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EIGENMODES IN NEARLY INTEGRABLE QUANTUM CHAINS

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*I would like to express my sincere gratitude to prof. dr hab.
Marcin Mierzejewski for being my*

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Abstract

Apparent incompatibility of classical irreversible thermodynamics with

Keywords: *integrals of motion, ETH, nearly integrable systems, spin chains*

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1

Introduction

1.1 Nearly integrable quantum systems

One of the most widely disputed problems in modern physics is the reconciliation of irreversible thermodynamics [1, 2] with unitary, time-reversible dynamics predicted by quantum mechanics [3, 4]. In other words, it is the question of whether a generic, isolated quantum system can and will ‘forget’ about its initial, nonequilibrium state. In recent years, this problem has attracted the attention of many physicists, especially taking into account experimental evidence of the loss of information, or thermalization, in isolated systems [5–9]. Understanding this phenomenon is a necessary first step to controlling it, and perhaps to the creation of very sought-after, robust systems which do not exhibit such behaviour. After all, ‘forgetting’ about the initial state is equivalent to scrambling of quantum information and decoherence, which has been known for a long time to be one of the most important hindrances on the way to a functional and scalable quantum computer [10, 11]. Given the multitude of possible applications of such a device, both purely scientific and commercial, controlling thermalization in isolated systems could be the next big breakthrough [12].

Preventing thermalization A possible theoretical explanation of the thermalization in isolated quantum systems has been proposed in seminal papers by Deutsch [13] and Srednicki [14] in form of an ansatz for matrix elements of local quantum observables $A_{mn} = \langle m|A|n\rangle$ (in eigenbasis $H|n\rangle = \varepsilon_n|n\rangle$ of some Hamiltonian), known as **Eigenstate Thermalization Hypothesis** (ETH)

$$A_{mn} = A(\bar{\varepsilon})\delta_{mn} + e^{-S(\bar{\varepsilon})/2}f_A(\bar{\varepsilon}, \omega)R_{mn} \quad (1.1)$$

where $\bar{\varepsilon} = (\varepsilon_n + \varepsilon_m)/2$, $\omega = \varepsilon_n - \varepsilon_m$ and $S(\bar{\varepsilon})$ is the thermodynamic entropy at energy $\bar{\varepsilon}$, $A(\bar{\varepsilon})$ and $f_A(\bar{\varepsilon}, \omega)$ are some smooth functions of their parameters and R_{mn} is a random real or complex variable. The origin of ETH is the Random Matrix Theory [15, 16], but it was the key insight of Deutsch and Srednicki that connected it directly to statistical mechanics. Unraveling the physics behind equation (1.1), we have that, for generic systems, long-time (thermalized) expected values of local observables are related to the predictions of Gibbsian ensembles known



from equilibrium statistical physics [17]. Diagonal matrix elements $A_{nn} \simeq A(\varepsilon_n)$ are smooth functions of energy and coincide with the microcanonical average at energy ε_n , whereas the off-diagonal matrix elements and fluctuations of the diagonal ones are postulated to decrease exponentially with system size [18]. While ETH has been shown to hold analytically in only a few selected systems [19], numerical clues can be found in various systems with many-body interactions such as hard core bosons, interacting spin chains [20–23] and fermions [24, 25].

Given the lack of a definitive answer to the question of when ETH holds and the fact that our ultimate goal is preventing thermalization, it is desirable to look for systems which explicitly violate this hypothesis. There are a few known classes of such systems: quantum integrable models, systems with ‘scars’, which freeze thermalization for some infrequent, but physically relevant states [26, 27], quantum time crystals with broken time-translation symmetry [28, 29] and systems with many-body interactions together with some form of disorder [30]. As the thermalization in those systems is slowed down or even completely stopped, in principle they could preserve information about the initial state for an arbitrarily long time. This behaviour is in strong contrast with what is usually observed in interacting, many-body systems, namely fast dynamics on the time scales of tens of femtoseconds [31]. In this thesis we shall concern ourselves only with the case of **quantum integrable models**.

Robustness of integrability In quantum mechanics, as opposed to classical mechanics, a unique definition of integrability is yet to emerge [32, 33]. Nevertheless, a common practice is to take as a sufficient condition of integrability the presence of an extensive number (increasing linearly with the system size) of local observables that are integrals of motion, i.e. commute with the Hamiltonian, called LIOMs for short. The significance of such systems is at least twofold. First, as already mentioned, they can provide a new method of storage of information, encoded in expectation values of LIOMs, which can pave the way for the creation of the sought-after quantum memory. Second, they are among a few quantum many-body systems that are susceptible to analytical methods and so provide a rich playground for both theoretical physicists and mathematicians. Tools such as Algebraic Bethe Ansatz [34–36] or Generalized Hydrodynamics [37–41] lead to considerable insight regarding the nature of integrable systems.

Unfortunately, it is often the case for integrable systems such as Heisenberg, Hubbard or Lieb-Linger models, that their integrability relies on a certain set of fine-tuned parameters. Any deviation from these parameters, eg. in the form of some perturbation, can very easily destroy the integrability. Exactly this situation takes place in most experimental setups (albeit some signatures of integrability were observed [42], suggesting sufficient proximity to an integrable system), even though the capabilities and precision of control have reached remarkable levels [43]. Therefore, **more realistic systems are expected to be described by nearly integrable systems**, containing some non-negligible perturbations that impact integrability [44, 45]. This renders all the formalism for investigations of purely integrable systems inapplicable and forces one to rely mostly on numerical methods (for a recent review see Bertini et al. [39]). A general expectation for such nearly integrable systems is such, that in the thermodynamic limit, an arbitrarily small perturbation should restore generic chaotic dynamics, which leads to thermalization [46]. However, there are some reports about surviving traces of integrability, for example in the form of residual quasiconserved

quantities [45]. Unfortunately, in most cases numerical methods can only access finite systems and indirect transitions to infinite system sizes, such as finite-size scaling, pose great difficulties when executed properly, eg. first thermodynamic limit and then infinite time limit [47, 48]. Therefore, it is important to first gain a deep understanding of **weakly-perturbed finite systems**. Such endeavour immediately raises a few questions: How strong should a perturbation in a finite systems be to destroy integrability and how to efficiently describe resulting slow dynamics? Recently, those and other similar questions have been asked concerning the phenomena of ergodicity breaking phase transitions [49, 50]. Insight from experiments with ultracold atomic gases suggest also another way for nearly integrable systems to emerge, namely generic, chaotic one- and quasi-one dimensional systems that exhibit approximately integrable dynamics on experimentally relevant timescales, because of a lack of rapid local thermalization [51, 52].

In classical mechanics, answers to those types of questions are given by the Hamiltonian perturbation theory [53]. There, the distinction between integrable and non-integrable systems is well understood. It is known, that for classical systems with n degrees of freedom to be integrable, it is sufficient to have n integrals of motion $\{H, F_i\} = 0$, $i \in \{1, \dots, n\}$ that are in involution, i.e. $\{F_i, F_j\} = 0$ for any $i, j \in \{1, \dots, n\}$. Then, dynamics are restricted to an n -dimensional torus in the phase space. The fate of such invariant tori under integrability-breaking perturbations is given by the famous Kolmogorov-Arnold-Moser theorem (KAM) [54–56], stating that for systems with finite degrees of freedom, majority of the invariant tori occupying the phase space survive the influence of small perturbations. However, as of now, there is no equivalent of this result in quantum mechanics. Nevertheless, such quantum systems are very intriguing as they can facilitate robust prethermalization plateaux, i.e. dynamics that at intermediate times resemble that of integrable models (at least for suitably weak perturbations), even though the system eventually thermalizes at longer times [57–60].

1.2 Motivation and aim of this dissertation

As argued in the previous section, nearly integrable quantum systems constitute an important generalization of ordinary integrable systems, facilitating experimental realizations. They form the broader context this thesis is set in and the main motivation. However, to keep it finite in size, we restrict our attention to two concrete problems.

First, we provide a pedagogical introduction to the so-called **Krylov subspace methods** which allow us to leverage the sparsity of local observables in order to avoid the limitations originating from exponential growth of many-body Hilbert spaces. Following the exposition by Trefethen and Bau [61], in Chapter 2 we start our journey seemingly far away from physics, investigating a general algorithm called Arnoldi iteration, which original aim was to reduce a matrix to ‘almost triangular’ or Hessenberg form. Along the way we discover that, as a byproduct, Arnoldi iteration produces a remarkably good approximations of extremal eigenvalues and eigenvectors. Contrary to most physics texts and in spirit of pedagogical nature of this chapter, we try to derive all results when possible and motivate them thoroughly when not. Setting course back to physics, next we assume that our matrices are Hermitian



and observe how the Arnoldi iteration simplifies tremendously, producing the well known Lanczos iteration [62]. Then, going beyond just groundstate calculations, we show how to slightly modify Lanczos iteration to be able to compute an approximation of action of any analytic function of hermitian matrix on a vector. Applying this scheme to the function $f(x) = \exp(-ixt)$, we obtain an efficient way of calculating pure state time evolution, called the Krylov propagator [63]. To end Chapter 2, we outline the recent concept of Quantum Typicality [64] and derive a numerical procedure for efficient calculation of correlation functions, without the need for Exact Diagonalization.

