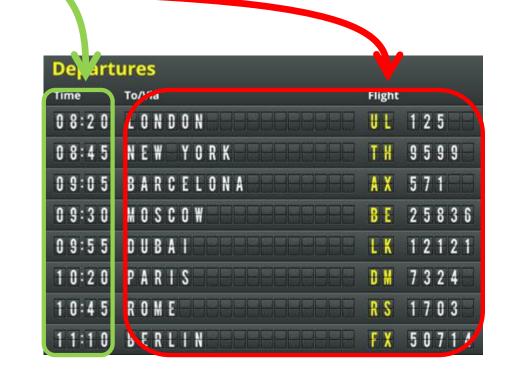
## Hashing

## Recap Problem: Flight Database

- One record of data:
  - Key
  - Data
- Dynamic collections
  - Can add or remove any one at anytime
- Can query the database
  - Find a particular record by the key
    - E.g. what is the flight at 09:05?
    - Or checathe stence
      - Is thereany flight between 09:00 to 09:23?
  - Find the on Frore or after
    - successo or predecessor



## Dictionary ADT

```
void insert (Key k, Value v) insert (k,v) into table
                                 get value paired with k
  Value search (Key k)
   Key successor (Key k)
                                 find next key > k
   Key predecessor (Key k)
                                 find next key < k
   void delete(Key k)
                                 remove key k (and value)
                                 is there a value for k?
boolean contains (Key k)
    int size()
                                 number of (k, v) pairs
```

## Examples

Dictionary: key = word

value = definition

Phone Book key = name

value = phone number

Internet DNS key = website URL

value = IP address

C++ compiler key = variable name

value = type and value

## Time Complexity for Each Operation

#### **Data Structure**

Linked List Sorted Array Unsorted Array Balanced Tree

Can we do....?

#### **Query, Modification**

O(n) $O(\log n)$ , O(n)

O(n)

 $O(\log n)$ 

O(1)



## Dictionary/Symbol Tables

- Spelling correction (key=misspelled word, data=word)
- Scheme interpreter (key=variable, data=value)
- Web server
  - Lots of simultaneous network connections.
  - When a packet arrives, give it to the right process to handle the connection.
  - key=ip address, data = connection handler
- In these cases,  $O(\log n)$  often isn't fast enough!

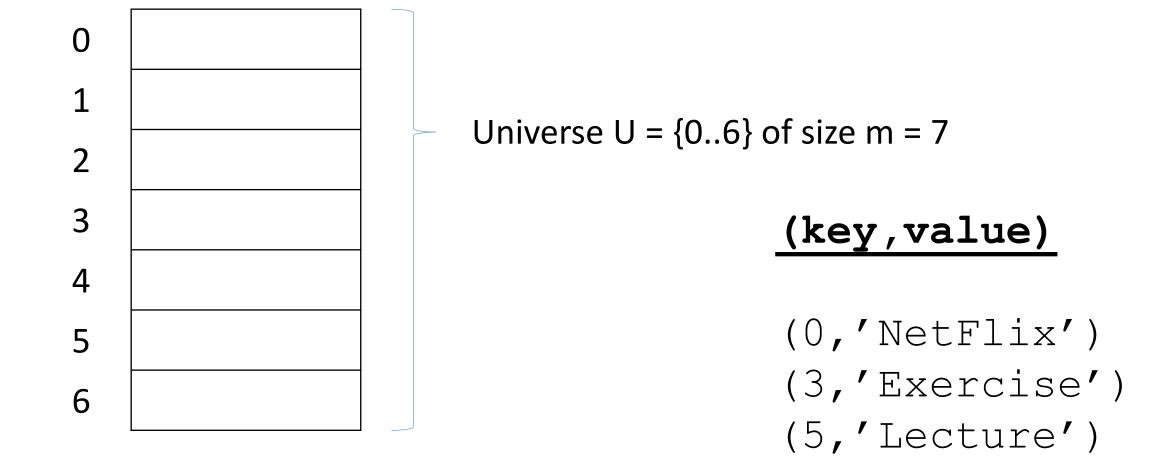
### Assumptions

- No duplicate keys allowed.
- No mutable keys
  - If you use an object as a key, then you can't modify that object later.

```
SymbolTable<Time, Plane> t =
             new SymbolTable<Time, Plane>();
Time t1 = new Time(9:00);
Time t2 = new Time(9:15);
t.insert(t1, "SQ0001");
                               Moral: Keys should be immutable.
t.insert(t2, "SQ0002");
t1.setTime(1000);
                               Examples: Integer, String
x = \text{new Time}(9:00);
t.search(x);
```

