

## Morphological Processing

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- Analyze images
- Define structure
- Define regions and boundaries
- Based on set theory
- Unified theoretical approach

## Morphology

The word morphology refers to the scientific branch that deals the forms and structures of animals/plants.

Morphology in image processing is a tool for extracting image components that are useful in the representation and description of region shape, such as **boundaries** and **skeletons**.

Furthermore, the morphological operations can be used for **filtering, thinning and pruning**.

The language of the Morphology comes from the set theory, where image objects can be represented by sets. For example an image object containing black pixels can be considered a set of black pixels in 2D space of  $Z^2$

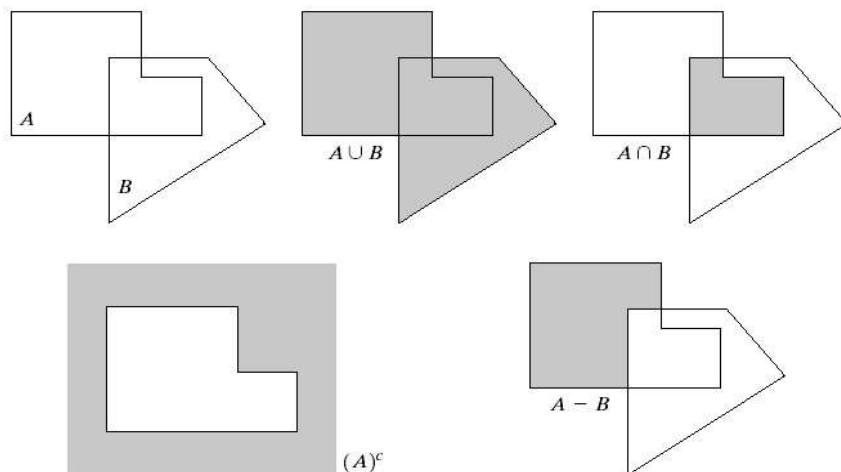
## Morphological Operations

- Dilation
  - Fill in gaps
- Erosion
  - Delete unneeded detail (noise)
- Opening
  - Smooth inner contours
- Closing
  - Smooth outer contours
- Hit or Miss Transformation
  - Detect shapes

## Set Theory Summary

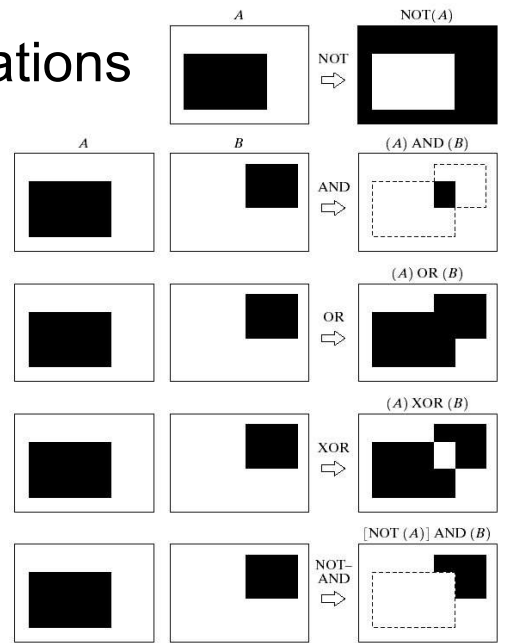
- $a = (x, y)$  is an element of  $A$   $a \in A$
- elements of images  $A \subseteq B$   
– pixel coordinates  $A \cup B$
- subset  $A \cap B$
- union
- intersection  $A^c = \{w \mid w \notin A\}$
- complement
- difference  $A - B = A \cap B^c$

## Set Theory



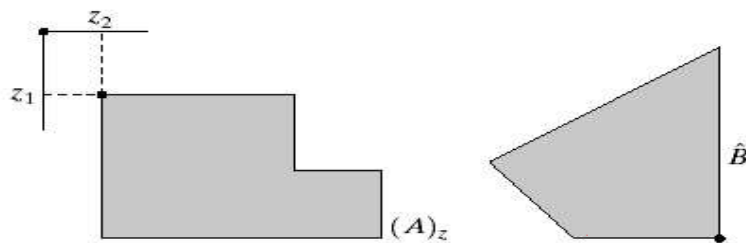
## Logic Operations

- Black = 1



## Morphological Operations

- Reflection  $\hat{B} = \{w \mid w = -b \text{ for } b \in B\}$
- Translation  $(A)_z = \{c \mid c = a + z \text{ for } a \in A\}$



## Dilation and Erosion

Dilation and erosion are the two fundamental operations used in morphological image processing. Almost all morphological algorithms depend on these two operations:

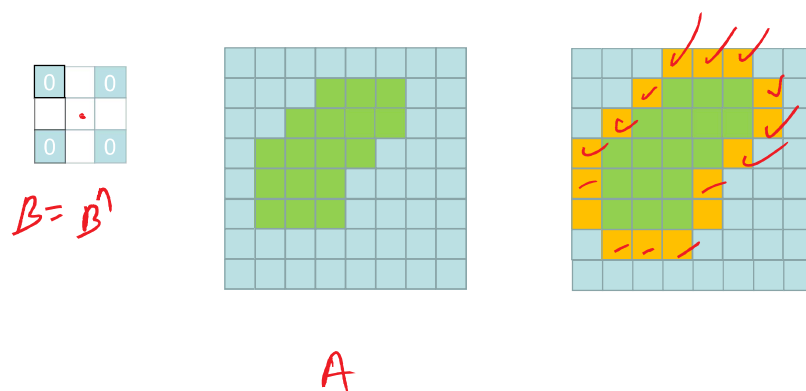
**Dilation:** Given A and B sets in  $Z^2$ , the dilation of A by B, is defined by:

