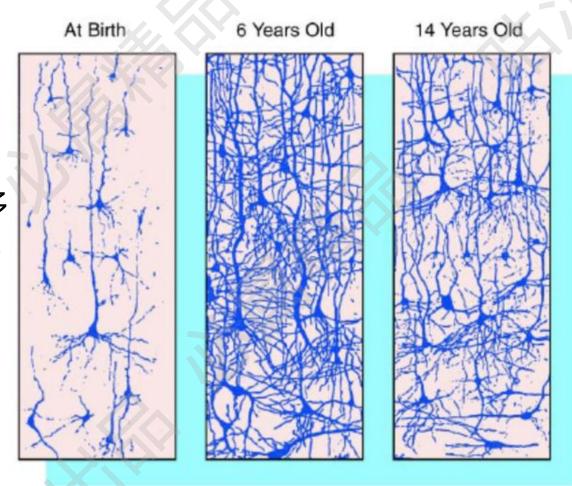
# 模型剪枝策略

#### ❤ 模型如人脑

- Ø 模型剪枝主要目的就是减少参数量
- ∅ 如右图所示,学习的内容会不断增多
- ∅ 一定程度上会降低效果,提升性能
- 必 通常会根据应用领域来选择剪枝



参考论文: Selective Brain Damage: Measuring the Disparate Impact of Model Pruning

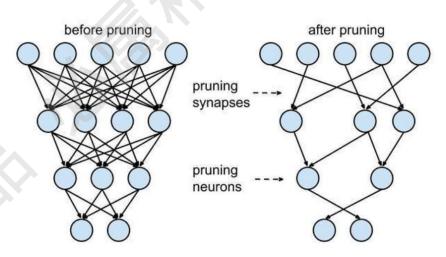
# 模型剪枝策略

network pruning

❷ 基本路线: 训练 (大型模型), 剪枝 (策略)和微调 (重新训练)

对冗余权重进行修剪并保留重要权重,以最大限度地保持精确性

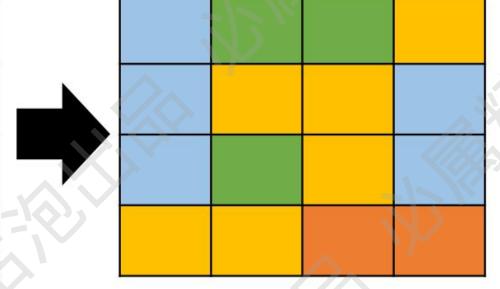
❷ 但是需要注意,剪枝效果并不一定完全有效,



参考论文: RETHINKING THE VALUE OF NETWORK PRUNING

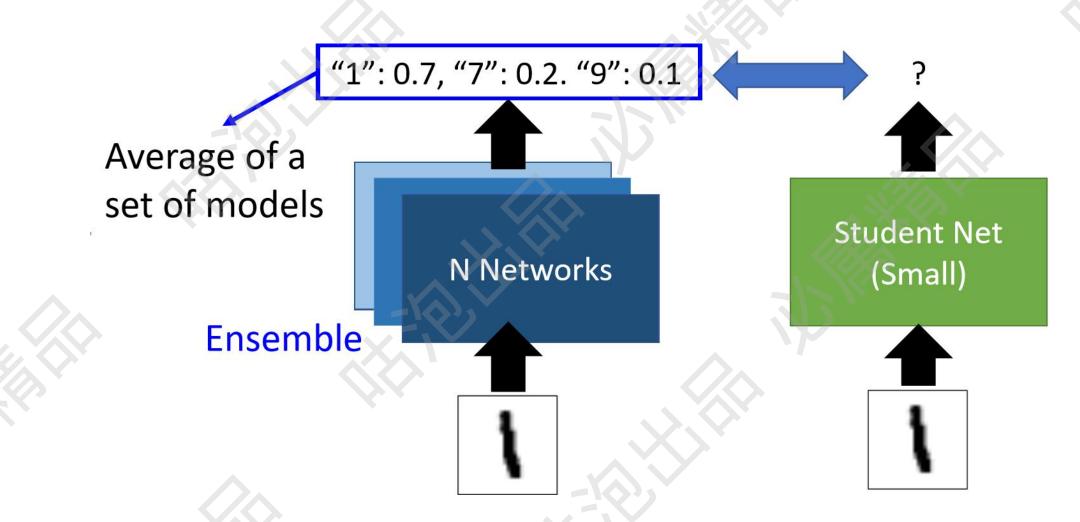
✅ 一些策略 (仅供参考)

0.5	1.3	4.3	-0.1
0.1	-0.2	-1.2	0.3
1.0	3.0	-0.4	0.1
-0.5	-0.1	-3.4	-5.0

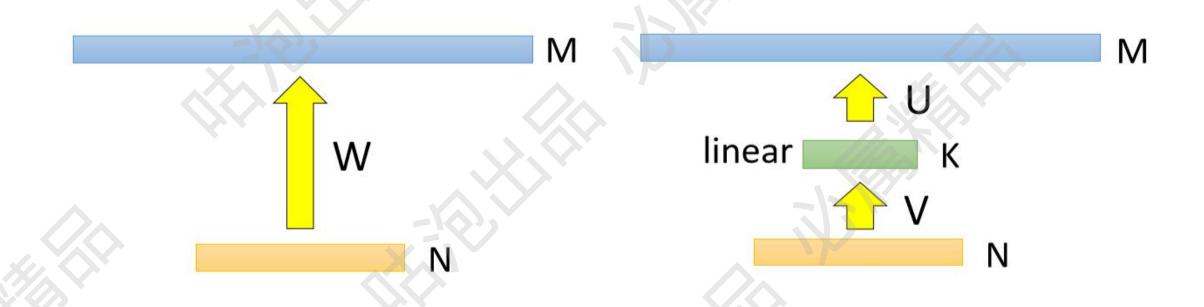


lable			
	-0.4		
	0.4		
	2.9		
	-4.2		

✓ 一些策略 (仅供参考)



