



#### **MNIST Training for BNN**

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Design Your Own CPU - Design of Embedded Systems



#### **Content**

#### 1. Neural Networks

- What is a neural network?
- Training
- Pytorch

#### 2. BNN Design

- The Network
- Layers
- Binarization of Input data

#### 3. BNN Training Analysis

- Layer Analysis
- Parameter Analysis





■ The heart of deep learning

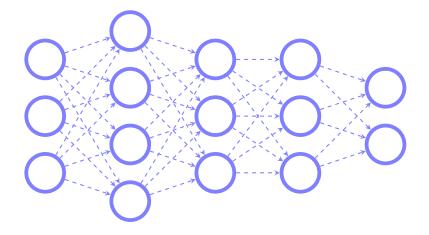


- The heart of deep learning
- Classify given data e.g. speech or image recognition

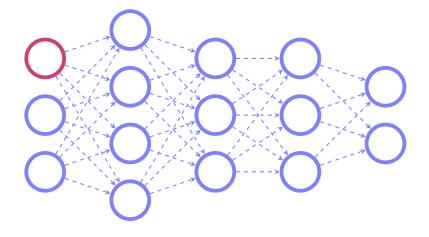


- The heart of deep learning
- Classify given data e.g. speech or image recognition
- Rely on training data

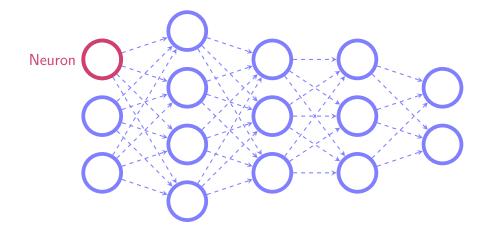












#### Neuron

■ Holds a single value  $v \in V_L$ 



#### Neuron

- Holds a single value  $v \in V_L$
- Semantics depend on class of layer





### Layer

Layer of neurons





### Layer

- Layer of neurons
- Three types:
  - Input layer: Network input neurons
  - Hidden layer: *Feature neurons*
  - Output layer: Network output neurons