$$A \oplus B = \left\{ z \mid (\hat{B})_z \cap A \neq \emptyset \right\}$$

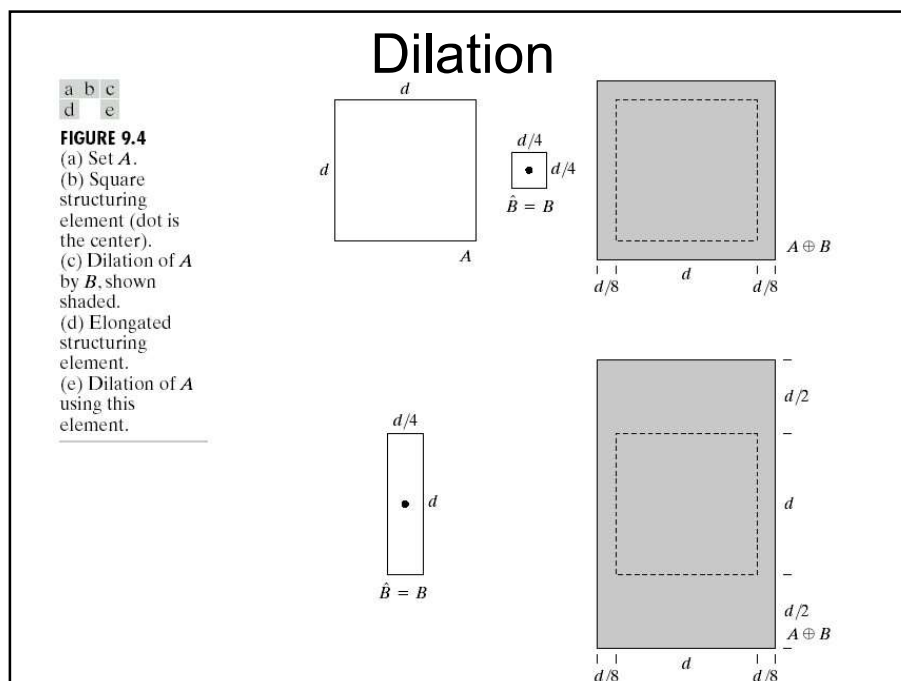
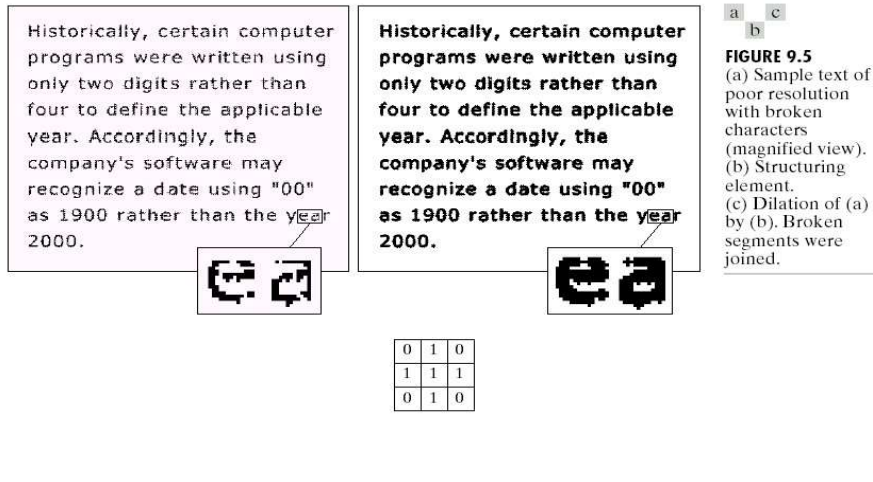
The dilation of A and B is a set of all displacements,  $z$ , such that B and A overlap by **at least** one element.

Set B is referred to as the **structuring element** and used in dilation as well as in other morphological operations. **Dilation expands/dilutes a given image.**

