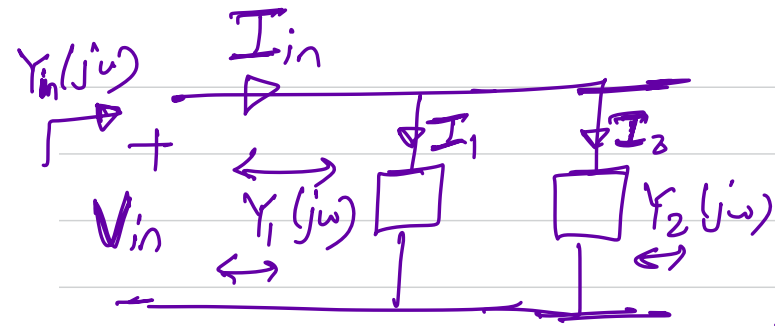


$$Z_{in}(j\omega) = \frac{V}{I} = Z_1(j\omega) + Z_2(j\omega)$$

$$\textcircled{I} = \frac{V}{Z_1(j\omega) + Z_2(j\omega)}$$

$$\sum V_i = V$$

$$\left\{ V_i = \frac{Z_i(j\omega)}{Z_1(j\omega) + Z_2(j\omega)} V \right\}$$



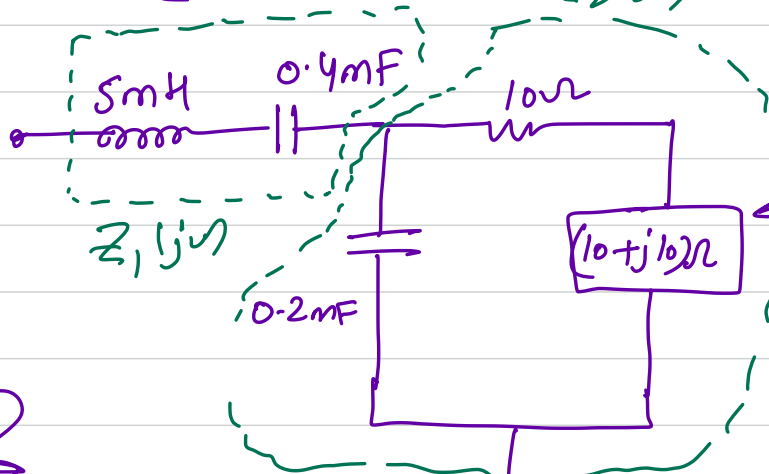
$$Y_{in}(j\omega) = Y_1(j\omega) + Y_2(j\omega)$$

$$I_i = \frac{Y_i(j\omega)}{Y_1(j\omega) + Y_2(j\omega)} I$$

$$I_2 = \frac{Z_1(j\omega)}{Z_1(j\omega) + Z_2(j\omega)}$$

Q

$$\omega = 5000 \text{ rad/s}$$



$$\frac{R + j\omega L}{(R + j\omega L)}$$

$$L = \frac{10}{\omega}$$

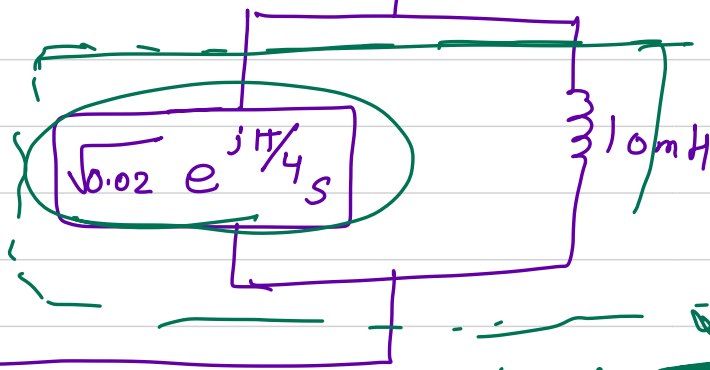
$$\frac{R}{j\omega C} \Rightarrow C = \frac{1}{j\omega C}$$

