Department of Mechatronic Engineering MXEN4000 - Mechatronic Engineering Research Project 1 Progress Report

Navigation Assistance for a Semi-Autonomous Smart Wheelchair

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Abstract

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1 Introduction

[1]

2 Aims

3 Results and Discussion

4 Future Work

5 References

[1] M. R. M. Tomari, Y. Kobayashi, and Y. Kuno, "Enhancing Wheelchair's Control Operation of a Severe Impairment User," in *The 8th International Conference on Robotic, Vision, Signal Processing & Power Applications*, H. A. Mat Sakim and M. T. Mustaffa, Eds., Singapore: Springer Singapore, 2014, pp. 65–72, ISBN: 978-981-4585-42-2. DOI: 10.1007/978-981-4585-42-2.