## Dilation Operation



## Dilation Operation



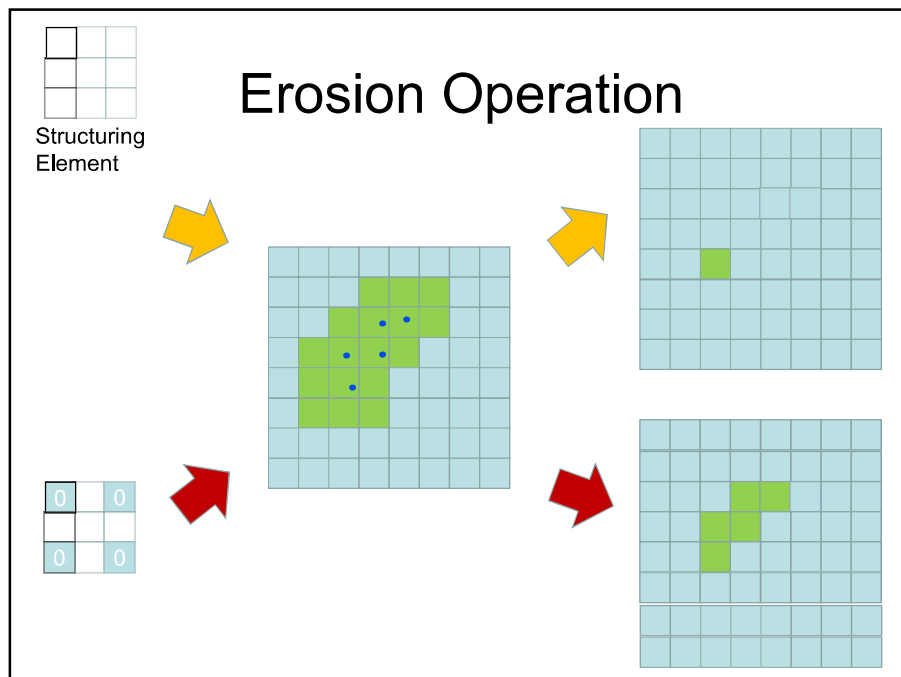
# Erosion

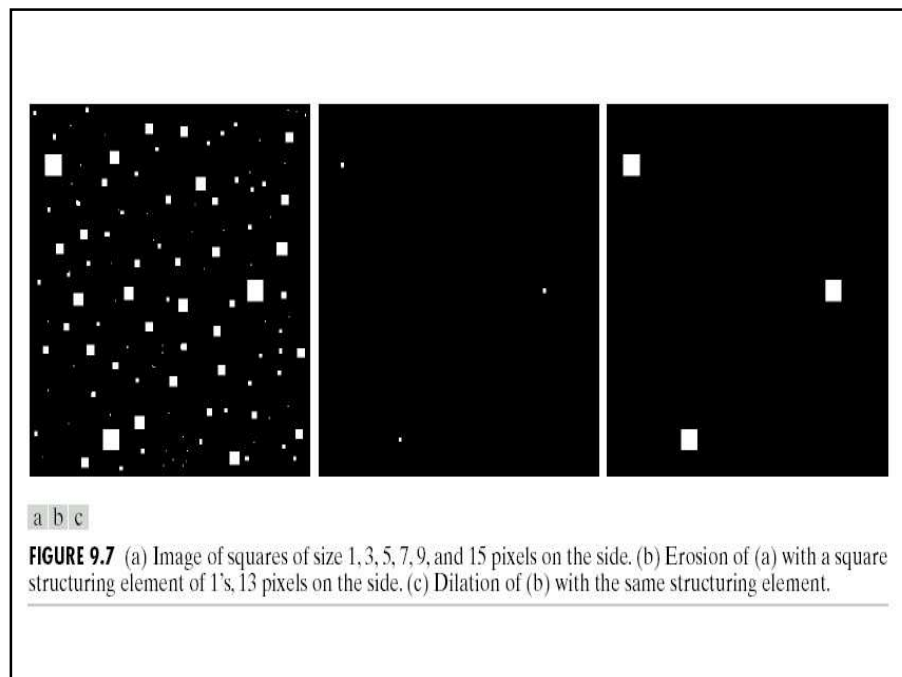
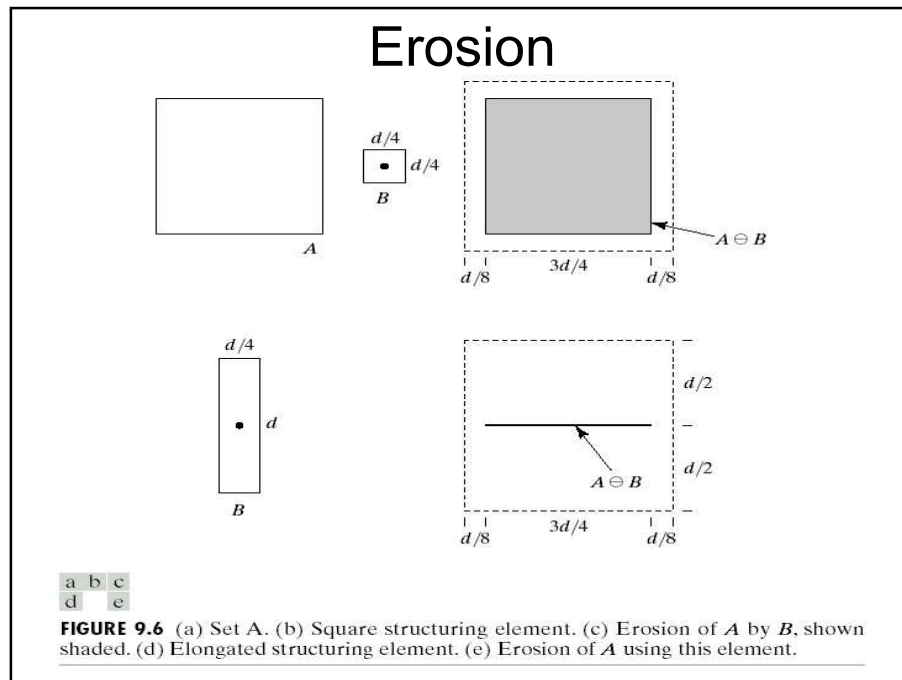
Erosion: Given A and B sets in  $\mathbb{Z}^2$ , the erosion of A by structuring element B, is defined by:

$$A \ominus B = \{z \mid (B)_z \subseteq A\}$$

The erosion of A by structuring element B is the **set of all points z, such that B, translated by z, is contained in A.**

Note that in erosion the structuring element B erodes the input image A at its boundaries. Erosion **shrinks** a given image.







## Opening Operation

**Opening:** The process of erosion followed by dilation is called opening.

It has the effect of eliminating small and thin objects, breaking the objects at thin points and smoothing the boundaries/contours of the objects.