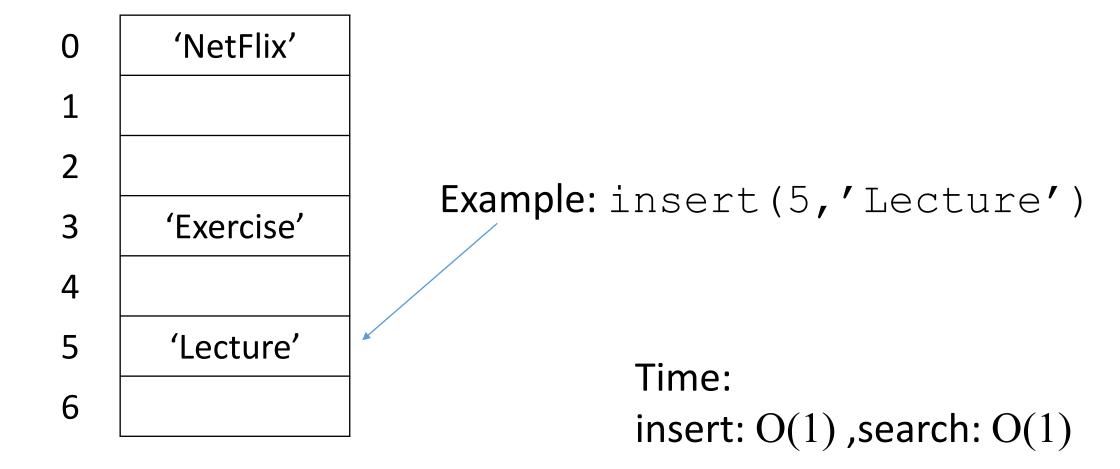
## Attempt #1: Use a table, indexed by keys

• What I do after dinner in the seven days of a week



## Attempt #1: Use a table, indexed by keys

• What I do after dinner in the seven days of a week



# Now ALL the keys are just 7 days

What if you have more types of keys?

## Attempt #1: Use a table, indexed by keys

- What I do after dinner in the seven days of a week
- What I do after dinner in the 365 days of a year?
- What I do after dinner in the 80 years of my life?
- What I do after dinner in the 8000 years of my life after I ate some elixir?!

- How large will the table be?
- And most of the nights I do nothing?

'NetFlix'
'Exercise'
'Lecture'

3

6

#### Direct Access Table

- Problems:
  - Too much space
  - If keys are ALL integers, then table-size > 4 billion

- What if keys are not integers?
  - Where do you put the key/value :

```
"(hippopotamus, bob)"
```

Where do you put 3.14159?

## Pythagoras said, "Everything is a number."



#### **Direct Access Tables**

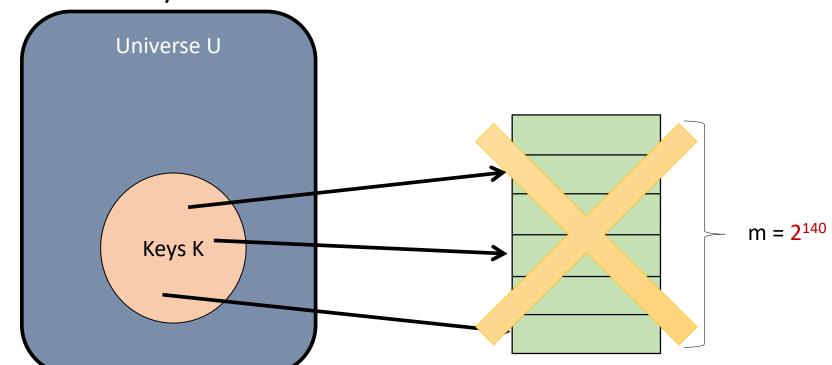
- Pythagoras said, "Everything is a number."
  - Everything is just a sequence of bits.
  - Treat those bits as a number.