$$R + \frac{1}{j\omega C} \Rightarrow \left(R - \frac{j}{\omega C} \right)$$

$$Z_{in}(j\omega)$$

$$\frac{1}{j\omega C} = X_C$$

$$j\omega L = X_L$$



$$Z_3(j\omega)$$

$$X_L = j\omega L$$

$$Y_L = \frac{1}{j\omega L} = \frac{-j}{\omega L}$$

$$Y_2(j\omega) = (20 + j10)^{-1} + j\omega C$$

$$Z_2(j\omega) = (5 - j10)\Omega$$

$$Y_2(j\omega) = 0.04 + j0.08$$

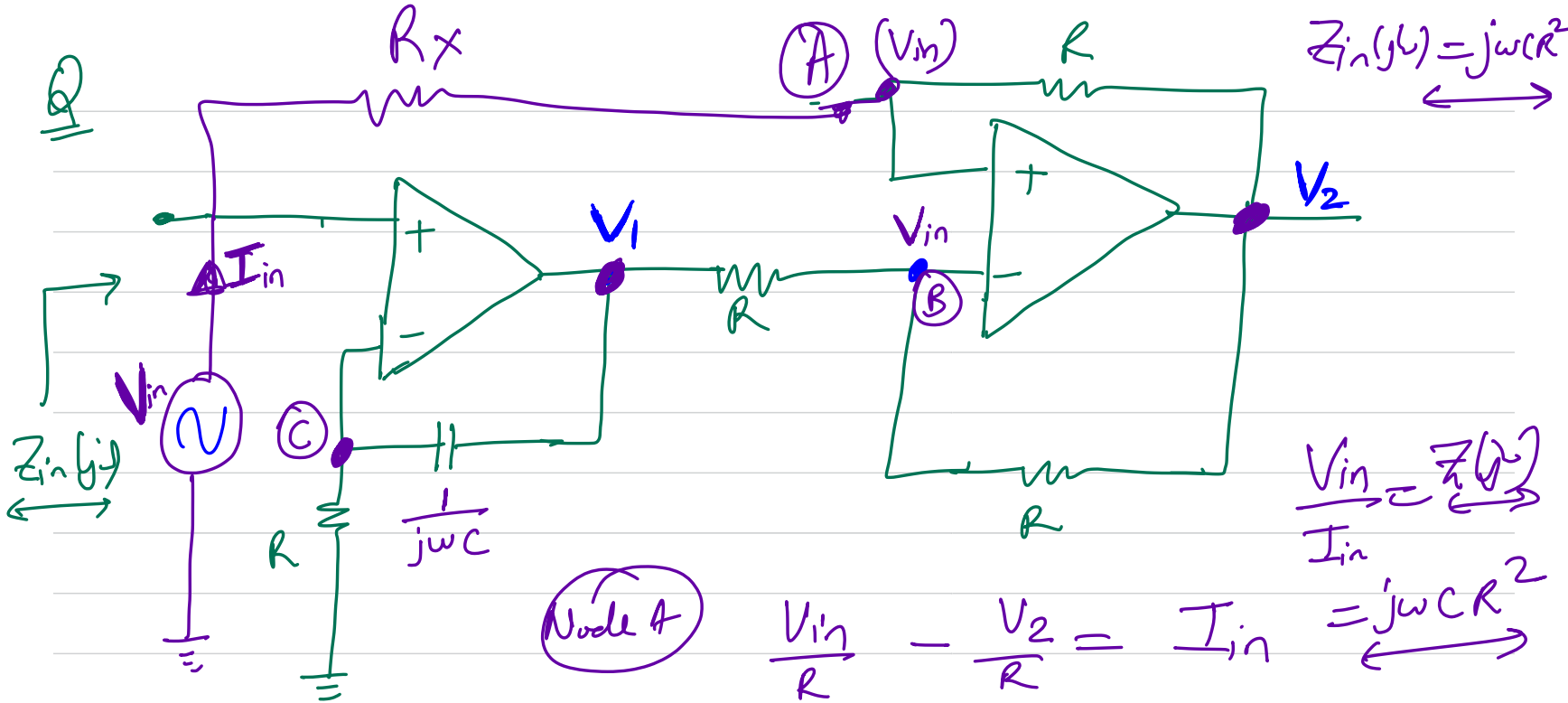
$$Z_1(j\omega) = \left(j\omega L + \frac{1}{j\omega C} \right) = j\omega L - \frac{j}{\omega C}$$

$$Y_3(j\omega) = \left\{ \sqrt{0.02} e^{j\pi/4} - \frac{j}{\omega L} \right\} = j \left(\omega L - \frac{1}{\omega C} \right)$$

