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NON-COMMUTING INTEGRALS OF MOTION IN XXZ MODEL

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Abstract

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Introduction

1.1 Motivation

1.2 Structure



XXZ model

We investigate a one dimensional XXZ Hamiltonian on a one-dimensional lattice of L sites with periodic boundary conditions. Throughout this thesis we will work in units such that $\hbar = 1$.

Spin operator algebra:

$$\begin{aligned} [S_i^\alpha, S_k^\beta] &= i\delta_{i,k}\epsilon_{\alpha\beta\gamma}S_i^\gamma \\ S_i^\pm &= S_i^x \pm iS_i^y \\ [S_i^+, S_k^+] &= 2\delta_{i,k}S_i^z \\ [S_i^z, S_k^\pm] &= \pm\delta_{i,k}S_i^\pm \end{aligned}$$

Write about tensor product, Hilbert space structure and such
Heisenberg Hamiltonian:

$$H_{XXZ} = J \sum_{j=1}^L (S_j^+ S_{j+1}^- + S_j^- S_{j+1}^+) + J\Delta \sum_{j=1}^L S_j^z S_{j+1}^z + \alpha H' \quad (2.1)$$

where H' is the perturbation that breaks integrability for nonzero α :

$$H' = \sum_{j=1}^L S_j^z S_{j+2}^z \quad (2.2)$$

We set $J = 1$ and subsequently work in units of J .



Integrals of motion

The problem of our interest is the systematic classification of all local and quasilocal integrals of motion (LIOMs and QLIOMs) supported on $m \in \mathbb{N}$ sites in a model given by 1-D tight-binding Hamiltonian H . To this end, we employ the algorithm first proposed in Mierzejewski, Prelovšek, and Prosen [1]. It allows us to classify integrals of motions for a given system size L . After doing so for accessible values of L , we then carry out finite size scaling to obtain information about the thermodynamic limit $L \rightarrow \infty$.

In our description and notation used, we will follow the works of Mierzejewski, Prelovšek, and Prosen [1], Mierzejewski et al. [2], and Mierzejewski, Kozarzewski, and Prelovšek [3]. The aim of this thesis is to provide a pedagogical introduction to the topic, so all derivations are presented in full detail, together with a simple proof of correctness for the algorithm.

3.1 Preliminaries

Space of observables Consider the vector space \mathcal{V}_L of traceless and translationally invariant observables, acting on a Hilbert space of dimension \mathcal{D} . We can define an inner product on this space:

$$(A|B) = \frac{1}{\mathcal{D}} \text{tr}(A^\dagger B) = \frac{1}{\mathcal{D}} \sum_{mn} A_{nm} B_{nm}^* \quad (3.1)$$

i.e. the Hilbert-Schmidt product, where $A_{nm} = \langle n|A|m\rangle$ and $H|n\rangle = E_n|n\rangle$. Moreover, we define the Hilbert-Schmidt norm of an operator to be $\|A\| = \sqrt{(A|A)}$. This product corresponds to the infinite temperature limit of averaging over a suitable ensemble (either canonical or grand canonical). Presented definitions are correct, as we work only with finite dimensional Hilbert spaces and taking the trace is a linear operation. We require the operators to be traceless, because they have zero overlap with the identity, $(A|\mathcal{I}) = \frac{1}{\mathcal{D}} \text{tr}(A) = 0$. Now we consider a subspace \mathcal{V}_L^m of m -local operators and a direct sum $\mathcal{V}_L^M = \bigoplus_{m=1}^M \mathcal{V}_L^m$ being a subspace of operators supported on up to M sites. We also define a basis of \mathcal{V}_L^M consisting of operators $O_s \in \mathcal{V}_L^M$ satisfying the following properties:

$$\begin{aligned} (O_s|O_t) &= \delta_{s,t} && \text{(orthonormality)} \\ (\forall A \in \mathcal{V}_L^M) \left(A &= \sum_s (O_s|A) O_s \right) && \text{(completeness)} \\ (\forall A \in \mathcal{V}_L) \left(A &= A^M + A^\perp = \sum_s (O_s|A) O_s + A^\perp \right), \text{ such that } (\forall s) ((O_s|A^\perp) = 0) && (3.2) \end{aligned}$$

Locality We begin with a definition of integral of motion in quantum mechanics.

Definition 3.1 Let H be a Hamiltonian operator. Then, any observable O fulfilling the equation:

$$[H, O] = 0$$

is an *integral of motion*.

It is easy to see, that there are many such observables. Let us consider the following

3.2 (Q)LIOMs finding algorithm

We now introduce a finite time averaging of an operator $A \in \mathcal{V}_L^M$, employing the Heisenberg picture [2]:

$$\begin{aligned}\bar{A}^\tau &= \frac{1}{\tau} \int_0^\tau dt A_H(t) = \frac{1}{\tau} \int_0^\tau dt e^{iHt} A e^{-iHt} = \sum_{m,n} \frac{1}{\tau} \int_0^\tau dt e^{iE_m t} |m\rangle \langle m| A |n\rangle \langle n| e^{-iE_n t} = \\ &= \sum_{m,n} A_{mn} |m\rangle \langle n| \frac{1}{\tau} \int_0^\tau dt e^{i(E_m - E_n)t} = \sum_{m,n} A_{mn} |m\rangle \langle n| \frac{1}{\tau} \frac{1}{i(E_m - E_n)} \left(e^{i(E_m - E_n)\tau} - 1 \right) \\ &= \sum_{m,n} A_{mn} |m\rangle \langle n| e^{i(E_m - E_n)\tau/2} \times \frac{\sin((E_m - E_n)\tau/2)}{\tau(E_m - E_n)}\end{aligned}\quad (3.3)$$

What this procedure does is essentially a cut off (cf. Figure 3.2) of for matrix elements determined by the value of $E_m - E_n$ in relation to the averaging time τ . However, this expression is quite complicated and therefore we replace it with a simplified time averaging (henceforth time averaging):

Definition 3.3 (Simplified time averaging)

$$\bar{A}^\tau \equiv \sum_{m,n} \theta\left(\frac{1}{\tau} - |E_m - E_n|\right) A_{mn} |m\rangle \langle n| = \sum_{m,n} \theta_{mn}^\tau A_{mn} |m\rangle \langle n| \quad (3.4)$$

where θ is the Heaviside step function, is the time averaged version of operator A .

Going to the infinite time limit we obtain the time averaging from Mierzejewski, Prelovšek, and Prosen [1]:

$$\bar{A} = \lim_{\tau \rightarrow \infty} \bar{A}^\tau = \sum_{\substack{m,n \\ E_m = E_n}} A_{mn} |m\rangle \langle n| \quad (3.5)$$

The quantity $(\bar{A}|\bar{A})$ is called the stiffness of operator A and corresponds to the infinite time limit of its autocorrelation function.