Go back to this part after finishing chapters on physics, add some citations Our second topic of interest is the **spin transport in the long range anisotropic Heisenberg model**. Existence of many interesting features of quantum many-body systems, such as ballistic dynamics in Heisenberg spin chains [39, 65], exotic frustrated magnetism [66], peculiar phase transitions [67, 68] and entangled spin liquids [69] depends strongly on the type and range of interaction present in them, so it is safe to say that it plays a crucial role. In the last few years, considerable development of experimental techniques has occurred, allowing for unprecedented control over the interactions. Platforms such as individually controlled Rydberg atoms, or optical lattices provide insight into the properties of quantum many-body systems. Whereas optical lattice facilitates mostly fermionic systems [70–73], Rydberg atoms can be used to simulate pure spin systems. Models such as Ising or XY emerge naturally from their properties [43], and the ability to control range of interactions make them suitable for the simulation of long-range models [74]. Using time-periodic driving one can turn naturally existing Hamiltonian into some other, effective one - the so-called Floquet Hamiltonian. So far, this method has been applied with great success to create tunable XXZ model [75], strongly distance selective interactions [76] and tunable XYZ models [77, 78]. Progress in experimental methods sparked theoretical interest in long-range models [79–90], yet their dynamical properties are still largely unknown, which motivates our interest in long range anisotropic Heisenberg model in this thesis. In Chapter 3, motivated by experiments with density expansion in cold atoms [91–93], we study the dynamics of spin domains using the Krylov propagator, followed by Exact Diagonalization studies of the optical conductivity. Chapter 4 is devoted to investigating a class of local observables exhibiting similar properties to the spin current, using a numerical procedure searching for most conserved operators [94]. It is worth noting that the results presented in Chapters 3 and 4 have been recently published in Mierzejewski et al. [95].

The remainder of this chapter is devoted to the short introduction to the long range anisotropic Heisenberg model and other quantities of interest.

1.3 Long range anisotropic Heisenberg model

Krylov subspace methods for quantum many-body systems

One of the two purposes of this thesis is to develop and test a set of numerical tools based on the Krylov subspace methods, which is a family of **iterative** methods concerned with projecting high dimensional problems into smaller dimension subspaces and solving them therein. Given a finite dimensional vector space $V \cong \mathbb{C}^m$, a vector $\mathbf{v} \in \mathbb{C}^m$ and a linear operator $A \in \mathbb{C}^{m \times m}$, represented as a matrix, the **k-th Krylov subspace** \mathcal{K}_k is defined as

$$\mathcal{K}_k := \text{span}\{\mathbf{v}, A\mathbf{v}, A^2\mathbf{v}, \dots, A^{k-1}\mathbf{v}\} \subseteq \mathbb{C}^m \quad (2.1)$$

Maximal dimension of a Krylov subspace is bounded from above by $\text{rank}(A) + 1$ [96].

This chapter serves as a pedagogical introduction to the core ideas of these methods, including some of the usually omitted mathematical details. For the initial part of this exposition we follow the excellent textbook of numerical linear algebra by Trefethen and Bau [61], whereas for further applications to quantum many-body physics we rely on the excellent treatments of the topic found in Sandvik [62] and PhD thesis by Crivelli [97].

We start this chapter by quickly sketching the problems with **direct** algorithms such as Exact Diagonalization (ED), and quickly follow with the fundamental iterative algorithm for sparse nonhermitian matrices, the Arnoldi iteration. Its output admits several possible interpretations, however we shall focus on the problem of locating extremal eigenvalues. Afterwards, we restrict our attention to the class of hermitian matrices, to which of course all typical tight-binding Hamiltonians belong to, and describe the Lanczos algorithm, which allows for efficient calculation of the ground state eigenvalue and eigenvector, and thus the ground state properties of a system. Yet in this work we are mainly interested in infinite temperature calculations, for which in principle sampling of the whole spectrum is required. To this end, in subsequent sections we develop a scheme for time evolution of arbitrary state, called the Krylov propagator [63], and in the last section combine it with the idea of Dynamical Quantum Typicality (DQT), which states that a single pure state can have the same properties as an ensemble density matrix [98–100]. This will produce a numerical algorithm for efficient calculation of time dependent correlation functions without the need for Exact Diagonalization.



2.1 Problems with Exact Diagonalization

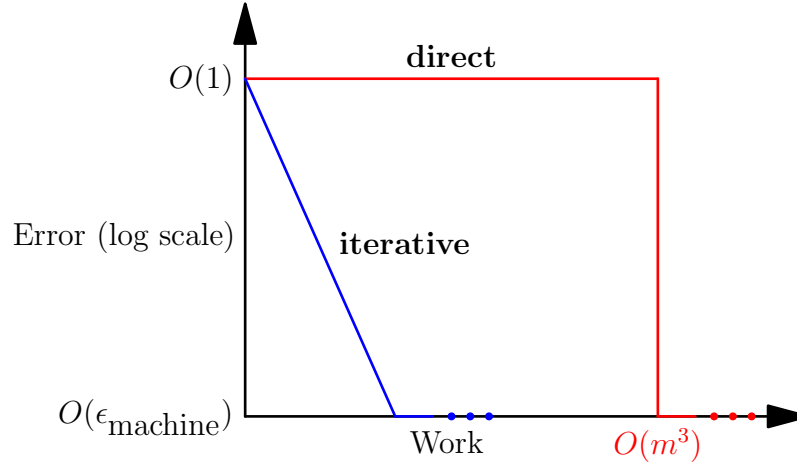


Figure 2.1: Schematic representation of difference between direct (such as Exact Diagonalization) and iterative (such as Lanczos iteration) algorithms. The advantage of iterative methods comes from the fact that they can be stopped midway, after desired precision is reached. On the other hand, direct algorithms require all $O(m^3)$ operations before any results can be extracted. Figure reproduced from Trefethen and Bau [61].

The most straightforward numerical method for studying discrete quantum many-body systems is without a doubt Exact Diagonalization (ED) [101]. It belongs to the family of the so-called direct algorithms (cf. Fig 2.1) and allows one to obtain numerically exact set of eigenvalues and eigenvectors and subsequently compute any desired properties of the system, be it thermal expectation values, time evolution, Green's functions etc. Unfortunately, the starting point of any ED calculation is the expression of the Hamiltonian as a dense matrix, in the Hilbert space basis of choice. Taking into account the fact that the dimension many-body Hilbert space grows exponentially with the size of the system, the memory cost quickly becomes prohibitive, even when exploiting conservation laws and related symmetries. For example, in the case of a spin chain of length L , with on-site basis dimension being 2, the full dimension of the Hilbert space would be $\mathcal{D} = 2^L$. Taking a modest length of 25 sites, that gives $2^{25} = 33554432 \approx 3.36 \cdot 10^7$ basis states and a memory footprint of Hamiltonian matrix of around 9PB (using double-precision floating point numbers), which is 9000 times more than the typical consumer hard drive capacity of 1TB. Even assuming some kind of distributed memory platform allowing for handling such large matrices, the computational complexity of ED, requiring $O(\mathcal{D}^3)$ operations, is the next major hurdle. Therefore, it is exceedingly difficult to probe the thermodynamic limit physics and ED calculations suffer from finite size effects.

Closer investigation of the Hamiltonian matrix, expressed in computational basis¹ quickly reveals the inefficiency of dense storage. Looking at Figure 2.2, we see that most of the matrix elements are zero. In fact only about $\mu \propto \mathcal{D}$ out of \mathcal{D}^2 matrix elements are non-zero. Hence, a numerical scheme leveraging this sparsity is highly desirable. This is exactly what the Krylov subspace algorithms do, by the virtue of requiring only a "black box" computation of

¹For spin systems, it is the eigenbasis of S^z operator, also called the Ising basis.

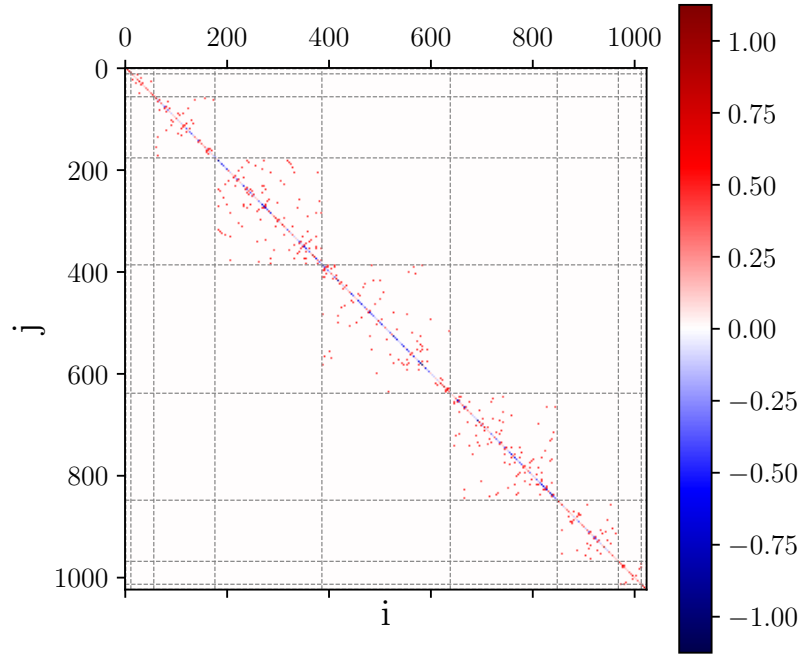


Figure 2.2: Ising basis representation of matrix of the XXZ Hamiltonian $H = J \sum_i \left[\frac{1}{2} (S_i^+ S_{i+1}^- + S_i^- S_{i+1}^+) + \Delta S_i^z S_{i+1}^z \right]$ on 10 sites, with $J = 1$ and $\Delta = 0.5$. Basis states are sorted according to the magnetization which yields the block structure emphasized by dashed lines. The filling factor μ is approximately 0.005.

matrix-vector product, which can be fairly easily implemented in a way requiring only $O(\mu D)$ operations.

2.2 Calculation of ground state

Our goal in this section is to develop the Lanczos algorithm for ground state search of hermitian matrices, and along the way understand how and why it works.

