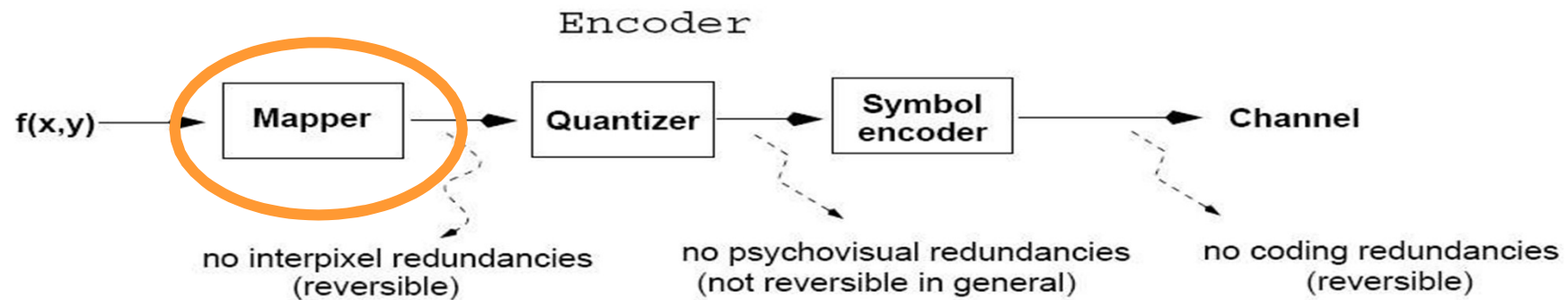


Image Compression Model



-
- **Mapper:** transforms input data in a way that facilitates reduction of interpixel redundancies (spatial and temporal redundancy)
- Example - Run length coding

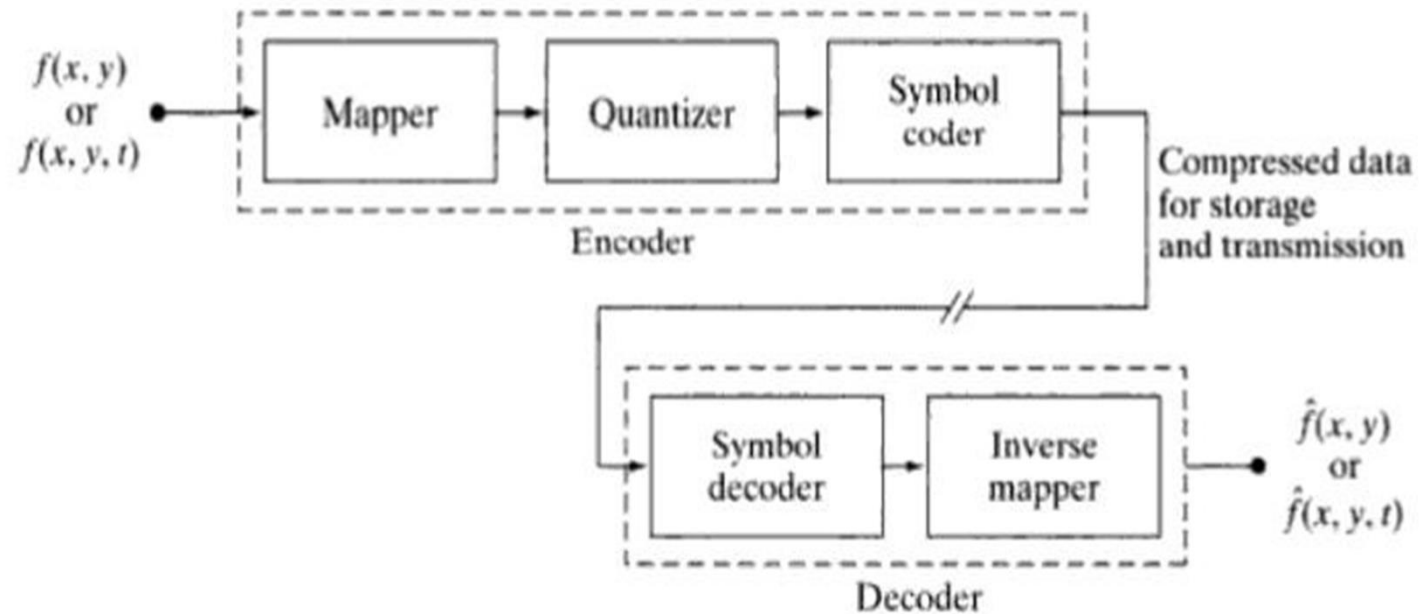
Image Compression Model (cont'd)

- **Quantizer** : the accuracy of the mapper's output in accordance with some pre-established fidelity criteria.
 - The goal is to keep irrelevant information out of the compressed representation.
 - It is irreversible but it must be omitted when error free compression is desired.

