



MNIST Training for BNN

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Design Your Own CPU - Design of Embedded Systems



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- Training
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- Layers
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3. BNN Training Analysis

- Layer Analysis
- Parameter Analysis





■ The heart of deep learning

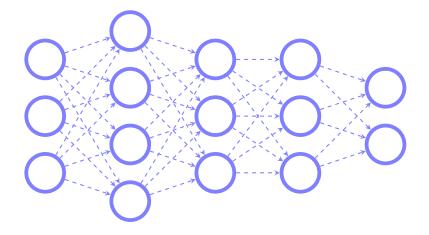


- The heart of deep learning
- Classify given data e.g. speech or image recognition

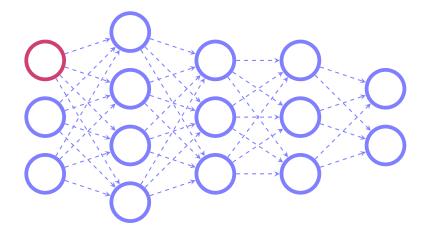


- The heart of deep learning
- Classify given data e.g. speech or image recognition
- Rely on training data

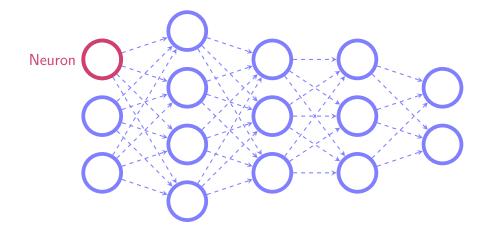












Neuron

lacksquare Holds a single value $v \in V_L$



Neuron

- Holds a single value $v \in V_L$
- Semantics depend on class of layer





Layer

Layer of neurons



Layer

- Layer of neurons
- Three types:
 - Input layer: Network input neurons
 - Hidden layer: Feature neurons
 - Output layer: Network output neurons

