2. BUILD A SIMPLE CNN MODEL FOR IMAGE SEGMENTATION

EX.N0: 2	BUILD A SIMPLE CNN MODEL FOR IMAGE
	SEGMENTATION
DATE : 03/02/2025	

AIM:

To build and train a simple Convolutional Neural Network (CNN) for performing binary image segmentation using the CIFAR-10 dataset.

ALGORITHM:

- Step 1: Import necessary libraries like TensorFlow, NumPy, and Matplotlib.
- Step 2: Load the CIFAR-10 dataset and normalize the images.
- Step 3: Create binary segmentation masks using a threshold on image brightness.
- Step 4: Design a simple CNN-based encoder-decoder architecture for segmentation.
- Step 5: Compile the model using binary cross entropy loss and accuracy metric.
- Step 6: Train the model with training images and corresponding masks.
- Step 7: Evaluate the model using test data.
- Step 8: Visualize the original image, ground truth mask, and predicted segmentation mask.

PROGRAM:

import tensorflow as tf from tensorflow.keras import layers, models import numpy as np import matplotlib.pyplot as plt from tensorflow.keras.datasets import cifar10 (x_train, y_train), (x_test, y_test) = cifar10.load_data()

```
x train = x train.astype("float32") / 255.0 x test = x test.astype("float32") / 255.0
y train segmentation = np.where(x train.mean(axis=-1, keepdims=True) > 0.5, 1, 0)
y test segmentation = np.where(x test.mean(axis=-1, keepdims=True) > 0.5, 1, 0)
def create segmentation model(input shape): model = models.Sequential([
layers.InputLayer(input shape=input shape), layers.Conv2D(32, (3, 3),
activation="relu", padding="same"), layers.MaxPooling2D((2, 2)),
layers.Conv2D(64, (3, 3), activation="relu", padding="same"),
layers.MaxPooling2D((2, 2)), layers.Conv2D(128, (3, 3), activation="relu",
padding="same"), layers.Conv2DTranspose(64, (3, 3), strides=2, activation="relu",
padding="same"), layers.Conv2DTranspose(32, (3, 3), strides=2, activation="relu",
padding="same"), layers.Conv2D(1, (1, 1), activation="sigmoid", padding="same")
1)
return model input shape = x train.shape[1:] \# (32, 32, 3) model =
create segmentation model(input shape) model.compile(optimizer="adam",
loss="binary crossentropy", metrics=["accuracy"]) model.summary() history =
model.fit(x train, y train segmentation, validation data=(x test,
y test segmentation), epochs=5, batch size=32
loss, accuracy = model.evaluate(x test, y test segmentation)
print(f"Test Loss: {loss:.4f}, Test Accuracy: {accuracy:.4f}")
predictions = model.predict(x test) num images = 3
```

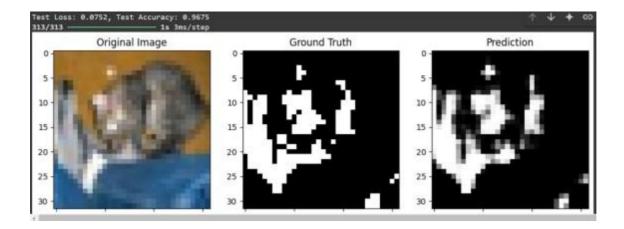
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```
plt.figure(figsize=(12, num_images * 4)) for i in range(num_images): plt.subplot(num_images, 3, i * 3 + 1) plt.title("Original Image") plt.imshow(x_test[i]) plt.axis('off') plt.subplot(num_images, 3, i * 3 + 2) plt.title("Ground Truth")
```

COMPUTER VISION AND ITS APPLICATIONS

plt.imshow(y_test_segmentation[i].squeeze(), cmap="gray")
plt.axis('off') plt.subplot(num_images, 3, i * 3 + 3)
plt.title("Prediction") plt.imshow(predictions[i].squeeze(),
cmap="gray") plt.axis('off') plt.tight_layout() plt.show()

OUTPUT:



RESULT:

Thus, the Program has been executed successfully and verified.

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