\sigma=t diff(ln(M)) restart; with (PDEtools): with (linalg): with (LinearAlgebra): alias (S [n]=S[n](t),siqma=siqma(t),phi=phi(t),psi=psi(t),Phi=Phi(t)); S_{n} , σ , ϕ , ψ , Φ **(1)** > S5:=t^2*(diff(sigma, t, t))^2-(2*(diff(sigma, t))^2-t*(diff $(sigma, t)+sigma)^2+(4*(diff(sigma, t)+k[0]))*(diff(sigma, t)+k[1])*(diff(sigma, t)+k[2])*(diff(sigma, t)+k[3]);$ $S5 := t^2 \left(\frac{\partial^2}{\partial t^2} \sigma \right)^2 - \left(2 \left(\frac{\partial}{\partial t} \sigma \right)^2 - t \left(\frac{\partial}{\partial t} \sigma \right) + \sigma \right)^2 + 4 \left(\frac{\partial}{\partial t} \sigma + k_0 \right) \left(\frac{\partial}{\partial t} \sigma + k_1 \right) \left(\frac{\partial}{\partial t} \sigma + k_1 \right)$ **(2)** $+k_2$ $\left(\frac{\sigma}{\partial t} \sigma + k_3\right)$ > K2a2:=diff(phi, t, t)=(alpha)*phi/t-(beta-t)*diff(phi,t)/t;K3a2:= diff(K2a2, t):K4a2:=diff(K3a2, t): $K2a2 := \frac{\partial^2}{\partial t^2} \phi = \frac{\alpha \phi}{t} - \frac{(\beta - t) \left(\frac{\partial}{\partial t} \phi\right)}{t}$ (3)> A:=-(5/8)*(n+1)^2+((1/4)*beta+1/4+(1/2)*alpha+(3/4)*t)*(n+1)-(1/8*(2*alpha+1-beta))*(2*alpha+1-beta+2*t); k[0] := -(1/4)*(2*alpha+1-beta+2*t); kalpha-3*beta-n+2); k[1]:=-1/4*(2*alpha+beta-n-2); k[2]:= 1/4*(2*alpha+beta-n-2); k[2]:= 1/4alpha-beta+n+2); k[3] := 1/4*(2*alpha-beta-3*n-2); $A := -\frac{5}{8} (n+1)^2 + \left(\frac{1}{4} \beta + \frac{1}{4} + \frac{1}{2} \alpha + \frac{3}{4} t\right) (n+1) - \frac{1}{8} \left(2 \alpha + 1 - \beta\right) \left(2 \alpha + 1 - \beta\right)$ +2t $k_0 := -\frac{1}{2} \alpha + \frac{3}{4} \beta + \frac{1}{4} n - \frac{1}{2}$ $k_1 := -\frac{1}{2} \alpha - \frac{1}{4} \beta + \frac{1}{4} n + \frac{1}{2}$ $k_2 := \frac{1}{2} \alpha - \frac{1}{4} \beta + \frac{1}{4} n + \frac{1}{2}$ $k_3 := \frac{1}{2} \alpha - \frac{1}{4} \beta - \frac{3}{4} n - \frac{1}{2}$ **(4)** epsilon[3]=1; (5)> phi*exp(-t):for K from 1 to n+1 do;l[K]:=diff(%,t)*t;od:wronskian ([phi*exp(-t), seq(l[j], j=1..n)], t): for j from 1 to n+1 do; h[j]:=Row(%,1);row(%%,2);wronskian(%*t,t):od:subs(K4a2,K3a2,K2a2,<seq(simplify(h[j]), j=1..n+1)>):W:=det(%):Error, (in linalg:-row) row index out of bounds > sigma:=convert(simplify(subs(K4a2,K3a2,K2a2,t*diff(ln(W),t)))+A, parfrac,diff(phi,t)); $\sigma := \frac{t\left(\frac{\partial}{\partial t}\phi\right)}{\frac{1}{4}} - \frac{1}{4}t - \frac{3}{8} + \frac{1}{4}\beta + \frac{1}{2}\alpha - \frac{1}{8}\left(2\alpha + 1 - \beta\right)\left(2\alpha + 1 - \beta + 2t\right)$ **(6)**

simplify(subs(K4a2,K3a2,K2a2,S5)):simplify(%);

(7)

```
n := 1
                                                                                                             (8)
> K2a:=diff(phi, t, t)=(alpha+1)*phi/t-(beta+1-t)*diff(phi,t)/t;
    K3a:=diff(K2a, t):K4a:=diff(K3a, t):
                      K2a := \frac{\partial^2}{\partial t^2} \phi = \frac{(\alpha + 1) \phi}{t} - \frac{(\beta + 1 - t) \left(\frac{\partial}{\partial t} \phi\right)}{t}
                                                                                                             (9)
> K2b:=diff(psi, t, t)=(alpha+1)*psi/t-(beta+2-n-t)*diff(psi,t)/t;
    K3b:=diff(K2b, t):K4b:=diff(K3b, t):
                      K2b := \frac{\partial^2}{\partial t^2} \ \psi = \frac{(\alpha + 1) \ \psi}{t} - \frac{(\beta + 1 - t) \left(\frac{\partial}{\partial t} \ \psi\right)}{t}
                                                                                                           (10)
> K2c:=diff(Phi, t, t)=(alpha+n)*Phi/t-(beta+n-t)*diff(Phi,t)/t;
    K3c:=diff(K2c, t):K4c:=diff(K3c, t):
                      K2c := \frac{\partial^2}{\partial t^2} \Phi = \frac{(\alpha + 1) \Phi}{t} - \frac{(\beta + 1 - t) (\frac{\partial}{\partial t} \Phi)}{t}
                                                                                                           (11)
A := -(5/8)*n^2+(-(3/4)*t+1/2-(1/2)*alpha+(3/4)*beta)*n-(1/8*(2*)
    alpha-beta))*(2*alpha+2*t-beta);k[0] := -(1/4)*beta-(1/2)*alpha-beta)
    (1/4)*n;k[1] := (1/2)*alpha+(3/4)*n-(1/4)*beta;k[2] := -(1/2)*
