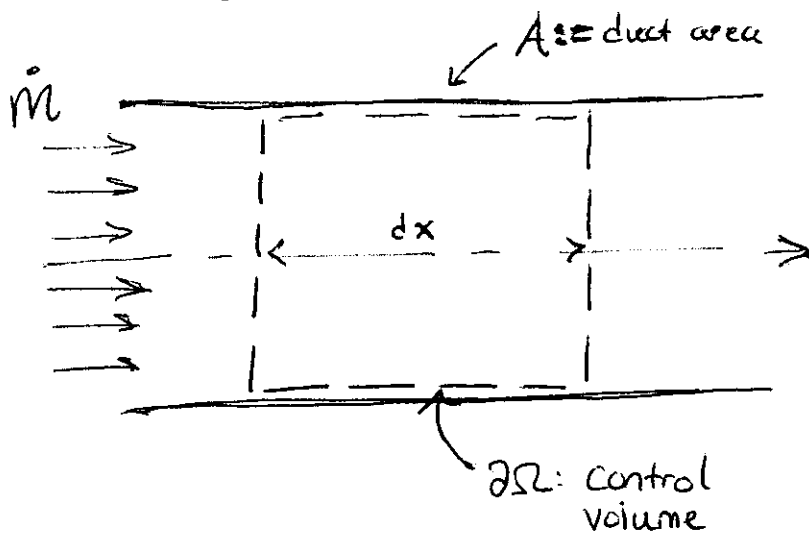


LECTURE 16 : What if the walls are rough?

Now we want to look at the rough wall simple problem. We will use a single straight section of pipe as well.



$$\frac{dA}{dx} = 0 \quad (\text{straight})$$

$$q_r = 0 \quad (\text{adiabatic})$$

$$\mu, \epsilon, \Delta S > 0 \quad (\text{frictional losses})$$

* If we are going to consider frictional losses we must consider shear at the wall. τ_w

* We also wouldn't you believe it need a FANNING FRICTION FACTOR " f " which we will define as.

$$f = \frac{\tau_w}{\frac{1}{2} \rho V^2} \quad (1)$$

Since we are working usually with NON-CIRCULAR DUCTS all diameters will be hydraulic

$$D_H = \frac{4A}{P} \quad (2)$$

LECTURE 16 :

For our mass balance of the control volume we can just use the previous result.

$$\cancel{\frac{dA}{A}} + \frac{d\rho}{\rho} + \frac{dV}{V} = 0$$

$$\therefore \boxed{\frac{d\rho}{\rho} + \frac{dV}{V} = 0}$$

Like wise we will assume an ideal gas (as always).

$$\boxed{P = \rho RT}$$

The energy equation for a steady state gas problem is phrased in terms of enthalpy.

$$\boxed{h + \frac{V^2}{2} = C_0} \quad (\text{for all states})$$

All we need is a momentum relationship to tell us how pressure (forces) prescribe motion (velocity).

$$\Sigma F_{\text{ext}} = \int_{\partial\Omega} \rho A V (\vec{V} \cdot \hat{n}) dA$$

$$AP - A(P+dP) - \tau_w P dx = \rho A V (V+dV - V)$$

$$\therefore \boxed{dp + \frac{4f}{D_H} \frac{\rho V^2}{2} dx + \frac{\rho V^2}{2} \frac{dV^2}{V^2} = 0}$$

LECTURE 16

Essentially all we do now is use all our equations to sub into our momentum relationship. But let's write them all out to see how one would come to this solution.

$$\frac{dp}{\rho} + \frac{dV}{V} = 0 \quad \text{"continuity"} \quad (1)$$

$$P - \rho RT = 0 \quad \text{"equation of state"} \quad (2)$$

$$dh + VdV = 0 \quad \text{"energy"} \quad (3)$$

$$Ma^2 - \frac{V^2}{\gamma RT} = 0 \quad \text{"Mach Definition"} \quad (4)$$

$$ds \geq 0 \quad \text{"Irreversibility"} \quad (5)$$

$$dP + \frac{4f}{D_H} \frac{\rho V^2 dx}{2} + \frac{\rho V^2 dV^2}{2 V^2} = 0 \quad \text{"Momentum"} \quad (6)$$

We have count'em 7 unknowns and 6 equations!

