

Introduction to Model Checking and NuSMV

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Outline

1. How to write (temporal) properties:
 - (a) Linear Temporal Logic (LTL).
 - (b) Computation Tree Logic (CTL).
2. How to use the NuSMV model checker, part 1.

Linear Temporal Logic (LTL)

1. **Propositions:** $p, \neg p, p \wedge q, p \vee q$ (also for subformulas)

2. **Temporal operators**

X next \bigcirc

U until

F finally \Diamond

G globally \Box

Other operators exists but they are not used quite as frequently, and can be derived from the ones above.

Semantics: defined on *paths*

1. **Propositions:** $p, \neg p, p \wedge q, p \vee q$ (also for subformulas)

Formula p is true if p holds in first state: $w \models p$ if $p \in w(0)$

Negation: $w \models \neg p$ if $w \not\models p$; conjunct: $w \models p \wedge q$ if $w \models p$ and $w \models q$

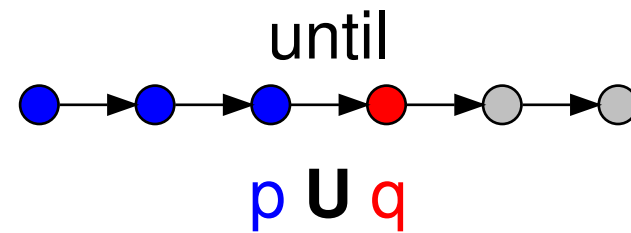
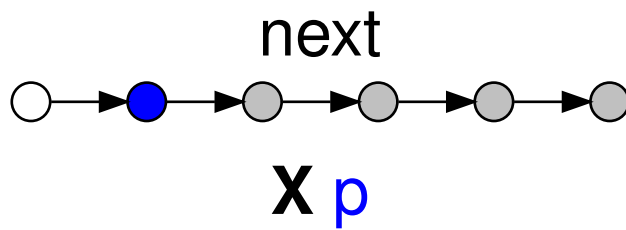
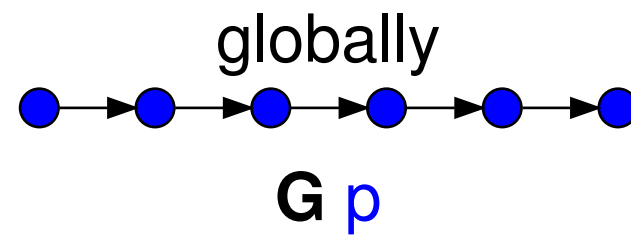
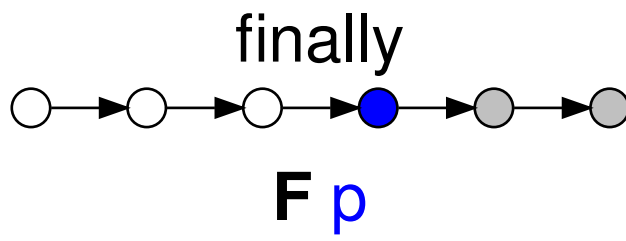
2. **Temporal operators**

X p	next	$\bigcirc p$	$w \models \mathbf{X}p$ if $w_1 \models p$
$p \mathbf{U} q$	until		$\exists j \geq 0, w_j \models q \wedge \forall i, 0 \leq i < j, w_i \models p$
F p	finally	$\Diamond p$	$\text{true U } p$, equivalent to $\exists j \geq 0, w_j \models p$
G p	globally	$\Box p$	$\neg \mathbf{F} \neg p$, equivalent to $\forall j \geq 0, w_j \models p$

