

Homework 5

● Graded

Student

Jaiden Rain Atterbury

Total Points

39 / 40 pts

Question 1

Question 1

10 / 10 pts

✓ - 0 pts Correct, line $y \approx 1.25424x + 0.67797$ found using projection technique, line and points plotted, and the value the line minimizes is ≈ 1.7966 (with work shown at each step!)

Question 2

Question 2

9 / 10 pts

✓ - 1 pt b.iii

- 1 Why?
- 2 This is not correct.
- 3 There's a very short proof using the results from both (iii) and (iv).
- 4 It's not necessary to include this.
- 5 What about the general case?

Question 3

Question 3

10 / 10 pts

✓ - 0 pts correct

- 6 The question is asking what the column space is specifically.

Question 4

Question 4

10 / 10 pts

✓ - 0 pts All parts sufficiently answered (a 2pt, b 5pt, c 3pt)

Question assigned to the following page: [1](#)

Jaiden Atterbury 04/23/2022 Homework 5

(1) Linear Regression

(a) Goal: Find a line $C + Dx = y$ going through 4 points:

$$C + 0D = 0 \quad \text{Point 1}$$

$$C + 1D = 3 \quad \text{Point 2}$$

$$C + 3D = 4 \quad \text{Point 3}$$

$$C + 5D = 7 \quad \text{Point 4}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 4 \\ 7 \end{bmatrix}$$

has no solutions
 $b \notin \text{Col}(A)$

therefore we must solve $A\hat{x} = b_v$ for \hat{x} , where b_v is the orthogonal projection of b on $V = \text{Col}(A)$,

$$\text{Solution: } \hat{x} = \begin{bmatrix} C \\ D \end{bmatrix} = (A^T A)^{-1} A^T b$$

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 5 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 5 \end{bmatrix} \quad A^T A = \begin{bmatrix} 4 & 9 \\ 9 & 35 \end{bmatrix} \quad (A^T A)^{-1} = \begin{bmatrix} 35/59 & -9/59 \\ -9/59 & 4/59 \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} 4 & 9 \\ 9 & 35 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 3 & 5 \end{bmatrix} \begin{bmatrix} 0 \\ 3 \\ 4 \\ 7 \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} 35/59 & -9/59 \\ -9/59 & 4/59 \end{bmatrix} \begin{bmatrix} 14 \\ 50 \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 40/59 \\ 74/59 \end{bmatrix}$$

\therefore Linear regression line is $y = \frac{40}{59} + \frac{74}{59}x$

$$(b) E = \|e\|^2 = e_1^2 + e_2^2 + e_3^2 + e_4^2 \quad \text{where } e = [e_1 \ e_2 \ e_3 \ e_4]^T$$

$$e = b - p$$

$$b = \begin{bmatrix} 0 \\ 3 \\ 4 \\ 7 \end{bmatrix} \quad p = A\hat{x} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 3 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} 40/59 \\ 74/59 \end{bmatrix} = \begin{bmatrix} 40/59 \\ 114/59 \\ 262/59 \\ 410/59 \end{bmatrix}$$