Image Compression Model (cont'd)

- **Symbol encoder:** assigns the shortest code to the most frequently occurring output values – thus minimizing coding redundancy.

Image Compression Models (cont'd)

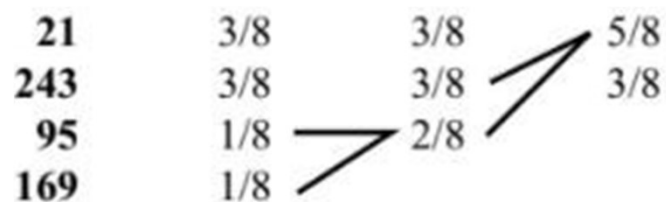


- Inverse operations are performed.

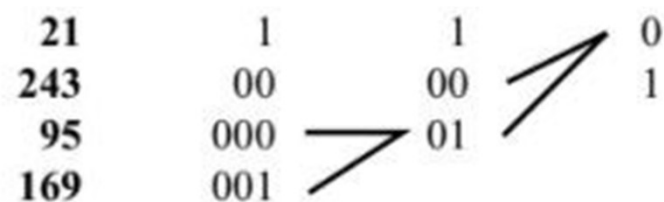
Consider the simple 4×8 , 8-bit image:

21	21	21	95	169	243	243	243
21	21	21	95	169	243	243	243
21	21	21	95	169	243	243	243
21	21	21	95	169	243	243	243

- (b)** Compress the image using Huffman coding.
- (c)** Compute the compression achieved and the effectiveness of the Huffman coding.



Source reductions



Code assignments

(c) Using Eq. (8.1-4), the average number of bits required to represent each pixel in the Huffman coded image (ignoring the storage of the code itself) is

$$L_{avg} = 1 \left(\frac{3}{8} \right) + 2 \left(\frac{3}{8} \right) + 3 \left(\frac{1}{8} \right) + 3 \left(\frac{1}{8} \right) = \frac{15}{8} = 1.875 \text{ bits/pixel.}$$

Thus, the compression achieved is

$$C = \frac{8}{1.875} = 4.27.$$

Because the theoretical compression resulting from the elimination of all coding redundancy is $\frac{8}{1.811} = 4.417$, the Huffman coded image achieves $\frac{4.27}{4.417} \times 100$ or 96.67% of the maximum compression possible through the removal of coding redundancy alone.

Using the previously discussed Huffman decode the encoded string
0101000001010111110100

Original source		
Sym.	Prob.	Code
a_2	0.4	1
a_6	0.3	00
a_1	0.1	011
a_4	0.1	0100
a_3	0.06	01010
a_5	0.04	01011

a3 a6 a6 a2 a5 a2 a2 a2 a4.

Decoding in LZW

Dictionary

0	a
1	b

0 1 2 4 3

000 001 010 011 100

Decoding in LZW

Dictionary

0 a

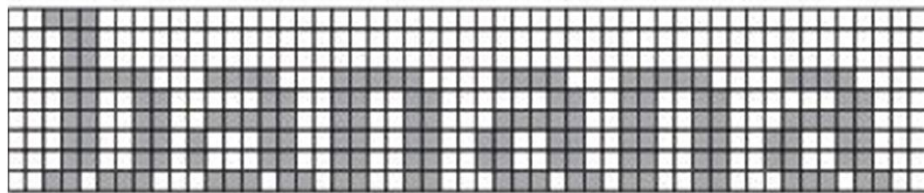
1 b

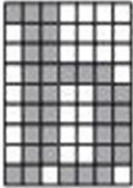
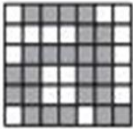
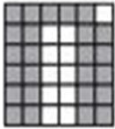
0 1 2 4 3

a b ab aba ba

Symbol-Based Coding

In *symbol-* or *token-based* coding, an image is represented as a collection of frequently occurring sub-images, called *symbols*. Each such symbol is stored in a *symbol dictionary* and the image is coded as a set of triplets $\{(x_1, y_1, t_1), (x_2, y_2, t_2), \dots\}$, where each (x_i, y_i) pair specifies the location of a symbol in the image and *token* t_i is the address of the symbol or sub-image in the dictionary.