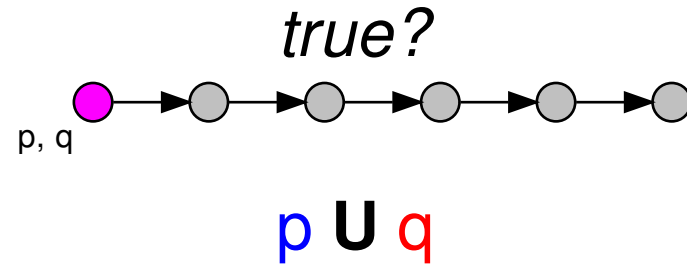
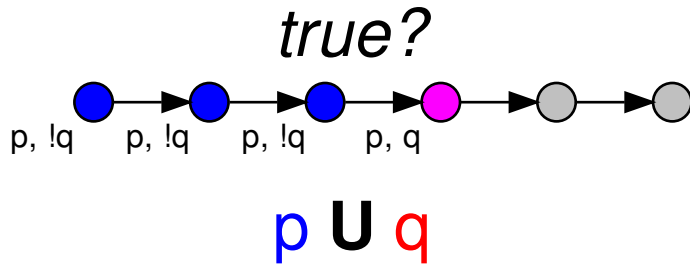
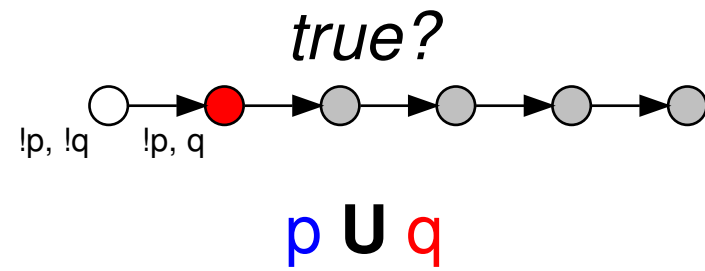
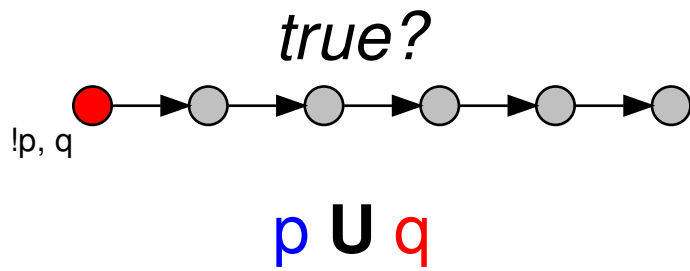
3. **Temporal operators can be nested.**

Furthermore, instead of just atomic propositions for p and q , we can also use other temporal formulas as subexpressions.

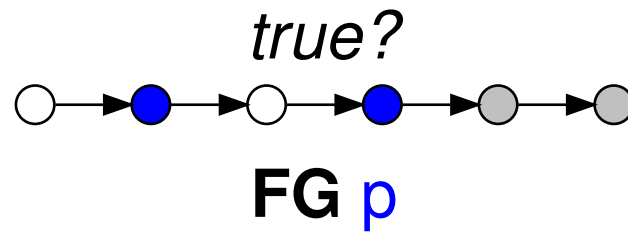
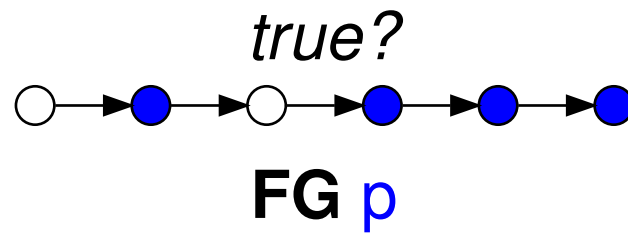
Examples



Until



Nesting

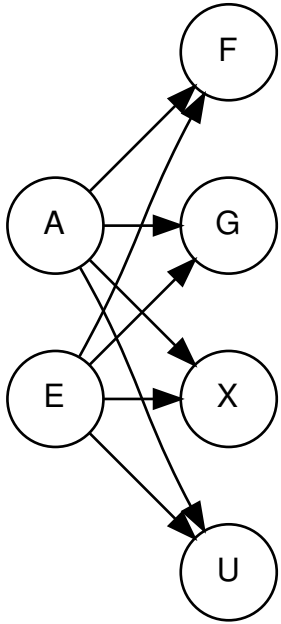


How about infinite traces?

Computation Tree Logic

1. Propositions

2. Path quantifiers + temporal operators



AF p : For all paths, p is eventually true.

AG p : For all paths, p is always true.

AX p : For all paths, p is true in the next state.

A $[p \textbf{U} q]$: For all paths, p holds until q holds.

E: There exists a path...