sum of squared errors
 \downarrow

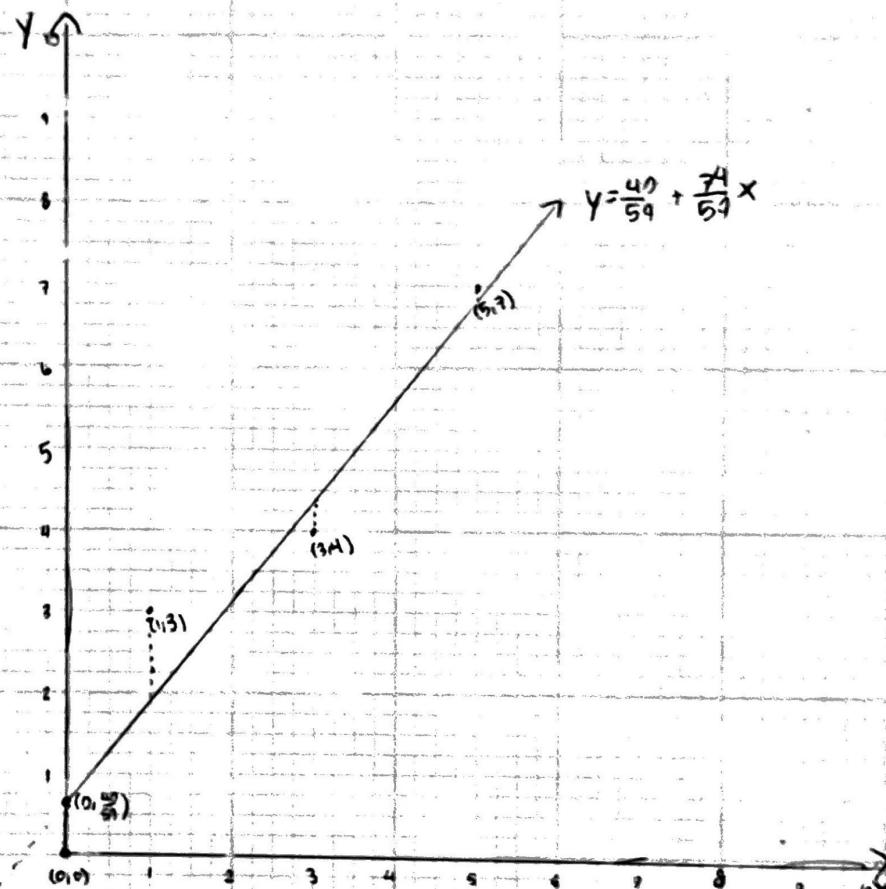
$$e = \begin{bmatrix} 0 \\ 3 \\ 4 \\ 7 \end{bmatrix} - \begin{bmatrix} 40/59 \\ 114/59 \\ 262/59 \\ 410/59 \end{bmatrix} = \begin{bmatrix} -40/59 \\ 63/59 \\ -26/59 \\ 31/59 \end{bmatrix}$$

$$E = \|e\|^2 = \left(\frac{-40}{59}\right)^2 + \left(\frac{63}{59}\right)^2 + \left(\frac{-26}{59}\right)^2 + \left(\frac{31}{59}\right)^2 = \frac{106}{59}$$

Question assigned to the following page: [1](#)

(1) Linear Regression

(a)



Question assigned to the following page: [2](#)

(2) Oblique Projectors

$$(a) P = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$(i) P^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = 0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = P \quad \checkmark$$

$$P = P + 0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$\therefore P$ is a projector

$$(ii) P = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \rightarrow \text{Col}(P) = \text{Span}\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}\}$$

$$P = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \xrightarrow{x_1=0} \text{Null}(P) = \text{Span}\{\begin{bmatrix} 0 \\ 1 \end{bmatrix}\}$$

$$(iii) \vec{x} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

$$P\vec{x} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 2 \end{bmatrix} = 5 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$\vec{x} - P\vec{x} = \begin{bmatrix} 5 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

Picture on separate page

(b)(i) If $\vec{v} \in \text{Col}(P)$

$$\vec{v} = P\vec{w} \quad (\text{linear combination of columns of } P) \quad \text{[CHECK]} \quad \vec{v} \in \text{Col}(P) \text{ since } \vec{v} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and}$$

$$\text{then } P\vec{P}\vec{w} = P^2\vec{w} = P\vec{w} = \vec{v}$$

$$\text{since } \text{Col}(P) = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

$$\therefore P\vec{v} = \vec{v}$$

$$\text{since } P(P\vec{w}) = P\vec{w}$$

$$P^2\vec{w} = P\vec{w}$$

$$P\vec{w} = P\vec{w}$$

$$\vec{v} = \vec{v} \quad \checkmark$$

$$P\vec{v} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \vec{v} \quad \checkmark$$

$$\therefore \text{If } \vec{v} \in \text{Col}(P) \text{ then } P\vec{v} = \vec{v}$$

(ii) for all \vec{v} , then $\vec{v} - P\vec{v} \in \text{Null}(P)$

Proof: for $\vec{v} - P\vec{v}$ to be in $\text{Null}(P)$, $P(\vec{v} - P\vec{v})$ must equal $\vec{0}$:

$$P(\vec{v} - P\vec{v}) = P\vec{v} - P^2\vec{v} = P\vec{v} - P\vec{v} = \vec{0}$$

$$\therefore \vec{v} - P\vec{v} \in \text{Null}(P)$$

Question assigned to the following page: [2](#)