2.2.1 Arnoldi iteration

The Lanczos algorithm is special case of a more general algorithm, called Arnoldi iteration, designed to transform a general, nonhermitian matrix $A \in \mathbb{C}^{m \times m}$ via a orthogonal ² similarity transformation to a Hessenberg form $A = QHQ^\dagger$. Such transformation always exist [102]. A square, $m \times m$ matrix H is said to be in **upper Hessenberg form** if $\forall i, j \in \{1, \dots, n\} : i > j + 1 \implies (A)_{i,j} = 0$. It is said to be in **lower Hessenberg form**, if its transpose is in upper Hessenberg form. A Hessenberg matrix differs from a triangular one by one additional super- or subdiagonal. Such form is desirable, because many numerical algorithms in linear algebra experience considerable speedup from leveraging triangular structure of a matrix, and sometimes those benefits carry over to this almost-triangular case. A particularly important strength of the Arnoldi iteration is that it can be interrupted before completion (cf. fig 32.1),

²Orthogonal in this context means that $Q^\dagger Q = I_{m \times m}$



thus producing only an approximation of the Hessenberg form in situation where m is so large, that full computations are infeasible (eg. in quantum many-body physics).

Assume now that we are able to only compute the first $n < m$ columns of the equation $AQ = QH$. Let Q_n be the restriction of Q to n columns and let them be denoted by $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n \in \mathbb{C}^m$. Denoting by \tilde{H}_n the $(n+1) \times n$ upper left section of H , which is also a Hessenberg matrix, we can write down the following n -step approximation to the full decomposition

$$AQ_n = Q_{n+1}\tilde{H}_n \quad (2.2)$$

From this equation we can deduce an $n+1$ term recurrence relation for the column \mathbf{q}_{n+1} , however it is perhaps best illustrated with a simple example in the first place.

Example 2.1 Let $A \in \mathbb{C}^{3 \times 3}$, $AQ = QH$ be the Hessenberg decomposition and corresponding matrix elements be denoted by lowercase letters. We consider the approximation for $n = 2$, i.e. $AQ_2 = Q_3\tilde{H}_2$. On the right hand side

$$\begin{aligned} AQ_2 &= \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} q_{11} & q_{12} \\ q_{21} & q_{22} \\ q_{31} & q_{32} \end{bmatrix} = \begin{bmatrix} a_{11}q_{11} + a_{12}q_{21} + a_{13}q_{31} & a_{11}q_{12} + a_{12}q_{22} + a_{13}q_{32} \\ a_{21}q_{11} + a_{22}q_{21} + a_{23}q_{31} & a_{21}q_{12} + a_{22}q_{22} + a_{23}q_{32} \\ a_{31}q_{11} + a_{32}q_{21} + a_{33}q_{31} & a_{31}q_{12} + a_{32}q_{22} + a_{33}q_{32} \end{bmatrix} \\ &= \begin{bmatrix} (A\mathbf{q}_1)_1 & (A\mathbf{q}_2)_1 \\ (A\mathbf{q}_1)_2 & (A\mathbf{q}_2)_2 \\ (A\mathbf{q}_1)_3 & (A\mathbf{q}_2)_3 \end{bmatrix} \end{aligned}$$

On the left hand side

$$\begin{aligned} Q_3H_2 &= \begin{bmatrix} q_{11} & q_{12} & q_{13} \\ q_{21} & q_{22} & q_{23} \\ q_{31} & q_{32} & q_{33} \end{bmatrix} \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \\ 0 & h_{32} \end{bmatrix} = \begin{bmatrix} q_{11}h_{11} + q_{12}h_{21} & q_{11}h_{12} + q_{12}h_{22} + q_{13}h_{32} \\ q_{21}h_{11} + q_{22}h_{21} & q_{21}h_{12} + q_{22}h_{22} + q_{23}h_{32} \\ q_{31}h_{11} + q_{32}h_{21} & q_{31}h_{12} + q_{32}h_{22} + q_{33}h_{32} \end{bmatrix} \\ &= \begin{bmatrix} h_{11}(\mathbf{q}_1)_1 + h_{21}(\mathbf{q}_2)_1 & h_{12}(\mathbf{q}_1)_1 + h_{22}(\mathbf{q}_2)_1 + h_{32}(\mathbf{q}_3)_1 \\ h_{11}(\mathbf{q}_1)_2 + h_{21}(\mathbf{q}_2)_2 & h_{12}(\mathbf{q}_1)_2 + h_{22}(\mathbf{q}_2)_2 + h_{32}(\mathbf{q}_3)_2 \\ h_{11}(\mathbf{q}_1)_3 + h_{21}(\mathbf{q}_2)_3 & h_{12}(\mathbf{q}_1)_3 + h_{22}(\mathbf{q}_2)_3 + h_{32}(\mathbf{q}_3)_3 \end{bmatrix} \end{aligned}$$

From the above calculation and 2.2 we can read off two identities

$$\begin{aligned} A\mathbf{q}_1 &= h_{11}\mathbf{q}_1 + h_{21}\mathbf{q}_2 \\ A\mathbf{q}_2 &= h_{21}\mathbf{q}_1 + h_{22}\mathbf{q}_2 + h_{32}\mathbf{q}_3 \end{aligned}$$

Therefore we get, assuming \mathbf{q}_1 is known,

$$\begin{aligned} \mathbf{q}_2 &= \frac{A\mathbf{q}_1 - h_{11}\mathbf{q}_1}{h_{21}} \\ \mathbf{q}_3 &= \frac{A\mathbf{q}_2 - h_{21}\mathbf{q}_1 - h_{22}\mathbf{q}_2}{h_{32}} \end{aligned}$$

Generalizing the above example, we arrive at the desired $n+1$ term recurrence relation for \mathbf{q}_{n+1}

$$\mathbf{q}_{n+1} = \frac{A\mathbf{q}_n - \sum_{m=1}^n h_{mn}\mathbf{q}_m}{h_{n+1,n}} \quad (2.3)$$

Algorithm 1 Arnoldi iteration

Input: $\mathbf{v} \in \mathbb{C}^m$, $A \in \mathbb{C}^{m \times m}$, number of steps n **Output:** columns of Q_n , matrix elements of H_n

```
1:  $\mathbf{q}_1 = \mathbf{v} / \|\mathbf{v}\|$  ▷ components of  $\mathbf{v}$  are usually drawn from uniform distribution
2: for  $i = 1 : n - 1$  do
3:    $\mathbf{q} = A\mathbf{q}_i$ 
4:   for  $j = 1 : i$  do
5:      $h_{ji} = \text{cdot}(\mathbf{q}_j, \mathbf{q})$  ▷  $\text{cdot}$  is the complex dot product on  $\mathbb{C}^m$ .
6:      $\mathbf{q} = \mathbf{q} - h_{ji}\mathbf{q}_j$  ▷ In exact arithmetic, this ensures orthogonality.
7:   end for
8:    $h_{i+1,i} = \|\mathbf{q}\|$ 
9:    $\mathbf{q}_{i+1} = \mathbf{q} / h_{i+1,i}$ 
10: end for
```

We can now easily cast the above recurrence into a pseudocode algorithm:

Step 9 of the Algorithm 1 may be questionable, as we are dividing by a norm of a vector, which after all can be equal to zero. However, in practical applications of Arnoldi iteration it usually means that our calculations have converged and the iterations may be stopped.

Examining closely the Arnoldi iteration algorithm, we notice that it is essentially the Gram-Schmidt procedure applied to the vectors $\{\mathbf{v}, A\mathbf{v}, \dots, A^{n-1}\mathbf{v}\}$ and hence the vectors $\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n\}$ form an orthonormal basis of the Krylov subspace \mathcal{K}_n . The orthonormality condition is concisely expressed by the fact that $Q_n^\dagger Q_{n+1}$ is the $n \times (n+1)$ identity matrix. Multiplying the left-hand side of equation (2.2) by Q_n^\dagger we get

$$Q_n^\dagger A Q_n = \underbrace{Q_n^\dagger Q_{n+1}}_{\text{Id}_{n \times (n+1)}} \tilde{H}_n = H_n \in \mathbb{C}^{n \times n} \quad (2.4)$$

where H_n is the Hessenberg matrix \tilde{H}_n with its last row removed.

To understand the meaning of matrix H_n from the point of view of linear algebra, consider the following reasoning. Imagine we are given an endomorphism of the space \mathbb{C}^m , represented in the standard basis by a matrix A . We would like to restrict it to an endomorphism of the Krylov subspace \mathcal{K}_n , $n < m$. Of course, as $\mathbf{q} \in \mathcal{K}_n \implies \mathbf{q} \in \mathbb{C}^m$, we can calculate the action of A on a vector from Krylov subspace in a straightforward way. However, the resulting vector $A\mathbf{q}$ is not guaranteed to be an element of \mathcal{K}_n . We need to orthogonally project it back to the subspace. Such projection is realized by $Q_n Q_n^\dagger \in \mathbb{C}^{m \times m}$ and hence, with respect to the standard basis on \mathbb{C}^m , the desired restriction can be written as $Q_n Q_n^\dagger A$. Transforming it to the basis given by columns of Q_n we get $Q_n^{-1} (Q_n Q_n^\dagger A) Q_n = Q_n^\dagger A Q_n$. Thus, matrix H_n is the orthogonal projection of A to the subspace \mathcal{K}_n , represented in the basis $\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n\}$.

H_n is once again a square matrix, so we can talk about its eigenvalues $\{\theta_i\}_{i=1}^n$ in the usual fashion. These numbers are called the *Arnoldi eigenvalues estimates at step n* , or the *Ritz values with respect to \mathcal{K}_n* . Given the interpretation above, we may suspect that they would be related to the eigenvalues of the original matrix A . Indeed, as we shall see in a moment, some of the Ritz values are extremely good approximations of some of the original eigenvalues.