3. Temporal operators always follow path quantifier

Semantics: Defined on *transition systems*

1. **Propositions:** same as above

2. **Temporal operators** for model $M(S, \rightarrow, L)$

$$\mathbf{AX} p \quad ((M, s) \models \mathbf{AX} p) \Leftrightarrow (\forall \langle s \rightarrow s_1 \rangle ((M, s_1) \models p))$$

$$\mathbf{AG} p \quad ((M, s) \models \mathbf{AG} p) \Leftrightarrow (\forall \langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \forall i ((M, s_i) \models p))$$

$$\mathbf{AF} p \quad ((M, s) \models \mathbf{AF} p) \Leftrightarrow (\forall \langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \exists i ((M, s_i) \models p))$$

$$\mathbf{A} [p \mathbf{U} q] \quad ((M, s) \models \mathbf{A} [p \mathbf{U} q]) \Leftrightarrow \forall (\langle s_1 \rightarrow s_2 \rightarrow \dots \rangle (s = s_1) \exists j ((M, s_j) \models q) \wedge (\forall (i < j) (M, s_i) \models p))$$

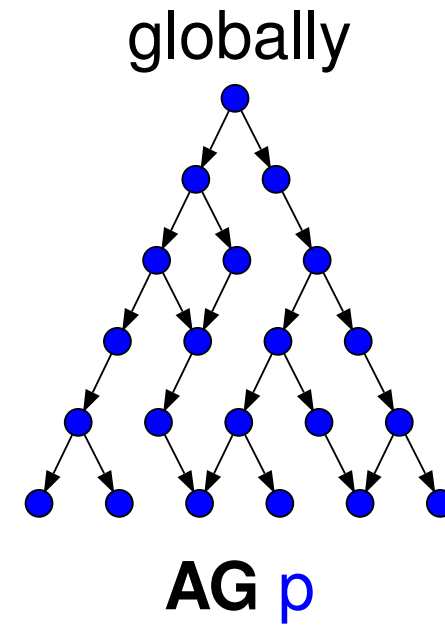
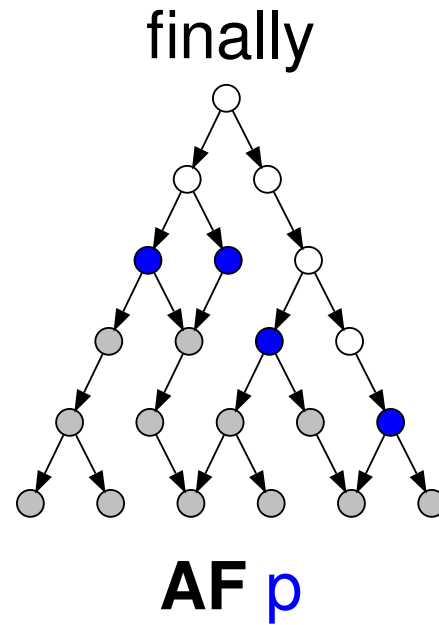
E... defined analogously with existential path quantifier.

3. **Temporal operators canNOT be directly nested.**

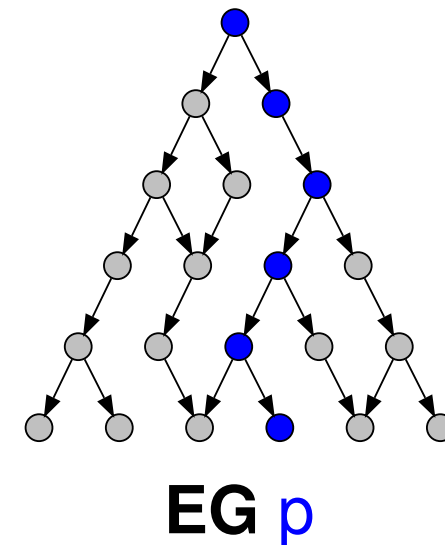
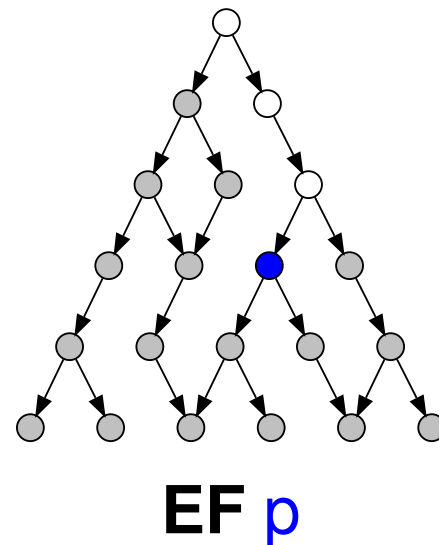
However, instead of just atomic propositions for p and q , we can also use other temporal formulas as subexpressions.