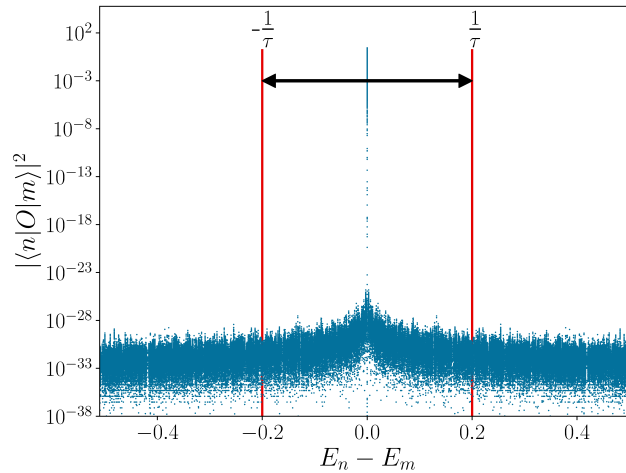


Figure 3.2: Illustration of averaging procedure as defined by equation (3.3). The sum of matrix elements is restricted by the theta function to the region between the two red lines. In the case of operator in question, we see that only the matrix elements corresponding to differences of energies very close to zero contribute to the time average.

Observing that $(\theta_{mn}^\tau)^2 = \theta_{mn}^\tau$ and $(\bar{A}^\tau)_{mn} = \theta_{mn}^\tau A_{mn}$ we can easily show some crucial properties of the time averaging:



Proposition 3.1 For any $A, B \in \mathcal{V}_L$

$$(\bar{A}^\tau | \bar{B}^\tau) = (A | \bar{B}^\tau) = (\bar{A}^\tau | B)$$

and

$$\overline{(\bar{A}^\tau)}^\tau = (\bar{A}^\tau)$$

Proof.

$$\begin{aligned} (\bar{A}^\tau | \bar{B}^\tau) &= \frac{1}{\mathcal{D}} \sum_{mn} (\bar{A}^\tau)_{mn} (\bar{B}^\tau)_{mn}^* = \frac{1}{\mathcal{D}} \sum_{mn} (\theta_{mn}^\tau)^2 A_{mn} B_{mn}^* \\ &= \frac{1}{\mathcal{D}} \sum_{mn} (\theta_{mn}^\tau) A_{mn} B_{mn}^* = (A | \bar{B}^\tau) = (\bar{A}^\tau | B) \\ \overline{(\bar{A}^\tau)}^\tau &= (\theta_{mn}^\tau)^2 A_{mn} = \theta_{mn}^\tau A_{mn} = (\bar{A}^\tau) \end{aligned}$$

These two facts reveal an interesting interpretation of the time averaging, namely that it can be thought of as an orthogonal projection in vector space \mathcal{V}_L . The involutive character of this operation explains, why we can consider \bar{A}^τ time independent in the time window $(0, \tau)$.

Let us now calculate the commutator of time-averaged operator with the Hamiltonian:

$$\begin{aligned} [H, \bar{A}^\tau] &= \sum_n \sum_{k,p} E_n \theta_{kp}^\tau A_{kp} [|n\rangle\langle n|, |k\rangle\langle p|] \\ &= \sum_{k,p} (E_k - E_p) \theta_{kp}^\tau A_{kp} |k\rangle\langle p| \xrightarrow{\tau \rightarrow \infty} 0 \end{aligned} \quad (3.6)$$

The last limit follows directly from equation (3.5). We can see that the infinite time averaging procedure creates an integral of motion, i.e. $[H, \bar{A}] = 0$. Nonetheless, it is not enough to just time average a local operator in order to get a local integral of motion, because in general $A \in \mathcal{V}_L^M \not\Rightarrow \bar{A} \in \mathcal{V}_L^M$, that is the truncation of matrix elements modifies the support of an operator. One possible approach to checking its locality would be to express this operator in the basis defined in (3.2). If for some M we have $\bar{A} \in \mathcal{V}_L^M$, then it is local. Second possibility is that it can be written as a convergent series of operators from \mathcal{V}_L^m with increasing m — then it is quasilocal. Otherwise it is a generic nonlocal quantity. But can we do better than this direct approach?

To answer this question, we fix $0 \leq M \leq L/2$ and construct a basis $\{O_s\}$ of \mathcal{V}_L^M . How to actually perform such construction will be shown in Section 3.4. Next, we find time averages of all basis operators and build a matrix

$$K_{st}^\tau = \left(\bar{O}_s^\tau | \bar{O}_t^\tau \right) \quad (3.7)$$

This matrix is Hermitian by design. However, we assume that it is real and symmetric, as usually considered operators are of the form $O + O^\dagger$ or $i(O - O^\dagger)$. Therefore, the spectral theorem guarantees existence of an orthogonal matrix U that diagonalizes it. In other words, $D = UK^\tau U^T$ is diagonal and we have the following relations:

$$\begin{aligned} \sum_{s,t} U_{ns} K_{st}^\tau U_{tm}^T &= \delta_{nm} \lambda_n \in \mathbb{R}, \quad \lambda_n \text{ — eigenvalue of } K^\tau \\ UU^T = U^T U &= \mathbb{1} \implies \sum_s U_{ns} U_{sm}^T = \delta_{mn} \\ UK = DU &\implies \sum_s U_{ns} K_{st}^\tau = \sum_s \delta_{ns} \lambda_s U_{st} = \lambda_n U_{nt} \end{aligned} \quad (3.8)$$

With the help of the U matrix (eigenvectors of K^τ) we can define a new set of rotated operators that are time-independent in the window $(0, \tau)$:

$$Q_n = \sum_s U_{ns} \bar{O}_s^\tau \quad (3.9)$$

Proposition 3.2 *Operators Q_n are orthogonal, i.e. $(Q_n|Q_m) \propto \delta_{nm}$*

Proof. Let Q_n, Q_m be two operators defined as in (3.9). Their orthogonality can be shown by direct calculation:

$$\begin{aligned} (Q_n|Q_m) &= \sum_{s,t} U_{ns} \left(\bar{O}_s^\tau | \bar{O}_t^\tau \right) U_{tm}^T = \sum_t \left(\sum_s U_{ns} K_{st}^\tau \right) U_{tm}^T \\ &\triangleq \lambda_n \sum_t U_{nt} U_{tm}^T \triangleq \lambda_n \delta_{mn} \end{aligned}$$

■

The last two equalities, marked with \triangleq , follow from properties (3.8). We can learn something more about the eigenvalues of K^τ matrix from a simple corollary to Proposition 3.2.