2.2.2 Polynomial approximation and eigenvalues

By carrying out the Arnoldi iterations for successive steps, and at each step n (or at just some of the steps) calculating the eigenvalues of the Hessenberg matrix H_n , we are left with sequences of Ritz values. Some of them often converge rapidly to, what we reasonably assume, eigenvalues of the original matrix A . However in practice, the maximal accessible n is much smaller than m , so we cannot expect to find all eigenvalues. As it turns out, Arnoldi iteration typically finds extremal eigenvalues, which fortunately are those that we are interested in.

Before we will understand the details, let us introduce different, seemingly unrelated problem of *polynomial approximation*. We can take any $\mathbf{q} \in \mathcal{K}_n$ and using the defining basis of Krylov subspace \mathcal{K}_n (Definition 2.1), expand it as

$$\begin{aligned}\mathbf{q} &= a_0 \mathbf{v} + a_1 A \mathbf{v} + a_2 A^2 \mathbf{v} + \dots + a_{n-1} A^{n-1} \mathbf{v} \\ &= \left(a_0 \mathbf{1} + a_1 A + a_2 A^2 + \dots + a_{n-1} A^{n-1} \right) \mathbf{v}\end{aligned}$$

Utilizing the special structure of vectors from \mathcal{K}_n , we can define a polynomial $p(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_{n-1} z^{n-1}$, and concisely write our vector as $\mathbf{q} = p(A) \mathbf{v}$. As the vector \mathbf{q} was arbitrary, we have established an isomorphism between the n -th Krylov subspace and the space of complex polynomials of maximal degree $n - 1$. We are now ready to state the problem:

Arnoldi Approximation Problem

Given a matrix $A \in \mathbb{C}^{m \times m}$ and a vector $\mathbf{v} \in \mathbb{C}^m$, find
 $p \in P^n := \{ a_0 + a_1 z + \dots + a_{n-1} z^{n-1} + z^n \mid a_0, a_1, \dots, a_{n-1} \in \mathbb{C} \}$
 such that $\|p(A) \mathbf{v}\|_2$ is minimized.

Remarkably, the Arnoldi approximation is the exact solution to this problem. This fact is interesting enough that we state it here as a theorem and, following Trefethen and Bau [61], provide a complete proof.

Theorem 2.1 *If $\dim(\mathcal{K}_n) = n$, i.e. matrix having columns $\mathbf{v}, A\mathbf{v}, \dots, A^{n-1}\mathbf{v}$ is of rank n , then the Arnoldi Approximation Problem has a unique solution $p^n \in P^n$, given by the characteristic polynomial of the matrix H_n , defined by (2.4).*

Proof. We start with an observation, that given a polynomial $p \in P^n$, the vector $p(A) \mathbf{v}$ can be written as $p(A) \mathbf{v} = A^n \mathbf{v} - Q_n \mathbf{r}$ for some $\mathbf{r} \in \mathbb{C}^n$. To see that, note that $(A^n \mathbf{v} - p(A) \mathbf{v}) \in \mathcal{K}_n$ and columns of Q_n form an orthonormal basis of \mathcal{K}_n . Now, we can recast our problem into a slightly different language, namely finding a vector in \mathcal{K}_n that is the closest in the sense of L_2 norm to $A^n \mathbf{v}$. In short:

$$\mathbf{r}^* = \min_{\mathbf{r} \in \mathbb{C}^n} \|A^n \mathbf{v} - Q_n \mathbf{r}\|$$

To achieve that, we need to have $p(A) \mathbf{v} \perp \mathcal{K}_n$, that is $p(A) \mathbf{v}$ must be orthogonal to all basis vectors spanning \mathcal{K}_n . This is concisely expressed as $Q_n^\dagger p(A) \mathbf{v} = \mathbf{0} \in \mathbb{C}^n$.

Now, we know that the Hessenberg factorization $A = QHQ^\dagger$ exists, and is approximated by n steps of the Arnoldi iteration. Thus, the matrices Q and H can have the following block

structure:

$$Q = \begin{bmatrix} Q_n & V \end{bmatrix}, \quad H = \begin{bmatrix} H_n & 0_{n \times (m-n)} \\ Y & 0_{(m-n) \times (m-n)} \end{bmatrix} \quad (2.5)$$

where $V \in \mathbb{C}^{m \times (m-n)}$ is a matrix with orthonormal columns, which are also orthogonal to columns of Q_n , and matrix $Y \in \mathbb{C}^{(m-n) \times n}$ has only the upper-right entry different from zero (the one from the last row of \tilde{H}_n). Using the Hessenberg factorization we can write our condition as $Q_n^\dagger Q p(H) Q_n^\dagger \mathbf{v} = \mathbf{0}$, and because equation (2.5) introduces partitions into *conformable* blocks, we can use the rules of block-matrix algebra to simplify it further [103].

First, let us investigate closely the structure of $p(H)$. We observe that

$$\begin{aligned} H^2 &= \begin{bmatrix} H_n & 0_{n \times (m-n)} \\ Y & 0_{(m-n) \times (m-n)} \end{bmatrix}^2 = \begin{bmatrix} H_n^2 & 0_{n \times (m-n)} \\ Y H_n & 0_{(m-n) \times (m-n)} \end{bmatrix} \\ H^3 &= \begin{bmatrix} H_n & 0_{n \times (m-n)} \\ Y & 0_{(m-n) \times (m-n)} \end{bmatrix}^3 = \begin{bmatrix} H_n^3 & 0_{n \times (m-n)} \\ Y H_n^2 & 0_{(m-n) \times (m-n)} \end{bmatrix} \\ &\dots \\ H^n &= \begin{bmatrix} H_n & 0_{n \times (m-n)} \\ Y & 0_{(m-n) \times (m-n)} \end{bmatrix}^n = \begin{bmatrix} H_n^n & 0_{n \times (m-n)} \\ Y H_n^{n-1} & 0_{(m-n) \times (m-n)} \end{bmatrix} \end{aligned}$$

Thus $p(H)$ can be written as

$$\begin{aligned} p(H) &= a_0 \mathbb{1} + a_1 H + a_2 H^2 + \dots + a_{n-1} H^{n-1} + H^n \\ &= \begin{bmatrix} a_0 \mathbb{1} + a_1 H_n + a_2 H_n^2 + \dots + a_{n-1} H_n^{n-1} + H_n^n & 0_{n \times (m-n)} \\ a_0 \mathbb{1} + a_1 Y + a_2 Y H_n + \dots + a_{n-1} Y H_n^{n-2} + Y H_n^{n-1} & 0_{(m-n) \times (m-n)} \end{bmatrix} \\ &= \begin{bmatrix} p(H_n) & 0 \\ \tilde{Y} & 0 \end{bmatrix} \end{aligned}$$

We have now all the pieces to simplify the orthogonality condition:

$$\begin{aligned} \mathbf{0} &= Q_n^\dagger Q p(H) Q_n^\dagger \mathbf{v} \\ &= \begin{bmatrix} Q_n^\dagger \end{bmatrix} \begin{bmatrix} Q_n & V \end{bmatrix} \begin{bmatrix} p(H_n) & 0_{n \times (m-n)} \\ \tilde{Y} & 0_{(m-n) \times (m-n)} \end{bmatrix} \begin{bmatrix} Q_n^\dagger \\ U^\dagger \end{bmatrix} \mathbf{v} \\ &= \begin{bmatrix} \mathbb{1}_{n \times n} & 0_{n \times (m-n)} \end{bmatrix} \begin{bmatrix} p(H_n) & 0_{n \times (m-n)} \\ \tilde{Y} & 0_{(m-n) \times (m-n)} \end{bmatrix} \begin{bmatrix} Q_n^\dagger \\ U^\dagger \end{bmatrix} \mathbf{v} \\ &= \begin{bmatrix} p(H_n) & 0_{n \times (m-n)} \end{bmatrix} \begin{bmatrix} Q_n^\dagger \\ U^\dagger \end{bmatrix} \mathbf{v} \\ &= p(H_n) Q_n^\dagger \mathbf{v} \end{aligned}$$

As a final step, notice that by construction the first row of Q_n^\dagger is $\mathbf{v}/\|\mathbf{v}\|$, and all the remaining rows are orthogonal to \mathbf{v} , therefore only the first column of H_n , or the first n elements of the first column of H are required to be 0. By Cayley-Hamilton theorem, this is guaranteed if we take $p = p^n$, where p^n is the characteristic polynomial of H_n . For the uniqueness part, suppose that there exists another polynomial, say q^n such that $q^n \perp \mathcal{K}_n$. But then $p^n - q^n$ is



a nonzero polynomial of degree $n - 1$ (because p^n, q^n are monic) such that $(p^n - q^n)(A)\mathbf{v} = \mathbf{0}$, and hence vectors $\mathbf{v}, A\mathbf{v}, \dots, A^{n-1}\mathbf{v}$ are linearly dependent, which violates assumption that $\dim(\mathcal{K}_n) = n$. ■

This theorem allows us to interpret the Arnoldi eigenvalues estimates $\{\theta_i\}$ as the roots of the optimal polynomial. Following the above proof, it is relatively easy to see that they are scale invariant, i.e. if $A \rightarrow \alpha A$ for some $\alpha \in \mathbb{C}$, then $\{\theta_i\}_{i=1}^n \rightarrow \{\alpha\theta_i\}_{i=1}^n$ and invariant under unitary transformations, i.e. if $A \rightarrow UAU^\dagger$ and $\mathbf{v} \rightarrow U\mathbf{v}$ for some unitary U , then the Arnoldi estimates are unchanged. Furthermore, owing to the properties of monic polynomials, they are also translationally invariant, namely if $A \rightarrow A + \alpha\mathbb{1}$ for some $\alpha \in \mathbb{C}$, then $\{\theta_i\}_{i=1}^n \rightarrow \{\theta_i + \alpha\}_{i=1}^n$.