Computation Tree Logic (CTL): finally, globally

for
all
paths

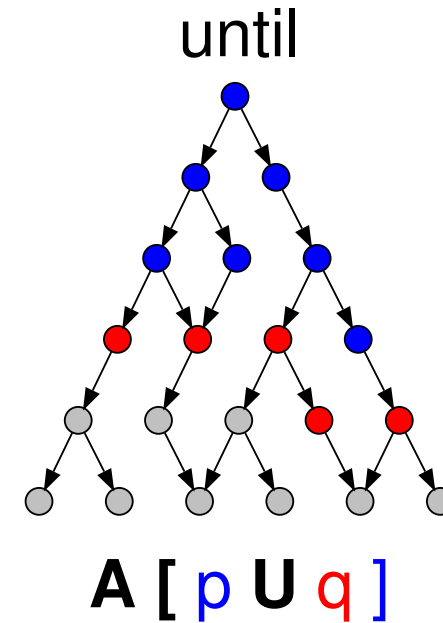
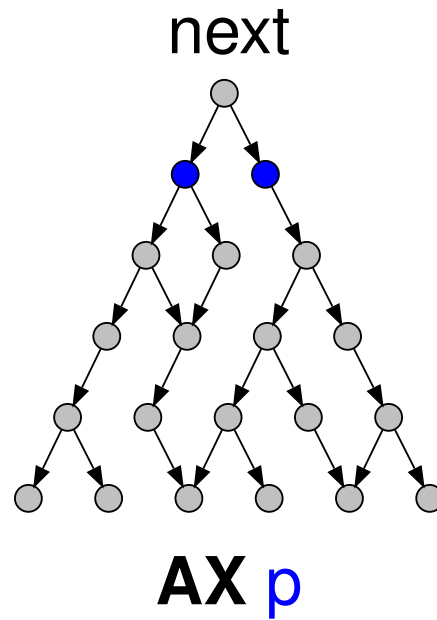


there
exists
a path

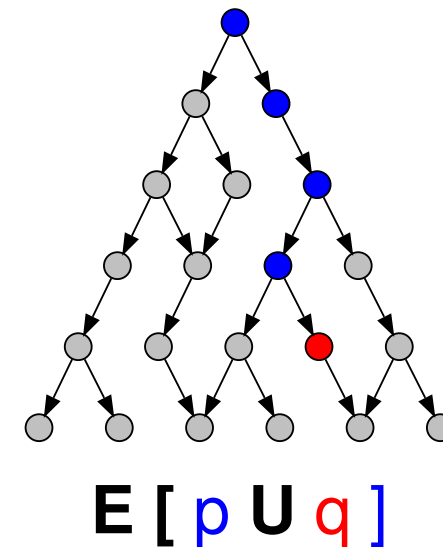
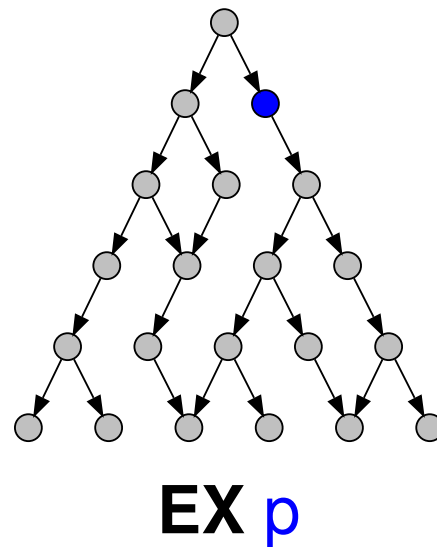


Computation Tree Logic (CTL): next, until

for
all
paths



there
exists
a path



LTL \neq CTL

1. **FG**(p)

2. **EX**(p)

- *Which logic can express the formulas above?*
- *What is the semantics of each formula?*
- *Where does the counterpart fail to express it?*

CTL* : Combines LTL and CTL.

SMV and NuSMV

- Symbolic Model Verifier (SMV):
First practical symbolic model checker by Ken McMillan/CMU.
- Re-implementation NuSMV (open source) at IRST Trento, Italy.
- NuSMV is still being maintained and developed.
- Current version is 2.6.0 (used in this course).