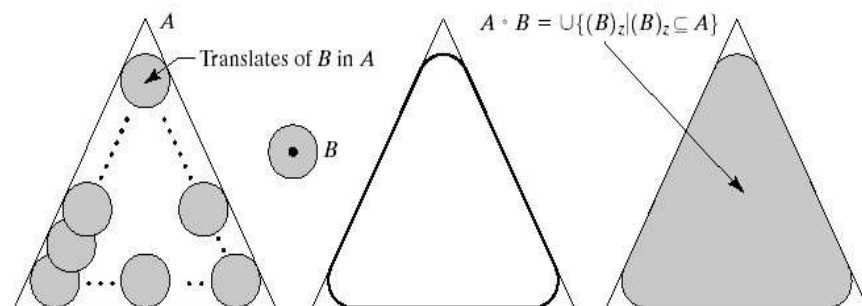
Given set  $A$  and the structuring element  $B$ . Opening of  $A$  by structuring element  $B$  is defined by:

$$A \circ B = (A \ominus B) \oplus B$$

The opening of  $A$  by the structuring element  $B$  is obtained by taking the union of all translates of  $B$  that fit into  $A$ .

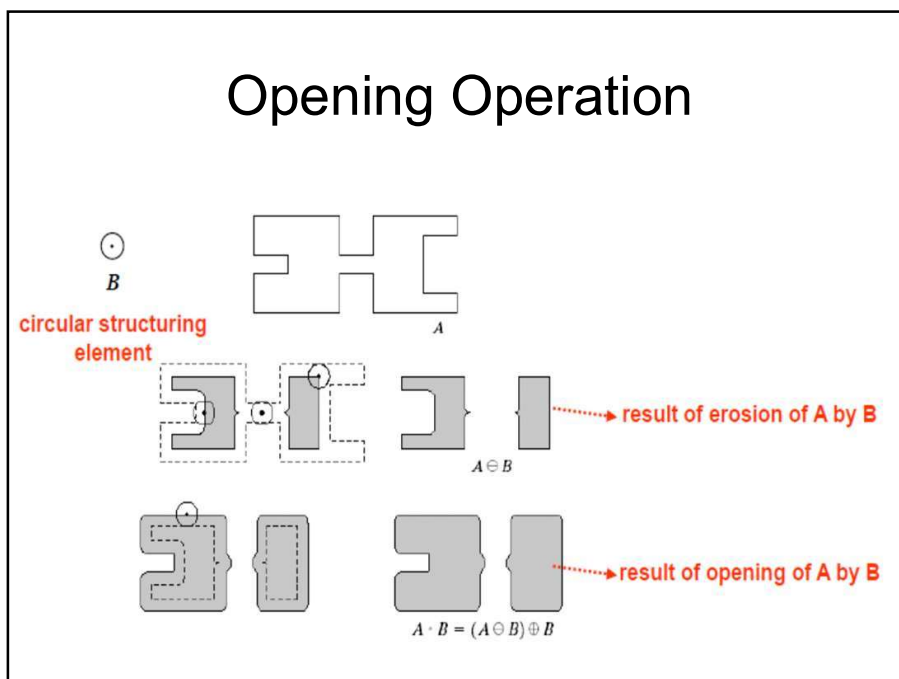
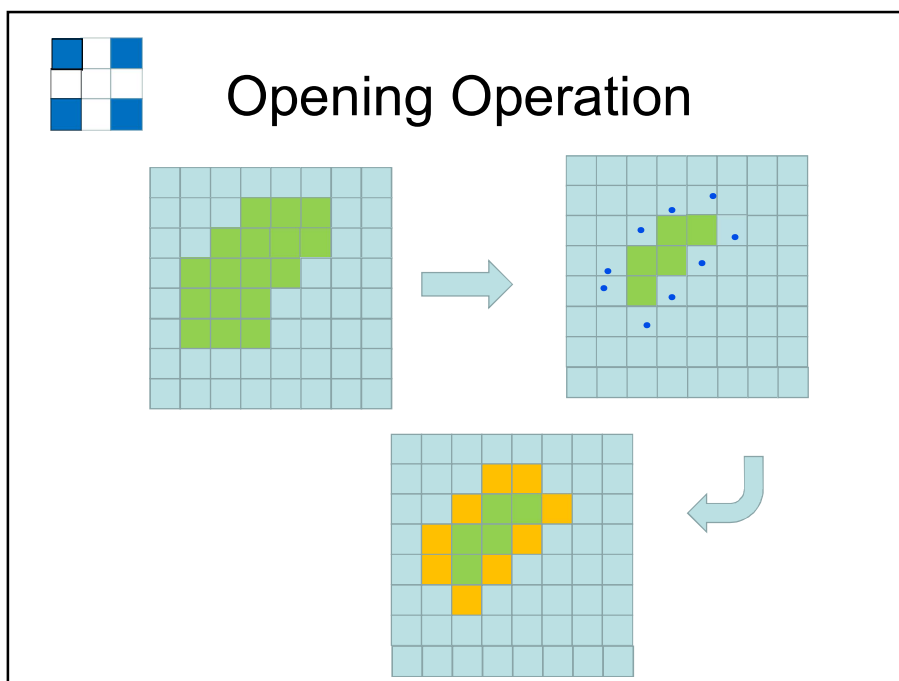
$$A \circ B = \bigcup \{B_z \mid (B_z) \subseteq A\}$$

## Opening Operation



a b c d

**FIGURE 9.8** (a) Structuring element  $B$  “rolling” along the inner boundary of  $A$  (the dot indicates the origin of  $B$ ). (c) The heavy line is the outer boundary of the opening. (d) Complete opening (shaded).