In the end we see that the direct purpose of Arnoldi iteration is to solve a polynomial approximation problem and not to find eigenvalues. However, those two problems have enough in common, that the Arnoldi iteration produces some correct eigenvalues as a ‘by-product’. We can reason along the following lines. If our task is to find a polynomial $p \in P^n$ minimizing $\|p(A)\|$, it may be a good idea to select a polynomial that has roots close to the eigenvalues of A . In an extreme situation, when there exists a diagonalization of A and it possesses only $n \ll m$ distinct eigenvalues, the minimal polynomial³ will coincide with the characteristic polynomial computed via Arnoldi iteration after n steps and the Arnoldi eigenvalue approximations will be exact, provided we start from \mathbf{v} having nonzero overlap with all eigenvectors of A . In most practical situations however, the agreement is only approximate, namely Arnoldi eigenvalues are close to real eigenvalues, and computed polynomial is such that $\|p(A)\|$ is small.

There is more to this story than we have told here, particularly a nice geometric interpretation of Algorithm 1 via *Arnoldi lemniscates*, which illustrates why extremal eigenvalues are found first, however we shall not concern ourselves with those matters any further. Interested readers are once again referred to Trefethen and Bau [61], whereas we turn our attention to the case of utmost interest in quantum mechanics, namely Arnoldi iteration for hermitian matrices.

2.2.3 Restriction to hermitian matrices: Lanczos iteration

After the mathematical detour of previous section, armed with deeper understanding of Krylov subspace and Arnoldi iteration, we are now going to investigate the algorithms that are of direct relevance to condensed matter physics, starting with Lanczos iteration. From this point onwards, we shall switch to the favored by physicists Dirac bra-ket notation, namely $|v\rangle \equiv \mathbf{v}$ and $\langle v| = \mathbf{v}^\dagger$. Moreover, we assume the matrix A to be hermitian, as in most use cases it will be the Hamiltonian of our system.

It immediately follows from (2.4) that, given A is hermitian, the Hessenberg matrix H_n will also be hermitian. But a matrix that is both Hessenberg and hermitian, must of course be tridiagonal! Indeed, to see this directly, let us write the equation for matrix elements $(H_n)_{ij}$ of H_n :

$$(H_n)_{ij} = \sum_{r,s} (Q_n^\dagger)_{ir} (A)_{rs} (Q_n)_{sj} = \langle q_i | A | q_j \rangle \quad (2.6)$$

³A minimal polynomial of matrix A is a polynomial p of the smallest degree such that $p(A) = 0$. It always divides the characteristic polynomial.

where $|q_i\rangle, |q_j\rangle$ are respectively i -th and j -th columns of matrix Q_n . From the recurrence relation (2.3) we know that $A|q_j\rangle \in \text{span}\{|q_1\rangle, \dots, |q_{j+1}\rangle\}$, and that it is orthogonal to all $|q_i\rangle$ with $i > j + 1$. Therefore $(H_n)_{ij} = 0$ for $i > j + 1$. Similarly, by taking the hermitian conjugate of equation (2.6), we get

$$(H_n)_{ij} = \langle q_j | A^\dagger | q_i \rangle \triangleq \langle q_j | A | q_i \rangle \quad (2.7)$$

where \triangleq follows from assumed hermiticity of A . Repeating the above reasoning we quickly obtain that $(H_n)_{ij} = 0$ also for $j > i + 1$ and hence the matrix is tridiagonal. In literature the diagonal is usually denoted by $\alpha_i \equiv (H_n)_{ii}$, whereas the sub- and superdiagonal are denoted by $\beta_i \equiv (H_n)_{i,i+1} = (H_n)_{i+1,i}$. The relation for $|q_{n+1}\rangle$ becomes a 3-step recurrence:

$$|q_{n+1}\rangle = \frac{A|q_n\rangle - \beta_{n-1}|q_{n-1}\rangle - \alpha_n|q_n\rangle}{\beta_n} \quad (2.8)$$

This has a tremendous impact on the practical applications of the algorithm, as both computational and memory costs decrease significantly. We are now ready to state the simplified version of the Algorithm 1. Another important observation is that α_n 's are diagonal elements

Algorithm 2 Lanczos iteration

Input: $|v\rangle \in \mathbb{C}^m$, $A \in \mathbb{C}^{m \times m}$ such that $A^\dagger = A$, number of steps n

Output: columns of Q_n , tridiagonal matrix H_n

- 1: $\beta_0 = 0$
 - 2: $|q_0\rangle = \mathbf{0} \in \mathbb{C}^m$
 - 3: $|q_1\rangle = |v\rangle / \| |v\rangle \|$
 - 4: **for** $i = 1 : n - 1$ **do**
 - 5: $|q\rangle = A|q_i\rangle$
 - 6: $\alpha_i = \langle q_i | q \rangle$
 - 7: $|q\rangle = |q\rangle - \beta_{i-1}|q_{i-1}\rangle - \alpha_i|q_i\rangle$
 - 8: $\beta_i = \| |q\rangle \|$
 - 9: $|q_{i+1}\rangle = |q\rangle / \beta_i$
 - 10: **end for**
-

of a hermitian matrix, and β_n 's are norms of vector $|q\rangle$ in subsequent iterations, both of which are real. Therefore, even if our Hamiltonian is complex, the numbers α_n and β_n can be stored as vectors of real floating point numbers, decreasing memory requirements even further. This is the first algorithm implemented for the purpose of this thesis, using the Armadillo linear algebra library [104] and Intel MKL.

Matrix Q_n is of dimension $m \times n$, so keeping it in full in the memory can still be costly. Fortunately, at each step of the Lanczos iteration no more than three vectors are necessary ($|q\rangle, |q_i\rangle, |q_{i-1}\rangle$) so the storage of full matrix Q_n is redundant. Extremal eigenvalues are then obtained by explicit diagonalization of the constructed matrix $H_n = V_n D_n (V_n)^\dagger$, which can be done efficiently using specialized routines for tridiagonal matrices. However, this approach has its drawbacks when we are interested also in the ground state eigenvector, which will be the case in further applications.



It turns out that the Lanczos iteration can approximate not only eigenvalues, but also corresponding eigenvectors. They are the eigenvectors of the tridiagonal matrix H_n , transformed back to the original Hilbert space. Given the full Hessenberg decomposition we would have

$$A = QHQ^\dagger = Q(VDV^\dagger)Q^\dagger = (QV)D(QV)^\dagger \quad (2.9)$$

Restriction to n -step iteration produces an approximation $A \approx (Q_n V_n) D_n (Q_n V_n)^\dagger$. The simplest form of Lanczos iteration presented in Algorithm 2 is sufficient to obtain only the ground state eigenvector with machine precision, because eigenvectors of excited states are plagued by loss of orthogonality stemming from the nature of floating point numbers. We shall have a brief look at this problem at the end of this section.

The ground state vector $|\psi_0\rangle$ can be then read of as the first column $Q_n V_n$. However, there is a problem. To conserve memory, we have not constructed the whole matrix Q_n explicitly, but only three of its columns at a given time and hence do not have access to the matrix product $Q_n V_n$. We need a second pass of the Lanczos iteration, with a single line added for iterative calculation of the first column. It can be summarized by the following piece of pseudocode:

Algorithm 3 Second pass of Lanczos iteration, for calculating ground state eigenvector

Input: $|\psi_0\rangle = \mathbf{0} \in \mathbb{C}^m$, matrix V_n from Alg. 2, rest of input data from Alg. 2

Output: columns of Q_n , tridiagonal matrix H_n

```

1:  $\beta_0 = 0$ 
2:  $|q_0\rangle = \mathbf{0} \in \mathbb{C}^m$ 
3:  $|q_1\rangle = |v\rangle / \|v\|$ 
4: for  $i = 1 : n - 1$  do
5:    $|\psi_0\rangle = |\psi_0\rangle + (V_n)_{i,1} |q_i\rangle$  ▷ this is the only difference from Alg. 2
6:    $|q\rangle = A |q_i\rangle$ 
7:    $\alpha_i = \langle q_i | q \rangle$ 
8:    $|q\rangle = |q\rangle - \beta_{i-1} |q_{i-1}\rangle - \alpha_i |q_i\rangle$ 
9:    $\beta_i = \|q\rangle\|$ 
10:   $|q_{i+1}\rangle = |q\rangle / \beta_i$ 
11: end for
```

To finish this section, let us discuss quickly the convergence properties of Lanczos iteration. We have one free parameter, namely the number of iterations n . If we had carried out the full Arnoldi iteration, as described in 1, the orthogonality of subsequent columns of matrix Q_n would be guaranteed by the explicit Gram-Schmidt procedure and we in principle could continue it up to $n = m$ obtaining the full Hessenberg decomposition. However, restricting ourselves to a three step recurrence in Lanczos iteration we rely on mathematical identities to force the orthogonality of $|q_i\rangle$ with all previous vectors. Those are valid in exact arithmetic, but can quickly break down when using floating point numbers, as it is done in practice. Therefore, the iteration is unstable and should be stopped as soon as desired accuracy is reached. Taking E_n^1 to be the lowest eigenvalues of H_n , the convergence criterion can be defined as $|E_{n+1}^1 - E_n^1| / |E_n^1| < \varepsilon$ for some small ε , e.g. 10^{-14} . As long as it is nondegenerate, the convergence usually happens quite quickly for both lowest eigenvalue and corresponding

eigenvector. To reliably obtain higher eigenstates one needs to perform reorthogonalization, but it requires keeping the matrix Q_n in memory which can be very costly.