Usage of NuSMV in the real world

- As a back-end to other tools:
 - NuSMV-PA: Safety analysis platform
 - Back-end for Petri net model checking (another modeling approach).
 - Test case generation.
- Case studies:
 - Kerberos protocol.
 - Web service composition.
 - Railway interlocking control tables.

A critique of NuSMV

Pro

open source

mature

fast

well-defined semantics

Con

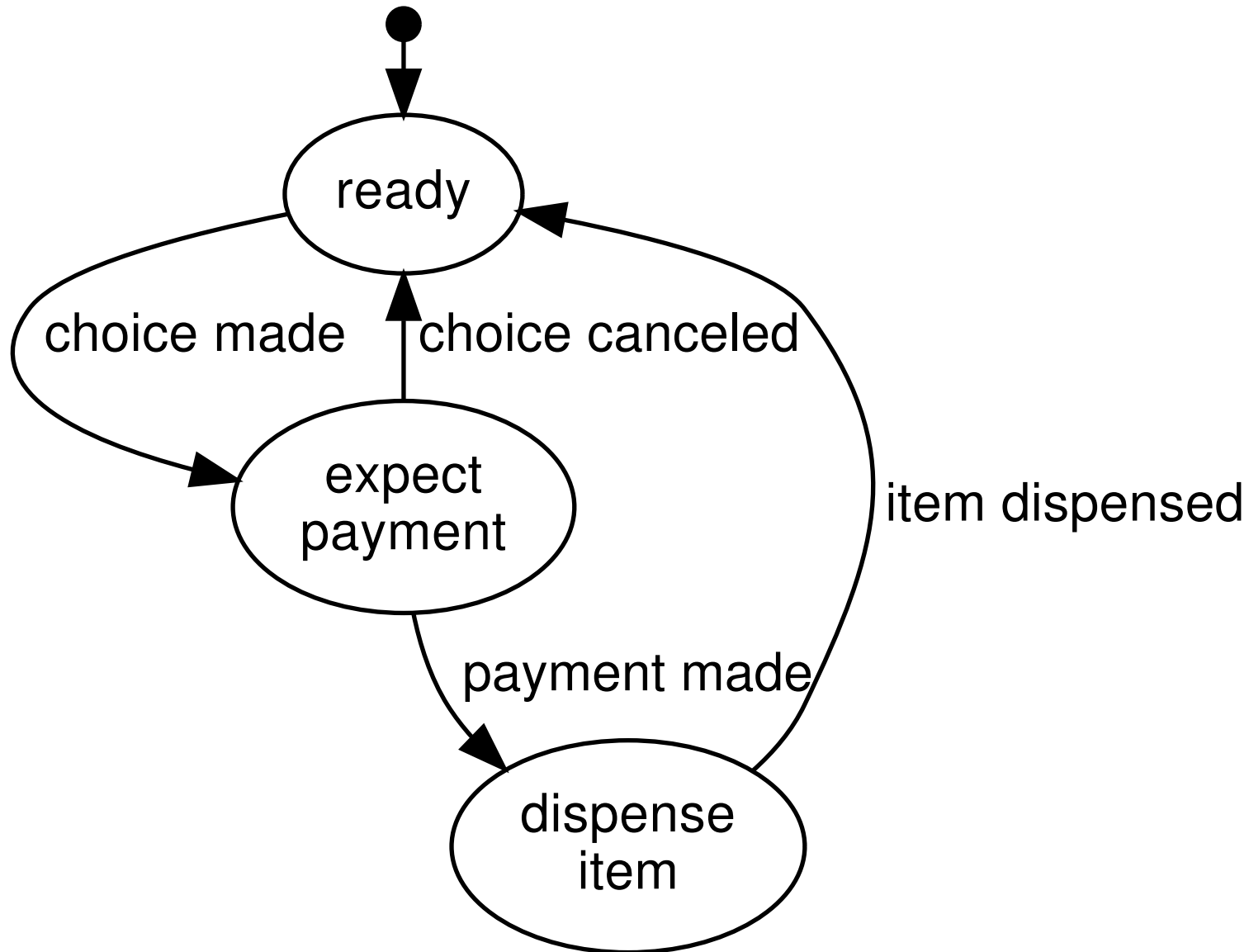
limited open tool set

limited syntax

no arrays of modules

focus on synchronous systems

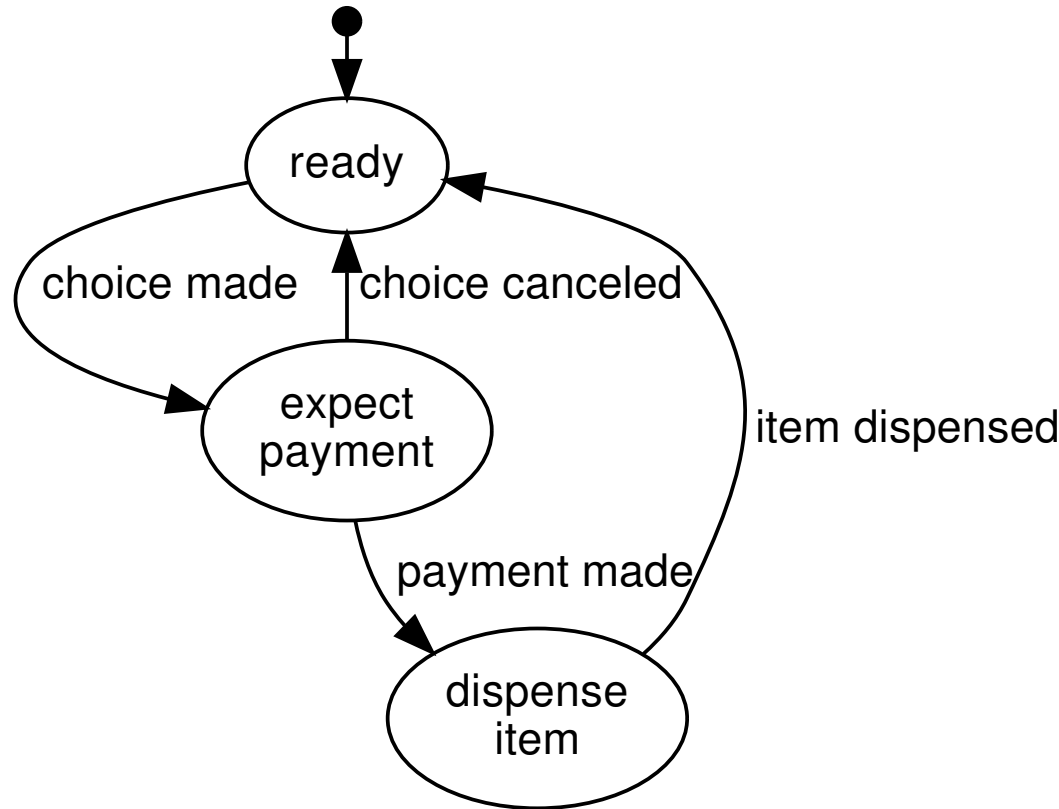
Example: Vending machine



Details not modeled

- How choice is made (how many choices) and canceled.
→ Button, timeout, both?
- How payment is handled/accepted; price of goods.
- Item dispenser mechanism, time taken to dispense item.

Example: Vending machine—2



- Three states: ready, expect_payment, dispense_item.
- Two user inputs (non-deterministic):
 1. Choice (of item); can be cancelled.
 2. Payment (requires choice to be made first).

Vending machine in NuSMV

```
MODULE main
VAR
  choice, payment:  boolean;
  state:  { ready, expect_payment, dispense_item };
ASSIGN
  init (state) := ready;
  next (state) := case
    state = ready          & choice:  expect_payment;
    state = expect_payment & payment: dispense_item;
    state = expect_payment & !choice: ready;
    state = dispense_item:  ready;
  esac;
```

NuSMV syntax

- Module, variables, assignments.
- case (follows order of declaration); can have multiple outcomes.

Error message

```
file vending.smv: line 3: at token ",": syntax error  
file vending.smv: line 3: Parser error  
NuSMV terminated by a signal
```

- Cannot declare more than one variable per line!
- Try again...

Another error message

file vending.smv: line 14: case conditions are not exhaustive

- Recall the **case** block:

```
state = ready           & choice: expect_payment;  
state = expect_payment & payment: dispense_item;  
state = expect_payment & !choice: ready;  
state = dispense_item:  ready;
```

- State should remain the same by default: specify!