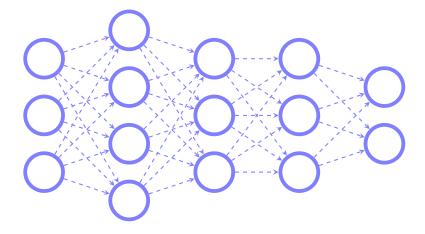




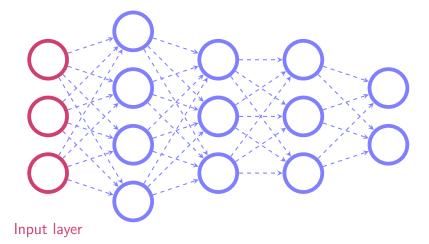


Layer

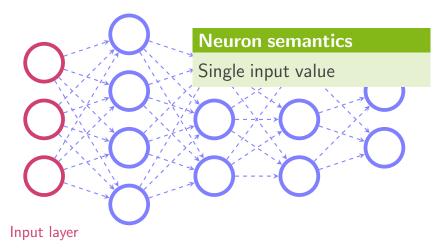




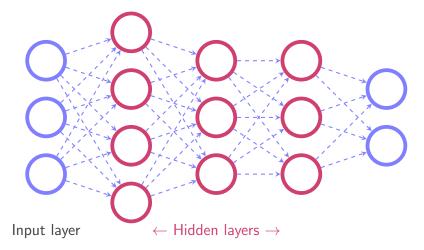




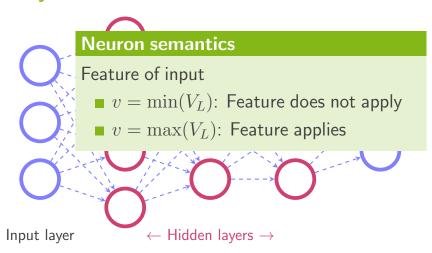




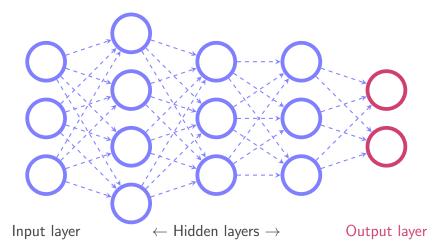




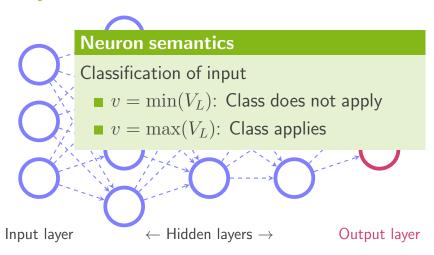




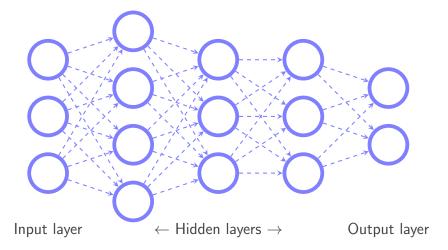




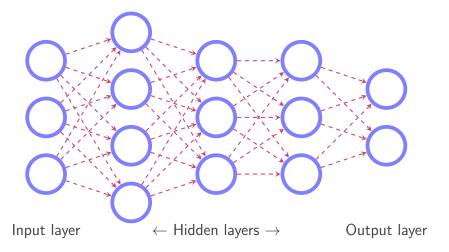






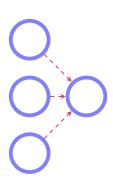






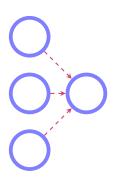


Connects all neurons between subsequent layers



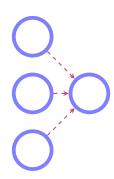


- Connects all neurons between subsequent layers
- Weighted



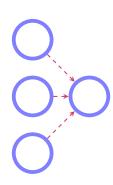


- Connects all neurons between subsequent layers
- Weighted
- Semantics: Higher weight
  - $\rightarrow \ \text{higher feature significance}$





- Connects all neurons between subsequent layers
- Weighted
- Semantics: Higher weight
  - $\rightarrow$  higher feature significance
- Training: Optimize weights!





# **Training**



1. Input data



- 1. Input data
- 2. Run the network



- 1. Input data
- 2. Run the network
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)



- 1. Input data
- 2. Run the network
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)
- 4. Run error back through network, adjust weights

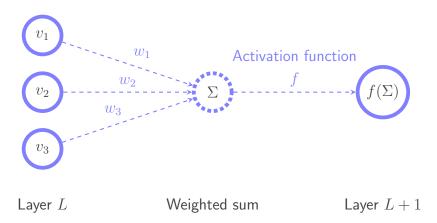


- Input data √
- 2. Run the network
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)
- 4. Run error back through network, adjust weights



- Input data √
- 2. Run the network?
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)
- 4. Run error back through network, adjust weights

#### Run the network





- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)
- 4. Run error back through network, adjust weights



- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)  $\checkmark$
- 4. Run error back through network, adjust weights



## **Training (Cycle)**

- Input data √
- 2. Run the network ✓
- 3. Compare output with expected values
  - $\rightarrow$  Calculate error (|v expected|)  $\checkmark$
- 4. Run error back through network, adjust weights?

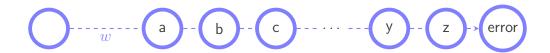


### **Adjusting weights**

### **Backpropagation**

Calculate change of error when adjusting some weight

 $\rightarrow$  Slope



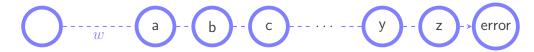


### **Adjusting weights**

## Backpropagation

Calculate change of error when adjusting some weight

ightarrow Slope



#### Chain rule

$$\frac{\delta \mathsf{error}}{\delta w} = \frac{\delta a}{\delta w} \cdot \frac{\delta b}{\delta a} \cdot \frac{\delta c}{\delta b} \cdot \dots \cdot \frac{\delta z}{\delta y} \cdot \frac{\delta \mathsf{error}}{\delta z}$$



# **Pytorch**



#### **Pytorch**

- Framework for NNs in Python
- lacksquare Easy to use o good for testing
- works cuda-accelerated



#### 1. Neural Networks

- What is a neural network?
- Training
- Pytorch

#### 2. BNN Design

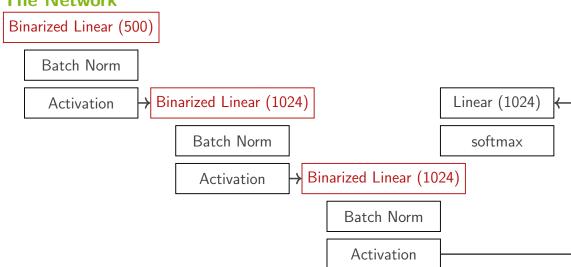
- The Network
- Layers
- Binarization of Input data