## Closing Operation

**Closing:** The process of dilation followed by erosion is called closing.

It has the effect of filling small and thin holes, connecting nearby objects and smoothing the boundaries/contours of the objects.

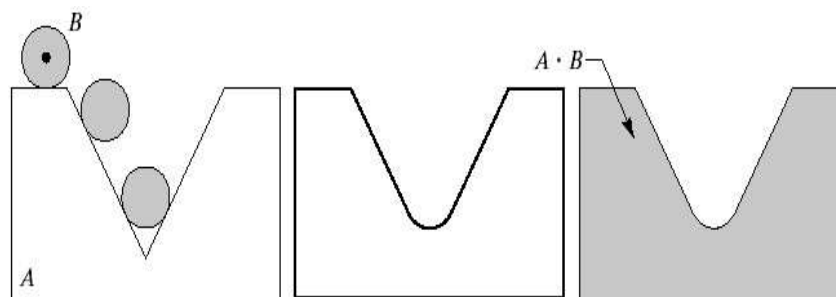
Given set  $A$  and the structuring element  $B$ . Closing of  $A$  by structuring element  $B$  is defined by:

$$A \bullet B = (A \oplus B) \ominus B$$

The closing has a similar geometric interpretation except that we roll  $B$  on the outside of the boundary.

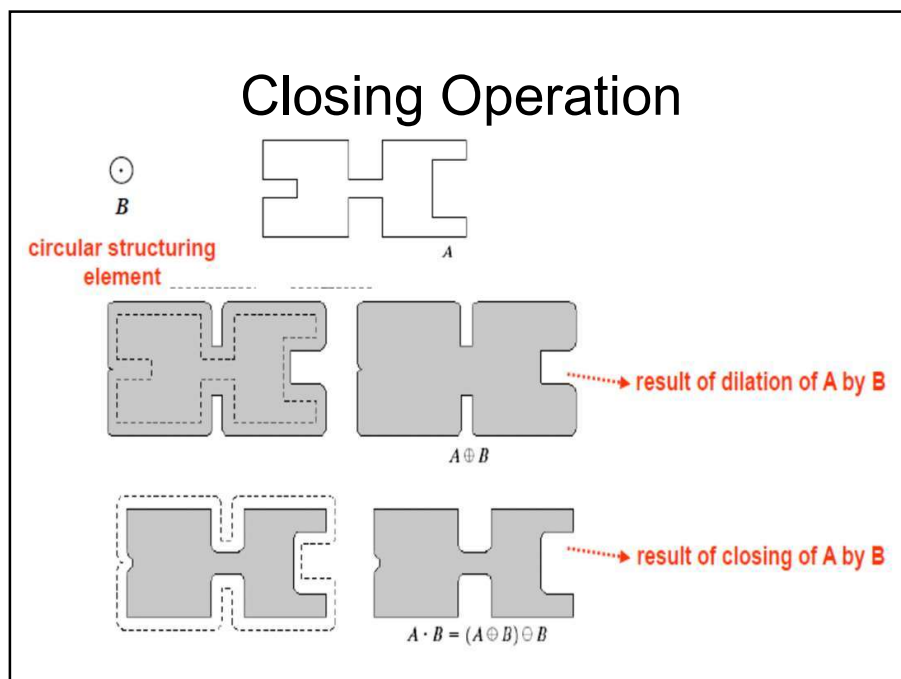
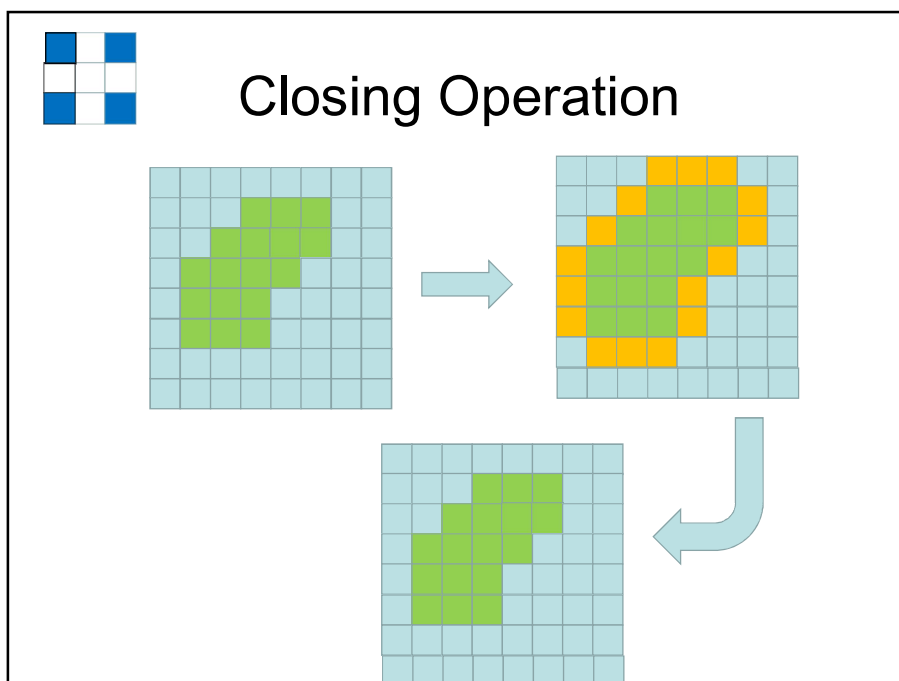
$$A \bullet B = \bigcup \{ (B_z) \mid (B_z) \cap A \neq \emptyset \}$$