Corollary 3.1 *K^τ is a positive semi-definite matrix.*

Proof. Let Q_n be defined as in (3.9). Then, from the defining properties of inner product we have that $(Q_n|Q_n) \geq 0$. However, we also have that $(Q_n|Q_n) = \lambda_n$. Combining these two equations, we get that $(\forall n) (\lambda_n \geq 0)$. Therefore K^τ is a positive semi-definite matrix. ■

This corollary provides us with a lower bound on spectrum of matrix K^τ .

Let us now examine the support of Q_n . By (3.2) and making use of Proposition 3.1 and properties (3.8), we can decompose into M -local part and nonlocal part:

$$\begin{aligned} Q_n &= \sum_s (O_s|Q_n) O_s + Q_n^\perp = \sum_{s,t} U_{nt} (O_s|\bar{O}_t^\tau) O_s + Q_n^\perp \\ &= \sum_{s,t} U_{nt} (\bar{O}_s^\tau|\bar{O}_t^\tau) O_s + Q_n^\perp = \sum_{s,t} U_{nt} K_{ts} O_s + Q_n^\perp \\ &= \sum_s \left(\sum_t U_{nt} K_{ts}^\tau \right) O_s + Q_n^\perp = \sum_s \lambda_n U_{ns} O_s + Q_n^\perp = Q_n^M + Q_n^\perp \end{aligned} \quad (3.10)$$

Now we are ready to derive central result, stating why this actually algorithm works. Combining the fact that $(Q_n|Q_n) = \lambda_n$ (see proof of Proposition 3.2) with (3.10) we obtain:

$$\begin{aligned} \lambda_n &= (Q_n|Q_n) = (Q_n^M + Q_n^\perp|Q_n^M + Q_n^\perp) = (Q_n^M|Q_n^M) + (Q_n^\perp|Q_n^\perp) + \underbrace{2(Q_n^M|Q_n^\perp)}_{=0 \text{ (cf. (3.2))}} \\ &= \left(\sum_s \lambda_n U_{ns} O_s \middle| \sum_t \lambda_n U_{nt} O_t \right) + \|Q_n^\perp\|^2 = \lambda_n^2 \sum_{s,t} U_{ns} (O_s|O_t) U_{tn}^T + \|Q_n^\perp\|^2 \\ &= \lambda_n^2 + \|Q_n^\perp\|^2 \end{aligned} \quad (3.11)$$

Rearranging the above equality we get that $\lambda_n - \lambda_n^2 = \|Q_n^\perp\|^2 \geq 0$, which together with Corollary 3.1 gives $\lambda_n \in [0, 1]$.

From now on, we will focus on the case $\tau \rightarrow \infty$, as it guarantees that \bar{O}_s 's and hence Q_n 's commute with the Hamiltonian. Consequently, we finally arrive at a classification scheme for the support of Q_n 's.

Definition 3.4 (Classification of IOMs) *An integral of motion Q_n is called:*

- *local*: $\lambda_n = 1 \implies \|Q_n^\perp\| = 0 \implies Q_n \in \mathcal{V}_L^M$
- *quasilocal*: $\lambda_n \in (0, 1) \implies \|Q_n^\perp\| > 0 \implies Q_n \in \mathcal{V}_L$
- *generic nonlocal*: $\lambda_n = 0 \implies \|Q_n\| = 0$



The procedure outlined above works for a fixed system size L . In principle, to assess the character of an integral of motion, we need to examine how λ_n behaves in the thermodynamic limit. To achieve this, we execute this algorithm for a few accessible values of L and then proceed with finite size scaling. However, in this thesis we will examine both the $L \rightarrow \infty$ case and $L = 14$ case, that is largest system size for exact diagonalization that we were able to attain. We will end the discussion about the algorithm with a short summary on support of Q_n :

$$\begin{aligned} Q_n &= Q_n^M + Q_n^\perp \\ \|Q_n\|^2 &= \lambda_n \\ \|Q_n^M\|^2 &= \lambda_n^2 \\ \|Q_n^\perp\|^2 &= \lambda_n - \lambda_n^2 \end{aligned} \tag{3.12}$$

Proof of correctness Suppose we have an operator $\mathcal{V}_L^M \ni A = \sum_s u_s O_s$, where $u_s \in \mathbb{R}$ for all s . We can identify this operator from \mathcal{V}_L^M with a vector $\vec{u} \in \mathbb{R}^{\dim \mathcal{V}_L^M}$. Using this picture, the stiffness of A can be calculated as follows:

$$(\bar{A}|\bar{A}) = \sum_{s,t} u_s (\bar{O}_s|\bar{O}_t) u_t = \sum_{s,t} u_s K_{st} u_t = \vec{u}^T K \vec{u} \tag{3.13}$$

Thus, a problem in quantum mechanics is reduced to a problem in linear algebra. Because all eigenvalues of K matrix are real, we can sort the corresponding operators (defined with columns of U matrix, i.e. eigenvectors of K) by their magnitude. We then say that the larger the eigenvalue, the ‘better’ the integral of motion is. But can we be sure, that the maximal eigenvalue obtained from the algorithm corresponds to the ‘best’ possible integral of motion? To put it another way, if the procedure detects neither local nor quasilocal integrals of motion, does that necessarily mean they do not exist for a given system? The answer to this question lies within the subsequent

Proposition 3.3 *Let λ be the maximal eigenvalue of K . Then the following equality holds:*

$$\lambda = \max_{\substack{\vec{v} \in \mathbb{R}^{\dim \mathcal{V}_L^M} \\ \|\vec{v}\|=1}} \vec{v}^T K \vec{v}$$

Proof. Assume the converse, i.e. there exists such $\vec{u} \in \mathbb{R}^{\dim \mathcal{V}_L^M}$ that $\vec{u}^T K \vec{u} > \lambda$ and $\|\vec{u}\| = 1$. Let $\{\vec{v}_n\}_n$ be a orthonormal basis consisting of eigenvectors of K . We can express \vec{u} in this basis as $\sum_n u_n \vec{v}_n$ for $u_n \in \mathbb{R}$. Then we have:

$$\begin{aligned} \vec{u}^T K \vec{u} &= \left(\sum_n u_n \vec{v}_n^T \right) K \left(\sum_m u_m \vec{v}_m \right) = \sum_{n,m} u_n u_m \lambda_m \underbrace{\vec{v}_n^T \vec{v}_m}_{\delta_{mn}} \\ &= \sum_n u_n^2 \lambda_n \leq \sum_n u_n^2 \lambda = \lambda \sum_n u_n^2 = \lambda \end{aligned}$$

Obtained contradiction concludes the proof. ■

3.3 Spectral function and Mazur bound

Spectral function After we have learned about local and quasilocal IOMs and how to find them, it is perhaps the time to ask why are they actually important? To answer this question in a convincing manner we will follow the discussion in Vidmar et al. [4] and introduce the concept of spectral functions.