$Z_1(j\omega) = -2.5j$

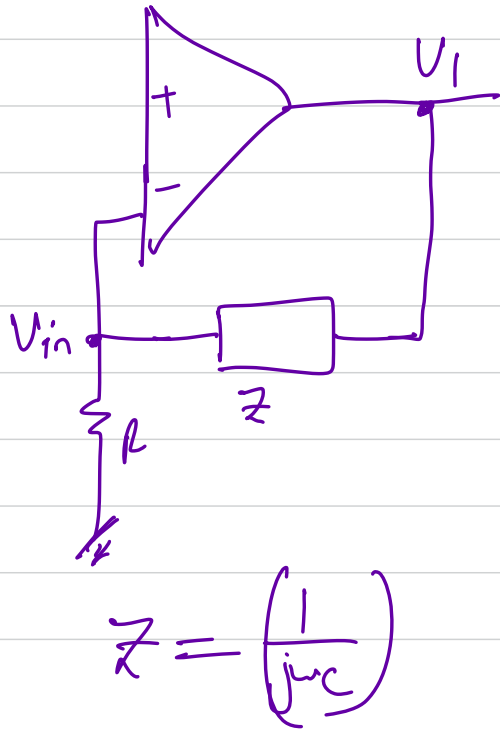
$$Y_3(j\omega) = (0.1 - j0.1)^{-1} \rightarrow Z_3(j\omega) = (5 + j5) \Omega$$

$$Z_h = Z_1 + Z_2 + Z_3 = (10 - j7.5) \Omega = 12.5 \angle -36.87^\circ$$



Node $\left\{ V_{in} \left\{ \frac{1}{R} + j\omega C \right\} - V_1 j\omega C = 0 \right\} \checkmark$