$(Ma, V, P, \rho, T, s, f) \text{ ? ? ? ? }$

This means we have to set a variable to get a solution.

LECTURE 16

What variable should we choose to set then?
Well again we are modeling the question...

How Does Friction Effect Flow?

So it's reasonable then to say we should set the friction term as an independent variable to probe it's effects on flow variables (V, P, ρ, T, s, Ma)!

Now this gets a little rough but let's hold onto a goal. In the end we are trying to relate everything to (Ma, \mathcal{F}) .

$$\frac{dMa}{Ma} = f_1(\mathcal{F}) \quad \frac{dP}{P} = f_3(\mathcal{F}) \quad ds = f_5(\mathcal{F})$$

$$\frac{dV}{V} = f_2(\mathcal{F}) \quad \frac{dT}{T} = f_4(\mathcal{F})$$

We are trying to determine these functions,

So we are going to combine all our equations by subbing and resubbing until we relate

$$\frac{dMa}{Ma} \sim \frac{4f dx}{D_H} \rightarrow \text{then back sub for the rest!}$$

LECTURE 16

You might as well see solving this many equations at least once in your undergrad. I will highlight common tricks and rational. We are going to use all (1)-(6) to arrive at $\frac{4f dx}{D_H} = C(M, \gamma) \frac{dM}{M}$.

Start with momentum. Why!? Because it's the only one with the f term!

$$\frac{dP}{P} + \frac{4f}{D_H} \frac{\rho V^2}{2P} dx + \frac{\rho V^2}{2P} \frac{dV^2}{V^2} = 0$$

$$\therefore \frac{\rho V^2}{2P} \cdot \frac{4f}{D_H} dx = \underbrace{-\frac{dP}{P} - \frac{\rho V^2}{2P} \frac{dV^2}{V^2}}$$

use (1)-(6) to get in terms of Ma !

We use (2) to get rid of dP/P . Take (d) of (2)

$$dP = d\rho RT + dT \rho R \quad / \frac{1}{P}$$

$$\frac{dP}{P} = \frac{d\rho}{\rho} + \frac{dT}{T}$$

Now we can use (1) to replace $d\rho/\rho$!

$$\frac{dP}{P} = \frac{dT}{T} - \frac{dV}{V}$$

Where are we now then...

$$\frac{\rho V^2}{2P} \cdot \frac{4f}{D_H} dx = \frac{dV}{V} - \frac{dT}{T} - \frac{\rho V^2}{2P} \frac{dV^2}{V^2}$$

Now we must get $\frac{dV}{V}$, $\frac{dT}{T}$, $\frac{\rho V^2}{2P}$, & $\frac{dV^2}{V^2}$ terms into Ma & γ expressions.

Lecture 16

We use (3) and the definition of c_p
(This is our first trick but it makes sense
as we want to go from $dh \rightarrow dT$ which
is what c_p does!)

$$dh = -VdV = -\frac{1}{2}dV^2 = \underbrace{c_p dT}_{\text{divide by } c_p T}$$

$d()$ basically
behaves like
the derivative...

$$\text{since } c_p = \frac{dh}{dT}$$

FOR IDEAL GAS!!!

$$\frac{dT}{T} = -\frac{1}{2} \frac{dV^2}{c_p T} = \frac{-dV^2}{2c_p T}$$

We need to get to Ma relations so c_p & T are
problematic.

$$c_p - c_v = R \Rightarrow c_p = R + c_v = R + (c_p - R)$$

$$c_p = \gamma R / (\gamma - 1) \quad (\text{a dirty trick...})$$

$$\frac{dT}{T} = \frac{-dV^2}{2} \frac{(\gamma - 1)}{\underbrace{\gamma R T}_{\text{use (4)}}} = \frac{-dV^2}{V^2} Ma^2 \frac{\gamma - 1}{2} \quad \checkmark$$

Reevaluate now...

$$\frac{\rho V^2}{2P} \frac{4f}{D_H} dx = \frac{dV}{V} + \frac{\gamma - 1}{2} Ma^2 \frac{dV^2}{V^2} - \frac{\rho V^2}{2P} \frac{dV^2}{V^2}$$

Lecture 16

We now have to deal with this $\rho V^2 / 2P$ term...

$$\rho V^2 = \rho \frac{V^2}{\gamma R T} \gamma R T = \gamma Ma^2 P \quad (\text{dirty trick} \dots)$$

Reevaluate...

$$\frac{4\gamma}{D_{H1}} dx = \frac{dV}{V} + \frac{\gamma-1}{2} Ma^2 \frac{dV^2}{V^2} - \frac{\gamma Ma^2 P}{2P} \frac{dV^2}{V^2}$$

eliminate pressure!!