✓ 一些策略 (仅供参考)



- ✓ 为什么需要它
  - ❷ 很多嵌入式,手机端无法使用庞大的网络结构
  - ❷一个几百M的模型能随便移植嘛。。。
  - ❷ Mobilenet不光模型参数小、计算量也很小、并且还能DIY



### ✓ V1版本

#### **Object Detection**

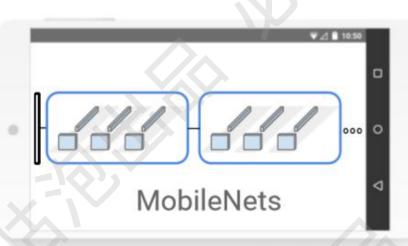


Photo by Juanedc (CC BY 2.0)

#### **Face Attributes**



Google Doodle by Sarah Harrison



#### **Finegrain Classification**



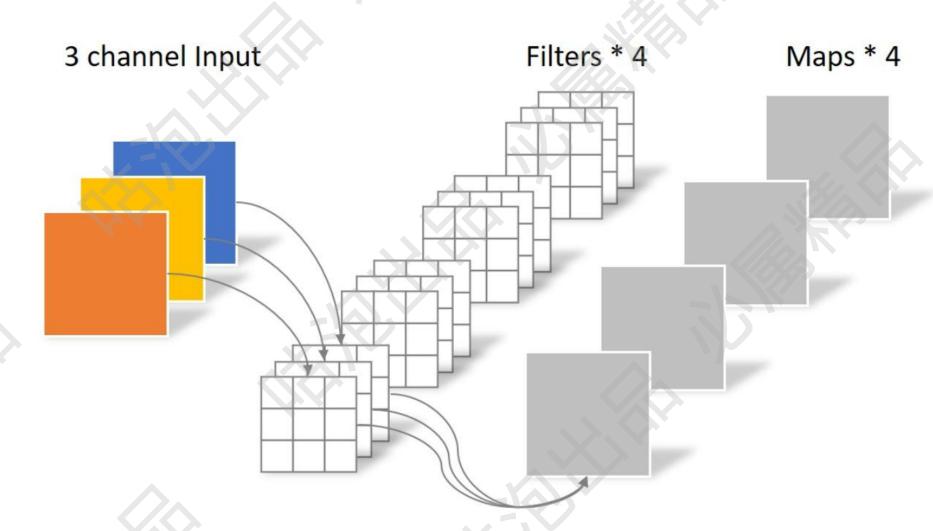
Photo by HarshLight (CC BY 2.0)

#### **Landmark Recognition**

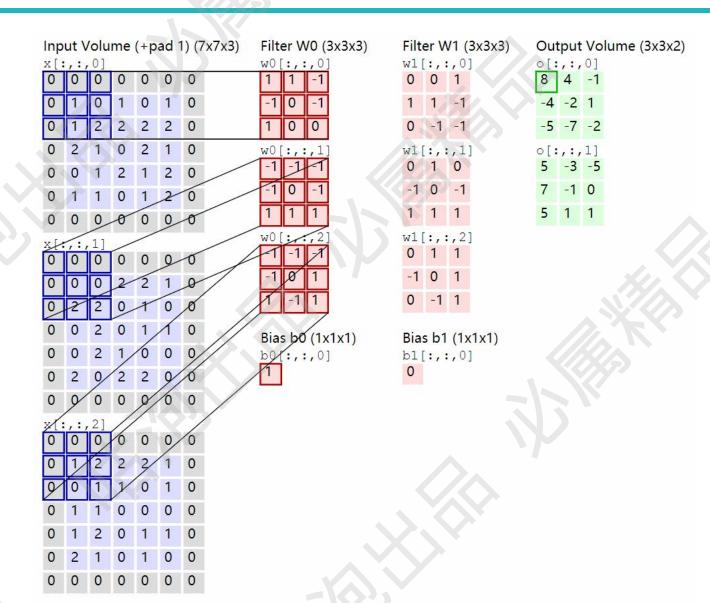


Photo by Sharon VanderKaay (CC BY 2.0)