$V_1 = \frac{V_{in} \left(\frac{1}{R} + j\omega C \right)}{j\omega C}$

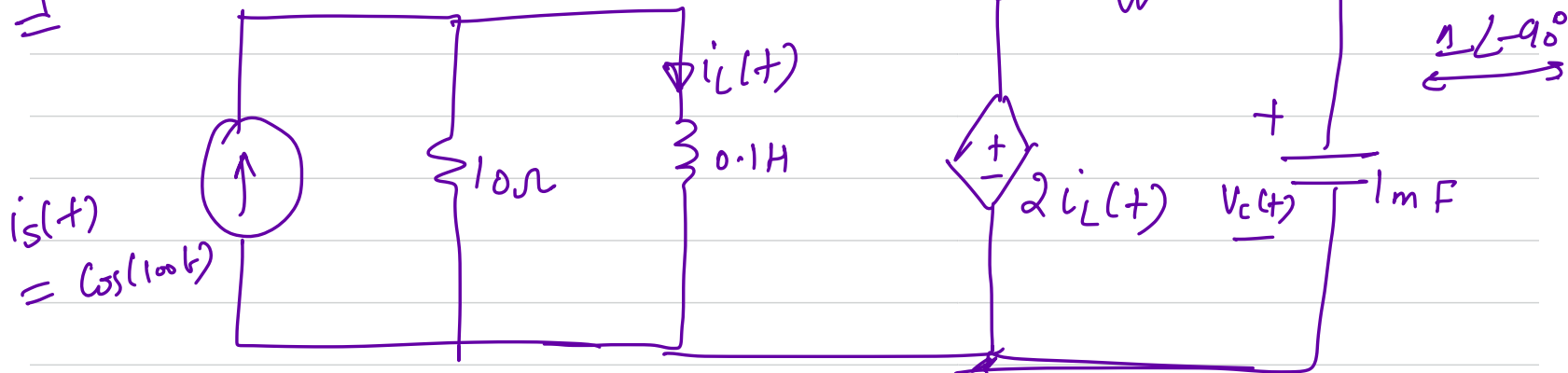


$$\frac{V_{in} - V_1}{Z} + \frac{V_{in}}{R} = 0$$

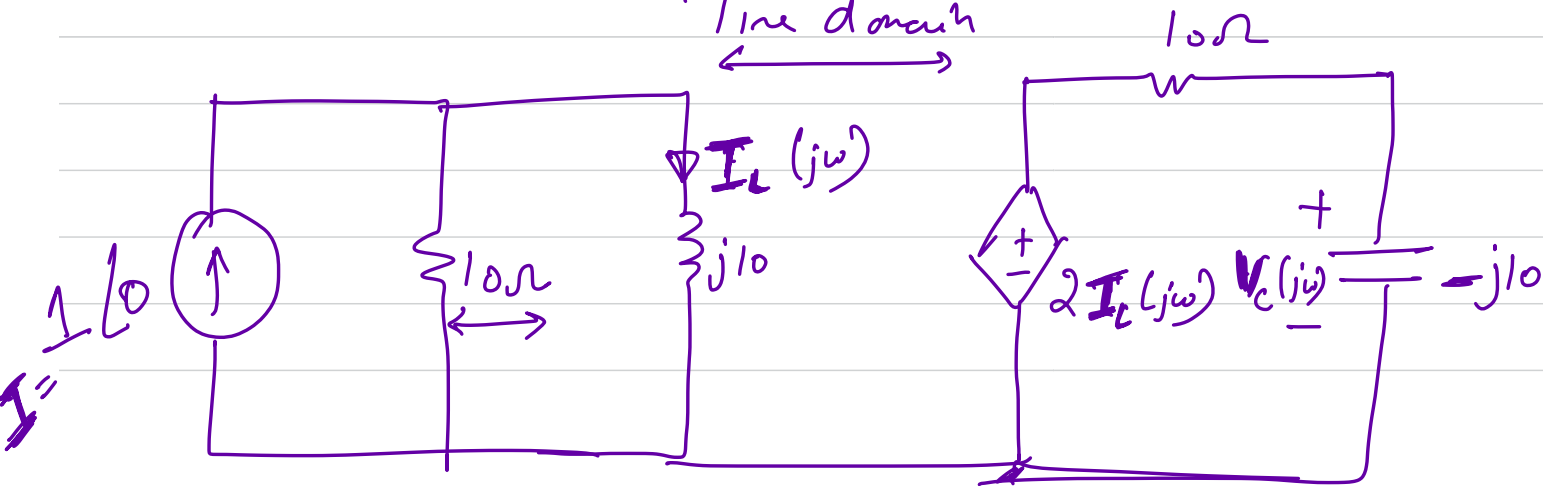
$$\left\{ V_{in} \left(\frac{1}{Z} + \frac{1}{R} \right) - \frac{V_1}{Z} = 0 \right\}$$