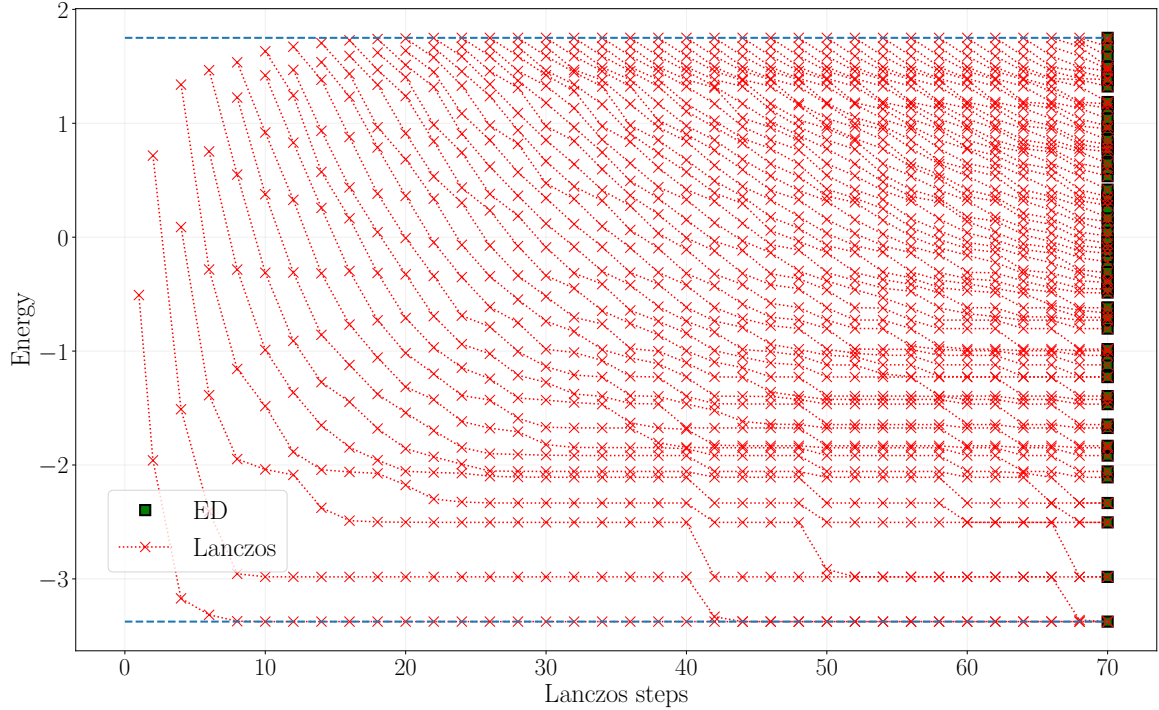


Figure 2.3: Plot of Arnoldi eigenvalues as a function of Lanczos steps, for a XXZ chain on 8 sites in the subspace with 0 total magnetization. The extremal eigenvalues converge very quickly to the values matching Exact Diagonalization. The numerical instability of Lanczos iteration is especially visible for a few lowest eigenvalues, where multiple ghosts start appearing. After $\binom{8}{4} = 70$ Lanczos steps, we should observe the exact spectrum emerging from Arnoldi approximates. However, we see that the ground state is triple degenerated, instead of unique as it should be.

This instability can manifest itself in an interesting way, namely in form of additional eigenvalues, called Lanczos ‘ghosts’. They are spurious copies of already found eigenvalues, which start appearing after too many iteration steps (cf. Fig. 2.3). They are difficult to understand rigorously, however Trefethen and Bau [61] offer a nice heuristic explanation. Reaching convergence of some Arnoldi approximated eigenvalue to the true eigenvalue of A causes annihilation of corresponding eigenvector component in the vector $|q\rangle$. However, rounding errors originating from floating point arithmetic cause $|q\rangle$ to again develop component in the direction of the eigenvector and thus, after certain number of iterations, appearance of another Arnoldi approximated eigenvalue is necessary to annihilate it. This can go on and on producing more and more Lanczos ‘ghosts’. Fortunately, for all further applications in this thesis we will only require the lowest eigenstate, so we can avoid most of the instability problems by stopping the iteration sufficiently quick.



2.3 Time evolution via the Krylov propagator

Even though the original purpose of Lanczos iteration was to approximate boundaries of the spectrum of matrices and solve systems of linear equation [105, 106], it can also be employed to evaluate functions of hermitian matrices. Given any unitary (or orthogonal) decomposition of matrix $A = QHQ^\dagger$, and an analytic function f^4 , we have $f(A) = Qf(H)Q^\dagger$. And indeed, Lanczos iteration gives us such decomposition, albeit an approximate one $A \approx Q_n H_n Q_n^\dagger$. Because of this approximate character and convergence problems discussed at the end of previous section, global approximation of $f(A)$ via Lanczos iteration is a hopeless endeavour. However, the goal of this section is to calculate time evolution, which boils down to evaluation how the time-evolution operator $\exp(-i\hat{H}t)$ acts on some state $|v\rangle$ in the Hilbert space for a given Hamiltonian \hat{H} . It is thus enough to restrict our attention the problem of calculating $f(A)|v\rangle$, for which the Lanczos iteration turns out to be an excellent tool.

Let us now assume that the matrix A is our Hamiltonian \hat{H} , acting on Hilbert space $\mathcal{H} \cong \mathbb{C}^m$ and $|v\rangle \in \mathcal{H}$ is some fixed state. Using the approximate factorization derived from (2.9), we get

$$f(\hat{H})|v\rangle \approx (Q_n V_n) f(D_n) (Q_n V_n)^\dagger |v\rangle \quad (2.10)$$

where D_n is a real diagonal matrix, so $f(D_n)$ is easy to compute. Previously, we have started the construction of Krylov subspace basis from some random vector. Now, let us change this slightly and start from the vector $|v\rangle$ instead, which we assume to be normalized. Then, the first column of Q_n will be $|v\rangle$, whereas all subsequent columns will be orthogonal (up to some numerical errors), yielding $Q_n^\dagger |v\rangle = |e_1\rangle$, which is the first vector in canonical basis of \mathbb{C}^n , i.e. $|e_1\rangle = [1, 0, 0, \dots, 0]$. Equation (2.10) then simplifies to

$$f(\hat{H})|v\rangle \approx Q_n (V_n f(D) V_n^\dagger) Q_n^\dagger |v\rangle = Q_n (V_n f(D) V_n^\dagger) |e_1\rangle = Q_n f(H_n) |e_1\rangle \quad (2.11)$$

Moreover, $f(H_n) |e_1\rangle$ is just the first column of $f(H_n)$, because $(f(H_n) |e_1\rangle)_i = \sum_j (f(H_n))_{i,j} \delta_{1,j} = (f(H_n))_{i,1}$. So we do not need to compute the full matrix, but only a single vector of the form

$$(f(H_n))_{i,1} = \sum_j (V_n)_{i,j} f(D_n)_j (V_n^\dagger)_{j,1} = \sum_j (V_n)_{i,j} (V_n^*)_{1,j} f(D_n)_j \quad (2.12)$$

where the diagonal matrix $f(D_n)$ is treated as a vector. Assuming that $f(D_n)$ is already computed, it boils down to a single dot product for each element of the column.

We are now ready to apply this procedure to the problem of interest, namely the time-evolution of a pure state $|\psi(t)\rangle$ in the interval $(t, \Delta t)$. It is described by the Schrödinger equation $i\partial_t |\psi(t)\rangle = \hat{H} |\psi(t)\rangle$, having a formal solution

$$|\psi(t + \Delta t)\rangle = \exp(-i\hat{H}\Delta t) |\psi(t)\rangle, \quad (2.13)$$

under the assumption that \hat{H} does not depend explicitly on time. Exact exponentiation of matrix amounts to exact diagonalization which, as mentioned at the beginning of this chapter, is a difficult task. However, by letting $f(\hat{H}) = \exp(-i\hat{H}\Delta t)$ and $|v\rangle = |\psi(t)\rangle$ in equation (2.11)

⁴A function f is real (complex) analytic if and only if its Taylor series about x_0 converges in some neighborhood of x_0 pointwise to the function, for every x_0 in the domain.

we get an approximation of the action of the time evolution operator on a state, called the **Krylov based propagator** [107], which was originally proposed in the 1980's by Park and Light [63] and has been since used with great success to investigate many different systems [108–111]. The final equation reads

$$|\psi(t + \Delta t)\rangle = \exp(-i\hat{H}\Delta t) |\psi(t)\rangle \approx Q_n \exp(-iH_n\Delta t) Q_n^\dagger |\psi(t)\rangle \quad (2.14)$$

$$= Q_n \exp(-iH_n\Delta t) |e_1\rangle = \sum_{j=1}^n (f(H_n))_{j,1} |q_j\rangle \quad (2.15)$$

where $|q_j\rangle$ are columns of the unitary (orthogonal) matrix Q_n . Because of this orthogonality, the approximation error is bounded from above by the last coefficient $(f(H_n))_{n,1}$, i.e.

$$\left\| |\psi(t + \Delta t)\rangle_{\text{exact}} - |\psi(t + \Delta t)\rangle_{\text{Krylov}} \right\| \leq |(f(H_n))_{n,1}| \quad (2.16)$$

assuming that $\| |\psi(t)\rangle \| = 1$. There also exists an estimate of the sufficient dimension of Krylov subspace [112]

$$n \gtrsim 1.5\rho_{\hat{H}}\Delta t > 10 \quad (2.17)$$

where $\rho_{\hat{H}}$ is the spectral radius of Hamiltonian and can be calculated as the difference between highest and lowest eigenvalue. It is now very simple to cast these expressions into a concrete algorithm

Algorithm 4 Krylov propagator

Input: input data from Algorithm 2, with $|v\rangle = |\psi(t)\rangle$, time step Δt

Output: propagated state $|\psi(t + \Delta t)\rangle$

- 1: Run Alg. 2, obtaining eigenvalues D_i
 - 2: Calculate $(f(H_n))_{i,1}$ using eq. (2.12)
 - 3: Run modified Alg. 3, with $(f(H_n))_{i,1}$ instead of $(V_n)_{i,1}$
-

We finish this section with a remark, that real-time propagator is not the only function of the Hamiltonian which can be calculated using Lanczos techniques. Fairly often encountered are also the imaginary-time propagator $\exp(-\beta H)$ and pure state Green's function of some observable Q : $\langle \psi_{\epsilon_0} | Q (\omega + i\eta + \epsilon_0 + H)^{-1} Q | \psi_{\epsilon_0} \rangle$ [113]. However, we will not need them for the purpose of this thesis.