#### • English:

- 26 letters => 5 bits/letter
- Longest word = 28 letters (antidisestablishmentarianism?)
- 28 letters \* 5 bits = 140 bits
- So we can store any English text in a direct-access array of size 2<sup>140</sup>.
  - ≈ number of atoms in observable universe

#### • Problem:

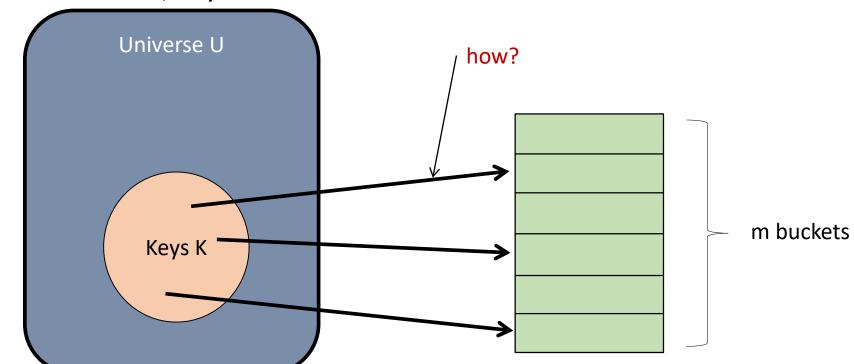
- Huge universe U of possible keys.
- Smaller number n of actual keys.
- We cannot have an array with size  $m = 2^{140}$



Pythagoras said, "Everything is a number."

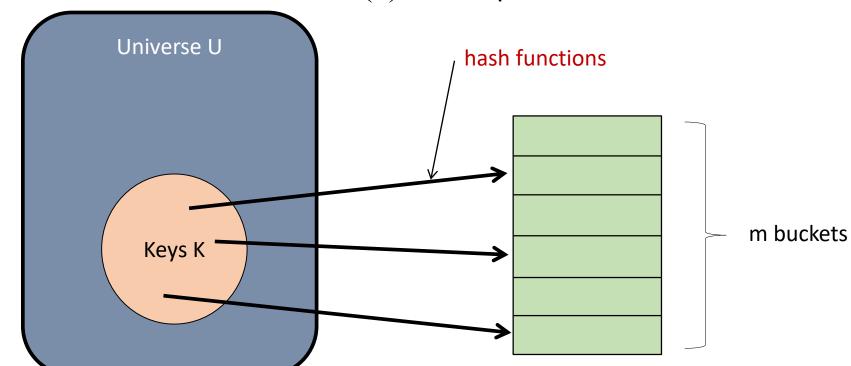
- English words:
  - There are possible 2<sup>140</sup> English words with less than or equal to 28 letters
  - But we actually have about 1 million (~2<sup>20</sup>) of REAL English words
    - Comparing to 2<sup>140</sup>

- Problem:
  - Huge universe U of possible keys.
  - Smaller number n of actual keys. ← e.g., n = 2<sup>20</sup>
  - How to put n items into, say m ≈ n buckets?



e.g.,  $u = 2^{140}$ 

- Define hash function  $h: U \rightarrow \{1..m\}$ 
  - Store key k in bucket h(k).
  - Time complexity:
    - Time to compute *h* + Time to access bucket
  - For now: assume hash function cost O(1) to compute.



- For example, the (key, value) pairs are:
  - ("pizza", "Clementi")
  - ("coffee", "NUS")
- For example, if the function h is the number of characters in an English word then
  - *h*("pizza") = 5
  - h ("coffee") = 6
- What is the potential problem?

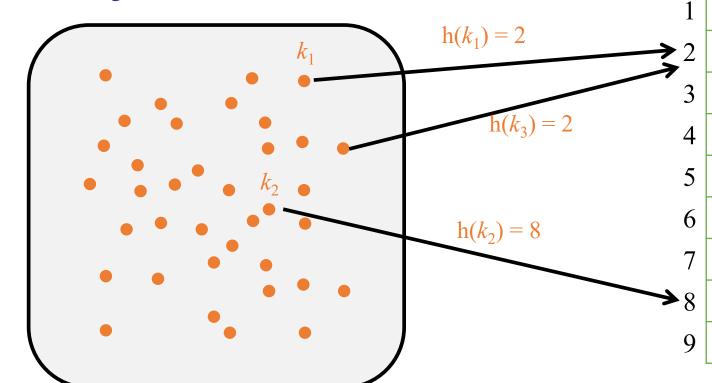
ti")
,")

 $insert(k_1, A)$ 

 $insert(k_2, B)$ 

 $insert(k_3, C)$ 

Collision!