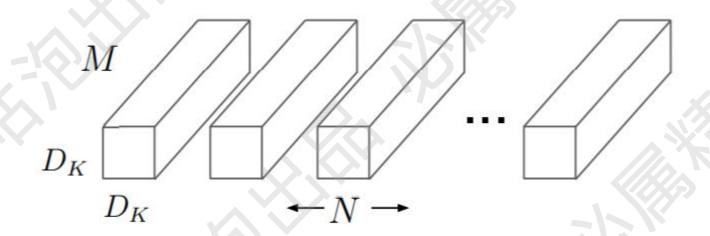
### ❤ 经典卷积计算



❤ 经典卷积计算



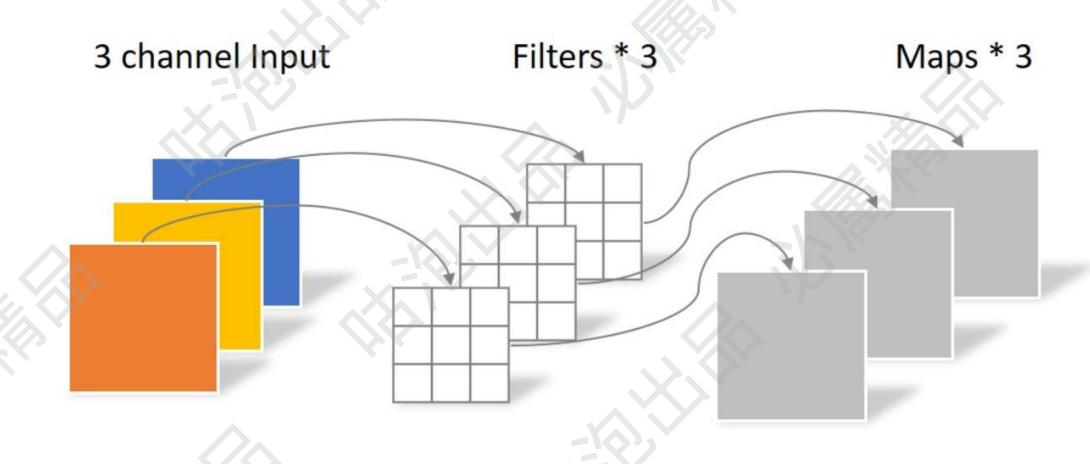
❤ 经典卷积计算



参 卷积核大小为DK\*DK\*M,使用N个卷积核来完成卷积操作

Ø 所需计算量为:  $D_K \times D_K \times M \times N \times D_W \times D_H$  (W,H为输入大小)



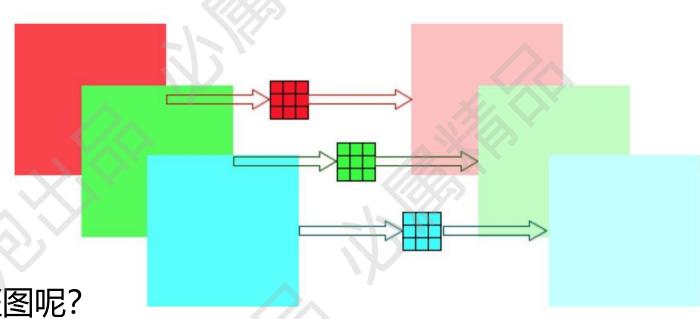


✓ Depthwise卷积

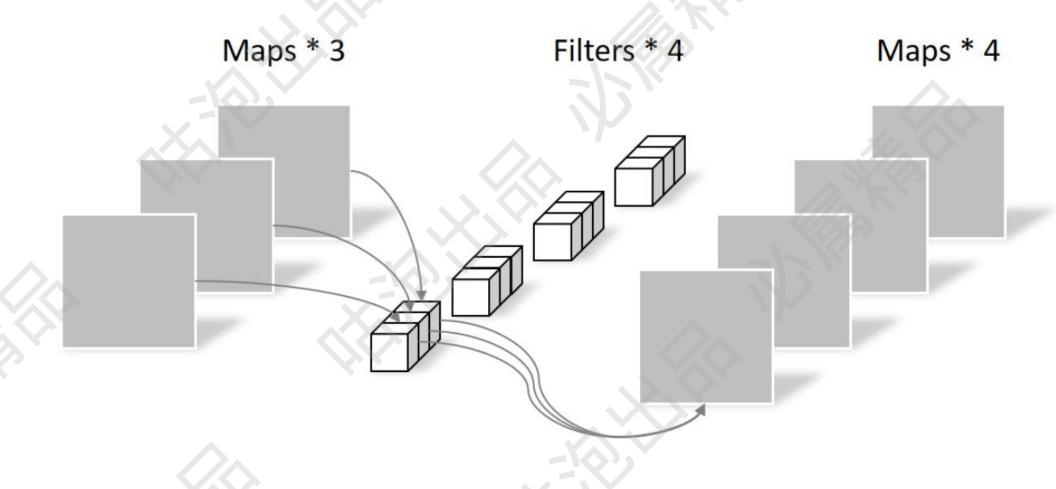
♂3个卷积核,不是1个

∅ 输出与输入是相对应的

如何才能得到更多的特征图呢?



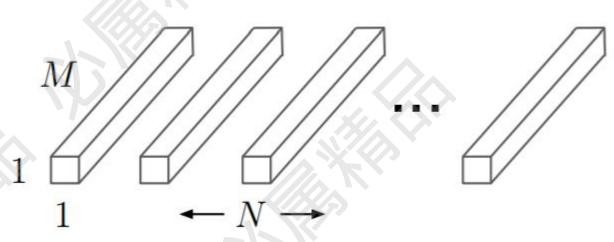
✓ Pointwise卷积



✓ Pointwise卷积

₫ 1\*1卷积来执行,参数比较省

❷ 跟传统卷积计算方法一样



Ø V1版本其实就是把Depthwise卷积和Pointwise卷积组合到一起了!

