Math 622 Lecture 5

Recall:

- · A basis for V is a linearly incluyed symming set for V.
- · Fundamental facts about bases:
 - If Svi,vi,...,vn3 is a basis for V, then each u ∈ V can be written uniquely as a linear combination of vi,vi,...,vn.
 - Assuming V is nontrivial and linearly independent,

 * every linearly undependent set in V is contained in a basis;

 * every spanning set for V contains a basis.

Here's another fundamental fact about bases:

Theorem: Any two bases for V contain the same number of vectors.

Proof: We have seen that every spanning set for V contains at least as many vectors as any linearly independent set. Let B, and B2 be bases for V. Then the number of elements of B1 (a linearly undependent set) is less than ar equal to the number of elements of B2 (a syanning set). But exactly the same reasoning shows that

the number of elements of B2 is less than or equal to the number of elements of B1. Therefore

|B1 | = |B2 | = |B1 | = |B2 |.//

Definition: Let V be a faite-dimensioned vector space. If V is nontrivial, then the dimension of V is the number of elements in a basis for V. If V is trivial, then dim(V)=0.

Examples

- $\{(1,0,0,0),(0,1,0,0),(0,0,1,0),(0,0,0,1)\}$ is a basis for F^{4} , So dim $(F^{4})=4$. Similarly, dim $(F^{n})=n$ $\forall n \in \mathbb{Z}^{+}$.
- " \[1, x, x^2, --, x^n \] is a basis for Bn, so dim (Bn) = n+1 \text{\text{\$\text{\$Y\$}}} \in \bar{Z}^t.

Theorem: If V is finite-dimensional and U is a subspace of V,
then dim(U) & dim(V).

Proof: Let $\{v_1, v_2, ..., v_n\}$ be a basis for U. Thun $\{v_1, v_2, ..., v_n\}$ is a linearly independent set in V and hence is contained in some basis $\{v_1, v_2, ..., v_n\}$ for V. It follows that $din[U] = k \le n = din[V]$

To prove that a given set is a basis, we must prove linear independence and spanning. The following theorem reduces the work in proving that a set is a basis, provided we know the dimension of the space.

Theorem: Let V be an n-dimensional vector space (whom $n \in \mathbb{Z}^+$). 1. If $\{v_1, v_2, ..., v_n\} \subseteq V$ is linearly independent, then it is a basis for V. 2. If $\{v_1, v_2, ..., v_n\} \subseteq V$ s pans V, it is a basis for V.

Proof: We know that every basis of V contains exactly a verters

- I. If {v,,v2,--,vn} \in V is linearly independent, then we have that is a subset of some basis. But if {v,,v2,--,vn} is a proper subspace of that basis, then the basis contains more than a vectors, which is impossible. Thus {v,,v2,--,vn} itself must be a basis for V.
- 2. If $\{v_{i},v_{1},...,v_{n}\}\in V$ spans V, then a subset of $\{v_{i},v_{1},...,v_{n}\}$ is a basis for V. But if the basis is a proper subset of $\{v_{i},v_{1},...,v_{n}\}$, then it contains fewer than a vectors, which is impossible. Thus $\{v_{i},v_{2},...,v_{n}\}$ itself must be a basis for V.

Example: Consider
$$v_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, v_2 = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \in \mathbb{R}^3$$
.

To preve that $\{v_i, v_i, v_3\}$ is a basis for TR^3 , we take advantage of the fact that $d_im(TR^3)=3$, and we have 3 vector. So we don't have to chech both linear independence and spanning, but only one. Linear independence is easier:

$$\alpha_1 V_1 + \alpha_2 V_2 + \alpha_3 V_3 = 0$$

$$\omega_1 + \alpha_2 + 2\alpha_3 = 0$$

$$\omega_1 - \alpha_2 + \alpha_3 = 0$$

$$\omega_1 - \alpha_2 + \alpha_3 = 0$$

At this point, we already
how that the only sol'n

is $\alpha_1 = \alpha_2 = \alpha_3 = 0$

$$\begin{bmatrix}
1 & 1 & 2 & 0 \\
2 & 1 & 0 & 0
\end{bmatrix}
\xrightarrow{\bullet}
\begin{bmatrix}
1 & 1 & 2 & 0 \\
0 & -1 & -4 & 0 \\
0 & -2 & -1 & 0
\end{bmatrix}
\xrightarrow{\bullet}
\begin{bmatrix}
1 & 1 & 2 & 0 \\
0 & -1 & -4 & 0 \\
0 & 0 & 7 & 0
\end{bmatrix}$$

Thus {v,v,v3} & livewhy independent and hence a basis.

Theorem: Let V be a finite-dimensional vector space and let U, U, he subspaces of V. Then

dim (U,+U2) = dim(U,) +dim(U2) - dim(U, NU2).

Proof: Let $\{u_1,...,u_j\}$ he a basis for $U_1 \cap U_2$ (in the special case that $U_1 \cap U_2 = \{0\}$, we replace this by the empty set and take j=0).

Since U, AUz is a subspace of U, we can extend Su, --, vij3to a basis Su, --, vij, vi, --, vij of U, , and since U, AUz is a subspace of Uz, we can extend Su,, -, vij3 to a basis Su, -, vij, w, -, vio) of Uz. Then

$$d_{im}(u, nu_{i}|=j,$$
 $d_{im}(u_{i})=j+h,$

$dim(U_z) = j+l$

It suffices to prove that (u,,-,uj,,v,,-,v,,w,,-,w,) is a basist for U,+U, since then

dun (U,+U,) = j+h+l = dim(h,) + din(U,) - din(U,NU2). Let us first prove that {u,, -, u, v,, -, w,} is linearly independent. Suppose

(x) $\omega_1 u_1 + \cdots + \omega_j u_j + \beta_1 v_1 + \cdots + \beta_u v_u + \delta_1 \omega_1 + \cdots + \delta_2 \omega_2 = 0$, and note that

Since $U_1 \cap U_2 \subseteq U_{i,j}$ it follows that $\alpha_1 u_i + \cdots + \alpha_j u_j + \beta_1 v_i + \cdots + \beta_k v_k \in U_i.$

But (x) implies that

 $\alpha_1 u_1 + \cdots + \alpha_j u_j + \beta_1 v_1 + \cdots + \beta_k v_k = - \sigma_1 \omega_1 - \cdots - \sigma_\ell \omega_\ell \in \mathcal{U}_2$

Thus

$$\Rightarrow$$
 $\angle_{u,+}$ $-+ \angle_{j}u_{j} + \beta_{j}v_{j} + \cdots + \beta_{u}v_{u} = \delta_{j}u_{i} + \cdots + \delta_{j}u_{j}$ for some $\delta_{j,-}, \delta_{j} \in F$

$$) \quad S_1 u_1 + \cdots + S_j u_j + S_1 w_1 + \cdots + S_\ell w_\ell = 0$$

Thus we have proven that [u,,-zuj, v,,-zV,,w,,-zwe] is linearly Melyandut.

Now we prove that [u,,-, uj, v,-, u, w,,-, wo 3 spans U,+ uz,

Let we U, + U2; then w = u+v for some ueU,, ve U2,

There exist dy--, dj, bu--, buEF such that

and 8,,-, Vi, fi,-, So EF such that

But the

W= U+V= (d,+x,)u,+ --+ (2,+x,)u,+ +>,v,+-+ &,w,+--+ &,w,

→ We span(u,, -, uj, v,, -, v,, w,, .-, w,).

Thus Su,,-, uj, Vi,-, Va, Wi, -, we I spans U,+U, and the proof is complete.