#### Hash Collisions

• We say that two distinct keys  $k_1$  and  $k_2$  collide if:

$$h(k_1) = h(k_2)$$

 ${f \cdot}$  For example, if the function h is the number of characters in an English word then

$$h("pizza") = h("mango") = 5$$

## Can we choose a hash function with no collisions?

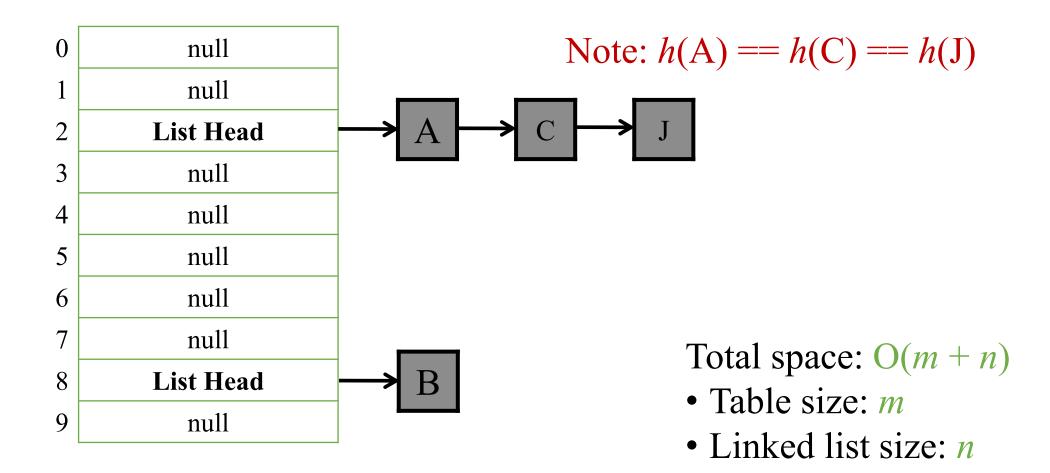
- Unavoidable!
  - The table size is smaller than the universe size.
- The pigeonhole principle says:
  - There must exist two keys that map to the same bucket.
  - Some keys must collide!

## Coping with Collision

- Idea 1: choose a new, better hash functions
  - Hard to find.
  - Requires re-copying the table.
  - Eventually, there will be another collision.
- Idea 2: chaining
  - Put both items in the same bucket!
- Idea 3: open addressing
  - Find another bucket for the new item.

## Chaining

Each bucket contains a linked list of items.



## Hashing with Chaining

#### Insertion

- insert(key, value)
- Calculate h (key)
- Lookup h (key) and add (key, value) to the linked list.

#### search(key)/deletion

- Calculate h (key)
- Search for (key, value) in the linked list.

#### Worst case?

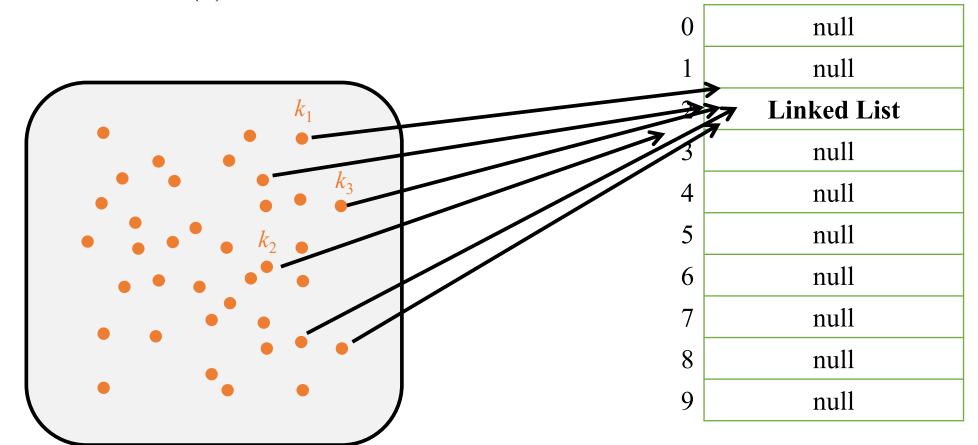
time depends on length of linked list

## Reminds me of this



## Hashing with Chaining

- Assume all keys hash to the same bucket!
  - Search costs O(n)