CHECK: $\vec{v} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, $P\vec{v} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, $\vec{v} - P\vec{v} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \vec{0} \in \text{Null}(P)$

Also, $\vec{v} = P\vec{v} + (\vec{v} - P\vec{v})$, if $\vec{v} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$

$$\begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} + (\begin{bmatrix} 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ 2 \end{bmatrix}) = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \checkmark$$

$\therefore P\vec{v}$ is the unique projection/shadow of \vec{v} into $\text{col}(P)$ along $\text{Null}(P)$

(iii) $I-P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \rightarrow$ complementary projector to P

$$(I-P)^2 = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} = I-P$$

$$(I-P) \cdot (I-P) = 1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$\therefore I-P$ is also a projector (since $(I-P)^2 = (I-P)$) 5

(iv) $\text{Col}(I-P) = \text{Null}(P)$

Proof: ① $\vec{v} \in \text{Null}(P)$ then $P\vec{v} = \vec{0}$

$$\text{then } (I-P)\vec{v} = \vec{v} - P\vec{v} = \vec{v} - \vec{0} = \vec{v}$$

since $(I-P)\vec{v} = \vec{v}$, $\vec{v} \in \text{Col}(I-P)$

$$\therefore \text{Null}(P) \subseteq \text{Col}(I-P)$$

② $\vec{w} \in \text{Col}(I-P)$ then $(I-P)\vec{w} = \vec{0}$

$$\text{then } (I-P)\vec{w} = \vec{w} - P\vec{w} = \vec{w} \rightarrow P\vec{w} = \vec{0}$$

since $P\vec{w} = \vec{0}$, $\vec{w} \in \text{Null}(P)$

$$\therefore \text{Col}(I-P) \subseteq \text{Null}(P)$$

Since $\text{Null}(P) \subseteq \text{Col}(I-P)$ & $\text{Col}(I-P) \subseteq \text{Null}(P)$

$$\therefore \text{Col}(I-P) = \text{Null}(P)$$

Question assigned to the following page: [2](#)

$$(V) \text{ Col}(P) = \text{Null}(I-P)$$

Proof: If $\vec{v} \in \text{Col}(P)$ then $P\vec{v} = \vec{v}$

$$\text{then } (I-P)\vec{v} = \vec{v} - P\vec{v} = \vec{v} - \vec{v} = \vec{0}$$

$$\text{since } (I-P)\vec{v} = \vec{0}, \vec{v} \in \text{Null}(I-P)$$

$$\therefore \text{Col}(P) \subseteq \text{Null}(I-P)$$

$$② \vec{x} \in \text{Null}(I-P) \text{ then } (I-P)\vec{x} = \vec{0}$$

$$\text{then if } P = I - (I-P)$$

$$\text{then } P\vec{x} = \vec{x} - (I-P)\vec{x} \rightarrow P\vec{x} = \vec{x}$$

$$\text{also, } (I-P)\vec{x} = \vec{x} - P\vec{x} \Rightarrow P\vec{x} = \vec{x}$$

$$\text{since } P\vec{x} = \vec{x}, \vec{x} \in \text{Col}(P)$$

$$\therefore \text{Null}(I-P) \subseteq \text{Col}(P)$$

$$\text{since } \text{Null}(I-P) \subseteq \text{Col}(P) \text{ and } \text{Col}(P) \subseteq \text{Null}(I-P)$$

$$\therefore \text{Col}(P) = \text{Null}(I-P)$$

3

$$(VII) \text{ Col}(P) \cap \text{Null}(P) = \{\vec{0}\}$$

Assume $\vec{v} \in \text{Col}(P) \cap \text{Null}(P)$

$$\vec{v} \in \text{Col}(P) \rightarrow P\vec{v} = \vec{v}$$

$$\vec{v} \in \text{Null}(P) \rightarrow P\vec{v} = \vec{0}$$

$\therefore \vec{v}$ must be $\vec{0}$ and only the $\vec{0}$

Question assigned to the following page: [2](#)

(vii) By definition 4.4.2 from the Math 208 notes if a set of vectors form a basis for \mathbb{R}^n then there is a way to write any vector \vec{v} as a linear combination of the basis vectors:

$B = \{u_1, \dots, u_n\}$ basis for \mathbb{R}^n then

$$\vec{v} = c_1 u_1 + \dots + c_n u_n$$

Since $\text{Col}(P) \cup \text{Null}(P)$ is linearly independent with n vectors, the union forms a basis for \mathbb{R}^n thus any vector can be written as a unique (because $\text{Col}(P) \cap \text{Null}(P) = \{0\}$) linear combination of vectors in $\text{Col}(P) = E_1$ and $\text{Null}(P) = E_0$

↑ for orthogonal projections

In this question in particular (oblique projection) we can't be sure that $\text{Col}(P) \cap \text{Null}(P)$ forms a basis for \mathbb{R}^n , but we can write \vec{v} uniquely, since $\text{Col}(P) \cap \text{Null}(P) = \{0\}$, as the sum of vectors in $\text{Col}(P)$ and $\text{Null}(P)$:

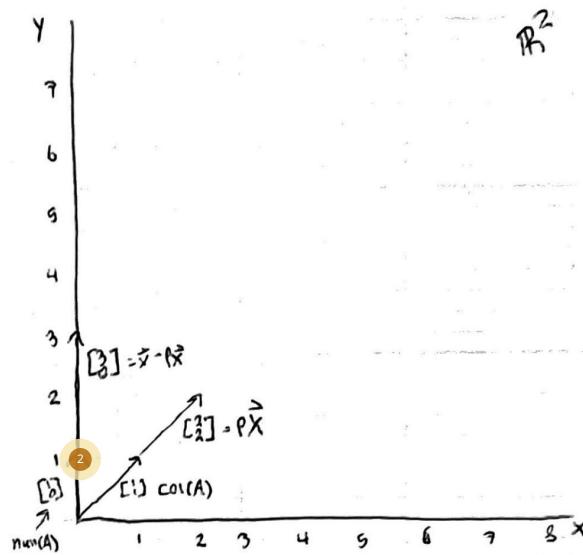
$$\left. \begin{aligned} \vec{v} &= P\vec{v} + (I-P)\vec{v} \\ &\quad \uparrow \quad \uparrow \\ &\quad \text{Col}(P) \quad \text{Null}(P) \end{aligned} \right\} \rightarrow \vec{v} = P\vec{v} + I\vec{v} - P\vec{v} \rightarrow \vec{v} = \vec{J} \vec{v}$$

$$\left[\begin{aligned} P\vec{v} &\in \text{Col}(P) & (I-P)\vec{v} &\in \text{Null}(P) \\ \text{by part (i) and (iv)} \end{aligned} \right]$$

Question assigned to the following page: [2](#)

(2) Oblique Projectors

(a) (ii) and (iii)



\mathbb{R}^2

Question assigned to the following page: [3](#)

(3) Orthogonal Projections

$$(a) P = \frac{1}{10} \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$$

$$(i) P^2 = \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} = \frac{1}{10} \begin{bmatrix} 1/10 \\ 3/10 \end{bmatrix} + \frac{3}{10} \begin{bmatrix} 3/10 \\ 9/10 \end{bmatrix} = \begin{bmatrix} 1/10 \\ 3/10 \end{bmatrix} \rightarrow \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} = P \checkmark$$

$$P = \frac{1}{10} \begin{bmatrix} 1/10 \\ 3/10 \end{bmatrix} + \frac{3}{10} \begin{bmatrix} 3/10 \\ 9/10 \end{bmatrix} = \begin{bmatrix} 3/10 \\ 9/10 \end{bmatrix}$$

$$P^T = \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} = P \checkmark$$

$\therefore P$ is an orthogonal projector.

(ii) Since all results from the previous problem apply, and
 PV the shadow of V under P lives in $\text{Col}(P)$ if $P \in \mathbb{R}^{n \times n}$
 is a projector. Therefore the orthogonal projector projects
 onto the column space of P . 6

$$(iii) P = \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} \sim \begin{bmatrix} 1/10 & 3/10 \\ 0 & 0 \end{bmatrix} \rightarrow \text{Col}(P) = E_1 = \text{Span}\left\{\begin{bmatrix} 1/10 \\ 3/10 \end{bmatrix}\right\} = \text{Span}\left\{\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right\} \text{ (for graph)}$$