✓ Depthwise Separable卷积(之前那俩哥们合体)

∅ 一件事分两次做了,但是效果不减

\*256

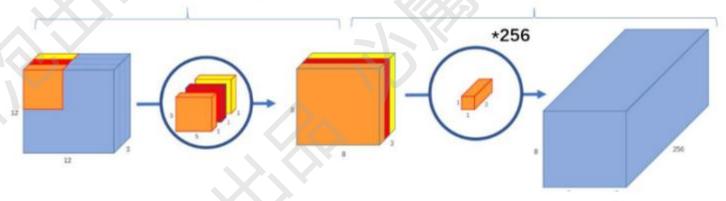
❷ 虽然感觉麻烦点,但参数少

12x12x3 - (5x5x3x256) -> 12x12x256

❷ 接下来,该算账了!

Depthwise卷积

Pointwise卷积



12x12x3 - (5x5x1x3) - > (1x1x3x256) -> 12x12x256

#### ✅ 参数量比较

 $\mathscr{O}$  传统卷积:  $D_K imes D_K imes M imes N$ 

(Dk为卷积核大小, M为输入通道数, N为卷积核个数)

 ${\mathscr O}$  Depthwise Separable卷积:  $D_K imes D_K imes M + M imes N$  Depthwise卷积 Pointwise卷积

夕算账: 
$$rac{D_K imes D_K imes M + M imes N}{D_K imes D_K imes M imes N} = rac{1}{N} + rac{1}{D_K^2}$$

#### ✅ 计算量比较

 $\mathscr{O}$  传统卷积:  $D_K imes D_K imes M imes M imes D_W imes D_H$ 

(Dk为卷积核大小, M为输入通道数, N为卷积核个数, DH,DW为输入大小)

 $\mathscr{O}$  MobileNet:  $D_K imes D_K imes M imes D_W imes D_H + M imes N imes D_W imes D_H$ 



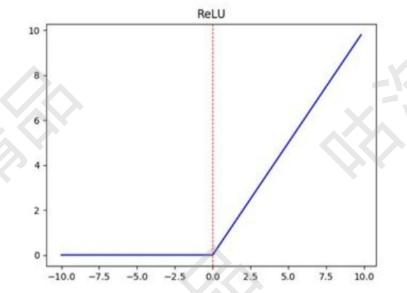


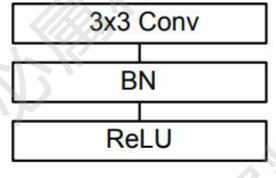
**夕** 算账: 
$$\frac{D_K imes D_K imes M imes D_W imes D_H + M imes N imes D_W imes D_H}{D_K imes D_K imes M imes M imes N imes D_W imes D_H} = \frac{1}{N} + \frac{1}{D_K^2}$$

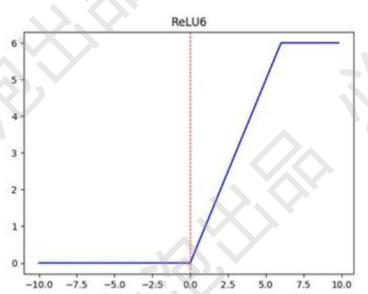
✓ 基础单元变化

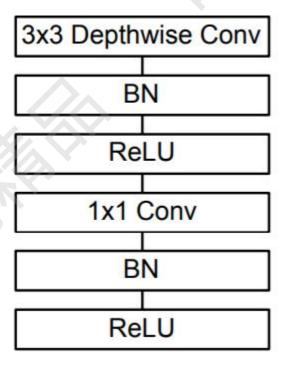
❷ 分两步走,还来了个老六

❷ 增加非线性与泛化能力









#### ❤ 网络结构

Ø 使用stride来进行降采样

♂ 参数集中在1\*1的卷积核中

Table 2. Resource Per Layer Type

Mult-Adds	Parameters
94.86%	74.59%
3.06%	1.06%
1.19%	0.02%
0.18%	24.33%
	94.86% 3.06% 1.19%

Table 1. MobileNet Body Architecture

Type / Stride	Filter Shape	Input Size
Conv/s2	$3 \times 3 \times 3 \times 32$	$224 \times 224 \times 3$
Conv dw / s1	$3 \times 3 \times 32 \text{ dw}$	$112 \times 112 \times 32$
Conv/s1	$1 \times 1 \times 32 \times 64$	$112 \times 112 \times 32$
Conv dw / s2	$3 \times 3 \times 64 \text{ dw}$	$112 \times 112 \times 64$
Conv / s1	$1 \times 1 \times 64 \times 128$	$56 \times 56 \times 64$
Conv dw / s1	$3 \times 3 \times 128 \text{ dw}$	$56 \times 56 \times 128$
Conv/s1	$1 \times 1 \times 128 \times 128$	$56 \times 56 \times 128$
Conv dw / s2	$3 \times 3 \times 128 \text{ dw}$	$56 \times 56 \times 128$
Conv/s1	$1\times1\times128\times256$	$28 \times 28 \times 128$
Conv dw / s1	$3 \times 3 \times 256 \text{ dw}$	$28 \times 28 \times 256$
Conv/s1	$1\times1\times256\times256$	$28 \times 28 \times 256$
Conv dw / s2	$3 \times 3 \times 256 \text{ dw}$	$28 \times 28 \times 256$
Conv/s1	$1 \times 1 \times 256 \times 512$	$14 \times 14 \times 256$
5× Conv dw / s1	$3 \times 3 \times 512 \text{ dw}$	$14 \times 14 \times 512$
Onv/s1	$1 \times 1 \times 512 \times 512$	$14 \times 14 \times 512$
Conv dw / s2	$3 \times 3 \times 512 \text{ dw}$	$14 \times 14 \times 512$
Conv/s1	$1 \times 1 \times 512 \times 1024$	$7 \times 7 \times 512$
Conv dw / s2	$3 \times 3 \times 1024 \text{ dw}$	$7 \times 7 \times 1024$
Conv/s1	$1\times1\times1024\times1024$	$7 \times 7 \times 1024$
Avg Pool / s1	Pool 7 × 7	$7 \times 7 \times 1024$
FC/s1	$1024 \times 1000$	$1 \times 1 \times 1024$
Softmax / s1	Classifier	$1 \times 1 \times 1000$