Suppose that we have an observable $A \in \mathcal{V}_L^M$ and we are interested in studying its time evolution. An obvious choice would be to calculate its autocorrelation function $(A(t)|A)$, where the time dependence of $A(t)$ is understood via the Heisenberg picture i.e. $A(t) = \exp(iHt) A \exp(-iHt)$. However, this quantity is rather unpleasant to work with. Instead, we will investigate the Fourier transform of autocorrelation function, formally defined as:

Definition 3.5 (Spectral function)

$$S(\omega) = \lim_{\varepsilon \rightarrow 0^+} \frac{1}{2\pi} \int_{-\infty}^{\infty} dt e^{i\omega t - |t|\varepsilon} (A(t)|A)$$

The limit in the definition is present in order to ensure proper convergence of the integral and ω corresponds to $\frac{1}{\tau}$ from earlier discussion. To connect this quantity with numerical calculations and to smoothen out any fluctuations, we can once again integrate it, but this time over a finite frequency window:

$$I(\omega) = \int_{-\omega}^{\omega} d\omega' S(\omega') = \frac{1}{D} \sum_{m,n} \theta(\omega - |E_m - E_n|) A_{mn}^2 \quad (3.14)$$

It turns out that this quantity is equal to the square of Hilbert-Schmidt norm of time averaged operator $\bar{A}^{\frac{1}{\omega}}$, which fits nicely within the previously discussed framework. Because all observables of interest are traceless and normalized to unity, we have this two important limits

$$\lim_{\omega \rightarrow \infty} I(\omega) = \frac{1}{D} \sum_{m,n} A_{mn}^2 = \|A\|^2 = 1 \quad (3.15)$$

$$\lim_{\omega \rightarrow 0^+} I(\omega) = \frac{1}{D} \sum_{\substack{m,n \\ E_m = E_n}} A_{mn}^2 = \|\bar{A}\|^2 \quad (3.16)$$

For frequencies small (long times) in comparison with system's characteristic energy scale, spectral function of an observable $A \in \mathcal{V}_L^M$ attains the following approximation:

$$S(\omega \ll J) \simeq D_A \delta(\omega) \quad (3.17)$$

where $D_A = \lim_{\omega \rightarrow 0^+} I(\omega)$ is the stiffness of an observable. Let us now imagine that we have a complete set of orthogonal (Q)LIOMs $(Q_n|Q_m) \propto \delta_{nm}$. It was shown by Mazur [5] and Suzuki [6] that the stiffness D_A of arbitrary observable A has its origin in the projections on these Q_n :

$$D_A = \sum_n D_n = \sum_n \frac{(A|Q_n)^2}{(Q_n|Q_n)} \quad (3.18)$$

Therefore, by calculating the overlap between our observable and all the (Q)LIOMs, we can infer about the long time behavior of its spectral function and thus its autocorrelation function. Because autocorrelation function of LIOMs is constant, its Fourier transform is a Dirac delta, which explains the form of equation (3.17).

Mazur bound If we know only a subset of the full set of (Q)LIOMs, this equality turns into a very useful lower bound for stiffness, called the *Mazur bound*. We will now proceed with a derivation of this bound for the case of one (Q)LIOM, in the spirit of a more modern discussion from Ilievski et al. [7].

Proposition 3.4 (Mazur bound for a single (Q)LIOM) *Let $A \in \mathcal{V}_L^M$ be an arbitrary observable and Q be a (quasi)local conserved quantity. Then the following inequality holds:*

$$D_A = (\bar{A}|\bar{A}) \geq \frac{(A|Q)^2}{(Q|Q)}$$

Proof. We define a new observable $\mathcal{A} = \bar{A} - \alpha Q$ for $\alpha \in \mathbb{R}$. Obviously, square of the norm of this quantity is positive i.e. $\|\mathcal{A}\|^2 = \text{tr}(\mathcal{A}\mathcal{A})/D \geq 0$. On the other hand, we can carry out an explicit computation of the norm:

$$\begin{aligned} \|\mathcal{A}\|^2 &= (\bar{A} - \alpha Q|\bar{A} - \alpha Q) = (\bar{A}|\bar{A}) - (\bar{A}|Q) - \alpha (Q|\bar{A}) + \alpha^2 (Q|Q) \\ &= (\bar{A}|\bar{A}) - 2\alpha (A|Q) + \alpha^2 (Q|Q) \geq 0 \end{aligned}$$



Between the first and the second line we have used the fact that $(\bar{A}|\bar{B}) = (\bar{A}|B) = (A|\bar{B})$ (cf. Proposition 3.1) and $\bar{Q} = Q$ for a conserved quantity. Let us now substitute $\alpha = \frac{(A|Q)}{(Q|Q)}$ to the above inequality.

$$D_A = (\bar{A}|\bar{A}) \geq 2 \frac{(A|Q)}{(Q|Q)} (A|Q) - \frac{(A|Q)^2}{(Q|Q)^2} (Q|Q) = \frac{(A|Q)^2}{(Q|Q)}$$

■

It is perhaps worth noting, that the derivation Mazur bound for a single (Q)LIOM is equivalent to the proof of the Cauchy-Schwarz inequality, found in any linear algebra textbook. By following exactly the same procedure, we can easily generalize this results to a set of orthogonal conserved quantities $\{Q_n\}$:

$$D_A = (\bar{A}|\bar{A}) \geq \sum_n \frac{(A|Q_n)^2}{(Q_n|Q_n)} \quad (3.19)$$

We have already seen that Mazur inequality turns into an equality, if the set $\{Q_n\}$ is complete. However, up until a few years ago, it was not clear how to systematically identify such a complete set in interacting models. This have changed with the work of Mierzejewski, Prelovšek, and Prosen [1], where the algorithm described in details in Section 3.2 was first proposed. We will now show that the following proposition holds:

Proposition 3.5 (Saturation of Mazur bound) *The set $\{Q_n\}$ of (Q)LIOMs obtained from the algorithm in Section 3.2 is complete, that is it saturates the Mazur bound.*

Proof. Consider once again an arbitrary observable $\mathcal{V}_L^M \ni A = \sum_s a_s O_s$, $(\forall s)(a_s \in \mathbb{R})$. We are interested in computing its stiffness $D_A = (\bar{A}|\bar{A})$, where $\bar{A} = \sum_s a_s \bar{O}_s$. Inverting the relation (3.9), we can write $\bar{O}_s = \sum_n U_{sn}^T Q_n = \sum_n U_{ns} Q_n$ and thus the following:

$$\bar{A} = \sum_s a_s \bar{O}_s = \sum_s a_s \sum_n U_{ns} Q_n = \sum_n \underbrace{\left(\sum_s a_s U_{ns} \right)}_{v_n} Q_n = \sum_n v_n Q_n$$