2.4 Correlation functions and Quantum Typicality

We are now ready to introduce **time dependent correlation functions** and a method of calculating them using already developed Krylov subspace machinery. This function is defined for a pair of operators A, B as

$$\tilde{C}_{AB}(t) \equiv \text{Re} \langle A(t) B \rangle = \text{Re} \text{Tr} (\hat{\rho} A(t) B) \quad (2.18)$$

where $\hat{\rho} = e^{-\beta H} / \mathcal{Z}$, $\mathcal{Z} = \text{Tr} (e^{-\beta H})$ is the canonical ensemble at temperature $T = 1/\beta$, and $A(t) = e^{i\hat{H}t} A e^{-i\hat{H}t}$ is understood via the Heisenberg picture. In this thesis we are interested



only in the infinite temperature properties, so $\hat{\rho} \rightarrow \frac{1}{\mathcal{D}}\mathbb{1}$, where \mathcal{D} is the dimension of Hilbert space, however let us keep the temperature finite for a while, so we are able to see the results of subsequent developments in full. Correlation functions allow us to probe the complex dynamics of interacting many-body systems and within Linear Response Theory are directly related to the transport properties [114], so they have been an object of intense study [115–121]. We can use a complete set of eigensetates $|n\rangle$ of the Hamiltonian \hat{H} in order to transform the correlation function into the so called spectral representation

$$\begin{aligned}
\langle A(t)B \rangle &= \frac{1}{\mathcal{Z}} \text{Tr} \left(A(t) B e^{-\beta H} \right) = \frac{1}{\mathcal{Z}} \text{Tr} \left(e^{i\hat{H}t} A e^{-i\hat{H}t} B e^{-\beta H} \right) \\
&= \frac{1}{\mathcal{Z}} \sum_k \sum_{m,n} \langle k | n \rangle \langle n | e^{i\hat{H}t} A e^{-i\hat{H}t} | m \rangle \langle m | B e^{-\beta H} | k \rangle \\
&= \frac{1}{\mathcal{Z}} \sum_k \sum_{m,n} \delta_{k,n} e^{i(\varepsilon_n - \varepsilon_m)t} e^{-\beta \varepsilon_k} \langle n | A | m \rangle \langle m | B | k \rangle \\
&= \frac{1}{\mathcal{Z}} \sum_{m,n} e^{i(\varepsilon_n - \varepsilon_m)t} e^{-\beta \varepsilon_n} \langle m | A | n \rangle^* \langle m | B | n \rangle
\end{aligned} \tag{2.19}$$

which is useful for the calculations using Exact Diagonalization. Unfortunately, we have already established that ED calculations suffer greatly from the exponential growth of the Hilbert space. We would like to have a more efficient method for calculating $C_{AB}(t)$, capable of accessing larger systems sizes, far beyond the reach of ED. The question is, how the Krylov subspace methods developed so far can help us? After all, we only know how to find the ground state and calculate time evolution of any state, whereas calculating a correlation function requires taking the trace over full ensemble of states. This were the concept of **(Dynamical) Quantum Typicality** ((D)QT) comes into play, which broadly speaking postulates that a set of states with a common feature e.g. the same energy, should give a narrow distribution of some other feature e.g. expected value of some observable [122]. For the pedagogical purposes, we shall now briefly review two approaches to (D)QT, first in Sec. 2.4.1 following the article by Popescu et al. [100] focusing on a conceptual point of view, and second in Sec. 2.4.2 following Bartsch and Gemmer [122] and Steinigeweg et al. [123], giving us a concrete numerical tool for evaluating correlation functions, complete with rigorous error analysis.

2.4.1 General Canonical Principle

Roughly speaking, Quantum Typicality is an attempt to replace the fundamental postulate of statistical mechanics [1], the equal *a priori* probability postulate, by a principle that is fundamentally different, referring not to statistical ensembles or time averages, but to individual states. Another key characteristic of this new postulate, dubbed **general canonical principle** [100] or **canonical typicality** [99] is the existence of a rigorous mathematical proof, unlike in the case of equal *a priori* probability postulate. Let us now consider an isolated quantum system, called the universe U , partitioned into two components, the system S and the much larger environment E . In language of Hilbert spaces, this decomposition is $\mathcal{H}_U = \mathcal{H}_S \otimes \mathcal{H}_E$ such that $\mathcal{D}_s = \dim(\mathcal{H}_S) \ll d_E = \dim(\mathcal{H}_E)$. We can also impose some global constraint R for the universe, represented as restriction of the allowed states to some

subspace $\mathcal{H}_R \subseteq \mathcal{H}_S \otimes \mathcal{H}_E$. We take the restricted universe to be in a maximally entangled state

$$\rho_R = \frac{1}{\mathcal{D}_R} \mathbb{1}_R \quad (2.20)$$

capturing our lack of knowledge about the system and being consistent with our intuition from statistical mechanics, about assigning *a priori* equal probability to each pure state. Now, we define a canonical state of our system S , as the density matrix obtained from ρ_R by tracing out the degrees of freedom of the environment E

$$\rho_S^C = \text{Tr}_E(\rho_R) \quad (2.21)$$

The crucial insight of canonical typicality is that we can take the universe to be in some pure state $\rho_R = |\psi\rangle\langle\psi|$ and the state of the system

$$\rho_S(\psi) = \text{Tr}_R(|\psi\rangle\langle\psi|) \quad (2.22)$$

will be very close to the canonical state ρ_S^C . Moreover, this ‘closeness’ can be quantified very precisely, using a mathematical result from the asymptotic theory of finite dimensional normed spaces, called the Levy’s lemma [124], which tells us about properties of typical points on high-dimensional hyperspheres. Because of normalization, pure quantum states can be represented as point of a hypersphere, hence the lemma is applicable. Let us now introduce some concepts necessary for the precise statement of the result. A precise notion of distance between two objects requires a metric and in our case a suitable metric will be induced by a norm on the vector space of operators. There are two norms relevant for this problem, the **trace norm**

$$\|\rho\|_1 = \text{Tr} |\rho| = \text{Tr} \left(\sqrt{\rho^\dagger \rho} \right) \quad (2.23)$$

and the **Hilbert-Schmidt norm**

$$\|\rho\|_2 = \sqrt{\text{Tr}(\rho^\dagger \rho)}. \quad (2.24)$$

The trace norm is used directly in the precise statements of the general canonical principle, because $\|\rho_1 - \rho_2\|_1$ quantifies how hard is to tell apart ρ_1 and ρ_2 using measurements. Indeed, it can be shown that $\|\rho\|_1 = \sup_{\|A\| \leq 1} \text{Tr}(\rho A)$, where $\|\cdot\|$ is the operator norm. The Hilbert-Schmidt norm is used during the proof, as it is a bit easier to manipulate and can be easily related to the trace norm using Jensen’s inequality [125] for convex functions applied to $\phi(x) = x^2$. Taking $\{\lambda_i\}_{i=1}^{\mathcal{D}}$ to be the eigenvalues of ρ we have

$$\begin{aligned} \|\rho\|_1^2 &= \left(\sum_{i=1}^{\mathcal{D}} |\lambda_i| \right)^2 = \mathcal{D}^2 \left(\sum_{i=1}^{\mathcal{D}} \frac{1}{\mathcal{D}} |\lambda_i| \right)^2 = \mathcal{D}^2 \phi \left(\sum_{i=1}^{\mathcal{D}} \frac{1}{\mathcal{D}} |\lambda_i| \right) \\ &\leq \mathcal{D}^2 \sum_{i=1}^{\mathcal{D}} \frac{1}{\mathcal{D}} \phi(\lambda_i) = \mathcal{D} \sum_{i=1}^{\mathcal{D}} |\lambda_i|^2 = \mathcal{D} \|\rho\|_2^2 \end{aligned} \quad (2.25)$$

Hence, $\|\rho\|_1 \leq \sqrt{\mathcal{D}} \|\rho\|_2$. We shall meet the Hilbert-Schmidt norm again in the next section, when discussing the algorithm searching for local integrals of motion. The precise theorem establishing the typicality is as follows



Theorem 2.2 *Let V be a function assigning to each subset of \mathcal{H}_U its volume (in the sense of a suitable Haar measure [124]). Then, the following inequality holds*

$$\frac{V \left[\{ |\psi\rangle \in \mathcal{H}_R \mid \frac{1}{2} \|\rho_S(\psi) - \rho_S^C\|_1 \geq \eta \} \right]}{V \left[\{ |\psi\rangle \in \mathcal{H}_R \} \right]} \leq \eta' \quad (2.26)$$

where

$$\eta = \epsilon + \frac{1}{2} \sqrt{\frac{\mathcal{D}_S}{\mathcal{D}_E^{\text{eff}}}}$$

$$\eta' = 4e^{-\frac{2}{9\pi^3} \mathcal{D}_R \epsilon^2}$$

and the effective dimension of environment subspace is $\mathcal{D}_E^{\text{eff}} = \frac{1}{\text{Tr}(\rho_E^2)} \geq \frac{\mathcal{D}_R}{\mathcal{D}_S}$, where $\rho_E = \text{Tr}_S(\rho_R)$.

