```
> restart; with (linalg): with (LinearAlgebra): alias(sigma=sigma(t)):
  > S3dash:=(t*diff(sigma,t,t))^2+(4*diff(sigma,t)^2-1)*(t*diff
                  (sigma, t) - sigma) + theta[0] * theta[2] * diff(sigma, t) - 1/4*(theta[0]^2 + 1/4
                theta[2]^2);
                                                                      \left(\frac{\partial^{2}}{\partial t^{2}} \sigma\right)^{2} + \left(4\left(\frac{\partial}{\partial t} \sigma\right)^{2} - 1\right)\left(t\left(\frac{\partial}{\partial t} \sigma\right) - \sigma\right) + \theta_{0} \theta_{2}\left(\frac{\partial}{\partial t} \sigma\right) - \frac{1}{4} \theta_{0}^{2} - \frac{1}{4} \theta_
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  (1)
                     \theta_2^2
 > n:=2;epsilon[1]:=1;epsilon[2]:=1;
                                                                                                                                                                                                                         n := 2
                                                                                                                                                                                                                       \varepsilon_1 := 1
                                                                                                                                                                                                                        \varepsilon_2 := 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  (2)
> phi:=t^(epsilon[1]*nu/2)*(BesselJ(nu,2*sqrt(epsilon[1]*epsilon[2]
                 *t))-BesselY(nu,2*sqrt(epsilon[1]*epsilon[2]*t)));
                                                                                                            \phi := t^{\frac{1}{2}v} \left( \text{BesselJ}(v, 2\sqrt{t}) - \text{BesselY}(v, 2\sqrt{t}) \right)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  (3)
> phi:for k from 1 to n do; l[k]:=diff(%,t)*t; od:wronskian([phi,seq
                  (1[j],j=1..n-1)],t):for j from 1 to n do;h[j]:=Row(%,1);row(%%,2)
                 ;wronskian(%*t,t):od:<seq(h[j],j=1..n)>:tau:=det(%):
> sigma:=simplify(t*diff(ln(tau),t)+1/2*(epsilon[1]*epsilon[2]*t+
               nu^2/2+n*(1-epsilon[1]*nu)-n^2/2)):
> theta[0]:=nu+n;theta[2]:=epsilon[1]*epsilon[2]*(nu-n);
                                                                                                                                                                                                             \theta_0 := v + 2
                                                                                                                                                                                                             \theta_2 := v - 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  (4)
             simplify(S3dash);
```

(5)