Now we need to get dV^2/V^2 into Ma expressions allright. Let's do a $d(\cdot)$ to (4) to build up dMa^2/Ma from scratch.

$$dMa^2 = d\left(\frac{V^2}{\gamma R T}\right) = \frac{dV^2 \gamma R T - \gamma R dT V^2}{(\gamma R T)^2} \quad \bigg/ \frac{1}{Ma^2}$$

$$\frac{dMa^2}{Ma^2} = \frac{dV^2}{\gamma R T Ma^2} - \frac{\gamma R V^2 dT}{(\gamma R T)^2 Ma^2}$$

$$= \frac{dV^2}{V^2} - \frac{dT}{T} \quad \left(\text{because } Ma^2 = \frac{V^2}{\gamma R T} \right)$$

We also have an expression for dT/T though!

$$\frac{dMa^2}{Ma^2} = \frac{dV^2}{V^2} + \frac{\gamma-1}{2} Ma^2 \frac{dV^2}{V^2} = \left(1 + \frac{\gamma-1}{2} Ma^2\right) \frac{dV^2}{V^2} \quad \underline{\underline{\text{Boom!}}}$$

Reevaluate!

$$\frac{\rho V^2}{2P} \frac{4\gamma}{D_{H1}} dx = \frac{dV}{V} + \left(\frac{\gamma-1}{2} Ma^2 - \frac{\gamma Ma^2}{2}\right) \frac{dV^2}{V^2}$$

Lecture 16

Almost done! Just need to take care of dV/V .

$$\frac{\rho V^2 4f}{2P D_{+1}} dx = \underbrace{\frac{dV}{V}}_{\text{last son of a bitch!}} + \left(\frac{\gamma-1}{2} Ma^2 - \frac{\gamma Ma^2}{2} \right) \left(\frac{\gamma-1}{2} Ma^2 + 1 \right)^{-1} \frac{dMa^2}{Ma}$$

! We can't just square root our dV^2/V^2 term!

! Because it's $d(V^2)/V^2$ not $(dV)^2/V^2$!!!!

We can use (1) since we haven't touched it yet.

$$\frac{dV}{V} = -\frac{d\rho}{\rho} \quad \text{or divide now by } \underline{\rho V^2/2P}.$$

$$\frac{4f}{D_{+1}} = \frac{2P}{\rho V^2} \left\{ \frac{dV}{V} + \frac{-Ma^2/2}{\left(\frac{\gamma-1}{2} Ma^2 + 1 \right)} \frac{dMa^2}{Ma^2} \right\}$$

$$= \frac{2P}{\gamma Ma^2 P} \left\{ \frac{dV}{V} + \dots \right\}$$

$$= \frac{2}{\gamma Ma^2} \left\{ \frac{1}{2} \frac{dV^2}{V^2} + \dots \right\}$$

Just get sub in for dV^2/V^2 our dMa^2/Ma^2 rearrange to

(**)

$$\frac{4f}{D_{+1}} dx = \frac{2(1-Ma^2)}{\gamma Ma^3 \left(1 + \frac{\gamma-1}{2} Ma^2 \right)} \frac{dMa}{Ma}$$