Mathematically inclined readers are referred to Popescu et al. [126] for the full proof of this theorem, but for us it is important what this theorem means, namely that all but exponentially rare pure states of the universe are on the level of the system indistinguishable from the canonical state ρ_S^C . For our purposes in this thesis, we are interested in the case where the constraint R is that the total energy in the universe is close to some fixed value E . Assuming that the systems is weakly coupled with the environment, it becomes a standard exercise in statistical mechanics to show that the canonical state is the Gibbs canonical ensemble

$$\rho_S^C \propto \exp \left(-\frac{H_S}{k_B T} \right) \quad (2.27)$$

where H_s is the Hamiltonian of the system and T is the temperature set by the energy E .

2.4.2 Dynamical Quantum Typicality

Another approach to Quantum Typicality is not concern directly with quantum states, but with expectation values of quantum observables instead. It was shown that for states drawn from a particular distribution in Hilbert space, the expectation values of a generic observable Q are very similar [127]. This result was further extended in the case of a unitarily invariant probability distribution, that is normalized states of the form

$$|\psi\rangle = \sum_{i=1}^{\mathcal{D}} c_i |i\rangle \quad (2.28)$$

where $\text{Re } c_i$ and $\text{Im } c_i$ are drawn from multidimensional Gaussian distribution with zero mean, and $\{|i\rangle\}_{i=1}^{\mathcal{D}}$ is an arbitrary basis. Technically, because $\sum_{i=1}^{\mathcal{D}} |c_i|^2 = 1$, the coefficients are not independent, thus the full distribution is not necessarily Gaussian. However, Central Limit Theorem ensures that for \mathcal{D} suitably large the distribution is indeed close Gaussian, with the standard deviation equal $1/\sqrt{2\mathcal{D}}$ [128]. Using the **Hilbert space average method**, analytical expressions for both the average HA and variance HV of $\langle \psi | Q | \psi \rangle$ were derived [122]. They are as follows

$$\text{HA} [\langle \psi | Q | \psi \rangle] = \frac{\text{Tr}(Q)}{\mathcal{D}} \quad (2.29)$$

$$\text{HV} [\langle \psi | Q | \psi \rangle] = \frac{1}{\mathcal{D} + 1} \left(\frac{\text{Tr}(Q^2)}{\mathcal{D}} - \left(\frac{\text{Tr}(Q)}{\mathcal{D}} \right)^2 \right) \quad (2.30)$$

Proof of the above equations is not difficult conceptually, however requires evaluation of rather cumbersome integrals over high-dimensional hyperspheres so we shall refrain from spelling it out in full. Interested reader can find all the details in a book by Gemmer et al. [128]. Let us now take $Q(t) = \hat{\rho}A(t)B$ and define a quantity

$$\alpha = \mathcal{D} \langle \psi | \sqrt{\hat{\rho}}A(t)B\sqrt{\hat{\rho}} | \psi \rangle \quad (2.31)$$

Note that because density matrix $\hat{\rho}$ is positive semi-definite and Hermitian, the square root $\sqrt{\hat{\rho}}$ exists and is well defined. The next step is to plug α into equations (2.29) and (2.30)

$$\text{HA}[\alpha] = \text{Tr} \left(\sqrt{\hat{\rho}}A(t)B\sqrt{\hat{\rho}} \right) = \text{Tr} (\hat{\rho}A(t)B) = \frac{\text{Tr} (e^{-\beta H} A(t)B)}{\mathcal{Z}} \quad (2.32)$$

$$\begin{aligned} \text{HV}[\alpha] &= \frac{\mathcal{D}^2}{\mathcal{D}+1} \left(\frac{\text{Tr} \left((\sqrt{\hat{\rho}}A(t)B\sqrt{\hat{\rho}})^2 \right)}{\mathcal{D}} - \left(\frac{\text{Tr} (\sqrt{\hat{\rho}}A(t)B\sqrt{\hat{\rho}})}{\mathcal{D}} \right)^2 \right) \\ &\leq \frac{\mathcal{D}}{\mathcal{D}+1} \text{Tr} (\hat{\rho}A(t)B\hat{\rho}A(t)B) < \text{Tr} (\hat{\rho}A(t)B\hat{\rho}A(t)B) \end{aligned} \quad (2.33)$$

Looking at eq. (2.32) we immediately see the desired way of calculating the correlation function.

$$\tilde{C}_{AB}(t) = \text{Re} \frac{\text{Tr} (e^{-\beta H} A(t)B)}{\mathcal{Z}} = \text{Re} \frac{\mathcal{D}}{\mathcal{Z}} \langle \psi | e^{-\frac{\beta H}{2}} e^{iHt} A e^{-iHt} B e^{-\frac{\beta H}{2}} | \psi \rangle + \text{Re} \epsilon \quad (2.34)$$

where ϵ is the error we made by using just one random state $|\psi\rangle$. Let us massage this expression a bit more by introducing two auxiliary states $|\psi_\beta(t)\rangle = e^{-iHt} e^{-\frac{\beta H}{2}} |\psi\rangle$ and $|\phi_\beta(t)\rangle = e^{-iHt} B e^{-\frac{\beta H}{2}} |\psi\rangle$. We can also calculate the partition function using the random state $|\psi\rangle$ as

$$\mathcal{Z} = \text{Tr} (e^{-\beta H}) = \mathcal{D} \langle \psi | e^{-\beta H} | \psi \rangle = \mathcal{D} \langle \psi_\beta(0) | \psi_\beta(0) \rangle \quad (2.35)$$

Combining (2.34) and (2.35), we arrive at the final expression, as seen in literature [115, 120, 121]

$$\tilde{C}_{AB}(t) = \text{Re} \frac{\langle \psi_\beta(t) | A | \phi_\beta(t) \rangle}{\langle \psi_\beta(0) | \psi_\beta(0) \rangle} + \text{Re} \epsilon \quad (2.36)$$

We have successfully shifted time evolution and the action of density matrix to state vectors instead of operators, hence we may apply the Krylov time propagator, studied in previous section, to calculate both real and imaginary time evolution. Apart from that, the only other numerical calculations are sparse matrix-vector multiplication⁵ and inner products of vectors, which are much less demanding than full exact diagonalization.

The final thing left is to estimate the error ϵ , in order to show that this approach actually makes sense. From eq. (2.33) it is clear that the Hilbert Space Average of ϵ is zero, as

$$\text{HA}(\epsilon) = \text{HA}(\alpha - \text{Tr}(\hat{\rho}A(t)B)) = 0 \quad (2.37)$$

⁵Matrices representing local observables will also be sparse.



Equation (2.33), for Hilber Space Variance, allows us to estimate the standard deviation

$$\begin{aligned}
(\sigma(\epsilon))^2 &= \text{HV}[\epsilon] = \text{HV}[\alpha] < \text{Tr}(\hat{\rho}A(t)B\hat{\rho}A(t)B) \\
&= \sum_{m,n} \frac{e^{-\beta\epsilon_m}}{\mathcal{Z}} \langle m|A(t)B|n\rangle \frac{e^{-\beta\epsilon_n}}{\mathcal{Z}} \langle n|A(t)B|m\rangle \\
&< \sum_{m,n} \frac{e^{-\beta\epsilon_m}}{\mathcal{Z}} \langle m|A(t)B|n\rangle \frac{e^{-\beta\epsilon_0}}{\mathcal{Z}} \langle n|A(t)B|m\rangle \\
&= \frac{1}{\text{Tr}(e^{-\beta(H-\epsilon_0)})} \sum_m \frac{e^{-\beta\epsilon_m}}{\mathcal{Z}} \langle m|A(t)BA(t)B|m\rangle \\
&= \frac{1}{\text{Tr}(e^{-\beta(H-\epsilon_0)})} \text{Tr}(\hat{\rho}A(t)BA(t)B)
\end{aligned} \tag{2.38}$$

Where the red inequality follows from the fact that Boltzmann factor is a strictly decreasing function and assuming that the spectrum of H is ordered in increasing fashion. Defining the effective dimension $\mathcal{D}_{\text{eff}} \equiv \text{Tr}(e^{-\beta(H-\epsilon_0)})$, we finally obtain the upper bound on standard deviation of error as

$$\sigma(\text{Re } \epsilon) < \sqrt{\frac{\text{Re}\langle A(t)BA(t)B\rangle}{\mathcal{D}_{\text{eff}}}} \tag{2.39}$$

From this bound we see that at infinite temperature, the error is exponentially suppressed in system size and thus for suitably large systems even a single pure state $|\psi\rangle$ is enough to obtain a very good approximation of the correlation function. It becomes progressively worse with lower temperature, however as the mean error is 0 we can always average over a few random states. Fortunately, in this thesis we are only interested in the case $\beta \rightarrow 0$, so usually a single run will be enough.

As an example application, we shall look at spin current in XXZ model. Sum rule, normalized corr etc. Add relevant equations, depending on whats in the introduction.

Spin transport in long range anisotropic Heisenberg model

The results concerning spin transport in the long range XXZ have already been published in Mierzejewski et al. [\[95\]](#).



4

Slowly decaying fermionic eigenmodes

The results concerning spin transport in the long range XXZ have already been published in Mierzejewski et al. [\[95\]](#). Section about Krylov approach to lioms moved here.



5

Summary

AAA



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Hilbert subspaces with fixed momentum