## Let's be optimistic first....

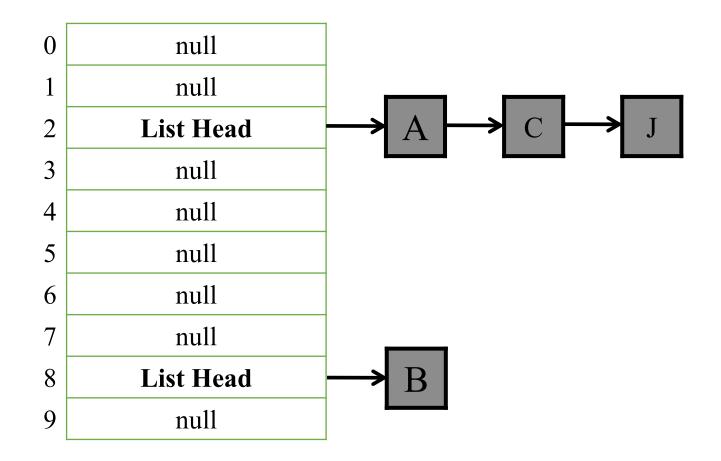
- The Simple Uniform Hashing Assumption
  - Every key is equally likely to map to every bucket.
  - Keys are mapped independently.

#### • Intuition:

- Each key is put in a random bucket.
- Then, as long as there are enough buckets, we won't get too many keys in any one bucket.

## A little probability

• What is the expected number of items in a bucket?



## Let's be optimistic today.

- The Simple Uniform Hashing Assumption
  - Assume:
    - *n* items
    - *m* buckets
  - Define: load(hash table) = n/m

= average # items / buckets.

• Expected search time = 1 + n/m

linked list traversal

- hash function + array access
   If m > n
  - Expected search time = O(1)



## Hashing with Chaining

- Searching:
  - Expected search time = 1 + n/m = O(1)
  - Worst-case search time = O(n)

- •Inserting:
  - Worst-case insertion time = O(1)

## Reality Fights Back

- Simple Uniform Hashing doesn't exist.
- Keys are not random.
  - Lots of regularity.
  - Mysterious patterns.
- Patterns in keys can induce patterns in hash functions unless you are very careful.

## Example

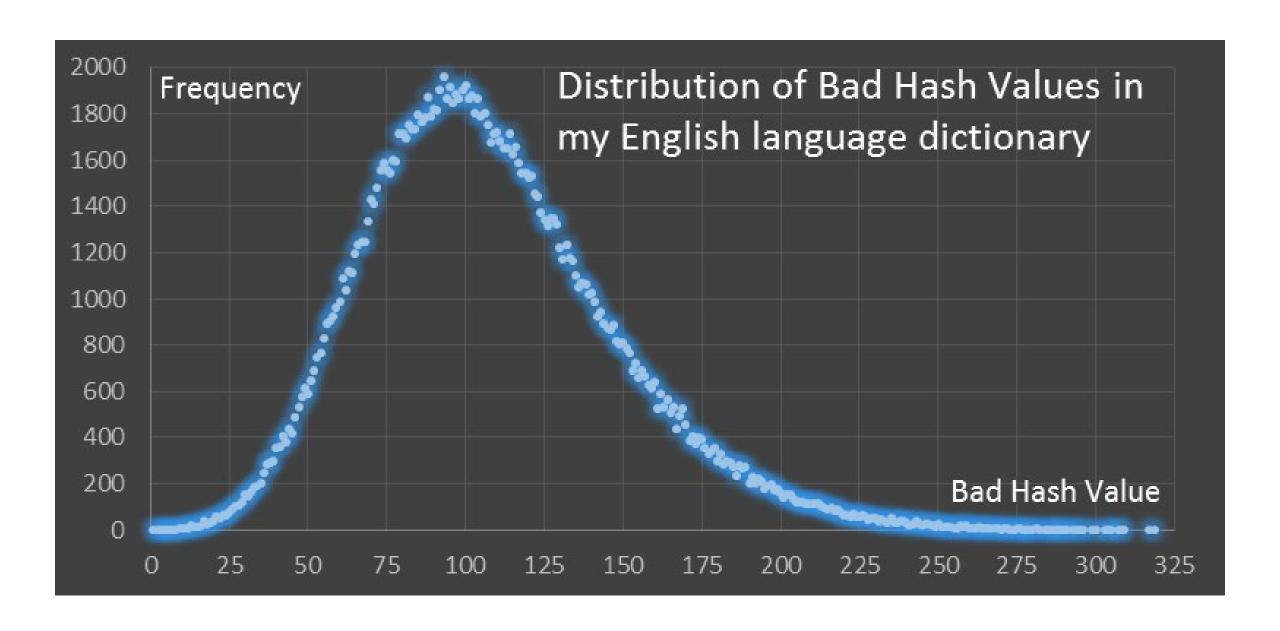
- One bucket for each letter [a..z]
- Hash function: h (string) = first letter.
  - E.g., h ("hippopotamus") = h.