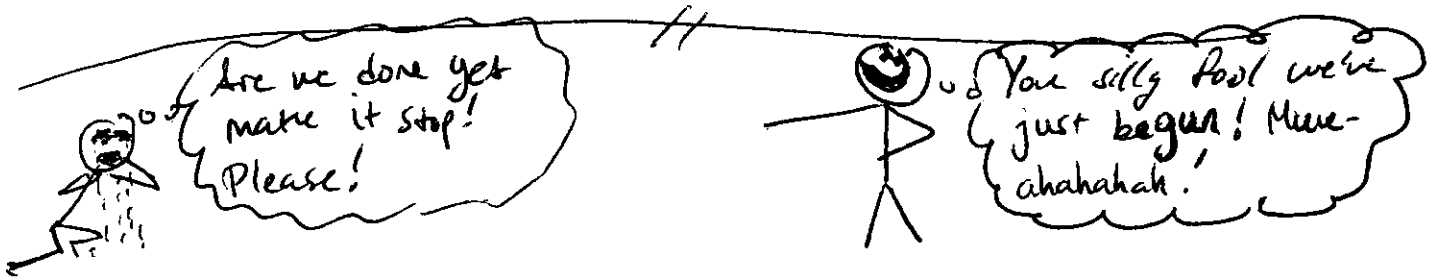
Lecture 16

This ode for $Ma(x)$ tells us how losses effect speed as we traverse the rough duct. The ODE is found solving for dMa/dx !

$$\frac{4 f Ma}{D_{H1}} \frac{\gamma Ma^3 \left(1 + \frac{\gamma-1}{2} Ma^2\right)}{2(1-Ma^2)} = \frac{dMa}{dx}$$

$$\therefore \frac{dMa}{dx} = \frac{2 f \gamma Ma^4 \left(1 + \frac{\gamma-1}{2} Ma^2\right)}{(1-Ma^2)}$$

- Non-linear
- First Order
- Autonomous
- Singular



We can use (**) to just back sub now for dp/p , dT/T , $d\rho/\rho$, and dV/V !

$$\frac{dV}{V} = \frac{\gamma Ma^2}{2(1-Ma^2)} \frac{4 f dx}{D_{H1}} \Rightarrow \text{ODE for } V(x)$$

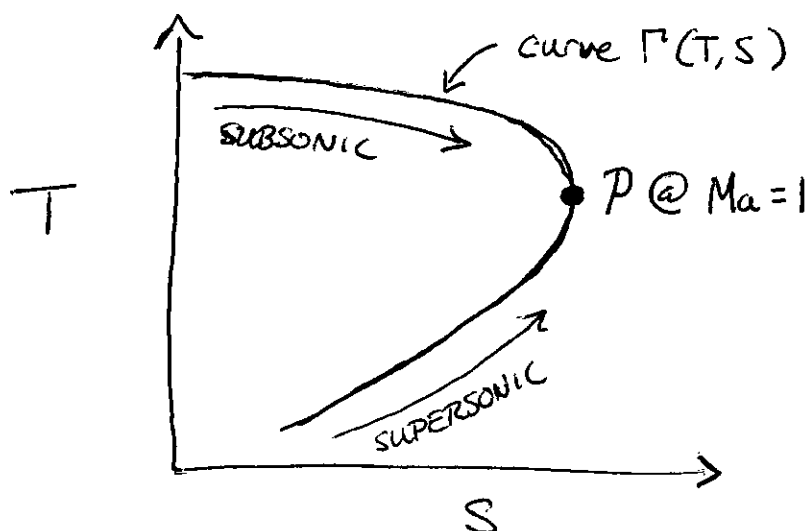
$$\frac{dP}{P} = - \frac{\gamma Ma^2 (1 + [\gamma-1] Ma^2)}{2(1-Ma^2)} \frac{4 f dx}{D_{H1}} \Rightarrow \text{ODE for } P(x)$$

$$\frac{dT}{T} = - \frac{\gamma(\gamma-1) Ma^4}{2(1-Ma^2)} \frac{4 f dx}{D_{H1}} \Rightarrow \text{ODE for } T(x)$$