Token	Symbol
0	
1	
2	

Triplet
(0, 2, 0) (3, 10, 1) (3, 18, 2) (3, 26, 1) (3, 34, 2) (3, 42, 1)

Compression ratio??

In this case, the starting image has $9 \times 51 \times 1$ or 459 bits and, assuming that each triplet is composed of 3 bytes, the compressed representation has $6 \times 3 \times 8$ $+ [(9 \times 7) + (6 \times 7) + (6 \times 6)]$ or 285 bits; the resulting compression ratio= 1.61

Bit-Plane Coding

The symbol-based technique of the previous section can be applied to images with more than two intensities by processing their bit planes individually. The technique, called bit-plane coding, is based on the concept of decomposing a multilevel (monochrome or color) image into a series of binary images.

The intensities of an m -bit monochrome image can be represented in the form of the base-2 polynomial

$$a_{m-1}2^{m-1} + a_{m-2}2^{m-2} + \dots + a_12^1 + a_02^0$$

Example: display different bits as an individual image

```
>> clear
>> x=imread('cameraman.tif');
>> imshow(x);
>> x=double(x);
>> for k=1:256
    for j=1:256
        if x(k,j)>=128
            x1(k,j)=128;
        else
            x1(k,j)=0;
        end;
    end;
end;
>> figure
>> imshow(x1);
>> y1=imsubtract(x,x1);
>> for k=1:256
    for j=1:256
        if y1(k,j)>=64
            x2(k,j)=64;
        else
            x2(k,j)=0;
        end;
    end;
end;
>> figure
>> imshow(x2)
>> |
```



original

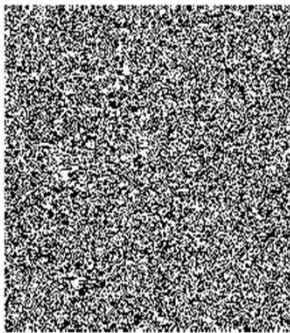


Bit 7

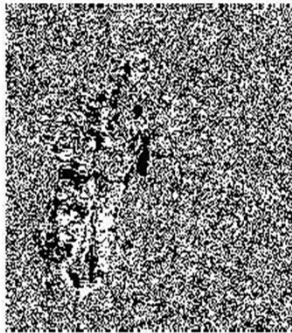


Bit 6

LSB Bit Plane



2nd Bit Plane



3rd Bit Plane



4th Bit Plane



5th Bit Plane



6th Bit Plane



7th Bit Plane



MSB Bit Plane



Bit plane slicing: solution??

127	128	127
128	127	128
127	128	127

0	1	0
1	0	1
0	1	0

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

1	0	1
0	1	0
1	0	1

Gray codes instead of binary!

128 \Rightarrow 10000000 \Rightarrow 11000000

127 \Rightarrow 01111111 \Rightarrow 01000000

$$g_i = a_i \oplus a_{i+1} \quad 0 \leq i \leq m - 2$$
$$g_{m-1} = a_{m-1}$$

Bit plane slicing: solution??

