7.1 Fundamentals of Subprograms

- General characteristics of subprograms:
 - 1. A subprogram has a single entry point
 - 2. The caller is suspended during execution of the called subprogram
 - 3. Control always returns to the caller when the called subprogram's execution terminates
- Basic definitions:
 - A subprogram definition is a description of the actions of the subprogram abstraction
 - A *subprogram call* is an explicit request that the subprogram be executed
 - A subprogram header is the first line of the definition, including the name, the kind of subprogram, and the formal parameters
 - The *parameter profile* of a subprogram is the number, order, and types of its parameters
 - The *protocol* of a subprogram is its parameter profile plus, if it is a function, its return type

7.1 Fundamentals of Subprograms (continued)

- A subprogram *declaration* provides the protocol, but not the body, of the subprogram
- A formal parameter is a dummy variable listed in the subprogram header and used in the subprogram
- An actual parameter represents a value or address used in the subprogram call statement
- Actual/Formal Parameter Correspondence:
- 1. Positional
- 2. Keyword

```
e.g. SORT(LIST => A, LENGTH => N);
```

Advantage: order is irrelevant

Disadvantage: user must know the formal

parameter's names

- Default Values:

7.1 Fundamentals of Subprograms (continued)

- Procedures provide user-defined statements
- Functions provide user-defined operators

7.2 Design Issues for Subprograms

- 1. What parameter passing methods are provided?
- 2. Are parameter types checked?
- 3. Are local variables static or dynamic?
- 4. What is the referencing environment of a passed subprogram?
- 5. Are parameter types in passed subprograms checked?
- 6. Can subprogram definitions be nested?
- 7. Can subprograms be overloaded?
- 8. Are subprograms allowed to be generic?
- 9. Is separate or independent compilation \ supported?

7.3 Local referencing environments

- If local variables are stack-dynamic:
 - Advantages:
 - a. Support for recursion
 - b. Storage for locals is shared among some subprograms
 - Disadvantages:
 - a. Allocation/deallocation time
 - b. Indirect addressing
 - c. Subprograms cannot be history sensitive
- Static locals are the opposite
- Language Examples:
 - 1. FORTRAN 77 and 90 most are static, but the implementor can choose either (User can force static with SAVE)
 - 2. C both (variables declared to be static are) (default is stack dynamic)
 - 3. Pascal, Java, and Ada dynamic only

7.4 Parameter Passing Methods

- We discuss these at several different levels:
 - Semantic Models: in mode, out mode, inout mode
 - Conceptual Models of Transfer:
 - 1. Physically move a value
 - 2. Move an access path
- Implementation Models:
 - 1. Pass-by-value (in mode)
 - Either by physical move or access path
 - Disadvantages of access path method:
 - Must write-protect in the called subprogram
 - Accesses cost more (indirect addressing)
 - Disadvantages of physical move:
 - Requires more storage (duplicated space)
 - Cost of the moves (if the parameter is large)

- 2. Pass-by-result (out mode)
 - Local's value is passed back to the caller
 - Physical move is usually used
 - Disadvantages:
 - a. If value is passed, time and space
 - b. In both cases, order dependence may be a problem e.g.

```
procedure sub1(y: int, z: int);
    ...
sub1(x, x);
```

Value of x in the caller depends on order of assignments at the return

- 3. Pass-by-value-result (inout mode)
 - Physical move, both ways
 - Also called pass-by-copy
 - Disadvantages:
 - Those of pass-by-result
 - Those of pass-by-value

- 4. Pass-by-reference (inout mode)
 - Pass an access path
 - Also called pass-by-sharing
 - Advantage: passing process is efficient (no copying and no duplicated storage)
 - Disadvantages:
 - a. Slower accesses
 - b. Allows aliasing:
 - i. Actual parameter collisions:

```
e.g. procedure sub1(a: int, b: int);
...
sub1(x, x);
```

ii. Array element collisions:

```
e.g.
```

```
sub1(a[i], a[j]); /* if i = j */
Also, sub2(a, a[i]); (a different one)
```

- iii. Collision between formals and globals
 - Root cause of all of these is: The called subprogram is provided wider access to nonlocals than is necessary
 - Pass-by-value-result does not allow these aliases (but has other problems!)

- 5. Pass-by-name (multiple mode)
 - By textual substitution
 - Formals are bound to an access method at the time of the call, but actual binding to a value or address takes place at the time of a reference or assignment
 - Purpose: flexibility of late binding
 - Resulting semantics:
 - If actual is a scalar variable, it is pass-by-reference
 - If actual is a constant expression, it is pass-by-value
 - If actual is an array element, it is like nothing else e.g.

```
procedure sub1(x: int; y: int);
  begin
  x := 1;
  y := 2;
  x := 2;
  y := 3;
  end;
sub1(i, a[i]);
```

- If actual is an expression with a reference to a variable that is also accessible in the program, it is also like nothing else

- Disadvantages of pass by name:
 - Very inefficient references
 - Too tricky; hard to read and understand
- Language Examples:
 - 1. FORTRAN
 - Before 77, pass-by-reference
 - 77 scalar variables are often passed by value-result
 - 2. ALGOL 60
 - Pass-by-name is default; pass-by-value is optional

- 3. ALGOL W
 - Pass-by-value-result
- 4. C
 - Pass-by-value
- 5. Pascal and Modula-2
 - Default is pass-by-value; pass-by-reference is optional
- 6. C++
 - Like C, but also allows reference type parameters, which provide the efficiency of pass-by-reference with in-mode semantics
- 7. Ada
 - All three semantic modes are available
 - If out, it cannot be referenced
 - If in, it cannot be assigned
- 8. Java
 - Like C++, except only references
- Type checking parameters (Now considered very important for reliability)
 - FORTRAN 77 and original C: none
 - Pascal, FORTRAN 90, Java, and Ada: it is always required
 - ANSI C and C++: choice is made by the user

- Implementing Parameter Passing
 - ALGOL 60 and most of its descendants use the run-time stack
 - Value copy it to the stack; references are indirect to the stack
 - Result same
 - Reference regardless of form, put the address in the stack
 - Name run-time resident code segments or subprograms evaluate the address of the parameter; called for each reference to the formal; these are called thunks
 - Very expensive, compared to reference or value-result

Ada

- Simple variables are passed by copy (value-result)
- Structured types can be either by copy or reference
 - This can be a problem, because
 - a) Of aliases (reference allows aliases, but value-result does not)
 - b) Procedure termination by error can produce different actual parameter results
 - Programs with such errors are "erroneous"

- Multidimensional Arrays as Parameters
 - If a multidimensional array is passed to a subprogram and the subprogram is separately compiled, the compiler needs to know the declared size of that array to build the storage mapping function
 - C and C++
 - Programmer is required to include the declared sizes of all but the first subscript in the actual parameter
 - This disallows writing flexible subprograms
 - Solution: pass a pointer to the array and the sizes of the dimensions as other parameters; the user must include the storage mapping function, which is in terms of the size parameters (See example, p. 371)
 - Pascal
 - Not a problem (declared size is part of the array's type)
 - Ada
 - Constrained arrays like Pascal
 - Unconstrained arrays declared size is part of the object declaration (See example p. 371) (Java is similar)