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Aim: To implement 2D Transformations: Translation, Scaling, Rotation.

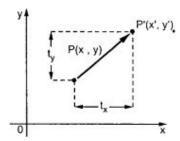
Objective:

To understand the concept of transformation, identify the process of transformation and application of these methods to different object and noting the difference between these transformations.

Theory:

1) Translation –

Translation is defined as moving the object from one position to another position along straight line path. We can move the objects based on translation distances along x and y axis. tx denotestranslation distance along x-axis and ty denotes translation distance along y axis.



Consider (x,y) are old coordinates of a point. Then the new coordinates of that same point (x',y') can be obtained as follows:

$$x' = x + tx$$

$$y' = y + ty$$

We denote translation transformation as P. we express above equations in matrix form as: P' = P + T, where

$$P = \begin{bmatrix} x \\ y \end{bmatrix} \qquad P' = \begin{bmatrix} x' \\ y' \end{bmatrix} \qquad T = \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$

Program:

```
#include<stdio.h>
#include<conio.h>
#include<graphics.h>
#include<math.h>

void main()
{
  int gd =DETECT,gm,ch,sx,sy,tx,ty,nx1,nx2,ny1,ny2;
  double r,t;

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```



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```
initgraph(&gd,&gm,"C:\\TURBOC3\\BGI");
line(100,100,200,100);
printf("Transition ");

printf("enter trans factor \n");
    scanf("%d%d",&tx,&ty);
    nx1=100+tx;
    ny1=100+ty;
    nx2=200+tx;
    ny2=100+ty;
    line(nx1,ny1,nx2,ny2);
    getch();
    closegraph();
}
```

Output -

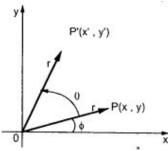


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2) Rotation -

A rotation repositions all points in an object along a circular path in the plane centered at the pivot point. We rotate an object by an angle theta. New coordinates after rotation depend on both x and y.



$$x' = x \cos \theta - y \sin \theta$$

 $y' = x \sin \theta + y \cos \theta$

The above equations can be represented in the matrix form as given below



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```
[x' \ y'] = [x \ y] \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}P' = P \cdot R
```

where R is the rotation matrix and it is given as

$$R = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

Program:

```
#include<stdio.h>
#include<conio.h>
#include<graphics.h>
#include<math.h>
void main()
int gd =DETECT,gm,ch,sx,sy,tx,ty,nx1,nx2,ny1,ny2;
double r,t;
initgraph(&gd,&gm,"C:\\TURBOC3\\BGI");
line(100,100,200,100);
printf("Rotation ");
printf("enter angle");
  scanf("%lf",&r);
  t=(3.14*r)/180;
  nx1 = (int)(100 + (200-100)*cos(t) - (100-100)*sin(t));
  ny1=(int)(100+(200-100)*sin(t)+(100-100)*cos(t));
  line(100,100,nx1,ny1);
  getch();
  closegraph();
```



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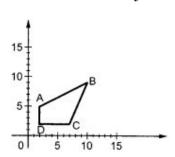
Output:
Rotation enter angle90

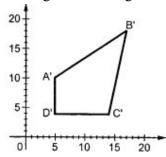
3) Scaling -

scaling refers to changing the size of the object either by increasing or decreasing. We will

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increase or decrease the size of the object based on scaling factors along x and y-axis.





If (x, y) are old coordinates of object, then new coordinates of object after applying scaling transformation are obtained as:

$$x' = x * Sx$$

$$y' = y * Sy$$

Sx and Sy are scaling factors along x-axis and y-axis. we express the above equations in matrix form as:

$$[x' \ y'] = [x \ y] \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix}$$
$$= [x \cdot S_x \quad y \cdot Sy]$$
$$= P \cdot S$$

Program:

```
#include<stdio.h>
#include<conio.h>
#include<graphics.h>
#include<math.h>
void main()
int gd =DETECT,gm,ch,sx,sy,tx,ty,nx1,nx2,ny1,ny2;
double r,t;
initgraph(&gd,&gm,"C:\\TURBOC3\\BGI");
line(100,100,200,100);
printf("Scaling");
printf("enter scaling factor \n");
  scanf("%d%d",&sx,&sy);
  nx1=100+sx;
  ny1=100+sy;
  nx2=200+sx;
  ny2=100+sy;
  line(nx1,ny1,nx2,ny2);
  getch();
  closegraph();
```



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Output -



Conclusion: Comment on:

1. Application of transformation:

2D transformations are fundamental in computer graphics and image processing.

Translation: Used for moving objects within an image or on a screen, such as dragging and dropping icons.

Scaling: Applied for resizing objects, zooming in/out, or adjusting the size of elements.

Rotation: Essential for tasks like rotating images, elements, or shapes.

2. Difference noted between methods:

Translation: Involves changing the coordinates of an object by adding/subtracting values to its x and y coordinates.

Scaling: Adjusts the size of an object by multiplying its coordinates by scale factors.



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Rotation: Rotates objects around a specified point (often the origin) by changing their angles.

3. Application t different object:

Translation: Useful for moving text, images, or any graphical element on a screen.

Scaling: Applied to images, fonts, and icons to control their size.

Rotation: Commonly used for rotating images, graphics, and shapes to achieve desired

orientations

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