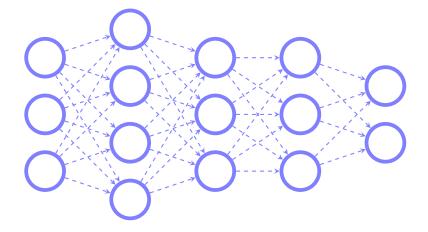




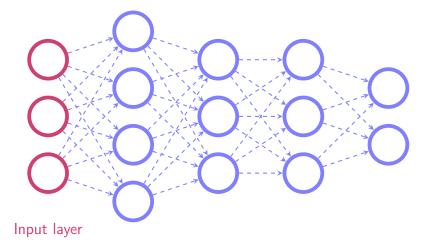


Layer

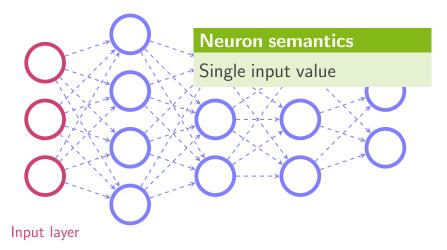




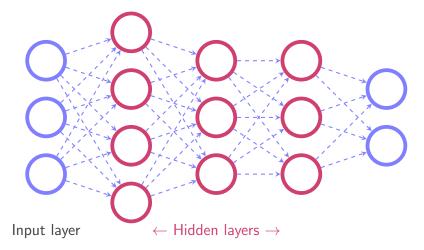




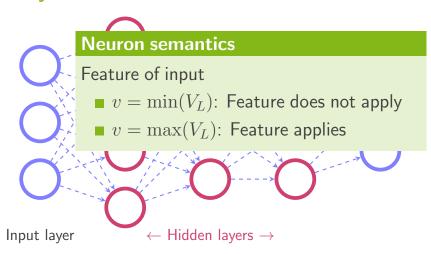




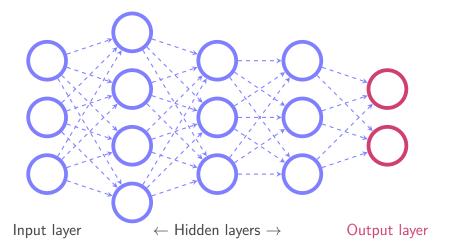




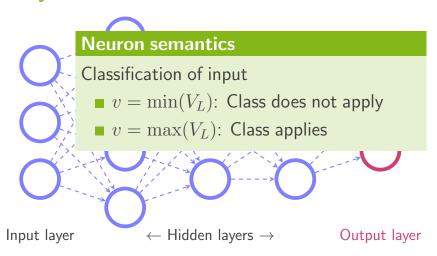




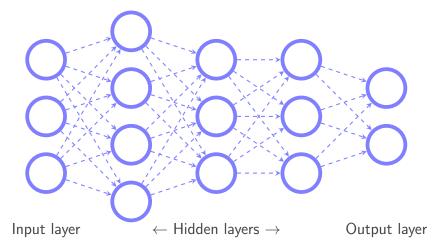




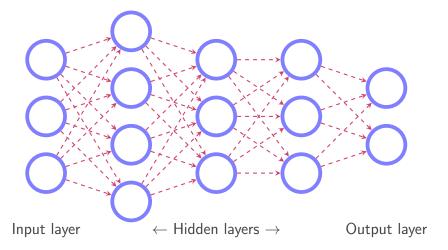






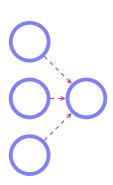






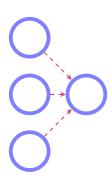


Connects all neurons between subsequent layers



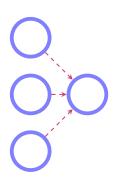


- Connects all neurons between subsequent layers
- Weighted



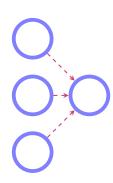


- Connects all neurons between subsequent layers
- Weighted
- Semantics: Higher weight
 - $\rightarrow \ \text{higher feature significance}$





- Connects all neurons between subsequent layers
- Weighted
- Semantics: Higher weight
 - ightarrow higher feature significance
- Training: Optimize weights!





Training



1. Input data



- 1. Input data
- 2. Run the network



- 1. Input data
- 2. Run the network
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|)



- 1. Input data
- 2. Run the network
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|)
- 4. Run error back through network, adjust weights

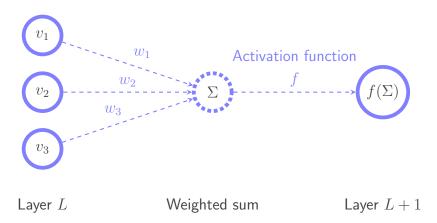


- Input data √
- 2. Run the network
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|)
- 4. Run error back through network, adjust weights



- Input data √
- 2. Run the network?
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|)
- 4. Run error back through network, adjust weights

Run the network





- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|)
- 4. Run error back through network, adjust weights



- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|) \checkmark
- 4. Run error back through network, adjust weights



Training (Cycle)

- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
 - \rightarrow Calculate error (|v expected|) \checkmark
- 4. Run error back through network, adjust weights?

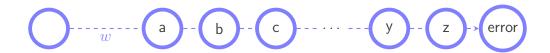


Adjusting weights

Backpropagation

Calculate change of error when adjusting some weight

 \rightarrow Slope

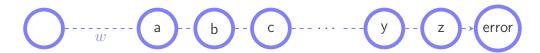




Adjusting weights

Backpropagation

Calculate change of error when adjusting some weight \rightarrow *Slope*



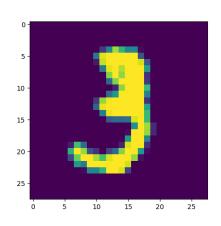
Chain rule

$$\frac{\delta \mathsf{error}}{\delta w} = \frac{\delta a}{\delta w} \cdot \frac{\delta b}{\delta a} \cdot \frac{\delta c}{\delta b} \cdot \dots \cdot \frac{\delta z}{\delta y} \cdot \frac{\delta \mathsf{error}}{\delta z}$$



Our Goal

- Create a BNN in PyTorch
- Image recognition on MNIST-Dataset
- \rightarrow Keep an accuracy of at least 90%
 - Export trained BNN





1. Neural Networks

- What is a neural network?
- Training
- Our Goa

2. BNN Design

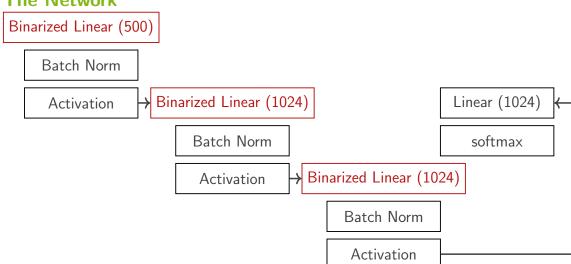
- The Network
- Layers
- Binarization of Input data