Now, let us express the overlap $(\bar{A}|Q_k)$ in two ways:

1. $(\bar{A}|Q_k) = \sum_n v_n \underbrace{(Q_n|Q_k)}_{=\lambda_n \delta_{nk}} = v_k \lambda_k$
2. $(\bar{A}|Q_k) = (A|\bar{Q}_k) = (A|Q_k)$

We are finally ready to make a direct calculation of stiffness of A :

$$\begin{aligned} D_A = (\bar{A}|\bar{A}) &= \sum_{nk} v_n v_k (Q_n|Q_k) = \sum_{nk} v_n v_k \delta_{nk} \lambda_k = \sum_{\substack{n \\ \lambda_n > 0}} v_n^2 \lambda_n \\ &= \sum_{\substack{n \\ \lambda_n > 0}} v_n^2 \lambda_n^2 \frac{1}{\lambda_n} = \sum_{\substack{n \\ \lambda_n > 0}} \frac{(A|Q_n)^2}{(Q_n|Q_n)} \end{aligned}$$

Therefore, the Mazur bound is saturated by our construction and the proof is concluded. ■

We will finish the section with an example of an application of Mazur bound. To this end, we can consider the topic of ballistic linear response [7]. Let J be an extensive current, for example the spin current. From Kubo linear response theory we have the following well-known expression for the real (non-dissipative) part of dynamical spin conductivity [8]:

$$\sigma'(\omega) = 2\pi D_J \delta(\omega) + \sigma_J^{reg}(\omega) \quad (3.20)$$

If there exists a (quasi)local conserved quantity Q such that $(J|Q) > 0$, the Mazur bound implies that $D_J > 0$. Such nonzero value of spin current stiffness is an indicator of *ballistic* DC transport (cf. Figure 3.3) — $\sigma'(0)$ diverges.

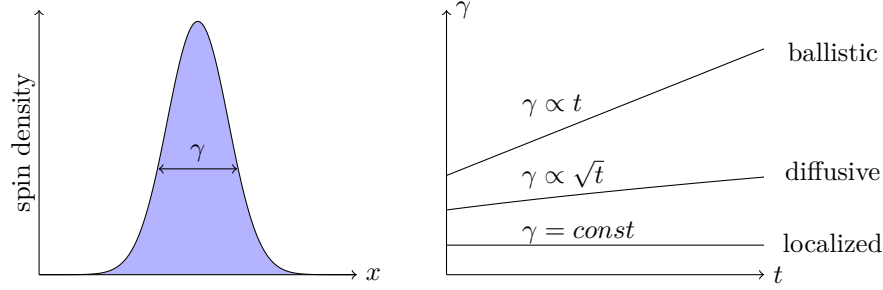


Figure 3.3: Illustration of different types of transport. On the left panel, we have some initial spin density characterized by width γ . On the right panel, we have the dependence of γ on time in three different cases.

3.4 Case of operators supported on up to 3 sites in the XXZ model

After explaining how and why to look for LIOMs and QLIOMs, let us now turn to an example.
Decomposition into 4 mutually orthogonal sectors

3.5 Commuting LIOM: Spin energy current

In order to test our (Q)LIOM finding algorithm and the correctness of its implementation, we investigate the known case of energy current in Spin-1/2 XXZ model [2]. For the sake of completeness, derivation of spin energy current for the general XYZ model will be presented, following the definitions in Zotos, Naef, and Prelovsek [9]. We start with the general XYZ Hamiltonian with periodic boundary conditions:

$$H_{XYZ} = \sum_{i=1}^L (J_x S_i^x S_{i+1}^x + J_y S_i^y S_{i+1}^y + J_z S_i^z S_{i+1}^z) \quad (3.21)$$

It is easy to see that this Hamiltonian can be represented as a sum of operators supported on two consecutive sites:

$$H_{XYZ} = \sum_{i=1}^L h_{i,i+1} \quad (3.22)$$

where $h_{i,i+1} = J_x S_i^x S_{i+1}^x + J_y S_i^y S_{i+1}^y + J_z S_i^z S_{i+1}^z$ and periodic boundary conditions require that $h_{L,L+1} = h_{L,1}$. The energy operator is a conserved quantity, thus the time evolution of its local density is given by the discrete continuity equation:

$$\frac{dh_{i,i+1}(t)}{dt} + \nabla \cdot j_i^E(t) = 0 \quad (3.23)$$

where $\nabla \cdot j_i^E(t) \equiv j_{i+1}^E(t) - j_i^E(t)$ is the discrete divergence of spin energy current density and $h_{i,i+1}(t) = e^{iH_{XYZ}t} h_{i,i+1} e^{-iH_{XYZ}t}$. On the other hand, time evolution of an arbitrary operator is determined by the Heisenberg equations:

$$\frac{dh_{i,i+1}(t)}{dt} = i[H_{XYZ}, h_{i,i+1}(t)] \quad (3.24)$$

Combining equations (3.23) and (3.24) we obtain the defining equations for the spin energy current density:

$$j_{i+1}^E - j_i^E = -i[H_{XYZ}, h_{i,i+1}] = i[h_{i,i+1}, H_{XYZ}] = i \sum_{k=1}^L [h_{i,i+1}, h_{k,k+1}] \quad (3.25)$$

Similar equations can be written for any operator being a sum of local operators such as the total spin operator or particle number operator in fermionic models. Detailed solution to the equation (3.25) is shown



in Appendix A. For the XXZ model we get the following expression:

$$\begin{aligned}
 j_i^E &= i \left(\underbrace{2JS_{i-1}^- S_i^z S_{i+1}^+ + J\Delta S_{i-1}^z S_i^+ S_{i+1}^- + J\Delta S_{i-1}^+ S_i^- S_{i+1}^z}_{O_i} \right. \\
 &\quad \left. - \underbrace{(2JS_{i-1}^+ S_i^z S_{i+1}^- + J\Delta S_{i-1}^z S_i^- S_{i+1}^+ + J\Delta S_{i-1}^- S_i^+ S_{i+1}^z)}_{O_i^\dagger} \right) \\
 &= i (O_i - O_i^\dagger)
 \end{aligned}$$

Obtaining the energy current operator is now simply the matter of summing over all the lattice sites:

$$J^E = \sum_{i=1}^L j_i^E \quad (3.26)$$

Tutaj dalej o tym że komutuje z H, stała funkcja autokorelacji i jak zanika przy zaburzeniu. Ale dopiero po rozdziale o algorytmie żeby notacja była ustalona. I o tym że lorenzian i że exp zanik.