• Bad hash function: many fewer words start with the letter x than start with the letter s.

## Example

- One bucket for each number from [1..26\*28]
- Hash function: h (string) = sum of the letters.
  - E.g., h ("hat") = 8 + 1 + 20 = 29.

• Bad hash function: lots of words collide, and you don't get a uniform distribution (since most words are short).



## Moral of the Story

- Don't design your own hash functions.
  - Ever.
- Unless you really need to.

- But pretty good hash functions do exist...
  - Optimism pays off!

# Designing Hash Functions (If you really have to)

- Two common hashing techniques...
  - Division Method
  - Multiplication Method

#### Division Method

- $h(k) = k \mod m$ 
  - For example: if m = 7, then h(17) = 3
  - For example: if m = 20, then h(100) = 0
  - For example: if m = 20, then h(97) = 17

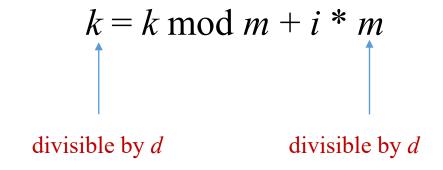
• Two keys  $k_1$  and  $k_2$  collide when:

$$k_1 \mod m = k_2 \mod m$$

• Collision unlikely if keys are random.

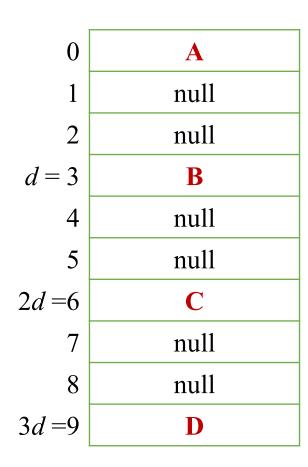
#### Division Method Problem: Regularity

• What if k and m has a common divisor d?



- Implies that  $h(k) = k \mod m$  is divisible by d.
- For all those key values that are divisible by d, by what fraction of the hash table will they utilize?

1/d



#### Division Method

- $h(k) = k \mod m$
- Choose m = prime number
- Division method is popular (and easy), but not always the most effective.
  - Division is slow.

#### Multiplication Method

- Fix table size:  $m = 2^r$ , for some constant r.
- Fix word size: w, size of a key in bits.
- Fix (odd) constant A.

$$h(k) = (Ak) \mod 2^w \gg (w - r)$$

$$h(k) = (Ak) \mod 2^w \gg (w - r)$$
 (A\*k) = 2w bits
• A and k are w bits integers

 $(A*k) \mod 2^w = w \text{ bits}$ 

(A\*k) mod 
$$2^w \gg (w-r) = r$$
 bits

#### Multiplication Method

- Faster than Division Method
  - Multiplication, shifting faster than division

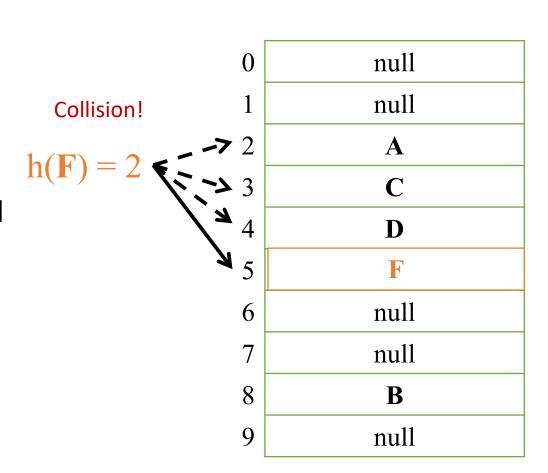
- Works reasonably well when A is an odd integer >  $2^{w-1}$ 
  - Odd: if it is even, then lose at least one bit's worth
  - Big enough: use all the bits in A.