✅ 网络效果

♂ 不同卷积的效果:

Table 4. Depthwise Separable vs Full Convolution MobileNet

Model	ImageNet	Million	Million
	Accuracy	Mult-Adds	Parameters
Conv MobileNet	71.7%	4866	29.3
MobileNet	70.6%	569	4.2

∅ 与经典网络对比:

Model	ImageNet	Million	Million	
	Accuracy	Mult-Adds	Parameters	
1.0 MobileNet-224	70.6%	569	4.2	
GoogleNet	69.8%	1550	6.8	
VGG 16	71.5%	15300	138	

#### ❤ 再度压缩

♂ 按比例减少通道数,例如0.25,0.5,0.75等进行倍率改变

$$D_K imes D_K imes lpha M imes D_F imes D_F + lpha M imes lpha N imes D_F imes D_F$$

Table 6. MobileNet Width Multiplier

Width Multiplier	ImageNet	Million	Million
	Accuracy	Mult-Adds	Parameters
1.0 MobileNet-224	70.6%	569	4.2
0.75 MobileNet-224	68.4%	325	2.6
0.5 MobileNet-224	63.7%	149	1.3
0.25 MobileNet-224	50.6%	41	0.5

🖉 压缩后效果:

#### ✓ 再度压缩

∅ 按比例降低特征图大小,例如从224\*224变成192\*192

$$D_K imes D_K imes lpha M imes 
ho D_F imes 
ho D_F + lpha M imes lpha N imes 
ho D_F imes 
ho D_F$$

Table	7.	Mobil	leNet	Reso	ution

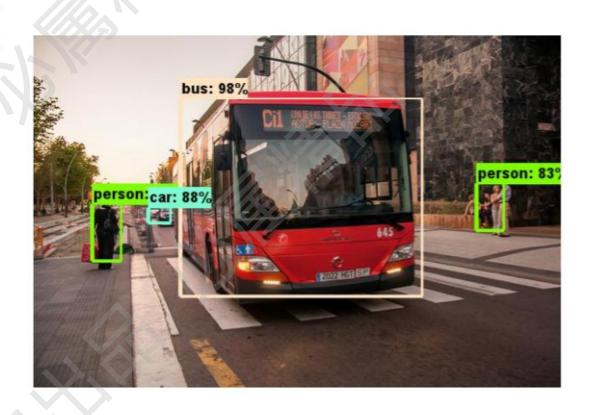
❷ 压缩后效果:

Resolution	ImageNet	Million	Million
	Accuracy	Mult-Adds	Parameters
1.0 MobileNet-224	70.6%	569	4.2
1.0 MobileNet-192	69.1%	418	4.2
1.0 MobileNet-160	67.2%	290	4.2
1.0 MobileNet-128	64.4%	186	4.2

#### ✅ 应用表现

Table 13. COCO object detection results comparison using different frameworks and network architectures. mAP is reported with COCO primary challenge metric (AP at IoU=0.50:0.05:0.95)

Framework	Model	mAP	Billion	Million
Resolution			Mult-Adds	Parameters
	deeplab-VGG	21.1%	34.9	33.1
SSD 300	Inception V2	22.0%	3.8	13.7
	MobileNet	19.3%	1.2	6.8
Faster-RCNN	VGG	22.9%	64.3	138.5
300	Inception V2	15.4%	118.2	13.3
	MobileNet	16.4%	25.2	6.1
Faster-RCNN	VGG	25.7%	149.6	138.5
600	Inception V2	21.9%	129.6	13.3
	Mobilenet	19.8%	30.5	6.1



✓ V2版本

❷ Relu激活函数改变,用线性替代

❷ 整体网络架构改变,类似resnet,但是反过来了

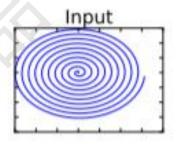
❷ 各方面表现效果较V1都有不错的提升

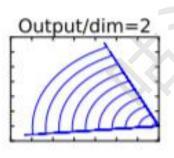
✓ Relu干了一件坏事

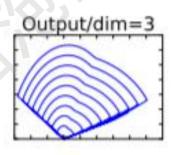
🖉 对不同输入特征进行对比分析,  $y_{m \times n} = ReLU(T_{m \times 2} \cdot x_{2 \times n})$ 

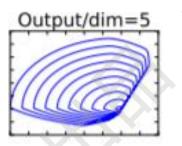
$$ilde{x}_{2 imes n} = T_{2 imes m}^{-1} \cdot y_{m imes n}$$