$$P = \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} \sim \begin{bmatrix} 1/10 & 3/10 \\ 0 & 0 \end{bmatrix} \xrightarrow{x_2=8/10, x_1=-3/10} \text{Null}(P) = E_2 = \text{Span}\left\{\begin{bmatrix} -3/10 \\ 1/10 \end{bmatrix}\right\} = \text{Span}\left\{\begin{bmatrix} -3 \\ 1 \end{bmatrix}\right\} \text{ (for graph)}$$

$$(iv) P_V = \begin{bmatrix} 1/10 & 3/10 \\ 3/10 & 9/10 \end{bmatrix} \begin{bmatrix} 10 \\ 20 \end{bmatrix} = \begin{bmatrix} 1 & 6 \\ 3 & 18 \end{bmatrix} = \begin{bmatrix} 7 \\ 21 \end{bmatrix} \in \text{Col}(P)$$

$$\vec{v} - P_V \vec{v} = \begin{bmatrix} 10 \\ 20 \end{bmatrix} - \begin{bmatrix} 7 \\ 21 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix} \text{ orthogonal to } P_V / \text{Col}(P)$$

(b)(i) By theorem 4.2.4 for any matrix $P \in \mathbb{R}^{m \times n}$ $\text{Col}(A)^\perp = \text{Null}(A^T)$
 and $\text{Col}(A) = \text{Null}(A^T)^\perp$

BUT since P is symmetric $P^T = P$

Thus $\text{Col}(P) = \text{Null}(P)^\perp$ and $\text{Null}(P) = \text{Col}(P)^\perp$

$\therefore \text{Col}(P)$ and $\text{Null}(P)$ are orthogonal complements

Question assigned to the following page: [3](#)

(ii) If $P = A(A^T A)^{-1} A^T$

$$\begin{aligned} \text{then } A^T &= (A(A^T A)^{-1} A^T)^T \\ &= A((A^T A)^{-1})^T A^T \\ &= A((A^T A)^T)^{-1} A^T \\ &\quad \left. \begin{array}{l} \uparrow \text{ by given fact} \\ \therefore A(A^T A)^{-1} A^T = P \end{array} \right\} P^T = P \end{aligned}$$

$$\begin{aligned} \text{Also } P^2 &= A(A^T A)^{-1} A^T A(A^T A)^{-1} A^T \\ &\quad \left. \begin{array}{l} \uparrow \\ = A(A^T A)^{-1} A^T = P \end{array} \right\} P^2 = P \end{aligned}$$

$\therefore P = A(A^T A)^{-1} A^T$ is an orthogonal projection

(iii) If $P = A(A^T A)^{-1} A^T$ then it projects onto $\text{Col}(A)$ by the proof of proposition 4.3.7 from the lecture notes. Since P is a projector, then for any vector $\vec{v} \in \mathbb{R}^n$, $P\vec{v}$ is the shadow of \vec{v} under P . From the problem description of problem 2 this shadow lives in $\text{Col}(P)$. Since P projects a vector \vec{v} onto $\text{Col}(A)$ and $\text{Col}(P)$, these two subspaces must be the same:

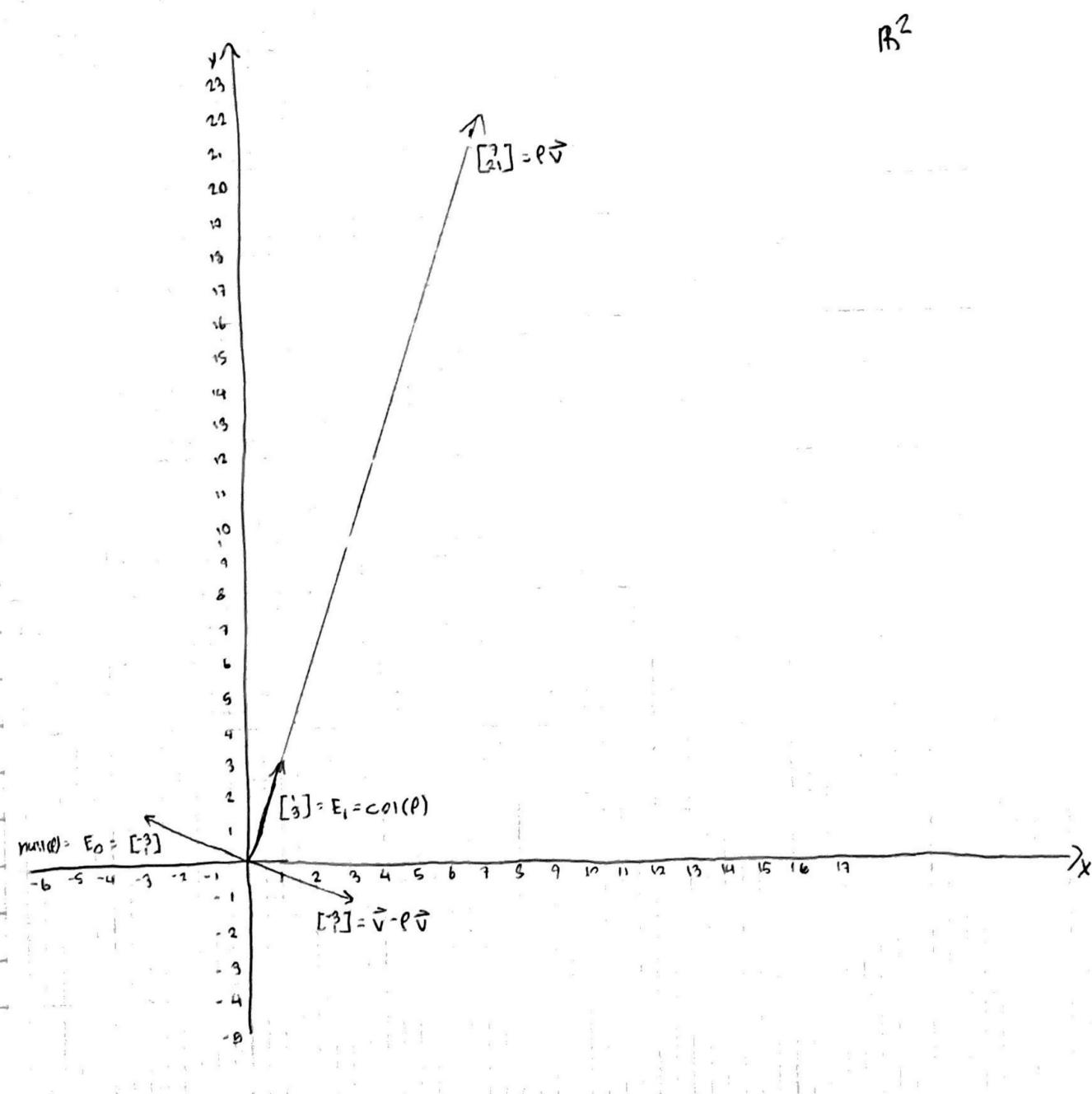
$$\text{Col}(A(A^T A)^{-1} A^T) = \text{Col}(P) = \text{Col}(A)$$

$$\therefore \text{Col}(A) = \text{Col}(A(A^T A)^{-1} A^T)$$

Question assigned to the following page: [3](#)

(3) Orthogonal Projections

Part (iii) and (iv)



Question assigned to the following page: [4](#)

(4) Reflections and Projections

(a) (i) $x+y+z=0 \rightarrow [1 \ 1 \ 1 \ 0]$

$$\text{null}([1 \ 1 \ 1 \ 0]) = \begin{matrix} x_2 = s_1 \\ x_3 = s_2 \\ x_1 = -s_1 - s_2 \end{matrix} \quad \text{null}(A) = \text{basis for } \mathbb{W} = \text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

(ii) $\lambda_1 = 1$ with multiplicity 2. This eigenspace represents the 2D plane $(x+y+z=0)$ that consists of vectors unchanged by the transformation T .

$$E_{\lambda_1} = E_1(T) = \text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$\lambda_2 = -1$ with multiplicity 1. This eigenspace represents the normal line perpendicular to the plane $(x+y+z=0)$. Thus if a vector is perpendicular to the plane it will stay perpendicular, just flipped.

$$E_{\lambda_2} = E_{-1}(T) = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

(iii) $T = A \vec{x}$ $A = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}$ * diagonalizable since Eigenspaces form a basis for \mathbb{R}^3

$$A = \begin{bmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1/\sqrt{3} & 2/\sqrt{3} & -1/\sqrt{3} \\ -1/\sqrt{3} & -1/\sqrt{3} & 2/\sqrt{3} \\ 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix}$$

$$A = \begin{bmatrix} 1/\sqrt{3} & -2/\sqrt{3} & -2/\sqrt{3} \\ -2/\sqrt{3} & 1/\sqrt{3} & -2/\sqrt{3} \\ -2/\sqrt{3} & -2/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & -2 & -2 \\ -2 & 1 & -2 \\ -2 & -2 & 1 \end{bmatrix}$$