#### Coping with Collision

- Idea 1: choose a new, better hash functions
  - Hard to find.
  - Requires re-copying the table.
  - Eventually, there will be another collision.
- Idea 2: chaining
  - Put both items in the same bucket!
- Idea 3: open addressing
  - Find another bucket for the new item.

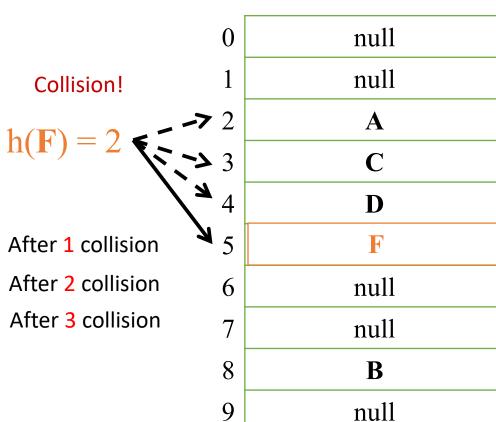
#### Open Addressing

- Advantages:
  - No linked lists!
  - All data directly stored in the table.
  - One item per slot.
- On collision
  - Probe a sequence of buckets until you find an empty one.

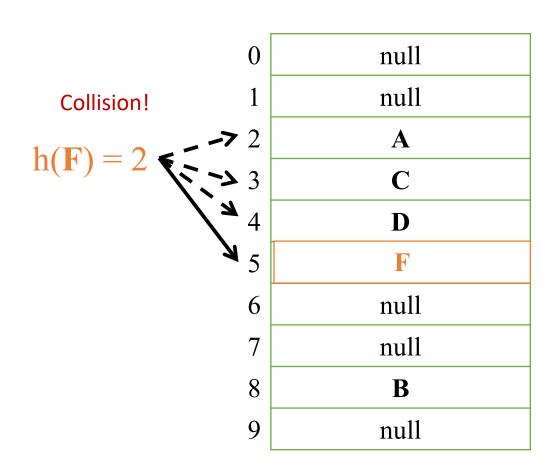


- Find the next position that's empty to insert a key
- If the current slot with index i in the table is occupied, try slot i + 1
- It is the same way to say
  - originally let's try h(F)
  - if it collides, try  $(h(F) + 1) \mod m$  After 1 collision
  - if it collides again, try  $(h(F) + 2) \mod m$  After 2 collision
  - if it collides again, try  $(h(F) + 3) \mod m$  After 3 collision

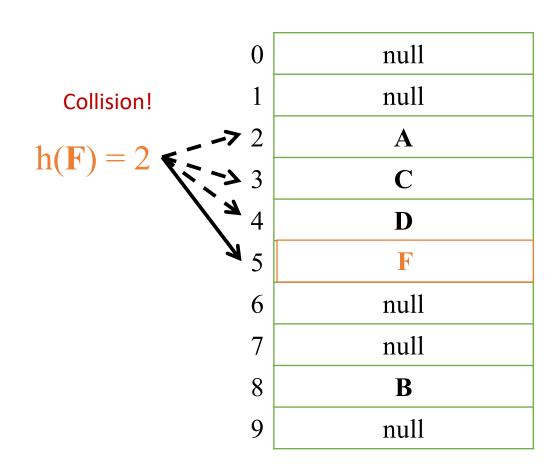
• ...