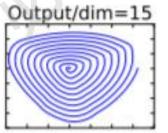
♂ 首先将2维特征经过矩阵T映射到M维,再进行relu计算,再还原回2维

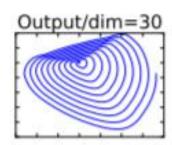










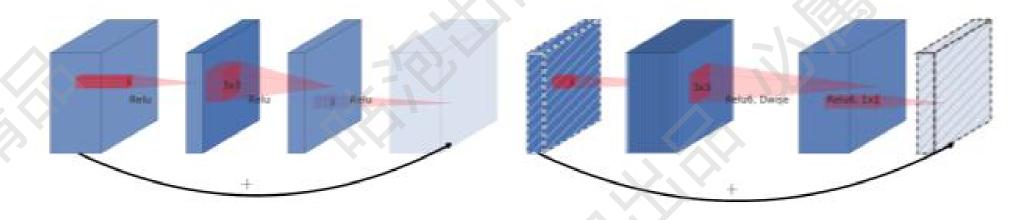


✓ Inverted Residuals

❷ 其实就是把残差模块给反过来了,为什么要升维后再接Relu呢?

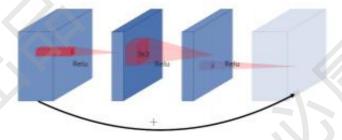
(a) Residual block

(b) Inverted residual block



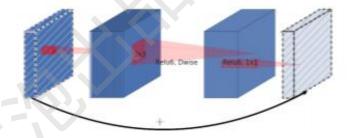
✅ 为什么改变残差模块

∅ 原始残差模块:

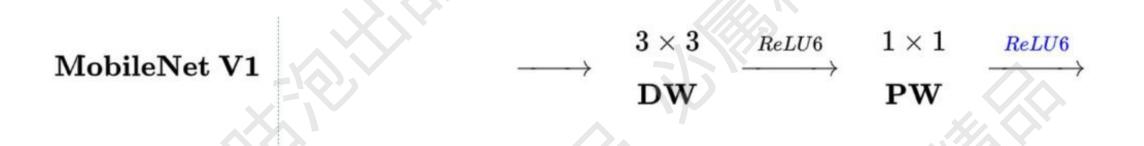


❷ 先1\*1卷积进行压缩,然后3\*3进行特征提取,再1\*1卷积得到更多特征图(还原)

Inverted Residuals:





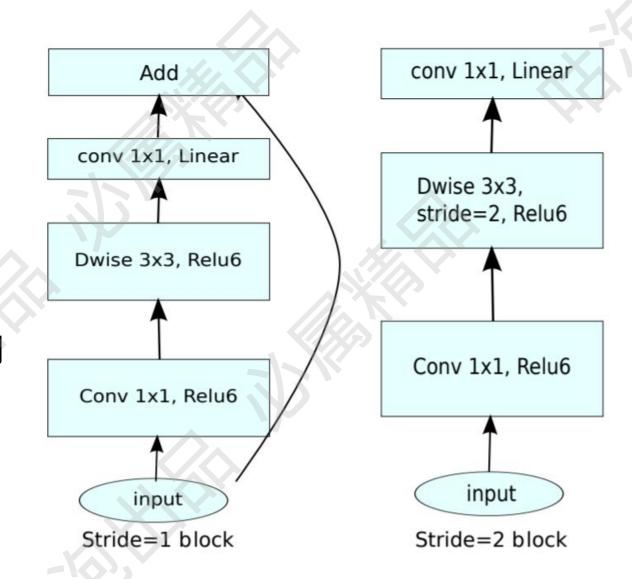


MobileNet V2 
$$\xrightarrow{C_{in}}$$
  $\xrightarrow{1 \times 1}$   $\xrightarrow{6 \times C_{in}}$   $\xrightarrow{3 \times 3}$   $\xrightarrow{6 \times C_{in}}$   $\xrightarrow{1 \times 1}$   $\xrightarrow{C_{out}(\approx C_{in})}$   $\xrightarrow{PW}$   $\xrightarrow{TW}$   $\xrightarrow{W}$   $\xrightarrow{W$ 

✓ V2结构分析

❷ 整体模块特点:

♂ 先升维再Relu,减少破坏



✓ V2整体网络

Ø t为倍率, n为次数

Input	Operator	t	c	$\mid n \mid$	s
$224^{2} \times 3$	conv2d	-	32	1	2
$112^2 \times 32$	bottleneck	1	16	1	1
$112^2 \times 16$	bottleneck	6	24	2	2
$56^2 \times 24$	bottleneck	6	32	3	2
$28^{2} \times 32$	bottleneck	6	64	4	2
$14^2 \times 64$	bottleneck	6	96	3	1
$14^{2} \times 96$	bottleneck	6	160	3	2
$7^2 \times 160$	bottleneck	6	320	1	1
$7^2 \times 320$	conv2d 1x1	-	1280	1	1
$7^2 \times 1280$	avgpool 7x7	-	_	1	-
$1 \times 1 \times 1280$	conv2d 1x1	-	k	_	

✓ V2版本

♂ 改进后的效果:

Network	Top 1	Params	MAdds	CPU
MobileNetV1	70.6	4.2M	575M	113ms
ShuffleNet (1.5)	71.5	3.4M	292M	-
ShuffleNet (x2)	73.7	5.4M	524M	-
NasNet-A	74.0	5.3M	564M	183ms
MobileNetV2	72.0	3.4M	300M	75ms
MobileNetV2 (1.4)	74.7	6.9M	585M	143ms

