

Math 672 Lecture 34

The best answers to the question, "What is the structure of a linear operator $T: V \rightarrow V$?" are provided by the spectral theorems:

- If V is complex and $T \in \mathcal{L}(V)$ is normal, then there exist $\lambda_1, \dots, \lambda_n \in \mathbb{C}$ and an orthonormal basis $\{v_1, \dots, v_n\}$ of V such that

$$T(v) = \sum_{j=1}^n \lambda_j \langle v, v_j \rangle v_j \quad \forall v \in V.$$

- If V is real and $T \in \mathcal{L}(V)$ is self-adjoint, then there exist $\lambda_1, \dots, \lambda_n \in \mathbb{R}$ and an orthonormal basis $\{v_1, \dots, v_n\}$ of V such that

$$T(v) = \sum_{j=1}^n \lambda_j \langle v, v_j \rangle v_j \quad \forall v \in V.$$

Application: V is real, $T \in \mathcal{L}(V)$ is self-adjoint, and the eigenvalues of T are all positive, say $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n > 0$. Suppose we wish to solve $T(v) = y$ for v , where $y \in V$ is given but may be noisy.

Suppose v^*, y^* are the exact values ($T(v^*) = y^*$), y is a (noisy) measurement of y^* , and v is the solution of $T(v) = y$. We would like to compare

$$\|v - v^*\|_V \quad \text{and} \quad \|y - y^*\|_V$$

or, even better,

$$\frac{\|v - v^*\|}{\|v^*\|} \quad \text{and} \quad \frac{\|y - y^*\|}{\|y^*\|}.$$

We have

$$T(v) = y$$

$$\Leftrightarrow \sum_{j=1}^n \lambda_j \langle v, v_j \rangle v_j = \sum_{j=1}^n \langle y, v_j \rangle v_j$$

$$\Leftrightarrow \lambda_j \langle v, v_j \rangle = \langle y, v_j \rangle, \quad j=1, 2, \dots, n \quad (\text{why?})$$

$$\Leftrightarrow \langle v, v_j \rangle = \frac{\langle y, v_j \rangle}{\lambda_j}, \quad j=1, 2, \dots, n$$

$$\Leftrightarrow v = \sum_{j=1}^n \frac{\langle y, v_j \rangle}{\lambda_j} v_j$$

Thus

$$T^{-1}(y) = \sum_{j=1}^n \frac{\langle y, v_j \rangle}{\lambda_j} v_j.$$

It follows that

$$\begin{aligned} v - v^* &= T^{-1}(y) - T^{-1}(y^*) = T^{-1}(y - y^*) \\ &= \sum_{j=1}^n \frac{\langle y - y^*, v_j \rangle}{\lambda_j} v_j \end{aligned}$$

$$\begin{aligned}
\Rightarrow \|v-v^*\|^2 &= \sum_{j=1}^n \frac{|\langle y-y^*, v_j \rangle|^2}{\lambda_j^2} \\
&\leq \frac{1}{\lambda_n^2} \sum_{j=1}^n |\langle y-y^*, v_j \rangle|^2 \\
&= \frac{\|y-y^*\|^2}{\lambda_n^2} \\
\Rightarrow \|v-v^*\| &\leq \frac{\|y-y^*\|}{\lambda_n}.
\end{aligned}$$

Note what this inequality says: The error in the data (y) can be magnified by as much as λ_n^{-1} when the equation is solved for v .

- If λ_n is not too small ($\lambda_n \gtrsim 1$), then the error in the solution is, at worst, not much bigger than the error in the data.
- But if $\lambda_n \ll 1$, then the error in the solution can be a lot bigger than the error in the data.

Actually, though, comparing the absolute errors is not so informative.

Note that

$$\begin{aligned}
\|y^*\|^2 &= \|\mathcal{T}(v^*)\|^2 = \left\| \sum_{j=1}^n \lambda_j \langle v^*, v_j \rangle v_j \right\|^2 \\
&= \sum_{j=1}^n \lambda_j^2 |\langle v^*, v_j \rangle|^2
\end{aligned}$$

$$\leq \lambda_1^2 \sum_{j=1}^n |\langle v^*, v_j \rangle|^2$$

$$= \lambda_1^2 \|v^*\|^2$$

$$\Rightarrow \|y^*\| \leq \lambda_1 \|v^*\|$$

$$\Rightarrow \frac{1}{\|v^*\|} \leq \frac{\lambda_1}{\|y^*\|}.$$

But then

$$\|v - v^*\| \leq \frac{\|y - y^*\|}{\lambda_n}, \quad \frac{1}{\|v^*\|} \leq \frac{\lambda_1}{\|y^*\|}$$

$$\Rightarrow \frac{\|v - v^*\|}{\|v^*\|} \leq \frac{\lambda_1}{\lambda_n} \frac{\|y - y^*\|}{\|y^*\|}.$$

This is quite meaningful — the relative error in the data can be magnified by as much as $\frac{\lambda_1}{\lambda_n}$ when the equation is solved. We call $\frac{\lambda_1}{\lambda_n}$ the condition number of T (or of the equation $T(v) = y$). It is a measure of how sensitive the problem (of solving $T(v) = y$) is to noise in the data.

The condition number is a very powerful concept. It would be advantageous to have it available for $T \in \mathcal{L}(V, W)$ with no special property.