Question assigned to the following page: [4](#)

$$(iv) A^2 = \begin{bmatrix} 1/3 & -2/3 & -2/3 \\ -2/3 & 1/3 & -2/3 \\ -2/3 & -2/3 & 1/3 \end{bmatrix} \begin{bmatrix} 1/3 & -2/3 & -2/3 \\ -2/3 & 1/3 & -2/3 \\ -2/3 & -2/3 & 1/3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I \checkmark$$

$$(b) H = I - 2uu^T \in \mathbb{R}^{n \times n} \quad u^Tu = 1$$

(i) If H is symmetric $H = H^T$ H is orthogonal if $H^T H = I$

$$H^T = (I - 2uu^T)^T \quad (\text{since a matrix with orthonormal columns satisfies } Q^T Q = I,$$

$$H^T = I^T - (2uu^T)^T$$

$$H^T = I^T - 2(uu^T)^T \quad \text{when } H \text{ is symmetric } H^T = H, \therefore H^T = I)$$

$$H^T = I - 2uu^T = H \checkmark \quad H^T H = (I - 2uu^T)(I - 2uu^T)$$

$$I - 2uu^T - 2uu^T + 4uu^T uu^T$$

$$I - 4uu^T + 4uu^T uu^T$$

I (since $u^Tu = 1$)

$$I - 4uu^T + 4uu^T$$

$$= I \checkmark$$

$\therefore H$ is both orthonormal/orthogonal and symmetric.

$$(ii) Hu = \lambda u$$

$$Hu = Iu - 2uu^T u$$

$$Hu = Iu - 2u$$

$$Hu = -u$$

$\therefore u$ is an eigenvector of H with $\lambda_u = -1$

Question assigned to the following page: [4](#)

(iii) $\vec{v} \in \mathbb{R}^n$ orthogonal to \vec{u}

$$\Rightarrow \vec{v}^T \vec{u} = 0 \quad \& \quad \vec{u}^T \vec{v} = 0$$

$$H\vec{v} = (\mathbf{I} - 2\vec{u}\vec{u}^T)\vec{v}$$

$$H\vec{v} = \vec{v} - 2\vec{u}\vec{u}^T\vec{v}$$

0 since $\vec{u}^T \vec{v} = 0$

$$H\vec{v} = \vec{v}$$

$\therefore \vec{v}$ is an eigenvector of H with corresponding eigenvalue

$$\lambda_v = 1$$

(iv) $\lambda_v = 1$

$$\text{If } (\mathbf{I} - 2\vec{u}\vec{u}^T)\vec{v} = \vec{v} \quad \text{and} \quad \text{span}\{\vec{u}\} = E_1(H)$$

then $\text{span}\{\vec{v}\} \subseteq E_1(H)$

$$\text{since } (\mathbf{I} - 2\vec{u}\vec{u}^T)\vec{w} = \vec{w}$$

$$\vec{w} - 2\vec{u}\vec{u}^T\vec{w} = \vec{w}$$

$$2\vec{u}\vec{u}^T\vec{w} = \vec{0}$$

This shows that $\text{span}\{\vec{u}\}^\perp = E_1(H)$

multiplicity of $\lambda_v = 1 \rightarrow \dim(\text{span}\{\vec{u}\}^\perp) = E_1(H) = n-1$ (hyperplanes)

multiplicity of $\lambda_u = 1 \rightarrow \dim(\text{span}\{\vec{u}\}) = E_1(H) = 1$ (line)

H is diagonalizable by proposition 6.1.7 which states that for

each eigenvalue of a symmetric matrix H , $\text{AM}(\lambda) = \text{GM}(\lambda)$

which shows H is diagonalizable since the eigenspaces

form a basis for \mathbb{R}^n .