❷ 应用效果:

mAP	Params	MAdd	CPU
23.2	36.1M	35.2B	-
26.8	36.1M	99.5B	-
21.6	50.7M	17.5B	-
22.2	5.1M	1.3B	270ms
22.1	4.3M	0.8B	200ms
	23.2 26.8 21.6 22.2	23.2 36.1M 26.8 36.1M 21.6 50.7M 22.2 5.1M	23.2 36.1M 35.2B 26.8 36.1M 99.5B 21.6 50.7M 17.5B 22.2 5.1M 1.3B

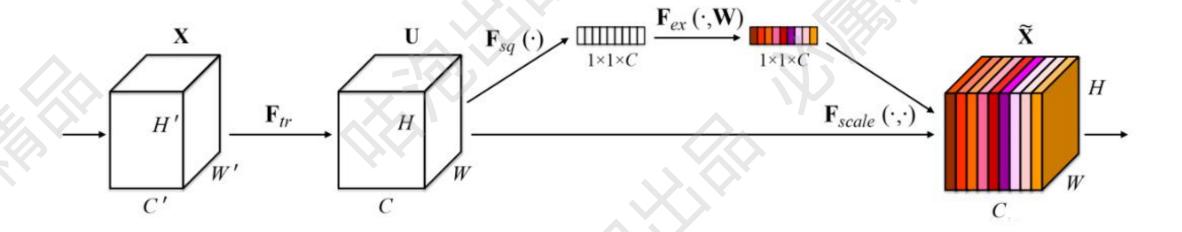
✓ V3版本

❷ 引入Squeeze- Excitation结构

✓ SE-net

Ø NLP中经常说到attention机制,那么特征图里有木有呢

❷ 这个就是SE-net整体的结构,它可以融入到任何网络模型中



✓ S: 操作

♂ 就是对特征图采取全局平均池化,得到1\*1\*C的结果

参 特征图中每个通道都相当于描述了一部分特征,操作后相当于是全局的

$$z_c = \mathbf{F} sq(\mathbf{u}_c) = rac{1}{W imes H} \sum_{i=1}^W \sum_{j=1}^H u_c(i,j)$$

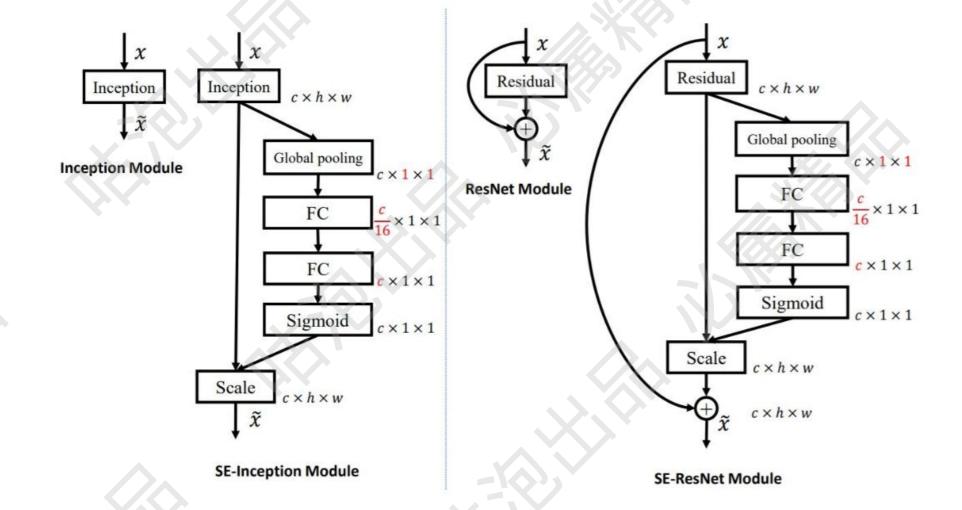
✓ E: Excitation操作

∅ 现在想得到每个特征图的重要程度评分,还需要再来两个全连接层

$$\mathbf{s} = \mathbf{F}_{ex}(\mathbf{z}, \mathbf{W}) = \sigma(g(\mathbf{z}, \mathbf{W})) = \sigma(g(\mathbf{W}_2 \delta(\mathbf{W}_1 \mathbf{z})))$$

 $\mathscr{O}$  完成加权操作:  $ilde{x}_c = \mathbf{F}_{scale}(\mathbf{u}_c, s_c) = s_c \cdot \mathbf{u}_c$ 