127	128	127
128	127	128
127	128	127

0	1	0
1	0	1
0	1	0

1	1	1
1	1	1
1	1	1

0	0	0
0	0	0
0	0	0

0	0	0
0	0	0
0	0	0

0	0	0
0	0	0
0	0	0

0	0	0
0	0	0
0	0	0

0	0	0
0	0	0
0	0	0

0	0	0
0	0	0
0	0	0



*All
bits*



a_7, g_7



a_6



g_6



a5



g5

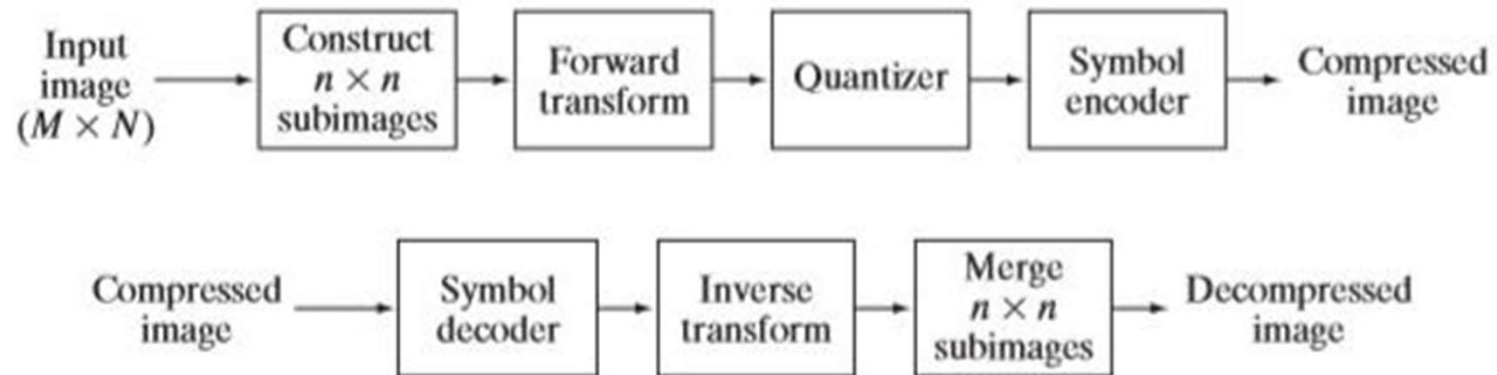


a4



g4

BLOCK TRANSFORM CODING



$g(x, y)$ of size $n \times n$ whose forward, discrete transform, $T(u, v)$, can be expressed in terms of the general relation

$$T(u, v) = \sum_{x=0}^{n-1} \sum_{y=0}^{n-1} g(x, y) r(x, y, u, v) \quad (8.2-10)$$

for $u, v = 0, 1, 2, \dots, n - 1$. Given $T(u, v)$, $g(x, y)$ similarly can be obtained using the generalized inverse discrete transform

$$g(x, y) = \sum_{u=0}^{n-1} \sum_{v=0}^{n-1} T(u, v) s(x, y, u, v) \quad (8.2-11)$$

for $x, y = 0, 1, 2, \dots, n - 1$. In these equations, $r(x, y, u, v)$ and $s(x, y, u, v)$ are called the *forward* and *inverse transformation kernels*, respectively.

Walsh-Hadamard Transform

$$r(x, y, u, v) = \frac{1}{n} (-1)^{\sum_{i=0}^{m-1} b_i(x)p_i(u) + b_i(y)p_i(v)}$$

$$\begin{aligned} p_0(u) &= b_{m-1}(u) \\ p_1(u) &= b_{m-1}(u) + b_{m-2}(u) \\ p_2(u) &= b_{m-2}(u) + b_{m-3}(u) \\ &\vdots \\ p_{m-1}(u) &= b_1(u) + b_0(u) \end{aligned}$$

$$N=4=2^m \rightarrow m=2$$

$$x, y = 0, 1, 2, 3$$

$$u, v = 0, 0$$

Walsh-Hadamard Transform

$$r(x, y, u, v) = \frac{1}{n} (-1)^{\sum_{i=0}^{m-1} b_i(x)p_i(u) + b_i(y)p_i(v)}$$

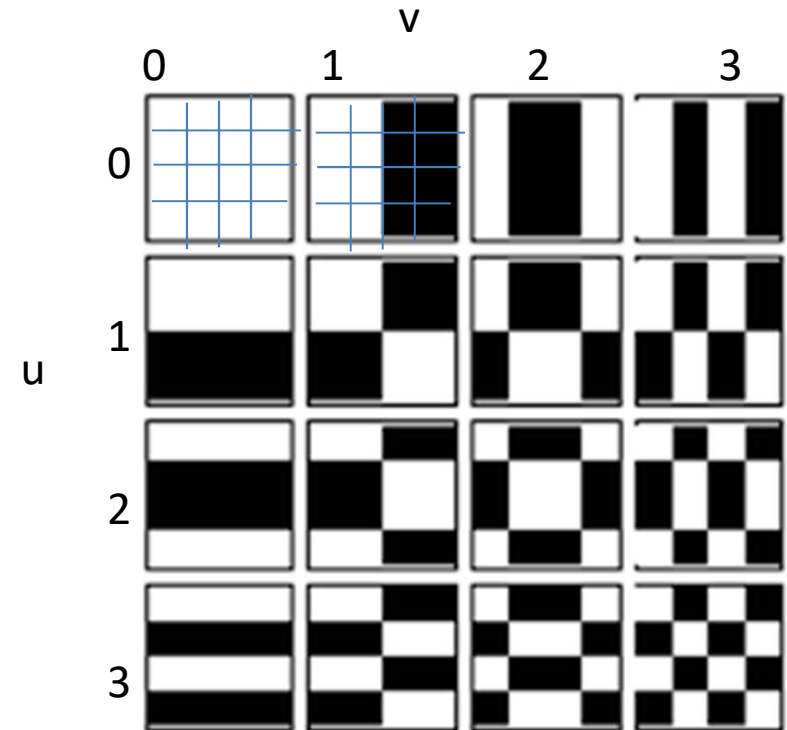
$$R(0,0,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(0,1,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(0,2,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(0,3,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$\begin{aligned} p_0(u) &= b_{m-1}(u) \\ p_1(u) &= b_{m-1}(u) + b_{m-2}(u) \\ p_2(u) &= b_{m-2}(u) + b_{m-3}(u) \\ &\vdots \\ p_{m-1}(u) &= b_1(u) + b_0(u) \end{aligned}$$



