

Vibrations (ch24)

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- Motivation

- Plate
- PianoTeq
- Earthquakes - Inge Lehmann
- Bruel og Kjaer

Redefine...

- Position of material particle at time t . (originally located at \mathbf{x})

- $\mathbf{x} + \mathbf{u}(\mathbf{x}, t)$

- *Note: this is different from strain chapter where \mathbf{x} was new pos.*

- So velocity field and acceleration field.

- $\mathbf{v} = \partial \mathbf{u} / \partial t$

- $\mathbf{w} = \partial^2 \mathbf{u} / \partial t^2$

TODO: consider D/Dt ..
more formally correct
Is this because these are
formulated as functions of orig pos.

- We aim to model small vibrations around an equilibrium state.

- The initial state may already be stressed and deformed.
 - (E.g. a piano frame is already under tremendous stress)
 - (So we can ignore body forces.)

- Probably have a good idea where we are going with this.

- $\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mathbf{f}^* = \cancel{\mathbf{f}} + \nabla \cdot \boldsymbol{\sigma}$

- Hooke:

- $\boldsymbol{\sigma} = 2\mu\boldsymbol{\epsilon} + \lambda \mathbf{I} \text{tr}(\boldsymbol{\epsilon})$

- Definition of cauchy strain tensor

- $\boldsymbol{\epsilon} = \mathbf{u} = \frac{1}{2}(\nabla \mathbf{u} + \nabla \mathbf{u}^T)$

- It would be simple to update our elastostatics cheese
 - Finite Diff code to have a velocity field.

Combine

- Assume isotropic medium
 - (so that we can treat material properties as constants)
- And insert (not shown – but see ch9 in index notation)
- $\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$
- “Navier’s equation of motion”
- You can already see it looks like a wave equation.
 - Second order time deriv. proportional to second order spatial deriv.
 - But now \mathbf{u} is a vector.

Splitting \mathbf{u} to transverse/longitudinal

- $\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$
- We can split \mathbf{u} into two components
 - $\mathbf{u} = \mathbf{u}_L + \mathbf{u}_T$
 - \mathbf{u}_T is divergence free. $\nabla \cdot \mathbf{u}_T = 0$
 - \mathbf{u}_L is curl free (purely divergent). $\nabla \times \mathbf{u}_L = 0$
- Motivation for this split.
 - Naviers eqn has two RHS terms – one deals purely with divergence.

- Divergence in displacement is associated with density and thus pressure change.
- For this reason the longitudinal component is also called the pressure or p-component.
- The divergence free transverse component (no pressure change) is also called the shear component or S-component.

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$$

Inserting...

- $\rho \frac{\partial^2 \mathbf{u}_T}{\partial t^2} = \mu \nabla^2 \mathbf{u}_T$
- Using $\nabla \times (\nabla \times \mathbf{u}_L) = \nabla(\nabla \cdot \mathbf{u}_L) - \nabla^2 \mathbf{u}_L$
- $\rho \frac{\partial^2 \mathbf{u}_L}{\partial t^2} = (2\mu + \lambda) \nabla^2 \mathbf{u}_L$
- Completely separate (uncoupled equations.)

- Two wave equations, different speeds

- $c_T = \sqrt{\frac{\mu}{\rho}}$
- $c_L = \sqrt{\frac{2\mu + \lambda}{\rho}}$

$$\rho \frac{\partial^2 \mathbf{u}_T}{\partial t^2} = \mu \nabla^2 \mathbf{u}_T$$

$$\rho \frac{\partial^2 \mathbf{u}_L}{\partial t^2} = (2\mu + \lambda) \nabla^2 \mathbf{u}_L$$

- Longitudinal faster than transverse.
 - Pressure faster than Shear
 - P & S conveniently also maps to Primary/secondary waves.
- Speed ratio can be rewritten in terms of poisson ratio.
- For normal materials (where $\nu = \frac{1}{3}$). $c_L = 2c_T$

- That's a wave-eqn...
- Natural to write the displacement as a harmonic series
 - Fourier – possible for any time dependent field
- So, if we figure something out for an oscillation of the form :

$$\mathbf{u}(\mathbf{x}) \cdot e^{-i\omega t}$$

Real part is the displacement. $\mathbf{u}(\mathbf{x}, t)$

Imag part: $\partial_t \mathbf{u}(\mathbf{x}, t) / \omega$

- Then we can superpose those to get to a more general soln.

Insert harmonic oscillation in Navier.

