

SC223 - Linear Algebra

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Lecture 13



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Vector Spaces

● **Definition:** A Vector space is a set V with a **field** $(\mathbb{F}, +_F, \times)$, and two binary operations, vector addition $+$ and scalar multiplication \cdot that satisfy the following axioms:

► $(V, +)$ is an **Abelian group**:

► $\forall x, y \in V, x + y \in V$

► $\exists \theta \in V, \forall x \in V, x + \theta = \theta + x = x$

► $\forall x \in V, \exists y \in V, x + y = y + x = \theta$. We will denote y by $-x$.

► $\forall x, y, z \in V, (x + y) + z = x + (y + z)$.

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► **Closure with respect to Scalar multiplication:** $\cdot: \mathbb{F} \times V \rightarrow V$.

► **Scalar Multiplication identity:** $\exists 1 \in \mathbb{F}$ such that $1 \cdot v = v, \forall v \in V$.

► **Distributivity:** $\forall a \in \mathbb{F}, \forall u, v \in V, a \cdot (u + v) = a \cdot u + a \cdot v$, and $\forall a, b \in \mathbb{F}, \forall u \in V, (a +_F b) \cdot u = a \cdot u + b \cdot u$.

► **Compatibility of field and scalar multiplication:**

$\forall a, b \in \mathbb{F}, \forall u \in V, (a \times b) \cdot u = a \cdot (b \cdot u)$.

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- Any element of the vector space $(V, +, \cdot)$ will be referred to as a **vector**, and any element $a \in \mathbb{F}$ will be referred to as a **scalar**.

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► **Distributivity:**

$$\forall a, b, c \in \mathbb{F}, (a +_F b) \times c = a \times c +_F b \times c, a \times (b +_F c) = a \times b +_F a \times c$$

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- $(\mathbb{L}_2(\mathbb{R}), +, \cdot)$ over \mathbb{R} , where $\mathbb{L}_2(\mathbb{R})$ denotes the set of all square-integrable functions $f : \mathbb{R} \rightarrow \mathbb{R}$.

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- **Proposition 5:** $\forall v \in V, (-1) \cdot v = -v$.

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► $V = \mathcal{L}^2(\mathbb{R})$, $W = \{f \in V \mid \int_{-\infty}^{\infty} f(t) dt = 0\}$.

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● Familiar examples of Subspaces: Let $A \in \mathbb{R}^{m \times n}$. Then, $C(A)$, $N(A^T)$ and $N(A)$, $C(A^T)$ are subspaces of \mathbb{R}^m and \mathbb{R}^n respectively.

Generating New subspaces from Old

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- **Definition:** (Sum of subspaces): Let U_1, \dots, U_n be subspaces of V . The **sum of subspaces** U_1, \dots, U_n is defined as:

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- **Proposition 7:** The sum of subspaces U_1, \dots, U_n of V is a subspace.

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- **Definition:** (Direct Sum of Subspaces) In a VS V with subspaces U_1, \dots, U_n , $W = U_1 + \dots + U_n$ is said to be a **Direct Sum** if $\forall w \in W$, w is **uniquely** expressed as a sum of elements $w_i \in U_i$, $i = 1, \dots, n$.

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- Direct sum notation: $W = U_1 \oplus U_2 \oplus \dots \oplus U_n$.

● **Proposition 8:** Let U_1, \dots, U_n be subspaces of V . Then $V = U_1 \oplus \dots \oplus U_n$ if and only if: (1) $V = U_1 + \dots + U_n$, and (2) The only representation of $\theta \in V$ is (θ, \dots, θ) .

● **Proposition 9:** Let V be a VS with subspaces U_1, U_2 . Then $V = U_1 \oplus U_2$ iff $V = U_1 + U_2$ and $U_1 \cap U_2 = \{\theta\}$.

Span and Linear Independence

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- **Proposition 10:** Let $U \subseteq V$. Then $\text{span}(U)$ is a subspace of V .

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● If so, after n iterations, we will reach a contradiction:

$\text{span}(\{w_1, w_2, \dots, w_n\}) = V$

Basis of a Vector space

● **Definition:** (Hamel Basis) Let V be a finite dimensional vector space. An ordered set $\beta := \{v_1, \dots, v_n\}$ is said to be a **(Hamel) basis** of V if (1) $\text{span}(\beta) = V$, and (2) β is a set of linearly independent vectors.

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● Examples:

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- **Proposition 14:** Any set of basis vectors of a VS contains the same number of elements.
- **Dimension of a Vector Space:** Let V be a FDVS. For any set of basis vectors β of V , we define the dimension of V as $\dim(V) := |\beta|$.