$$H = \left[\underbrace{\begin{matrix} E_{\lambda_4} & E_{\lambda_2} \\ \vdots & \vdots \\ \text{1 vector} & \underbrace{\text{n-1 vectors}} \end{matrix}}_{\text{1 vector}} \right] \left[\underbrace{\begin{matrix} -3 & 1 \text{ time} \\ 1 & \underbrace{\dots}_{\text{n-1 times}} \\ 1 & \vdots \\ 1 & \vdots \end{matrix}}_{\text{D}} \right] \left[\underbrace{\begin{matrix} E_{\lambda_4} & E_{\lambda_2} \\ \text{1 vector} & \underbrace{\text{n-1 vectors}} \end{matrix}}_{\text{1 vector}} \right]^{-1}$$

Question assigned to the following page: [4](#)

(v) Geometrically, H reflects a vector across a plane (hyperplane) that goes through the origin. If a vector is already in the $\text{Span}\{\vec{u}\}^\perp$, it will stay unchanged ($T(v)=v$). If n is orthogonal to the hyperplane, in the $\text{Span}\{\vec{u}\}$, the vector will flip across the plane and remain orthogonal ($T(n)=-n$). Lastly, if neither of these cases are true, a vector will be reflected across the hyperplane.

(vi) Yes, the transformation in part(a) and H are related as they both represent a reflection across a plane (or hyperplane in $n \geq 3$ case).

$$\vec{n} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad \|\vec{n}\| = \sqrt{3}$$

$\therefore \vec{u} = \begin{bmatrix} \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} \end{bmatrix}$ (reflection across plane with unit normal vector \vec{n}).

CHECK $H = UU^T$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 2 \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} -2/3 & -2/3 & -2/3 \\ -2/3 & -2/3 & -2/3 \\ -2/3 & -2/3 & -2/3 \end{bmatrix} = \begin{bmatrix} 1/3 & -2/3 & -2/3 \\ -2/3 & 1/3 & -2/3 \\ -2/3 & -2/3 & 1/3 \end{bmatrix} = T \text{ from part(a)} \checkmark$$

Question assigned to the following page: [4](#)

$$(c) P = I - uu^T \in \mathbb{R}^{n \times n} \quad u^T u = 1$$

$$(i) P = P^2 \quad P^T = (I - uu^T)^T$$

$$P^2 = (I - uu^T)(I - uu^T) \quad = I^T - (uu^T)^T$$

$$= I - uu^T - uu^T + uu^T uu^T \quad = I - uu^T = P$$

$$= I - 2uu^T + uu^T$$

$$= I - uu^T = P.$$

i. P is an orthogonal projector.

(ii) Since P is a projector, the eigenvalues are 0, 1 with corresponding eigenspaces $E_1(P) = \text{Col}(P)$ and $E_0 = \text{Null}(P)$.

If we set $\omega = \text{span}\{u\} \subseteq \mathbb{R}^n$ then

$$P_\omega = u(u^T u)^{-1} u^T \quad \text{with} \quad \text{Col}(P_\omega) = \omega$$

$$P_\omega = uu^T \quad \text{Null}(P_\omega) = \omega^\perp$$

thus $P = I - P_{\text{Null}(P)}$, by question (2)(b)(iv) $I - P$ obliquely projects onto $\text{Null}(P)$

so P orthogonally projects onto $\text{Null}(P_\omega) = \omega^\perp$

$$\therefore \text{Null}(P) = (\omega^\perp)^\perp = \omega$$

Finally this shows

$$E_0 = \text{Null}(P) = \text{span}\{\vec{u}\} = \text{line} = 1 \text{ dimensional}$$

$$E_1 = \text{Col}(P) = \text{span}\{\vec{u}\}^\perp = n \text{-dimensional hyperplane, } n-1 \text{ dimensional.}$$

Question assigned to the following page: [4](#)

(iii) A projector P projects onto $\text{col}(P)$, by problem description for problem 2, thus P projects onto $\text{null}(P)^\perp$ (since P is symmetric).

$\therefore P$ projects onto $\text{span}\{\tilde{u}\}^\perp$

(iv) Geometrically, P projects any vector onto the subspace $\text{span}\{\tilde{u}\}^\perp$. If a vector is already in $\text{span}\{\tilde{u}\}^\perp$ then after applying P it will stay the same. However if a vector is orthogonal to $\text{span}\{\tilde{u}\}^\perp$ (or more simply in the $\text{span}\{\tilde{u}\}$) then after applying P it will be mapped to the zero vector. More formally the orthogonal projection by b is the closest vector to b in $\text{span}\{\tilde{u}\}^\perp$.