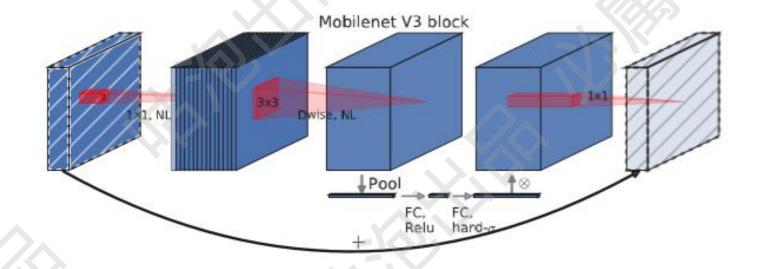
#### ✓ RE模块可以和很多经典模型融合



✓ 引入SE模块

Mobilenet V2: bottleneck with residual

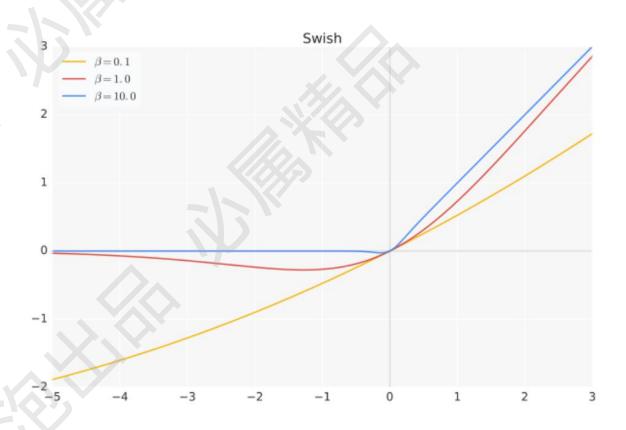
Relugion 1x1



✓ Swish激活函数

②公式:  $f(x) = x \cdot \operatorname{sigmoid}(\beta x)$ 

❷ 无上界有下界、平滑、非单调



✓ hard-swish

使用Relu来模拟sigmoid

$$h\text{-swish}[x] = x \frac{\text{ReLU6}(x+3)}{6}$$

Ø Relu实现的更高效:

	Top 1	Latency P-1
V3	75.2	66
0.85 V3	74.3	55
ReLU	74.5 (7%)	59 (-12%)
h-swish@16	75.4 (+.2 %)	78 (+20%)
h-swish @112	75.0 (3%)	64 (-3%)

Table 5. Effect of non-linearities on MobileNetV3-Large. In h-swish @N, N denotes the number of channels, in the first layer that has h-swish enabled.

### ✓ 网络结构 (large vs small)

Input	Operator	exp size	#out	SE	NL	s
$224^2 \times 3$	conv2d		16	-	HS	2
$112^{2} \times 16$	bneck, 3x3	16	16	-	RE	1
$112^{2} \times 16$	bneck, 3x3	64	24	-	RE	2
$56^2 \times 24$	bneck, 3x3	72	24	-	RE	1
$56^2 \times 24$	bneck, 5x5	72	40	✓	RE	2
$28^{2} \times 40$	bneck, 5x5	120	40	✓	RE	1
$28^{2} \times 40$	bneck, 5x5	120	40	1	RE	1
$28^2 \times 40$	bneck, 3x3	240	80	-	HS	2
$14^{2} \times 80$	bneck, 3x3	200	80		HS	1
$14^{2} \times 80$	bneck, 3x3	184	80	-:	HS	1
$14^{2} \times 80$	bneck, 3x3	184	80		HS	1
$14^{2} \times 80$	bneck, 3x3	480	112	1	HS	1
$14^{2} \times 112$	bneck, 3x3	672	112	<b>V</b>	HS	1
$14^{2} \times 112$	bneck, 5x5	672	160	<b>V</b>	HS	2
$7^{2} \times 160$	bneck, 5x5	960	160	1	HS	1
$7^2 \times 160$	bneck, 5x5	960	160	1	HS	1
$7^{2} \times 160$	conv2d, 1x1	-	960	-	HS	1
$7^{2} \times 960$	pool, 7x7	_	-		-	1
$1^{2} \times 960$	conv2d 1x1, NBN	_	1280	_	HS	1
$1^2 \times 1280$	conv2d 1x1, NBN	_	k		-	1

				_		
Input	Operator	exp size	#out	SE	NL	s
$224^2 \times 3$	conv2d, 3x3	-	16	-	HS	2
$112^{2} \times 16$	bneck, 3x3	16	16	✓	RE	2
$56^2 \times 16$	bneck, 3x3	72	24	-	RE	2
$28^2 \times 24$	bneck, 3x3	88	24	-	RE	1
$28^2 \times 24$	bneck, 5x5	96	40	✓	HS	2
$14^2 \times 40$	bneck, 5x5	240	40	✓	HS	1
$14^{2} \times 40$	bneck, 5x5	240	40	✓	HS	1
$14^{2} \times 40$	bneck, 5x5	120	48	✓	HS	1
$14^{2} \times 48$	bneck, 5x5	144	48	✓	HS	1
$14^{2} \times 48$	bneck, 5x5	288	96	✓	HS	2
$7^2 \times 96$	bneck, 5x5	576	96	✓	HS	1
$7^2 \times 96$	bneck, 5x5	576	96	✓	HS	1
$7^2 \times 96$	conv2d, 1x1	-	576	✓	HS	1
$7^2 \times 576$	pool, 7x7	-	-	-	-	1
$1^2 \times 576$	conv2d 1x1, NBN		1024	-	HS	1
$1^2 \times 1024$	conv2d 1x1, NBN	-	k		-	1

### 

Network	Top-1	MAdds	Params	P-1	P-2	P-3
V3-Large 1.0	75.2	219	5.4M	51	61	44
V3-Large 0.75	73.3	155	4.0M	39	46	40
MnasNet-A1	75.2	315	3.9M	71	86	61
Proxyless[5]	74.6	320	4.0M	72	84	60
V2 1.0	72.0	300	3.4M	64	76	56
V3-Small 1.0	67.4	56	2.5M	15.8	19.4	14.4
V3-Small 0.75	65.4	44	2.0M	12.8	15.6	11.7
Mnas-small [43]	64.9	65.1	1.9M	20.3	24.2	17.2
V2 0.35	60.8	59.2	1.6M	16.6	19.6	13.9

Table 3. Floating point performance on the Pixel family of phones (P-n denotes a Pixel-n phone). All latencies are in ms and are measured using a single large core with a batch size of one. Top-1 accuracy is on ImageNet.