Lecture 16

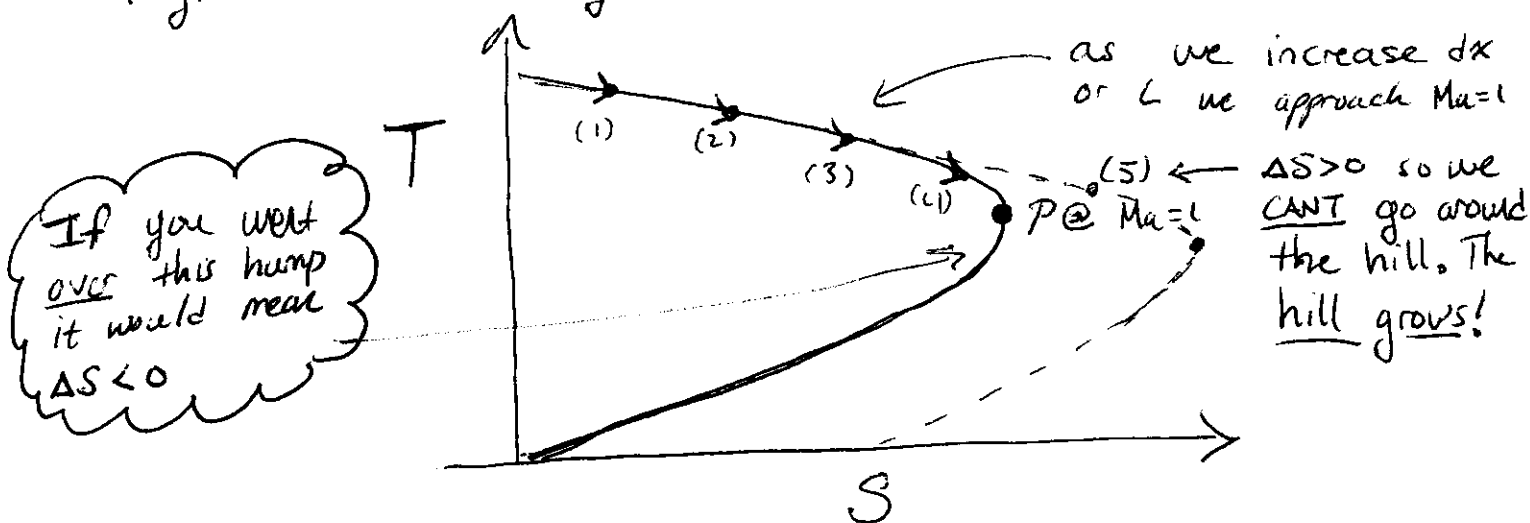
More often we actually use "Fanno" Lines to analyze systems though. I'll spare you their derivations after that last round and just explain them.

- The curve Γ represents all the states possible for Fanno Flow with a FIXED \dot{m} and h .
- For a given state at a given mass flowrate states MOVE TO THE RIGHT.



I honestly believe this is the first time you have to apply the 2nd law to rationalize something. Usually it's all 1st law.

a) What happens if flow starts $Ma < 1$ and length is continually added to the section of pipe?



Lecture 16

As we approach $Ma=1$ the flow becomes choked by friction. A decrease in \dot{m} results

THIS MEANS FOR A GIVEN INLET Ma CONDITION THERE EXISTS A L_{max} PAST WHICH \dot{m} DECREASES

* It is surprising that this compressible phenomenon of "choking" or maxing out \dot{m} occurs even for a straight pipe due to frictional effects

The other game for Fanno Flow is the use of Tables that tell the user about choked flow

Ma	T/T_*	P/P_*	P_t/P_{t*}	V/V_*	fL_{max}/D
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:
	:	:	:	:	:

Where $()_*$ is a property at $Ma=1$.

Lecture 16

The values in these tables come from Numerical Integration of our awful, disgusting vile, reprehensible equations we derived earlier.

For example...

$$\int_0^{L_{\max}} \frac{4f dx}{D_{+1}} = \int_{M=Ma \in \{0.01, 0.02, \dots, 4.99, 5\}}^{M=1} f(Ma) dMa$$

upper limit we know is for $Ma=1$

computer integrator for a discrete set of Ma values.

start at any arbitrary Ma value

$$\therefore \frac{f L_{\max}}{D_{+1}} = \{ \text{Make computer go brrrrrr.} \}$$

We do the exact same for the other relationships.