#### 3. BNN Training Analysis

- Layer Analysis
- Parameter Analysis



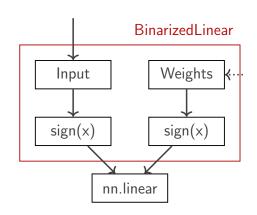
#### The Network





### **Binarisation of Linear Layer**

- binarisation of weights
- binarisation of input data for hidden layers
- calculation through nn.linear

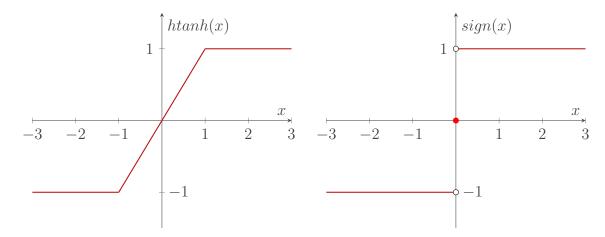




## Batch Norm (BN)

- In NN
  - normalize batches
  - mean 0
  - standard derivation 1
- In BNN
  - prevent expolding gradient

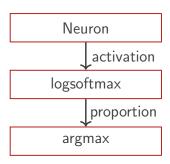
#### **Activation**





### **Evaluation of last layer**

- normalisation of activation
- decision of the network





# Binarization of Input data



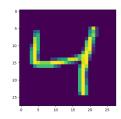
### Binarization of Input data

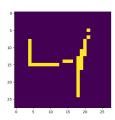
- Mapping 255 values to 0,1
- minimize accuracy losses
- 2 approaches
  - Threshold
  - Probability



#### **Threshold-Binarization**

- define static threshold
- filter pixel-array via: pixel > threshold

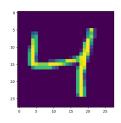


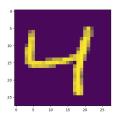




## **Probability-Binarization**

- each pixelvalue dictates its prob for being 1
- binarize same trainingset multiple times
  - Run each epoche with all trainingsets







### Comparison Threshold, Prob

- Threshold
  - Using integrated tensor-functions
  - 150ms per iteration
  - Convergence after approx.100 epochs

- Probability
  - Iterate through tensor manually
  - 250ms per iteration
  - Convergence after approx.20\*30 iterations



### **Evaluating Accuracy-Loss**

Run	Non-Binarized	threshold	prob
1	91.99%	89.24%	92.52%
2	91.99%	89.24%	91.82%
3	91.99%	89.24%	92.56%
4	91.99%	89.24%	91.02%
avg	91.99%	89.24%	91.98%

- 600 epochs for threshold, default
- 20 epochs, 30 trainingsets for prob



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### Consequences of linear layer binarisation

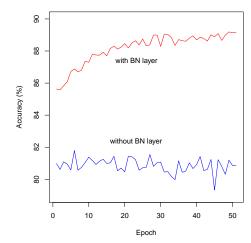
Run	binary	normal
1	88.29%	97.43%
2	87.32%	96.98%
3	87.19%	97.2%

- training for 50 epochs
- mean loss of 9,6%
- loss in granularity



#### **Effect of Batch Norm**

- 7.4% improved peak performance
- Less jitter with BN
- Reduced expolding gradient





## **Parameter Analysis**



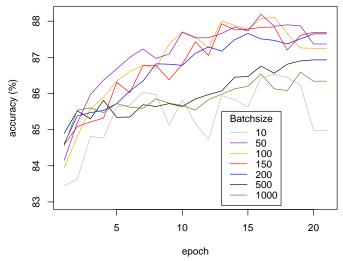
#### Batch size

- frequency of error calculation
- rate of parallelization

Batchsize	Time (s)
10	30,68
50	11,33
100	8,76
150	7,95
200	7,63
500	6,66
1000	6,39



#### **Evaluation of Batch size**



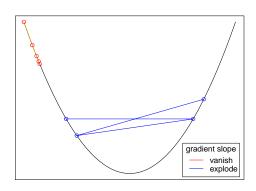
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BNN Training Analysis: Parameter Analysis



#### **Learning rate**

- lacktriangle higher value ightarrow more weights are updated
- balance between vanishing- and exploding gradient





#### evaluation learning rate