Decay of IOMs

We conducted preliminary studies for small values of L , without assuming translational invariance. Available resources allowed us to make unrestricted search for $L = 8, 9, 10, 11, 12$ in case of $m = 3$ and $L = 8, 9, 10, 11$ in case of $m = 4$. Nevertheless, operators that maximized stiffness for given L and Δ turned out to be translationally invariant. Therefore, we restrict our considerations to translationally invariant operators only. This allowed us to obtain numerical results for L up to 14 in case of $m = 3$ and up to 13 in case of $m = 4$. To study the case of $L = 16$ we considered a subspace of \mathcal{A}_L^m spanned by basis operators \overline{O}_s that have nonzero coefficients in operator with largest stiffness for $L = 14$. Then we diagonalized the resulting 2×2 correlation matrix to obtain the stiffness.



scratchpad

5.1 Meetings

27.10.2021 meeting:

- integrability of Heisenberg model for $\alpha = 0.0$ is Bethe ansatz?
 - bethe ansatz and existence of extensive number of IOMs
- sources for motivation and history in intro
 - From Chaos to Quantum Thermalization...
 - arXiv:2012.07849
- best way to introduce Heisenberg model?
 - follow Dirac as in Spalek book
- source for nonlocal operators stiffness vanishing in thermodynamic limit
 - just use Zotos1997
- is extrapolation with $1/L$ just finite size scaling?
 - yes

03.11.2021 meeting:

- is this algorithm valid for any lattice model? or just 1-D

5.2 Other

Now we introduce an orthonormal basis of \mathcal{A}_L^m :

$$O_{\underline{s}} = \sum_{j=1}^L \sigma_j^{s_1} \sigma_{j+1}^{s_2} \cdots \sigma_{j+m-1}^{s_m} \quad (5.1)$$

where $\sigma_j^z \equiv \sqrt{2}S_j^z$, $\sigma_j^\pm \equiv S_j^\pm$, $\sigma_j^0 \equiv \mathcal{I}$, $\underline{s} = (s_1, s_2, \dots, s_m)$ and $s_j \in \{+, -, z, 0\}$ while $s_{1,m} \in \{+, -, z\}$. For a fixed m , there are exactly $N_m = 3 \cdot 4^{m-2} \cdot 3$ such operators and they satisfy an orthonormality condition i.e $(O_{\underline{s}} | O_{\underline{s}'}) = \delta_{\underline{s}, \underline{s}'}$.

Quantity that is plotted in Figures 4–14:

- With extrapolation to thermodynamic limit:

$$R_l(\tau, \alpha) = \frac{\lambda_l(L \rightarrow \infty, \tau, \alpha)}{\lambda_l(L \rightarrow \infty, \tau \rightarrow \infty, \alpha = 0)} \quad (5.2)$$



- Without extrapolation to thermodynamic limit:

$$R_l^L(\tau, \alpha) = \frac{\lambda_l(L, \tau, \alpha)}{\lambda_l(L, \tau \rightarrow \infty, \alpha = 0)} \quad (5.3)$$

Energy current in integrable XXZ model:

$$J^E = \sum_i^L i [\beta_1 (S_{i-1}^- S_i^z S_{i+1}^+) + \beta_2 (S_{i-1}^z S_i^+ S_{i+1}^- + S_{i-1}^+ S_i^- S_{i+1}^z)] + \text{H.c.} \quad (5.4)$$

Spin LIOM for $\Delta = 1.0$:

$$\hat{O}_1 = \beta_3 \sum_{i=1}^L S_i^+ + \text{H.c.} \quad (5.5)$$

Spin QLIOM for $\Delta = -0.5$:

$$\hat{O}_1 = \beta_4 \sum_{i=1}^L (S_i^+ S_{i+1}^+ S_{i+2}^+) + \text{H.c.} \quad (5.6)$$

$$[J^E, S_{tot}^z] = 0 \text{ where } S_{tot}^z = \sum_i S_i^z$$

5.3 Operators with largest stiffness

In this section we list operators with leading eigenvalues.

Fermions with $m = 3$:

- $\hat{O}_{max} = \sum_{i=1}^L (\alpha_1 (S_i^+ S_{i+1}^+ \mathcal{I}_{i+2}) + \alpha_2 (S_i^+ S_{i+1}^z S_{i+2}^+))$ for even L and $\Delta = \pm 1.0$
- $\hat{O}_{max} = \sum_{i=1}^L (\alpha_1 (S_i^+ S_{i+1}^+ \mathcal{I}_{i+2}) + \alpha_2 (S_i^+ \mathcal{I}_{i+1} S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^+ S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^z S_{i+2}^+) + \alpha_5 (S_i^+ S_{i+1}^+ S_{i+2}^z))$ for odd L and $\Delta = \pm 1.0$
- $\hat{O}_{max} = \sum_{i=1}^L (\alpha_1 (S_i^+ S_{i+1}^+ \mathcal{I}_{i+2}) + \alpha_2 (S_i^+ S_{i+1}^z S_{i+2}^+))$ for $L = 8, 12$ and $\Delta = \pm 0.5$
- $\hat{O}_{max} = \sum_{i=1}^L (-1)^i \alpha_1 (S_i^+ S_{i+1}^+ \mathcal{I}_{i+2})$ for $L = 10, 14$ and $\Delta = \pm 0.5$
- $\hat{O}_{max} = \sum_{i=1}^L (\alpha_1 (S_i^+ S_{i+1}^+ \mathcal{I}_{i+2}) + \alpha_2 (S_i^+ \mathcal{I}_{i+1} S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^+ S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^z S_{i+2}^+) + \alpha_5 (S_i^+ S_{i+1}^+ S_{i+2}^z))$ for $L = 9, 11, 13$ and $\Delta = \pm 0.5$

Fermions with $m = 4$:

- $\hat{O}_{max} = \sum_{i=1}^L$

Spins with $m = 3$:

- $\hat{O}_{max} = \sum_{i=1}^L \alpha_1 (S_i^+ \mathcal{I}_{i+1} \mathcal{I}_{i+2})$ for all L and $\Delta = 1.0$ $\alpha_1 = \pm \frac{1}{\sqrt{L}}$