$$\int_P^{P^*} \frac{dP}{P} = \int_M^1 - \frac{\gamma Ma^2 (1 - (\gamma-1) Ma^2)}{2(1 - Ma^2)} \left\{ \frac{4f dx}{D_{+1}} \right\}$$

but we can express this in terms of Ma numbers! (**)

$$= \int_1^M \left[\frac{1 + (\gamma-1) Ma^2}{1 + \frac{\gamma-1}{2} Ma^2} \right] \frac{dM}{M} = \dots$$

$$= \{ \text{computer calculator for a bunch of } Ma \text{ values} \}$$

Lecture 16

Make sure you realize that you have to exponentiate the right-hand side after the computer is done integrating, because say you get a value of α for integration.

$$\int_P^{P_*} \frac{dP}{P} = \ln(P) \Big|_P^{P_*} = \ln\left(\frac{P_*}{P}\right) = \alpha \Rightarrow \boxed{\frac{P_*}{P} = e^\alpha}$$

SO WHEN CONNECTING 2 STATES OF GAS FLOW THAT FALL IN THE FANNO ASSUMPTIONS YOU MUST CONSULT A TABLE/DATABASE AND RELATE A STATE TO A CHOKED/MAXIMUM FLOW

Some qualitative properties that can be drawn from Fanno Lines.

If $Ma < 1 \Rightarrow T \downarrow$ as $Ma \uparrow$

If $Ma > 1 \Rightarrow T \uparrow$ as $Ma \downarrow$

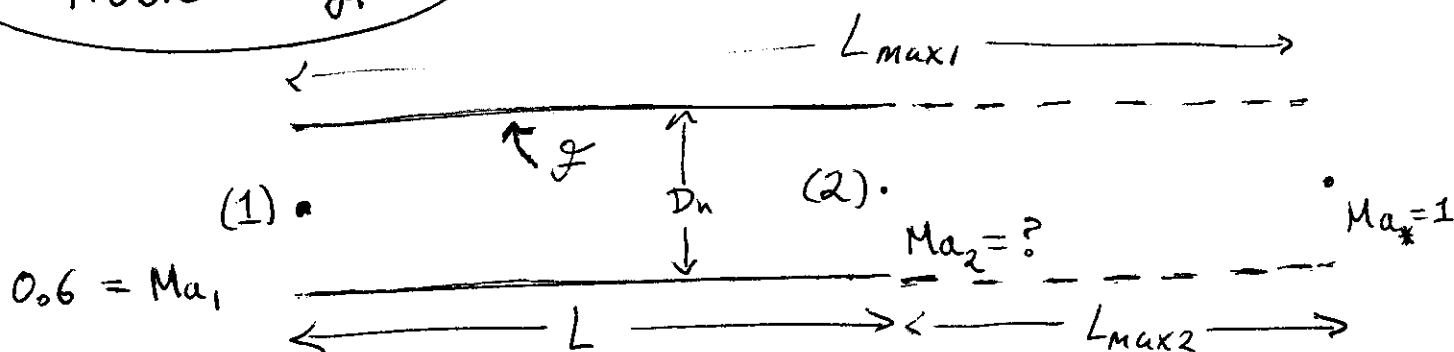
Some tricks using tables... say you want to get from state 1 to 2 but don't have to consider (*) properties in your problem?

$$\frac{P_2/P_*}{P_1/P_*} = \frac{P_2}{P_1} \quad \text{dirty trick right...}$$

Lecture 16

More on the "flow" of using tables is that you must specify the Ma value or the friction term $4fL_{max}/D_h$ to start solving anything. This is because this will tell you which row you're on.

Problem Types



Determine exit properties at (2)?

$$\alpha = \frac{fL_{max1}}{D_h} = \frac{fL_{max2}}{D_h} + \frac{fL}{D_h}$$

* you can get this number from a table because $Ma_1 = 0.6$ which specifies a row to look up the friction term.

