

Quiz 2 Jaiden Atterbury s#12028502

- (4.) Consider the linear system  $Ax=b$ , where  $A = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & 2 & -1 \end{pmatrix}$  and  $b = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ .  
For the following, show and upload all your work. Show each elimination step for each column.

- (a) compute the LU factorization of A. Is A regular is A invertible?

Step 1: Add row 1 to row 2:

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 2 & -1 \end{pmatrix} \quad L = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Step 2: Add -1 times row 1 to row 3:

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & -2 \end{pmatrix} \quad L = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

Step 3: Add -2 times row 2 to row 3

$$A = U = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -4 \end{pmatrix} \quad L = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 2 & 1 \end{pmatrix}$$

$$\text{thus } A = LU \Rightarrow A = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -4 \end{pmatrix}.$$

Since A can be factored  $A=LU$ , A is thus regular. Furthermore, since A is square and nonsingular, it is thus invertible.

- (b) Use the LU factorization from (a) to solve the linear system by forward/back substitution

Step 1: Let  $c=Ux$  and solve  $Lc=b$  using forward substitution

$$\begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

hence  $c_1 = 1$ ,  $c_2 = 3$ , and  $c_3 = -6$ .

Step 2: Solve  $AX=C$  by back substitution

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ -6 \end{bmatrix}$$

Hence  $x_3 = \frac{-6}{-4} = \frac{3}{2}$ ,  $x_2 = 3 - \frac{3}{2} = \frac{3}{2}$ ,  $x_1 = 1 - \frac{3}{2} = -\frac{1}{2}$ . Hence the solution to the linear system is  $(x_1, x_2, x_3)^T = (-\frac{1}{2}, \frac{3}{2}, \frac{3}{2})^T$ .

(c) compute  $A^{-1}$  by Gauss-Jordan elimination.

Gaussian  $\begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & -4 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1+R_2} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & -4 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-R_1+R_2} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & -4 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-2R_2+R_3} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & -4 & | & -3 & -2 & 1 \end{bmatrix}$

Jordan  $\xrightarrow{\frac{1}{4}R_3} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & \frac{3}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix} \xrightarrow{-R_3+R_2} \begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ 0 & 0 & 1 & | & \frac{3}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix} \xrightarrow{-R_3+R_1} \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{4} & -\frac{1}{2} & \frac{1}{4} \\ 0 & 1 & 0 & | & \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ 0 & 0 & 1 & | & \frac{3}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix}$

thus  $A^{-1} = \begin{bmatrix} \frac{1}{4} & -\frac{1}{2} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ \frac{3}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix}$

(d) Use  $A^{-1}$  from (c) to solve the linear system

If  $AX=b$ , and  $A^{-1}$  exist, then it follows that  $x=A^{-1}b$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{1}{4} & -\frac{1}{2} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ \frac{3}{4} & \frac{1}{2} & -\frac{1}{4} \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{4} - 1 + \frac{1}{4} \\ \frac{1}{4} + 1 - \frac{1}{4} \\ \frac{3}{4} + 1 - \frac{1}{4} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{2} \\ \frac{3}{2} \\ \frac{3}{2} \end{bmatrix}$$

Hence the solution to the linear system is

$$(x_1, x_2, x_3)^T = (-\frac{1}{2}, \frac{3}{2}, \frac{3}{2})^T$$

(e) Which method (LU decomposition or matrix inversion) has a lower flop count? Which method is preferred?

To create an LU decomposition takes  $\sim \frac{2}{3}n^3$  to compute, and  $\sim 2n^2$  per run to solve, while to create a matrix inverse takes  $\sim \frac{4}{3}n^3$  to compute, hence, asymptotically, LU decomposition has a lower flop count. Hence, due to its lower asymptotic flop count and versatility in solving linear systems with changing  $\vec{b}$  vectors, LU decomposition is preferred.