$$N=4=2^m \rightarrow m=2$$

$$x, y = 0, 1, 2, 3$$

$$u, v = 0, 0$$

Walsh-Hadamard Transform

$$r(x, y, u, v) = \frac{1}{n} (-1)^{\sum_{i=0}^{m-1} b_i(x)p_i(u) + b_i(y)p_i(v)}$$

$$R(1,0,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(1,1,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(1,2,0,0) = (1/4)(-1)^0 \rightarrow 1$$

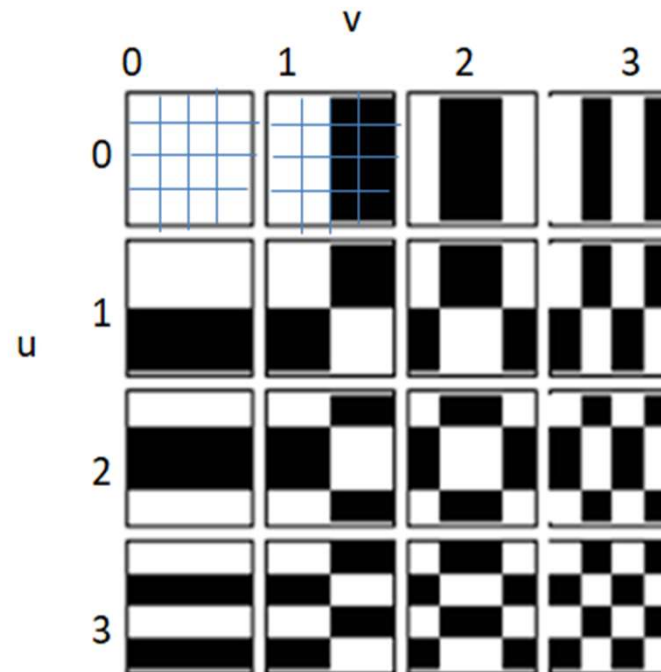
$$R(1,3,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,0,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,1,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,2,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,3,0,0) = (1/4)(-1)^0 \rightarrow 1$$



$$\begin{aligned} p_0(u) &= b_{m-1}(u) \\ p_1(u) &= b_{m-1}(u) + b_{m-2}(u) \\ p_2(u) &= b_{m-2}(u) + b_{m-3}(u) \\ &\vdots \\ p_{m-1}(u) &= b_1(u) + b_0(u) \end{aligned}$$

$$R(3,0,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(3,1,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(3,2,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$R(3,3,0,0) = (1/4)(-1)^0 \rightarrow 1$$

$$N=4=2^m \rightarrow m=2$$

Walsh-Hadamard Transform

$$x, y = 0, 1, 2, 3$$

$$u, v = 0, 1$$

$$r(x, y, u, v) = \frac{1}{n} (-1)^{\sum_{i=0}^{m-1} b_i(x)p_i(u) + b_i(y)p_i(v)}$$