- $\hat{O}_{max} = \sum_{i=1}^L (-1)^i \alpha_1 \left(S_i^+ \mathcal{I}_{i+1} \mathcal{I}_{i+2} \right)$ for even L and $\Delta = -1.0$ $\alpha_1 = \pm \frac{1}{\sqrt{L}}$
- $\hat{O}_{max} = \sum_{i=1}^L \left(\alpha_1 (S_i^+ \mathcal{I}_{i+1} \mathcal{I}_{i+2}) + \alpha_2 (S_i^- S_{i+1}^+ S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^z S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^- S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^- S_{i+1}^- S_{i+2}^+) + \alpha_6 (S_i^z S_{i+1}^+ S_i^z) + \alpha_6 (S_i^+ S_{i+1}^z S_{i+2}^z) \right)$ for odd L and $\Delta = -1.0$
- $\hat{O}_{max} = \sum_{i=1}^L \alpha_1 \left(S_i^+ S_{i+1}^+ S_{i+2}^+ \right)$ for all L and $\Delta = -0.5$
- $\hat{O}_{max} = \sum_{i=1}^L (-1)^i \alpha_1 \left(S_i^+ \mathcal{I}_{i+1} \mathcal{I}_{i+2} \right)$ for even L and $\Delta = 0.5$
- $\hat{O}_{max} = \sum_{i=1}^L (-1)^i \left(\alpha_1 (S_i^+ \mathcal{I}_{i+1} \mathcal{I}_{i+2}) + \alpha_2 (S_i^- S_{i+1}^+ S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^z S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^- S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^- S_{i+1}^- S_{i+2}^+) + \alpha_6 (S_i^z S_{i+1}^+ S_i^z) + \alpha_6 (S_i^+ S_{i+1}^z S_{i+2}^z) \right)$ for odd L and $\Delta = 0.5$

Konwencja w kodzie: $0 \longleftrightarrow \mathcal{I}$, $1 \longleftrightarrow S^+$, $2 \longleftrightarrow S^z$, $3 \longleftrightarrow S^-$
Spin operators supported on up to $m = 3$ sites:

- $\hat{O}_1 = \alpha_1 \sum_{i=1}^L S_i^+ + \text{H.c.}$, for all L and $\Delta = 1.0$ $\alpha_1 = \pm \frac{1}{\sqrt{L}}$
- $\hat{O}_1 = \alpha_1 \sum_{i=1}^L (-1)^i S_i^+ + \text{H.c.}$, for even L and $\Delta = -1.0$ $\alpha_1 = \pm \frac{1}{\sqrt{L}}$
- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+) + \alpha_2 (S_i^- S_{i+1}^+ S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^z S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^- S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^- S_{i+1}^- S_{i+2}^+) + \alpha_6 (S_i^z S_{i+1}^+ S_i^z) + \alpha_7 (S_i^+ S_{i+1}^z S_{i+2}^z) \right) + \text{H.c.}$, for odd L and $\Delta = -1.0$
- $\hat{O}_1 = \alpha_1 \sum_{i=1}^L \left(S_i^+ S_{i+1}^+ S_{i+2}^+ \right) + \text{H.c.}$, for all L and $\Delta = -0.5$ $\alpha_1 = \pm \frac{1}{\sqrt{L}}$
- $\hat{O}_1 = \alpha_1 \sum_{i=1}^L (-1)^i \left(S_i^+ S_{i+1}^+ S_{i+2}^+ \right) + \text{H.c.}$, for even L and $\Delta = 0.5$
- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+) + \alpha_2 (S_i^- S_{i+1}^+ S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^z S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^- S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^- S_{i+1}^- S_{i+2}^+) + \alpha_6 (S_i^z S_{i+1}^+ S_i^z) + \alpha_7 (S_i^+ S_{i+1}^z S_{i+2}^z) \right) + \text{H.c.}$, for odd L and $\Delta = 0.5$

Fermion operators supported on up to $m = 3$ sites:

- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+ S_{i+1}^+) + \alpha_2 (S_i^+ S_{i+1}^z S_{i+2}^+) \right) + \text{H.c.}$, for even L and $\Delta = \pm 1.0$
- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+ S_{i+1}^+) + \alpha_2 (S_i^+ \mathcal{I}_{i+1} S_{i+2}^+) + \alpha_3 (S_i^z S_{i+1}^+ S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^z S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^+ S_{i+1}^+ S_{i+2}^z) \right) + \text{H.c.}$, for odd L and $\Delta = \pm 1.0$



- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+ S_{i+1}^+) + \alpha_2 (S_i^+ S_{i+1}^z S_{i+2}^+) \right) + \text{H.c.},$ for $L = 8, 12$ and $\Delta = \pm 0.5$
- $\hat{O}_1 = \alpha_1 \sum_{i=1}^L (-1)^i \left(S_i^+ S_{i+1}^+ \right) + \text{H.c.},$ for $L = 10, 14$ and $\Delta = \pm 0.5$
- $\hat{O}_1 = \sum_{i=1}^L \left(\alpha_1 (S_i^+ S_{i+1}^+) + \alpha_2 (S_i^+ \mathcal{I}_{i+1} S_{i+1}^+) + \alpha_3 (S_i^z S_{i+1}^+ S_{i+2}^+) + \alpha_4 (S_i^+ S_{i+1}^z S_{i+2}^+) + \right.$
 $\left. \alpha_5 (S_i^+ S_{i+1}^+ S_{i+2}^z) \right) + \text{H.c.},$ for $L = 9, 11, 13$ and $\Delta = \pm 0.5$

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Derivation of spin energy current

Equation (3.25) is conceptually simple, yet quite tedious to solve due to the amount of commutators present. Luckily, leveraging commutator properties to our advantage will allow us to simplify the calculations. Let us begin with inserting the definition of $h_{i,i+1}$ into equation (3.25):

$$\begin{aligned} [h_{i,i+1}, h_{k,k+1}] &= [J_x S_i^x S_{i+1}^x + J_x S_i^y S_{i+1}^y + J_z S_i^z S_{i+1}^z, J_x S_k^x S_{k+1}^x + J_x S_k^y S_{k+1}^y + J_z S_k^z S_{k+1}^z] \\ &= J_x J_y [S_i^x S_{i+1}^x, S_k^y S_{k+1}^y] + J_x J_z [S_i^x S_{i+1}^x, S_k^z S_{k+1}^z] + J_y J_x [S_i^y S_{i+1}^y, S_k^x S_{k+1}^x] \\ &\quad + J_y J_z [S_i^y S_{i+1}^y, S_k^z S_{k+1}^z] + J_z J_x [S_i^z S_{i+1}^z, S_k^x S_{k+1}^x] + J_z J_y [S_i^z S_{i+1}^z, S_k^y S_{k+1}^y] \end{aligned}$$

By inspection it becomes clear that out of six terms present, only three will need to be directly evaluated, as commutators of the form $[A, B]$ will differ from $[B, A]$ by a sign and an index change.

