
    if (left > right) {
```

```
        mid = (left + right) / 2
```

```
        inversions = mergeSort(arr, left, mid)
```

```
        inversions += mergeSort(arr, mid + 1, right)
```

```
        inversions += merge(arr, left, mid, right)
```

```
        return inversions
```

```
    } else {
```

```
        return 0
```

```
function merge(arr, left, mid, right) {
```

```
    inversions = 0
```

```
    L = arr[left : mid + 1]
```

```
    R = arr[mid + 1 : right + 1]
```

```
    i = j = 0
```

```
    k = left
```

```
    while i < len(L) and j < len(R) {
```

```
        if L[i] <= R[j] {
```

```
            arr[k] = L[i]
```

```
            i++
```

```
        } else {
```

```
            arr[k] = R[j]
```

```
            j++
```

```
            inversions += (mid - i + 1)
```

```
        } k++
```

```
    } while i < len(L) {
```

```
        arr[k] = L[i]
```

```
        i++
```

```
        k++
```

```
    } while j < len(R) {
```

```
        arr[k] = R[j]
```

```
        j++
```

```
        k++
```

```
    } return inversions
```


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Q10. In which cases Quick sort will give the best and worst case time complexity?

Quick sort has a worst-case time complexity of $O(n^2)$. The worst-case time complexity occurs when the pivot element chosen at each step divides the array into two subarrays of size 0 and $n-1$, respectively. This can happen when the input array is already sorted or when all the elements in the array are the same. In this case, the recursive function calls will have to process $n-1$ elements each time, leading to a worst-case time complexity of $O(n^2)$.

The best-case time occurs when the pivot element chosen at each step divides the array into two subarrays of roughly equal size. In this case, the recursive function calls will have to process two subarrays of size roughly $n/2$ each time, leading to a best-case time complexity of $O(n \log n)$.

Q12. Selection sort is not stable by default but can you write a version of stable selection sort?

The idea behind stable selection sort is to modify the selection sort algorithm such that it always selects the smallest element among the unsorted, but it swaps this smallest element with the left most occurrence of that element in the unsorted part of the array. This ensures that the relative order of equal elements is preserved, making the algorithm stable.

Jai Kumar
09
CE

Stable-selection-sort(A):

```
n = length(A)
for i from 0 to n-2:
    min_idx = i
    for j from i+1 to n-1:
        if A[j] < A[min_idx]:
            min_idx = j
    for k from min_idx down to i+1:
        if A[k] == A[k-1]:
            A[k], A[k-1] = A[k-1], A[k]
        else:
            break
    A[i], A[min_idx] = A[min_idx], A[i]
```

Q13. Bubble sort scans whole array even when array is sorted. Can you modify the bubble sort so that it doesn't scan the whole array once it is sorted.

This optimization is known as the "flagged" or "adaptive" bubble sort algo.

Flagged-bubble-sort(A):

n = length(A)

sorted = False

while not sorted:

sorted = True

for i from 0 to n-2

if A[i] > A[i+1]:

A[i], A[i+1] = A[i+1], A[i]

sorted = False

n -= 1