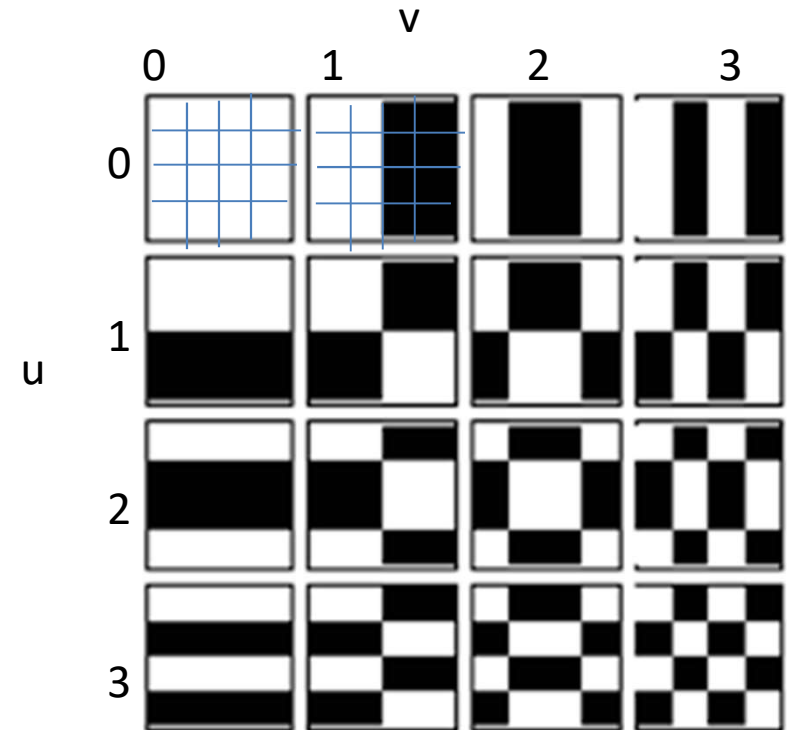
$$R(0,0,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(0,1,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(0,2,0,1) = (1/4)(-1)^1 \rightarrow -1$$

$$R(0,3,0,1) = (1/4)(-1)^1 \rightarrow -1$$

$$\begin{aligned} p_0(u) &= b_{m-1}(u) \\ p_1(u) &= b_{m-1}(u) + b_{m-2}(u) \\ p_2(u) &= b_{m-2}(u) + b_{m-3}(u) \\ &\vdots \\ p_{m-1}(u) &= b_1(u) + b_0(u) \end{aligned}$$



$$N=4=2^m \rightarrow m=2$$

$$x, y = 0, 1, 2, 3$$

$$u, v = 0, 1$$

Walsh-Hadamard Transform

$$r(x, y, u, v) = \frac{1}{n} (-1)^{\sum_{i=0}^{m-1} b_i(x)p_i(u) + b_i(y)p_i(v)}$$

$$R(1,0,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(1,1,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(1,2,0,1) = (1/4)(-1)^1 \rightarrow -1$$

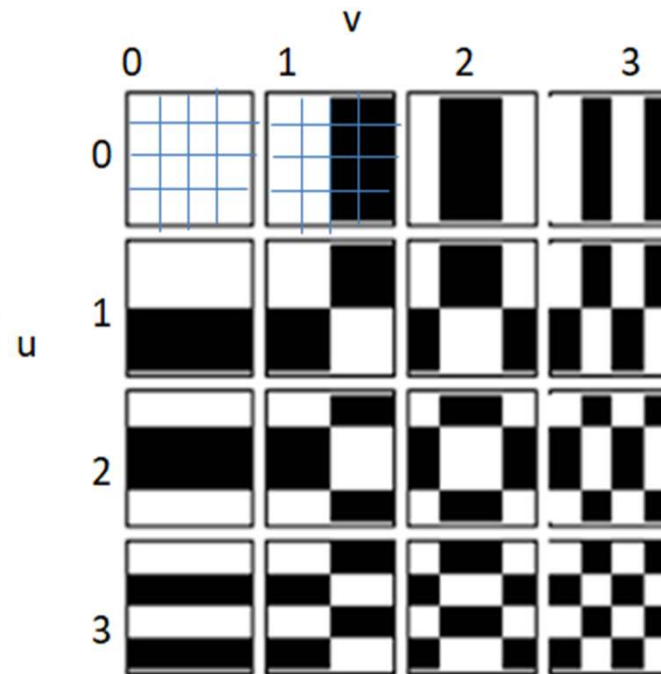
$$R(1,3,0,1) = (1/4)(-1)^1 \rightarrow -1$$

$$R(2,0,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,1,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(2,2,0,1) = (1/4)(-1)^1 \rightarrow -1$$