    alpha+(3/4)*beta-(1/4)*n;k[3] := -(1/4)*beta+(1/2)*alpha-(1/4)*n;
                A := -\frac{1}{8} - \frac{3}{4} t - \frac{1}{2} \alpha + \frac{3}{4} \beta - \frac{1}{8} (2 \alpha - \beta) (2 \alpha + 2 t - \beta)
                                      k_0 := -\frac{1}{4} \beta - \frac{1}{2} \alpha - \frac{1}{4}
                                       k_1 := \frac{1}{2} \alpha + \frac{3}{4} - \frac{1}{4} \beta
                                      k_2 := -\frac{1}{2} \alpha + \frac{3}{4} \beta - \frac{1}{4}
                                      k_3 := -\frac{1}{4} \beta + \frac{1}{2} \alpha - \frac{1}{4}
                                                                                                           (12)
> phi:for K from 1 to n do; l[K]:=diff(%,t)*t;od:wronskian([phi,seq
    (l[j],j=1..n-1)],t):for j from 1 to n do;h[j]:=Row(%,1);row(%%,2)
    ; wronskian (%*t, t):od:subs (K4a,K3a,K2a,<seq(simplify(h[j]),j=1..n)
    >):W:=det(%):
 Error, (in linalg:-row) row index out of bounds
                                                                                                   epsilon[3]=
-1;
> sigma:=convert(simplify(subs(K4a,K3a,K2a,t*diff(ln(W),t)))+A,
         \sigma := \frac{t\left(\frac{\partial}{\partial t} \phi\right)}{\frac{1}{4}} - \frac{1}{8} - \frac{3}{4} t - \frac{1}{2} \alpha + \frac{3}{4} \beta - \frac{1}{8} (2\alpha - \beta) (2\alpha + 2t - \beta)
                                                                                                           (13)
> simplify(subs(K4a,K3a,K2a,S5)):simplify(%);
                                                                                                           (14)
   phi:for K from 1 to n do;l[K]:=diff(%,t)*t;od:wronskian([phi,seq
```

```
(1[j],j=1..n-1)],t):for j from 1 to n do;h[j]:=Row(%,1);row(%%,2)
    ; wronskian(%*t,t):od:subs(K4a,K3a,K2a,<seq(simplify(h[j]),j=1..n)
   >):W:=det(%):
           (in linalg:-row) row index out of bounds
> tau[n]:=collect(subs(K4b,K3b,K2b,det(Wronskian([psi,seq(diff(psi,
   t$j),j=1..n-1)],t))),t,factor):
> tau2[n]:=collect(subs(K4c,K3c,K2c,det(Wronskian([t^(beta+n-2)*
   Phi, seq(diff(t^(t^(beta+n-2)*Phi,t$j),j=1..n-1)],t))),t,factor):
Solution using delta operator
> sigma:=convert(simplify(subs(K4a,K3a,K2a,t*diff(ln(W),t)))+A,
   parfrac,diff(phi,t));
        \sigma := \frac{t\left(\frac{\partial}{\partial t} \phi\right)}{\frac{1}{\alpha}} - \frac{1}{8} - \frac{3}{4} t - \frac{1}{2} \alpha + \frac{3}{4} \beta - \frac{1}{8} (2 \alpha - \beta) (2 \alpha + 2 t - \beta)
                                                                                                   (15)
> simplify(subs(K4a,K3a,K2a,S5)):simplify(%);
                                                                                                   (16)
LSolution using normal Wronskian
> sigma:=convert(simplify(subs(K4b,K3b,K2b,A-n/2*(1-n)+simplify(t*
   diff(ln(tau[n]),t)))),parfrac,diff(psi,t));
                                                                                                   (17)
    -\frac{1}{8} \frac{1}{\Psi} \left( \Psi + 6 t \Psi + 4 \alpha \Psi - 6 \beta \Psi + 4 \Psi \alpha^{2} + 4 \Psi \alpha t - 4 \Psi \alpha \beta - 2 \Psi \beta t + \Psi \beta^{2} \right)
     -8t\left(\frac{d}{dt}\psi\right)
> simplify(subs(K4b,K3b,K2b,S5)):simplify(%);
                                                                                                   (18)
Solution using normal Wronskian with seed t<sup>(beta+n-2)</sup>(M+U)
> sigma:=convert(simplify(subs(K4c,K3c,K2c,+A+(1/2)*n^2+(1/2-beta)*
   n+t*diff(ln(tau2[n]),t))),parfrac,diff(Phi,t));
                                                                                                   (19)
     -\frac{1}{8} \frac{1}{\Phi} \left( \Phi + 6 \Phi t + 4 \alpha \Phi - 6 \Phi \beta + 4 \Phi \alpha^{2} + 4 \alpha \Phi t - 4 \Phi \alpha \beta - 2 \beta \Phi t + \Phi \beta^{2} \right)
     -8\left(\frac{\partial}{\partial t}\Phi\right)t
  simplify(subs(K4c,K3c,K2c,S5)):simplify(%);
                                                                                                   (20)
```