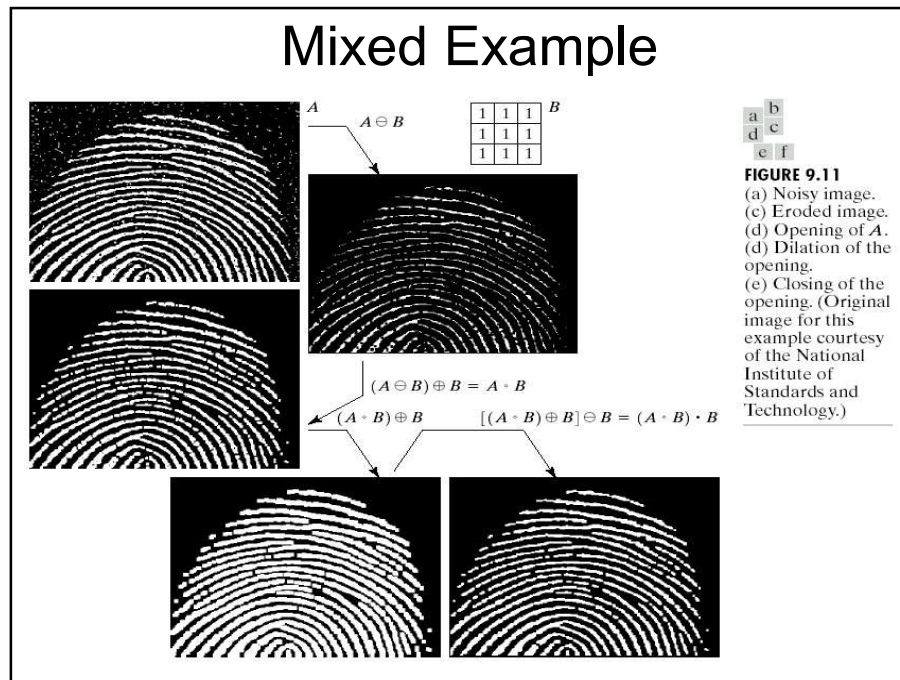
## Closing Operation



a b c

**FIGURE 9.9** (a) Structuring element  $B$  "rolling" on the outer boundary of set  $A$ . (b) Heavy line is the outer boundary of the closing. (c) Complete closing (shaded).

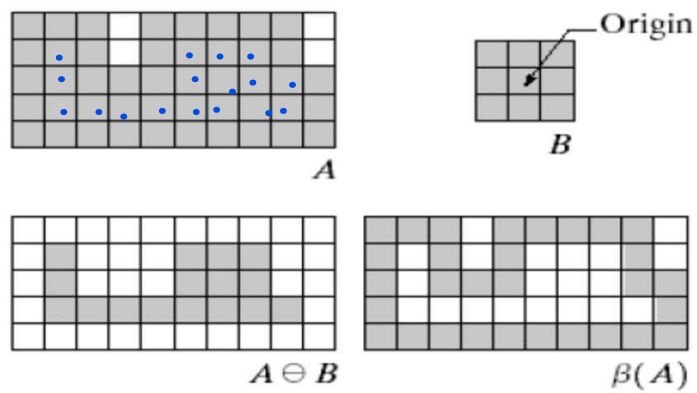




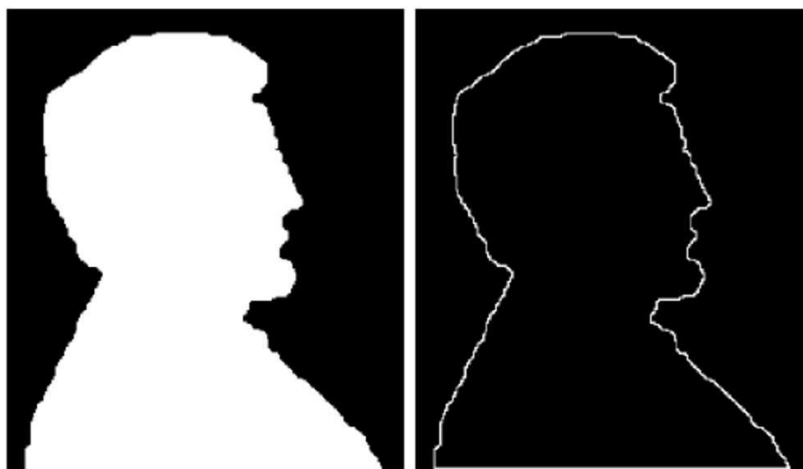
## Opening and Closing

- Opening
  - smooth contours
  - break narrow isthmus
  - eliminate narrow protrusions
- Closing
  - smooth contours
  - fuse breaks
  - eliminate holes
  - fill in small gaps