3. BNN Training Analysis

- Layer Analysis
- Parameter Analysis



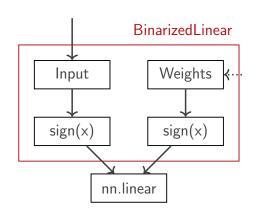
The Network





Binarisation of Linear Layer

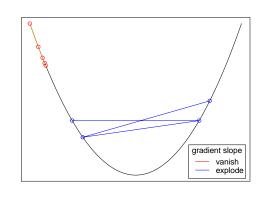
- binarisation of weights
- binarisation of input data for hidden layers
- calculation through nn.linear





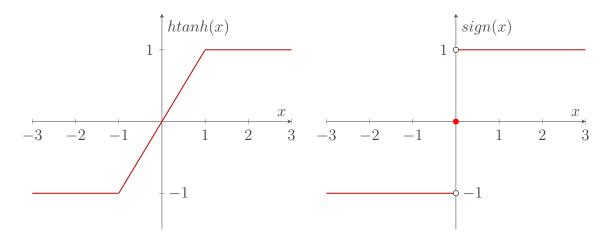
Batch Norm (BN)

- Batches = data calculated in parallel
- In NN
 - normalize batches
 - mean 0
 - standard derivation 1
- In BNN
 - prevent expolding gradient



Х

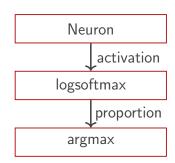
Activation



Evaluation of last layer

- normalisation of activation
- decision of the network

$$LogSoftmax(x_i) = log(\frac{e^{x_i}}{\sum_{i} e^{x_j}})$$





Binarization of Input data



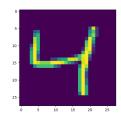
Binarization of Input data

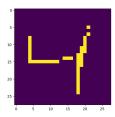
- Mapping 255 values to 0,1
- minimize accuracy losses
- 2 approaches
 - Threshold
 - Probability



Threshold-Binarization

- define static threshold
- filter pixel-array via: pixel > threshold

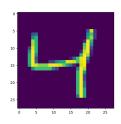


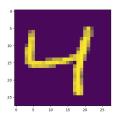




Probability-Binarization

- each pixelvalue dictates its prob for being 1
- binarize same trainingset multiple times
 - Run each epoche with all trainingsets







Comparison Threshold, Prob

- Threshold
 - Using integrated tensor-functions
 - 150ms per iteration
 - Convergence after approx.100 epochs

- Probability
 - Iterate through tensor manually
 - 250ms per iteration
 - Convergence after approx.20*30 iterations



Evaluating Accuracy-Loss

Run	Non-Binarized	threshold	prob
1	91.99%	89.24%	92.52%
2	91.99%	89.24%	91.82%
3	91.99%	89.24%	92.56%
4	91.99%	89.24%	91.02%
avg	91.99%	89.24%	91.98%

- 600 epochs for threshold, default
- 20 epochs, 30 trainingsets for prob



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Consequences of linear layer binarisation

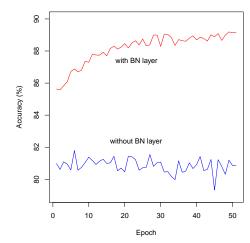
Run	binary	normal
1	88.29%	97.43%
2	87.32%	96.98%
3	87.19%	97.2%

- training for 50 epochs
- mean loss of 9,6%
- loss in granularity



Effect of Batch Norm

- 7.4% improved peak performance
- Less jitter with BN
- Reduced expolding gradient





Parameter Analysis



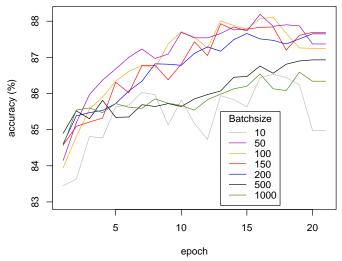
Batch size

- frequency of error calculation
- normalisation though Batch Norm
- rate of parallelization

Batchsize	Time (s)
10	30,68
50	11,33
100	8,76
150	7,95
200	7,63
500	6,66
1000	6,39



Evaluation of Batch size



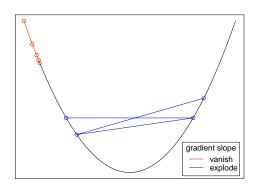
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BNN Training Analysis: Parameter Analysis



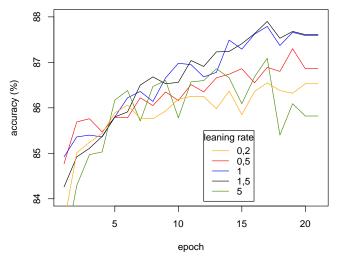
Learning rate

- lacktriangle higher value ightarrow more weights are updated
- balance between vanishing- and exploding gradient





Evaluation learning rate





Thank you for your attention!