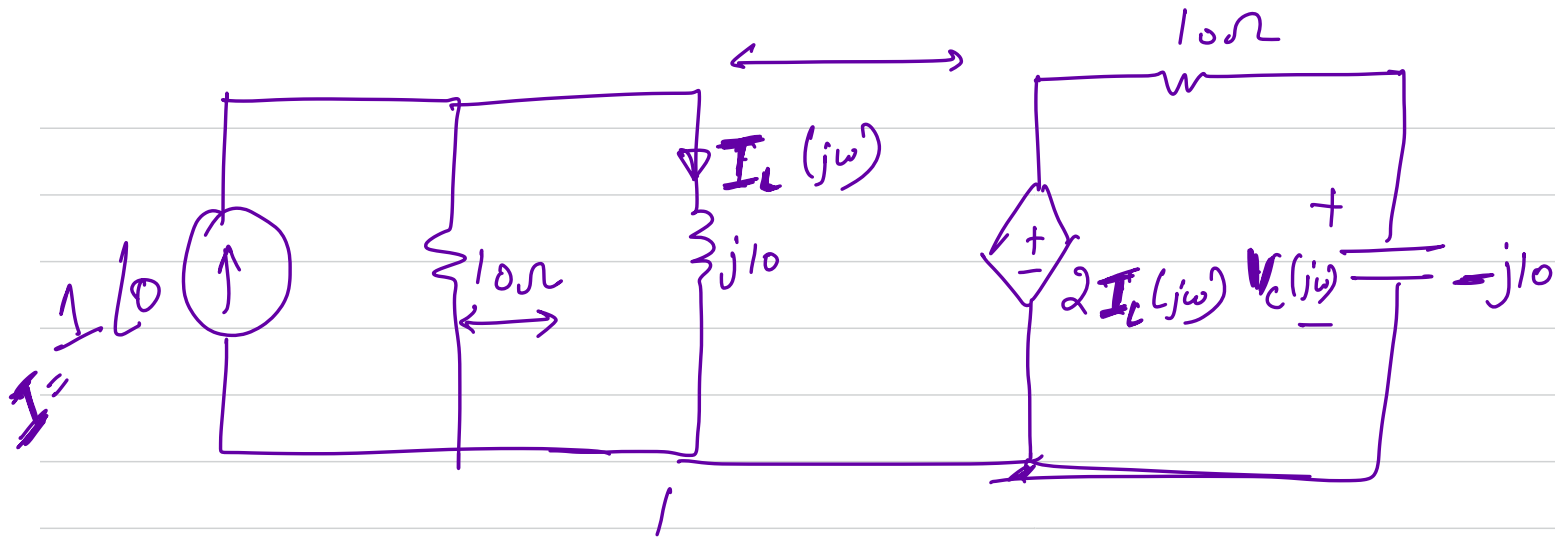
$$V_{in} \left\{ \frac{1}{R} + j\omega C \right\} - V_1 j\omega C = 0$$

Q11



Time domain





$$V_C(j\omega) = \frac{-j10}{(10\Omega - j10)} 2I_L(j\omega) = \frac{1}{\sqrt{2}} \angle -90^\circ$$

$V_C(+)$

$$I_L(j\omega) = \frac{10\Omega}{(10\Omega + j10)} 1\angle 0 = \frac{1}{\sqrt{2}} \angle -45^\circ$$

$$V_c(j\omega) = 1 \angle -90^\circ$$

$$V_c(t) = 1 \cos(1000t - 90^\circ)$$

$$\text{Re}\{1 \angle -90^\circ\}$$

$$\{\text{Re}\}\{1 e^{-j90^\circ}\}$$

$$1 \angle -90^\circ$$

$$(1 \cdot e^{-j90})$$

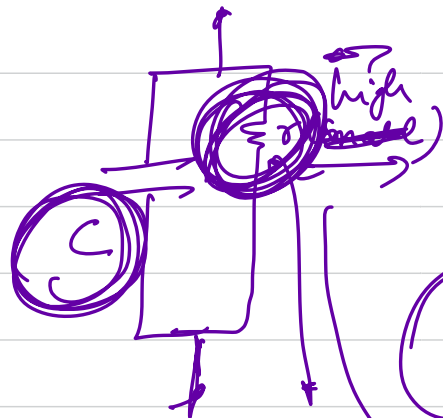
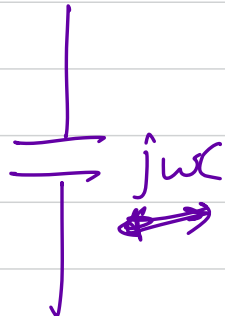
$$\cos 0, \sin 0$$

$$(\cos \phi + j \sin \phi)$$

$$\text{Im}\{\cos \phi + j \sin \phi\}$$

$$= \sin \phi$$

$$\text{Re}\{\cos \phi + j \sin \phi\} = \cos \phi$$



$$X_C \neq \frac{1}{j\omega C}$$

$$X_C = (j\omega C + 1)^{-1}$$

Approximation

Back bone

$$1 + 0.998j \Rightarrow 1 + j$$