This whole exercise of understanding the "structure" of a linear operator $T \in \mathcal{L}(V)$ essentially reduces to the question of choosing a basis B for V such that $M_{B,B}(T)$ is as simple as possible.

If we allow different bases for the domain and codomain of T , it turns out that we can handle any $T \in \mathcal{L}(V)$, or even any $T \in \mathcal{L}(V, W)$.

Theorem: Let V, W be finite-dimensional inner product spaces over F (\mathbb{R} or \mathbb{C}) and let $T \in \mathcal{L}(V, W)$. Then there exist orthonormal bases $B = \{v_1, \dots, v_n\}$ of V and $C = \{w_1, \dots, w_m\}$ of W and real numbers $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_t \geq 0$, $t = \min\{m, n\}$, such that

$$T(v) = \sum_{j=1}^t \sigma_j \langle v, v_j \rangle_v w_j$$

Proof: Note that $T^*T \in \mathcal{L}(V)$ is self-adjoint:

$$\begin{aligned} \langle (T^*T)(v), u \rangle_v &= \langle T^*(T(v)), u \rangle_v = \langle T(v), T(u) \rangle_w \\ &= \langle v, T^*(T(u)) \rangle_v \\ &= \langle v, (T^*T)(u) \rangle_v. \end{aligned}$$

Thus there exists an orthonormal basis $B = \{v_1, \dots, v_n\}$ of V and

corresponding eigenvalues $\lambda_1, \dots, \lambda_n$ such that

$$(T^*T)(v) = \sum_{j=1}^n \lambda_j \langle v, v_j \rangle v_j \quad \forall v \in V.$$

Wlog we can assume that $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$. Note that

$$\begin{aligned} \lambda_j &= \lambda_j \langle v_j, v_j \rangle_V = \langle \lambda_j v_j, v_j \rangle_V = \langle (T^*T)(v_j), v_j \rangle_V \\ &= \langle T(v_j), T(v_j) \rangle_W \geq 0 \end{aligned}$$

$$\Rightarrow \lambda_j \geq 0$$

Define $r \geq 0$ such that

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > \lambda_{r+1} = \dots = \lambda_n = 0$$

($r=0$ in the trivial case that $T=0$; $r=n$ is possible).

Define $\sigma_j = \sqrt{\lambda_j}$ for $j=1, \dots, r$ and

$$w_j = \sigma_j^{-1} T(v_j), \quad j=1, \dots, r.$$

We then have

$$\begin{aligned} \langle w_j, w_j \rangle_W &= \langle \sigma_j^{-1} T(v_j), \sigma_j^{-1} T(v_j) \rangle_W \\ &= \sigma_j^{-2} \langle T(v_j), T(v_j) \rangle_W \\ &= \lambda_j^{-1} \langle T^*T(v_j), v_j \rangle_V \\ &= \lambda_j^{-1} \langle \lambda_j v_j, v_j \rangle_V = 1, \quad j=1, \dots, r, \end{aligned}$$

and

$$\begin{aligned}
\langle w_i, w_j \rangle_w &= \langle \sigma_i^{-1} T(v_i), \sigma_j^{-1} T(v_j) \rangle_w \\
&= \sigma_i^{-1} \sigma_j^{-1} \langle T(v_i), T(v_j) \rangle_w \\
&= \sigma_i^{-1} \sigma_j^{-1} \langle T^* T(v_i), v_j \rangle_v \\
&= \sigma_i^{-1} \sigma_j^{-1} \langle \lambda_i v_i, v_j \rangle_v \\
&= \sigma_i \sigma_j^{-1} \langle v_i, v_j \rangle_v = 0, \quad 1 \leq i, j \leq r, i \neq j.
\end{aligned}$$

Thus $\{w_1, \dots, w_r\}$ is an orthonormal subset of W , which implies that $r \leq n$ (also $r \leq n$ by definition). Let us extend $\{w_1, \dots, w_r\}$ to an orthonormal basis $\{w_1, \dots, w_n\}$ of W and define $\sigma_j = 0$ for $j = r+1, \dots, n$. If $r < n$ and $r < j \leq n$, then $\lambda_j = 0$, which implies that

$$\begin{aligned}
(T^* T)(v_j) &= 0 \\
\Rightarrow \langle v_j, (T^* T)(v_j) \rangle_v &= 0 \\
\Rightarrow \langle T(v_j), T(v_j) \rangle_w &= 0 \\
\Rightarrow T(v_j) &= 0.
\end{aligned}$$

We then have

$$\begin{aligned}
T(v) &= T\left(\sum_{j=1}^n \langle v, v_j \rangle_v v_j\right) \\
&= \sum_{j=1}^n \langle v, v_j \rangle_v T(v_j)
\end{aligned}$$

$$\begin{aligned}
&= \sum_{j=1}^r \sigma_j \langle v, v_j \rangle_v w_j && \text{(since } T(v_j) = \sigma_j w_j \text{ for } j=1, \dots, r \text{ and } T(v_j) = 0 \\
& && \text{for } j=r+1, \dots, n) \\
&= \sum_{j=1}^t \sigma_j \langle v, v_j \rangle_v w_j && \text{(since } \sigma_j = 0 \text{ for } r < j \leq t). //
\end{aligned}$$