$$R(2,3,0,1) = (1/4)(-1)^1 \rightarrow -1$$



$$p_0(u) = b_{m-1}(u)$$

$$p_1(u) = b_{m-1}(u) + b_{m-2}(u)$$

$$p_2(u) = b_{m-2}(u) + b_{m-3}(u)$$

$$\vdots$$

$$p_{m-1}(u) = b_1(u) + b_0(u)$$

$$R(3,0,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(3,1,0,1) = (1/4)(-1)^0 \rightarrow 1$$

$$R(3,2,0,1) = (1/4)(-1)^1 \rightarrow -1$$

$$R(3,3,0,1) = (1/4)(-1)^1 \rightarrow -1$$

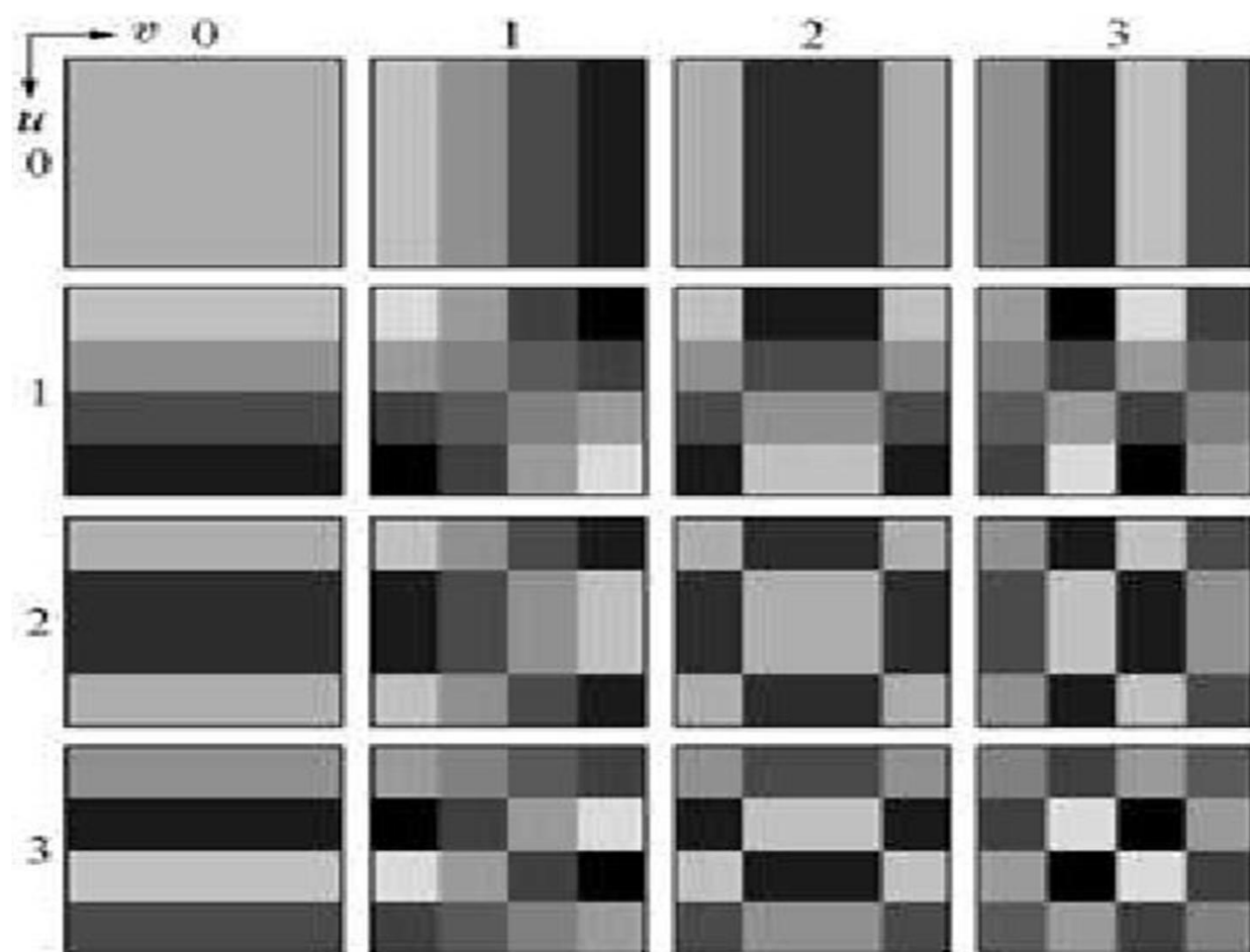
One of the transformations used most frequently for image **compression** is the *discrete cosine transform* (DCT). It is obtained by substituting the following (equal) kernels into Eqs. (8.2-10) and (8.2-11)