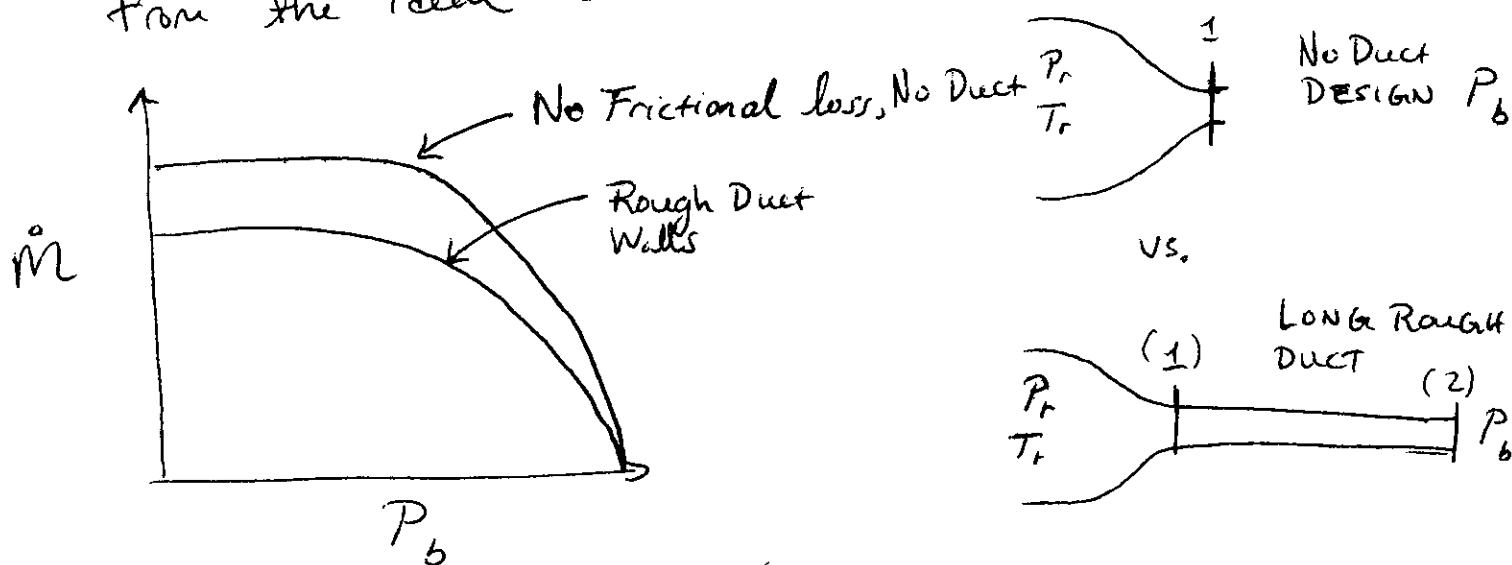
$$\therefore \frac{fL_{max2}}{D_h} = \frac{fL_{max1}}{D_h} - \alpha$$

* Since this specifies another row both states are now completely specified and both states can be related by

$$\frac{(\quad)_2}{(\quad)_1} = \frac{(\quad)_2 / (\quad)_*}{(\quad)_1 / (\quad)_*} \quad !$$

LECTURE 16

If we recall our \dot{m} graphs from last time this frictional loss is reducing \dot{m}_{\max} from the ideal case.



However... would you believe that people actually figured out all those integrals? Thru crazy algebra you can show... i.e. (partial fractions)

$$\frac{4L_{\max}}{D_H} f = \frac{1-Ma^2}{\gamma Ma^2} + \frac{\gamma+1}{2\gamma} \ln \left(\frac{(\gamma+1)Ma^2}{2(1+\frac{\gamma-1}{2}Ma^2)} \right) \quad (1)$$

$$\frac{V}{V_*} = Ma \left\{ \frac{\gamma+1}{2+(\gamma-1)Ma^2} \right\}^{1/2} \quad (2)$$

$$\frac{P}{P_*} = \left\{ \frac{\gamma+1}{Ma^2(2+(\gamma-1)Ma^2)} \right\}^{1/2} \quad (3)$$

$$\frac{T}{T_*} = \frac{\gamma+1}{2+(\gamma-1)Ma^2} \quad (4)$$

$$\frac{\rho}{\rho_*} = \frac{V_*}{V} \quad \text{and} \quad \frac{S-S_*}{c_p} = \ln \left\{ Ma^2 \right\} + \left\{ \frac{\gamma+1}{Ma^2[2+(\gamma-1)Ma^2]} \right\}^{1/2} \quad (5)$$

Extra credit
make your own
Fanno Tables in
excel