- $\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$

- $\mathbf{u}(\mathbf{x}, t) = \mathbf{u}(\mathbf{x}) \cdot e^{-i\omega t}$

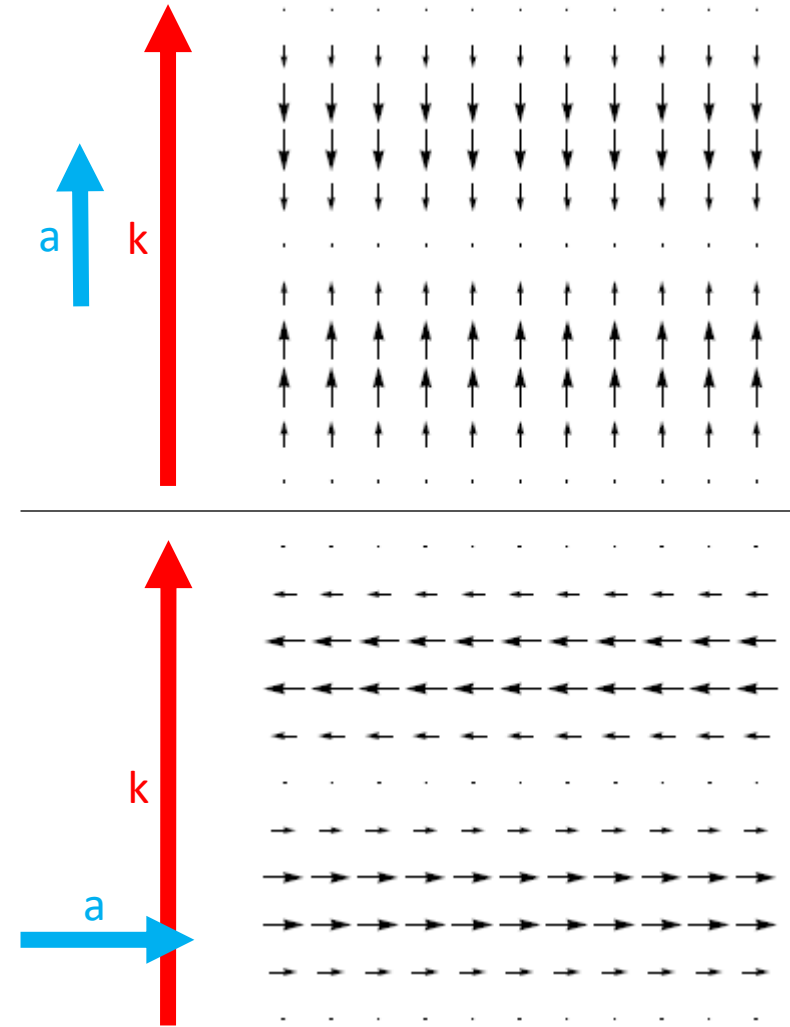
- $-\rho \omega^2 \mathbf{u} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$

- Now we have a time independent equation for $\mathbf{u}(\mathbf{x}, \omega)$

Consider a plane wave

$$-\rho\omega^2 \mathbf{u} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$$

- $\mathbf{u}(\mathbf{x}, t) = \mathbf{a} \cdot e^{i(\mathbf{k} \cdot \mathbf{x} - \omega t)}$
- \mathbf{k} : propagation direction & wavelength
- \mathbf{a} : “polarization vector” - complex



$$-\rho\omega^2 \mathbf{u} = \mu \nabla^2 \mathbf{u} + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u}$$

$$\mathbf{u}(\mathbf{x}, t) = \mathbf{a} \cdot e^{i(\mathbf{k} \cdot \mathbf{x} - \omega t)}$$

- If we insert $t=0$ then we can see how the wavelength $\frac{2\pi}{|\mathbf{k}|}$ is related to \mathbf{a} , ω

- $-\rho\omega^2 \mathbf{a} = \mu \mathbf{k}^2 \mathbf{a} + (\lambda + \mu) \mathbf{k} \mathbf{k} \cdot \mathbf{a}$

- Eigen-value equation

for the 3×3 matrix $\mu \mathbf{k}^2 \mathbf{1} + (\lambda + \mu) \mathbf{k} \mathbf{k} = \{\mu k^2 \delta_{ij} + (\lambda + \mu) k_i k_j\}$.

Eigen-value equation

what can we use that for?

- For a given propagation direction \mathbf{k}
- You can find the 3 eigenvectors \mathbf{a}
- -with corresponding eigenvalues $\rho\omega^2$
- I.e. 3 distinct 'modes' of polarization which are characterized by their own wavelength.

- Eigenvector 1: ***a*** aligned with ***k***
 - Eigenvalue 1: $\rho\omega^2 = (\lambda + 2\mu)\mathbf{k}^2$
 - Longitudinal – P-wave
- Eigenvectors 2&3: **a** perpendicular to **k**
 - Eigenvalue: $\rho\omega^2 = 2\mu\mathbf{k}^2$
 - Transverse – S-wave