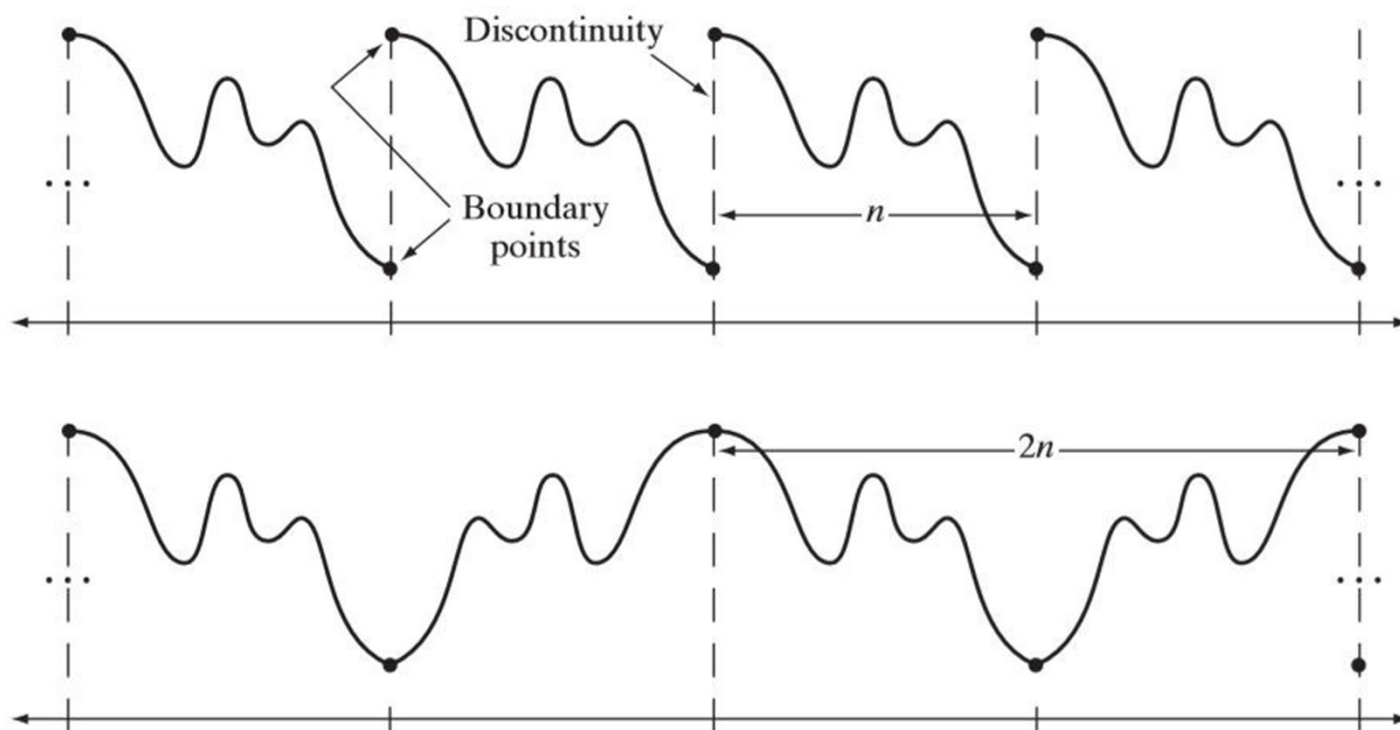
$$\begin{aligned} r(x, y, u, v) &= s(x, y, u, v) \\ &= \alpha(u)\alpha(v) \cos\left[\frac{(2x+1)u\pi}{2n}\right] \cos\left[\frac{(2y+1)v\pi}{2n}\right] \end{aligned} \quad (8.2-18)$$

where

$$\alpha(u) = \begin{cases} \sqrt{\frac{1}{n}} & \text{for } u = 0 \\ \sqrt{\frac{2}{n}} & \text{for } u = 1, 2, \dots, n-1 \end{cases} \quad (8.2-19)$$

and similarly for $\alpha(v)$. Figure 8.23 shows $r(x, y, u, v)$ for the case $n = 4$.





a
b

FIGURE 8.25 The periodicity implicit in the 1-D (a) DFT and (b) DCT.