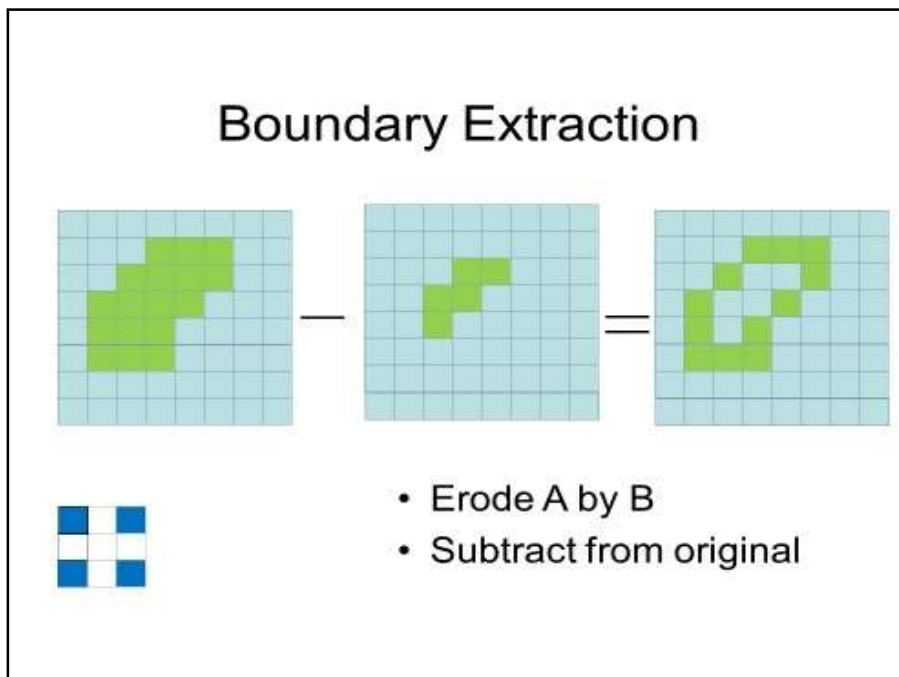
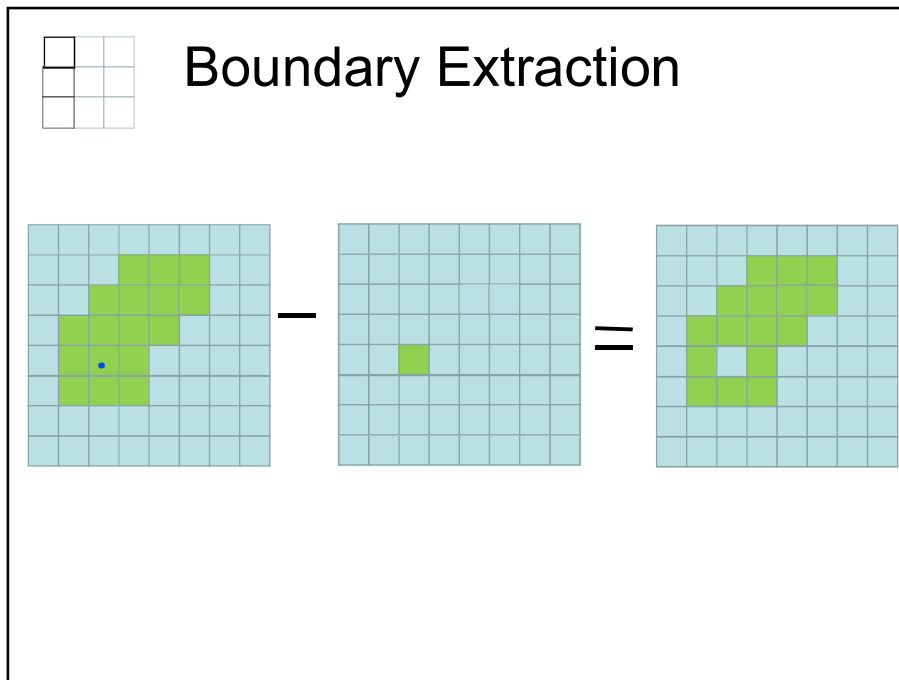
## Boundary Extraction



## Boundary Extraction



Note that thicker boundaries can be obtained by increasing the size of structuring element



## Region Filling

Region filling can be performed by using the following definition.

Given a symmetric structuring element  $B$ , one of the non-boundary pixels ( $X_k$ ) is consecutively dilated and its intersection with the complement of  $A$  is taken as follows:

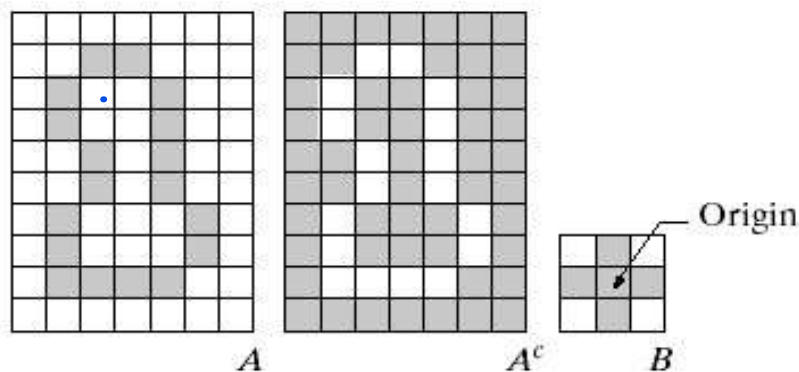
$$X_k = (X_{k-1} \oplus B) \cap A^c$$

$k = 1, 2, 3, \dots$   
*terminates when*  $X_k = X_{k-1}$   
 $X_0 = 1$  (inner pixel)

