

# Notes about the results

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## NFQ (offline)

### Car Environment

- *Setup 1 :*
  - nb\_episodes : 10
  - episodes\_per\_iter : 200
  - evaluation\_episodes : 10
  - gamma : 0.99
  - lr : 0.001
  - hidden\_layers : (5, 5)
  - **Training Time : 544.59 seconds (~9min)**
  - **Iterations to first success : 17**
  - model : `nfq_car_model_10_ep.pkl`

### Pendulum Environment

- *Setup 1 :*
  - nb\_episodes : 150
  - episodes\_per\_iter : 5000
  - evaluation\_episodes : 10
  - gamma : 0.99
  - lr : 0.001
  - hidden\_layers : (5, 5)
  - **Training Time : 140.84 seconds (~2min30)**
  - model : `nfq_pendulum_model_150_ep.pkl`

## DQN (online)

### Car Environment

- *Setup 1 :*
  - nb\_episodes : 500
  - iterations\_per\_ep : 200
  - target\_network\_update : 5
  - gamma : 0.99
  - lr : 0.001
  - hidden\_layers : (5, 5)
  - epsilon\_decay : 0.9995
  - **Training Time : 402.24 seconds (~7min)**
  - **Iterations to first success : 17**
  - model : `dqn_car_500_ep.pth`

## Pendulum Environment

- *Setup 1* :
  - nb\_episodes : 50000
  - iterations\_per\_ep : 5000
  - target\_network\_update : 5
  - gamma : 0.99
  - lr : 0.001
  - hidden\_layers : (5, 5)
  - epsilon\_decay : 0.9995
  - **Training Time : 305.56 seconds (~5min)**
  - model : `dqn_pendulum_50000_ep.pth`

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## Pendulum Environment

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