

# SC223 - Linear Algebra

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Lecture 14



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# Vector Spaces

● **Definition:** A Vector space is a set  $V$  with a **field**  $(\mathbb{F}, +_F, \times)$ , and two binary operations, vector addition  $+$  and scalar multiplication  $\cdot$  that satisfy the following axioms:

►  $(V, +)$  is an **Abelian group**:

►  $\forall x, y \in V, x + y \in V$

►  $\exists \theta \in V, \forall x \in V, x + \theta = \theta + x = x$

►  $\forall x \in V, \exists y \in V, x + y = y + x = \theta$ . We will denote  $y$  by  $-x$ .

►  $\forall x, y, z \in V, (x + y) + z = x + (y + z)$ .

►  $\forall x, y \in V, x + y = y + x$ .

► **Closure with respect to Scalar multiplication:**  $\cdot: \mathbb{F} \times V \rightarrow V$ .

► **Scalar Multiplication identity:**  $\exists 1 \in \mathbb{F}$  such that  $1 \cdot v = v, \forall v \in V$ .

► **Distributivity:**  $\forall a \in \mathbb{F}, \forall u, v \in V, a \cdot (u + v) = a \cdot u + a \cdot v$ , and  $\forall a, b \in \mathbb{F}, \forall u \in V, (a +_F b) \cdot u = a \cdot u + b \cdot u$ .

► **Compatibility of field and scalar multiplication:**

$\forall a, b \in \mathbb{F}, \forall u \in V, (a \times b) \cdot u = a \cdot (b \cdot u)$ .

# Examples of Vector spaces

- $(\mathbb{R}, +, \cdot)$  over  $\mathbb{R}$ .
- $(\mathbb{R}^n, +, \cdot)$  over  $\mathbb{R}$ .
- $(\mathbb{C}^n, +, \cdot)$  over  $\mathbb{C}$ .
- $(\mathbb{R}^\infty, +, \cdot)$  over  $\mathbb{R}$ , where  $\mathbb{R}^\infty$  is the set of all doubly-infinite sequences.
- $(\mathcal{P}(\mathbb{R}), +, \cdot)$  over  $\mathbb{R}$ , where  $\mathcal{P}(\mathbb{R})$  is the set of all polynomials of one variable with real coefficients.
- $(\mathbb{L}_2(\mathbb{R}), +, \cdot)$  over  $\mathbb{R}$ , where  $\mathbb{L}_2(\mathbb{R})$  denotes the set of all square-integrable functions  $f : \mathbb{R} \rightarrow \mathbb{R}$ .
- $(\mathcal{M}_n(\mathbb{R}), +, \cdot)$  over  $\mathbb{R}$ , where  $\mathcal{M}_n(\mathbb{R})$  denotes the set of all square matrices of size  $n$  with real number entries.

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- **Proposition 4:**  $\forall a \in \mathbb{F}, a \cdot \theta = \theta.$
- **Proposition 5:**  $\forall v \in V, (-1) \cdot v = -v.$



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►  $V = \mathcal{L}^2(\mathbb{R})$ ,  $W = \{f \in V \mid \int_{-\infty}^{\infty} f(t) dt = 0\}$ .



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● Familiar examples of Subspaces: Let  $A \in \mathbb{R}^{m \times n}$ . Then,  $C(A)$ ,  $N(A^T)$  and  $N(A)$ ,  $C(A^T)$  are subspaces of  $\mathbb{R}^m$  and  $\mathbb{R}^n$  respectively.

# Generating New subspaces from Old

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- **Definition:** (Sum of subspaces): Let  $U_1, \dots, U_n$  be subspaces of  $V$ . The **sum of subspaces**  $U_1, \dots, U_n$  is defined as:

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- **Proposition 7:** The sum of subspaces  $U_1, \dots, U_n$  of  $V$  is a subspace.

- If  $v = u_1 + \dots + u_n$ ,  $u_i \in U_i$ ,  $i = 1, \dots, n$ , we say that  $(u_1, \dots, u_n)$  is a decomposition of  $v$ .

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- Is this decomposition unique?
- **Definition:** (Direct Sum of Subspaces) In a VS  $V$  with subspaces  $U_1, \dots, U_n$ ,  $W = U_1 + \dots + U_n$  is said to be a **Direct Sum** if  $\forall w \in W$ ,  $w$  is **uniquely** expressed as a sum of elements  $w_i \in U_i$ ,  $i = 1, \dots, n$ .

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- Direct sum notation:  $W = U_1 \oplus U_2 \oplus \dots \oplus U_n$ .

● **Proposition 8:** Let  $U_1, \dots, U_n$  be subspaces of  $V$ . Then  $V = U_1 \oplus \dots \oplus U_n$  if and only if: (1)  $V = U_1 + \dots + U_n$ , and (2) The only representation of  $\theta \in V$  is  $(\theta, \dots, \theta)$ .

● **Proposition 9:** Let  $V$  be a VS with subspaces  $U_1, U_2$ . Then  $V = U_1 \oplus U_2$  iff  $V = U_1 + U_2$  and  $U_1 \cap U_2 = \{\theta\}$ .



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$$\text{span}(U) := \{a_1 v_1 + \dots + a_n v_n \mid \forall a_1, \dots, a_n \in \mathbb{F}\},$$

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- **Proposition 10:** Let  $U \subseteq V$ . Then  $\text{span}(U)$  is a subspace of  $V$ .

- Let  $V$  be a VS, and let  $W \subset V$ . If  $\text{span}(W) = V$ , we say that  $W$  is a spanning set of  $V$ , or  $W$  spans  $V$ .

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- **Linearly independent set:** Let  $V$  be a vector space and let  $W = \{v_1, \dots, v_n\} \subset V$ . We say that the set  $W$  is a set of linear independent vectors, if

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$U = \{u_1, \dots, u_n\}$ ,  $W = \{w_1, \dots, w_m\}$  be its subsets such that  $\text{span}(U) = V$  and  $W$  is LI.

●  $\{w_1, u_1, \dots, u_n\}$  is LD, i.e.,

$\exists u_j \in U, u_j \in \text{span}(\{w_1, u_i, i = 1, \dots, n, i \neq j\})$ .

●  $\text{span}(\{w_1, u_i, i = 1, \dots, n, i \neq j\}) = V$

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● Is it possible that  $m > n$ ?

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● If so, after  $n$  iterations, we will reach a contradiction:

$\text{span}(\{w_1, w_2, \dots, w_n\}) = V$

# Basis of a Vector space

● **Definition:** (Hamel Basis) Let  $V$  be a finite dimensional vector space. An ordered set  $\beta := \{v_1, \dots, v_n\}$  is said to be a **(Hamel) basis** of  $V$  if (1)  $\text{span}(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.

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● Examples:



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- **Proposition 14:** Any set of basis vectors of a VS contains the same number of elements.
- **Dimension of a Vector Space:** Let  $V$  be a FDVS. For any set of basis vectors  $\beta$  of  $V$ , we define the dimension of  $V$  as  $\dim(V) := |\beta|$ .