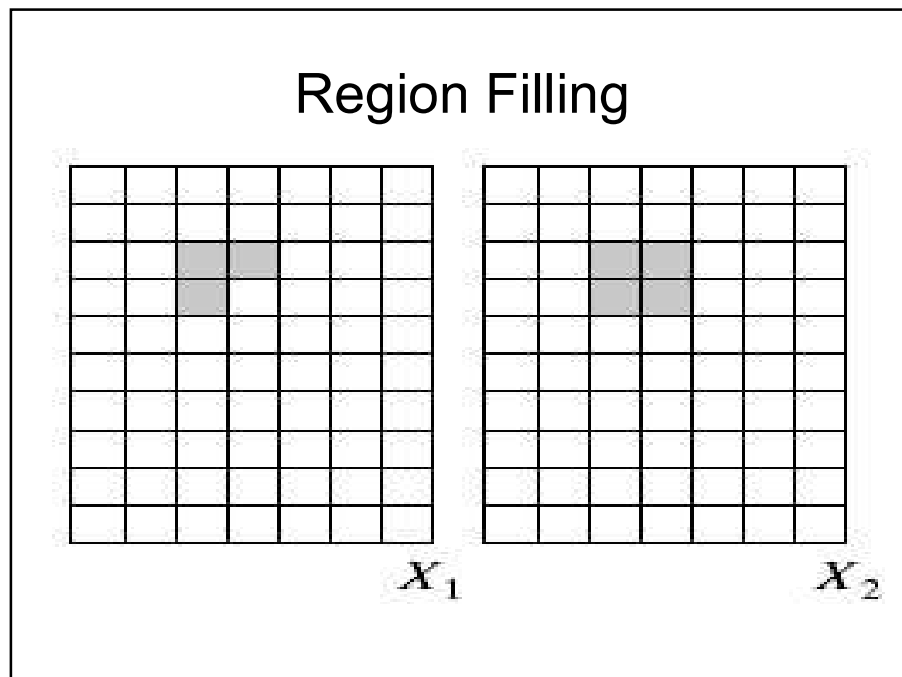
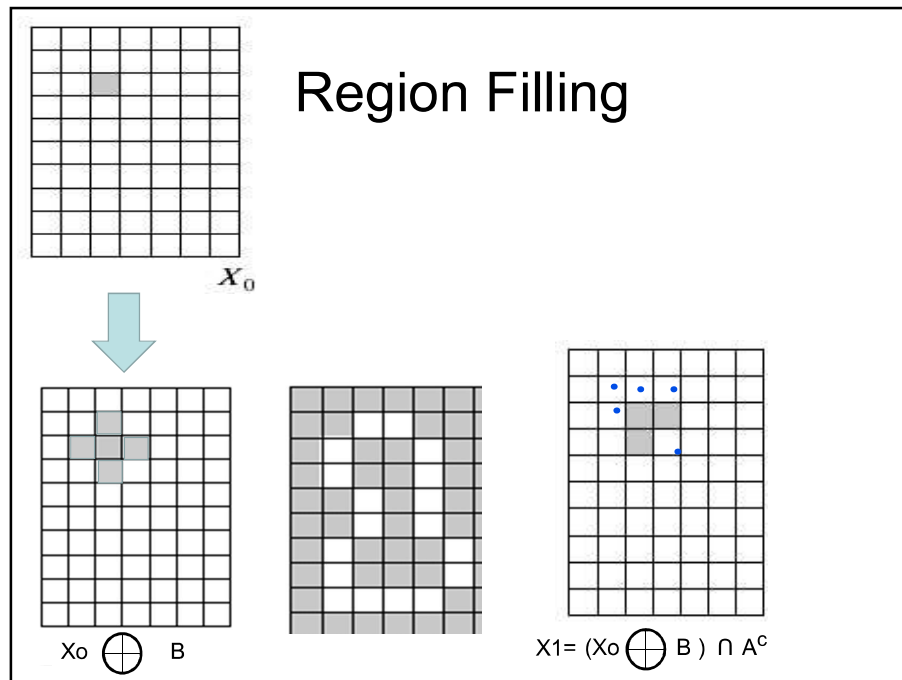
Following consecutive dilations and their intersection with the complement of  $A$ , finally resulting set is the filled inner boundary region and its union with  $A$  gives the filled region  $F(A)$

$$F(A) = X_k \cup A$$

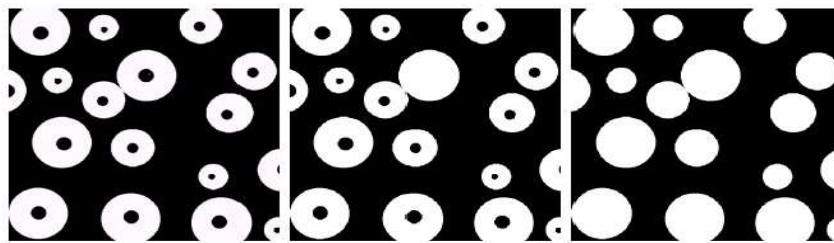
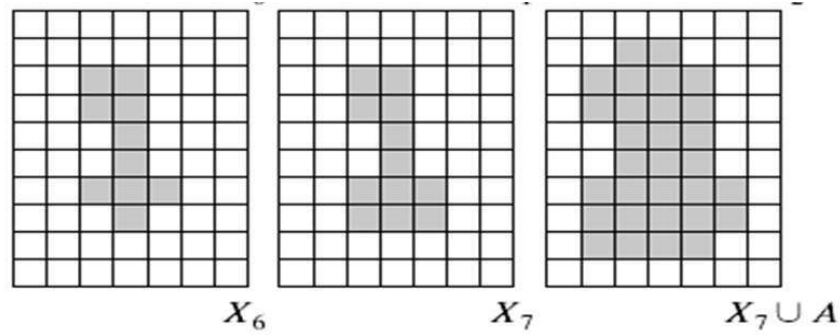
## Region Filling







## Region Filling



a b c

**FIGURE 9.16** (a) Binary image (the white dot inside one of the regions is the starting point for the region-filling algorithm). (b) Result of filling that region (c) Result of filling all regions.

Finding the **starting** points is often done **manually**