Complete case block

ASSIGN

```
init (state) := ready;
next (state) := case
    state = ready          & choice: expect_payment;
    state = expect_payment & payment: dispense_item;
    state = expect_payment & !choice: ready;
    state = dispense_item:  ready;
    TRUE:                  state;
esac;
```

- Transitions from ready and expect_payment depend on user choice.
- Cancellation is modeled as **choice** reverting to **false**.
- Transition from dispense_item back to ready is automatic.

Run NuSMV

- Nothing happens!
- We need properties...

LTLSPEC

```
G(choice -> F state = dispense_item);
```

- „Every time I choose something, I eventually get it”.

Nice try!

```
-- specification
  G (choice -> F state = dispense_item)  is false
-- as demonstrated by the following execution sequence
Trace Description: LTL Counterexample
Trace Type: Counterexample
  -- Loop starts here
-> State: 1.1 <-
    choice = TRUE
    payment = FALSE
    state = ready
-> State: 1.2 <-
    choice = FALSE
    state = expect_payment
-> State: 1.3 <-
    choice = TRUE
    state = ready
```

OK, I'll pay...

LTLSPEC

```
G(payment -> F state = dispense_item);  
-- specification  
G (payment -> F state = dispense_item) is false  
-- as demonstrated by the following execution sequence  
Trace Description: LTL Counterexample  
Trace Type: Counterexample  
-- Loop starts here  
-> State: 1.1 <-  
    choice = FALSE  
    payment = TRUE  
    state = ready  
-> State: 1.2 <-
```

- State 1.2: no progress.
- Payment is accepted even when no choice has been made!

Accept payment only when choice is made

```
MODULE main
```

```
VAR
```

```
    choice:  boolean;
```

```
    payment: boolean;
```

```
    acc_payment: boolean;
```

```
    state:    { ready, expect_payment, dispense_item };
```

```
ASSIGN
```

```
    init (state) := ready;
```

```
    next (state) := case
```

```
        state = ready           & choice:  expect_payment;
```

```
        state = expect_payment & acc_payment: dispense_item;
```

```
        state = expect_payment & !choice: ready;
```

```
        state = dispense_item:    ready;
```

```
        TRUE:                      state;
```

```
    esac;
```

```
    init (acc_payment) := FALSE;
```

```
    next (acc_payment) := (state = expect_payment & payment);
```

Another problem?!

G (acc_payment -> F state = dispense_item) is false

```
-> State: 1.1 <-  
  choice = FALSE  
  payment = FALSE  
  acc_payment = FALSE  
  state = ready  
-> State: 1.2 <-  
  choice = TRUE  
-> State: 1.3 <-  
  choice = FALSE  
  payment = TRUE  
  state = expect_payment  
-> State: 1.4 <-  
  payment = FALSE  
  acc_payment = TRUE  
  state = ready  
-- Loop starts here  
-> State: 1.5 <-  
  acc_payment = FALSE  
-> State: 1.6 <-
```

State 1.3: Choice is made,
next state = accept payment

State 1.4: accepting payment,
but choice is canceled just now!

- Need a way to prevent this transition back to *ready*.
- Use stricter **case** condition!
- Lab exercise 1.

Extension of the vending machine

- Limited capacity of n items.
- Payment should not be accepted when no items available.
- Counting down items:

```
next(n_items) := case
  ...: n_items - 1;
  TRUE: n_items;
esac;
```

- Fails!

```
file vending3.smv: line 16:
  cannot assign value -1 to variable n_items
```

Counting without over- or underflow

- NuSMV recognized possible over- or underflow at compile time.

```
next(n_items) := case
    ... & n_items > 0: n_items - 1;
    TRUE: n_items;
esac;
```

- Underflow needs to be prevented in code.

Additional properties

1. Number of items should always be ≥ 0 .
2. Payment should only be accepted if number of items > 0 .
3. If an item is dispensed, the counter of items is always reduced by 1.

First lab exercise (part of assignment 1): Summary

1. Use NuSMV on `vending1.smv`.
 - (a) Study error trace.
 - (b) Refine transition (**case** condition).
2. Counting remaining items.
 - (a) Add a counter `n_items` (see above).
 - (b) Write LTL or CTL properties for the three properties above.
 - (c) Ensure your model fulfills all properties.

Summary

Temporal logics

Linear temporal logic (LTL):

- No branching.
- Defined on paths.

Computational tree logic (CTL):

- Branching.
- Defined on transition systems.

Model checking

Enumerate all reachable states.

- Check if „bad” state reachable.
- Active research, many optimizations (such as BDDs).