$$\begin{aligned} J_x J_y [S_i^x S_{i+1}^x, S_k^y S_{k+1}^y] &= J_x J_y \left(S_i^x [S_{i+1}^x, S_k^y S_{k+1}^y] + [S_i^x, S_k^y S_{k+1}^y] S_{i+1}^x \right) \\ &= J_x J_y \left(S_i^x (S_k^y [S_{i+1}^x, S_{k+1}^y] + [S_{i+1}^x, S_k^y] S_{k+1}^y) + (S_k^y [S_i^x, S_{k+1}^y] + [S_i^x, S_k^y] S_{k+1}^y) S_{i+1}^x \right) \\ &= i J_x J_y \left(\delta_{i+1,k+1} S_i^x S_k^y S_{i+1}^z + \delta_{i+1,k} S_i^x S_{i+1}^z S_{k+1}^y + \delta_{i,k+1} S_k^y S_i^z S_{i+1}^x + \delta_{i,k} S_i^z S_{k+1}^y S_{i+1}^x \right) \end{aligned}$$

Carrying out the calculation of remaining two non-trivial commutators, we arrive at the following equations:

$$\begin{aligned} J_z J_x [S_i^z S_{i+1}^z, S_k^x S_{k+1}^x] &= i J_z J_x \left(\delta_{i+1,k+1} S_k^x S_i^z S_{k+1}^y + \delta_{i+1,k} S_i^z S_k^x S_{k+1}^y + \delta_{i,k+1} S_k^x S_{k+1}^y S_{i+1}^z + \delta_{i,k} S_k^y S_i^z S_{i+1}^x \right) \\ J_y J_z [S_i^y S_{i+1}^y, S_k^z S_{k+1}^z] &= i J_y J_z \left(\delta_{i+1,k+1} S_i^y S_k^z S_{i+1}^x + \delta_{i,k+1} S_k^z S_i^y S_{i+1}^x + \delta_{i+1,k} S_i^y S_{i+1}^z S_{k+1}^x + \delta_{i,k} S_i^z S_{k+1}^x S_{i+1}^y \right) \end{aligned}$$

Next step requires us to evaluate the sum over lattice sites to get rid of the Kronecker δ 's. As before, one of the three parts of calculations is provided in full detail:

$$\begin{aligned} &i \sum_{k=1}^L J_x J_y [S_i^x S_{i+1}^x, S_k^y S_{k+1}^y] + i \sum_{k=1}^L J_x J_y [S_i^y S_{i+1}^y, S_k^x S_{k+1}^x] = \\ &\quad - J_x J_y \left(\cancel{S_i^x S_{i+1}^z} + S_i^x S_{i+1}^z S_{i+2}^y + S_{i-1}^y S_i^z S_{i+1}^x + \cancel{S_i^z S_{i+1}^y S_{i+1}^x} \right) \\ &\quad + J_x J_y \left(\cancel{S_i^x S_{i+1}^z} + S_i^y S_{i+1}^z S_{i+2}^x + S_{i-1}^x S_i^z S_{i+1}^y + \cancel{S_i^z S_{i+1}^y S_{i+1}^x} \right) \\ &= J_x J_y \left(S_i^y S_{i+1}^z S_{i+2}^x - S_i^x S_{i+1}^z S_{i+1}^y - (S_{i-1}^y S_i^z S_{i+1}^x - S_{i-1}^x S_i^z S_{i+1}^y) \right) \\ \\ &i \sum_{k=1}^L J_x J_z [S_i^x S_{i+1}^x, S_k^z S_{k+1}^z] + i \sum_{k=1}^L J_x J_z [S_i^z S_{i+1}^z, S_k^x S_{k+1}^x] = \\ &= J_x J_z \left(S_i^x S_{i+1}^y S_{i+2}^z - S_i^z S_{i+1}^y S_{i+2}^x - (S_{i-1}^x S_i^y S_{i+1}^z - S_{i-1}^y S_i^z S_{i+1}^x) \right) \\ \\ &i \sum_{k=1}^L J_y J_z [S_i^y S_{i+1}^y, S_k^z S_{k+1}^z] + i \sum_{k=1}^L J_y J_z [S_i^z S_{i+1}^z, S_k^y S_{k+1}^y] = \\ &= J_y J_z \left(S_i^z S_{i+1}^x S_{i+2}^y - S_i^y S_{i+1}^x S_{i+2}^z - (S_{i-1}^z S_i^x S_{i+1}^y - S_{i-1}^x S_i^z S_{i+1}^y) \right) \end{aligned}$$

What now remains is to collect these parts and see that we finally arrive at the equation for the energy current density:

$$\begin{aligned}
 j_i^E &= J_x J_y (S_{i-1}^y S_i^z S_{i+1}^x - S_{i-1}^x S_i^z S_{i+1}^y) \\
 &+ J_x J_z (S_{i-1}^x S_i^y S_{i+1}^z - S_{i-1}^z S_i^y S_{i+1}^x) \\
 &+ J_y J_z (S_{i-1}^z S_i^x S_{i+1}^y - S_{i-1}^y S_i^x S_{i+1}^z) \\
 &= J_x J_y (S_{i-1}^y S_i^z S_{i+1}^x - S_{i-1}^x S_i^z S_{i+1}^y) + \text{cyclic permutations of } (x, y, z)
 \end{aligned} \tag{A.1}$$

which is precisely the expression from Zotos, Naef, and Prelovsek [9]. However, in this work we are interested in the XXZ model with the Hamiltonian (2.1). To this end, we need to set $J_x, J_z = 2J$, $J_y = \Delta$ and substitute $S_i^x = \frac{S_i^+ + S_i^-}{2}$, $S_i^y = \frac{S_i^+ - S_i^-}{2i}$. After some more lengthy calculations, we finally arrive at the desired form of energy current density operator:

$$j_i^E = i \left(\underbrace{2JS_{i-1}^- S_i^z S_{i+1}^+ + J\Delta S_{i-1}^z S_i^+ S_{i+1}^- + J\Delta S_{i-1}^+ S_i^- S_{i+1}^z}_{O_i} \right) \tag{A.2}$$

$$\begin{aligned}
 &- \underbrace{(2JS_{i-1}^+ S_i^z S_{i+1}^- + J\Delta S_{i-1}^z S_i^- S_{i+1}^+ + J\Delta S_{i-1}^- S_i^+ S_{i+1}^z)}_{O_i^\dagger} \\
 &= i (O_i - O_i^\dagger)
 \end{aligned} \tag{A.3}$$

It is evident that the energy current operator $J^E = \sum_{i=1}^L i (O_i - O_i^\dagger)$ has support of exactly 3 consecutive sites.