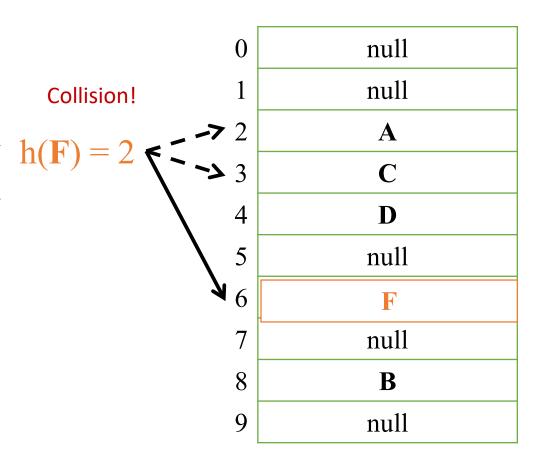
- Find the next position that's empty to insert a key
- If the current slot with index i in the table is occupied, try slot i + 1
- It is the same way to say
  - originally let's try h(F)
  - if it collides, try  $(h(F) + i) \mod m$ 
    - After *i* collisions
- Or if it collides, try  $(h(F) + f(i)) \mod m$ 
  - After *i* collisions
  - for f(i) = i



- Find the next position that's empty to insert a key
- originally let's try h(F)
- if it collides, try  $(h(F) + f(i)) \mod m$ 
  - After *i* collisions
  - for f(i) = i
- We have freedom to change f(i) into other functions
- For f(i) = i, it is called <u>Linear Probing</u>



- For  $f(i) = i^2$ , it is called **Quadratic Probing**
- Originally let's try h(F)
- if it collides, try  $(h(F) + 1^2) \mod m$
- if it collides again, try  $(h(F) + 2^2) \mod m$  h(F) = 2
- if it collides again, try  $(h(F) + 3^2) \mod m$
- •
- After *i* collisions, try  $(h(F) + i^2)$  mod m



#### Some Probing Functions

- Let's redefine the hashing function to be h(key, i) for i is the number of collisions
- Linear probing:

$$h(\text{key},i) = h(\text{key}) + i$$

Quadratic probing

$$h(\text{key},i) = h(\text{key}) + i^2$$

Double hashing (for another hashing function g)

$$h(\text{key}, i) = h(\text{key}) + i \times g(\text{key})$$

#### How do we search now?

```
int i = 0;
while (i \le m) {
                                                              D
                                                               F
     int bucket = h(key, i);
                                                      6
                                                              null
     if (T[bucket] == null) // Empty bucket!
                                                              null
           return key-not-found;
                                                              B
     if (T[bucket].key == key) // Full bucket.
                                                              null
                 return T[bucket].data;
     <u>i++;</u>
```

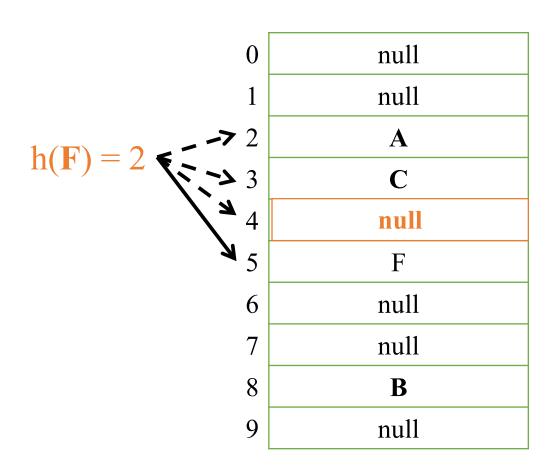
return key-not-found; // Exhausted entire table.

null

null

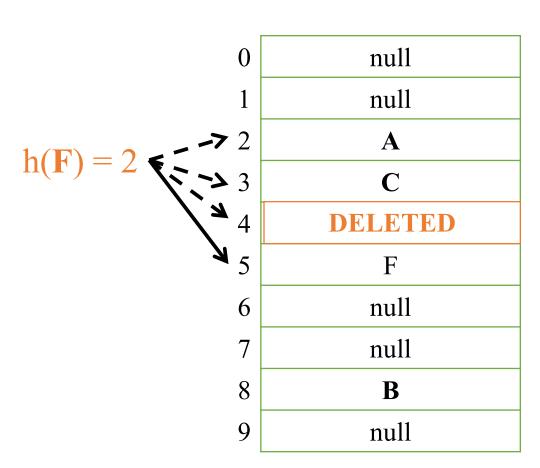
## Open Addressing with Probing

- Now we can
  - Insert
  - Search
- How about deleting an item?
  - Just set the slot to "null"?
  - E.g. delete(D)?
  - Problem?



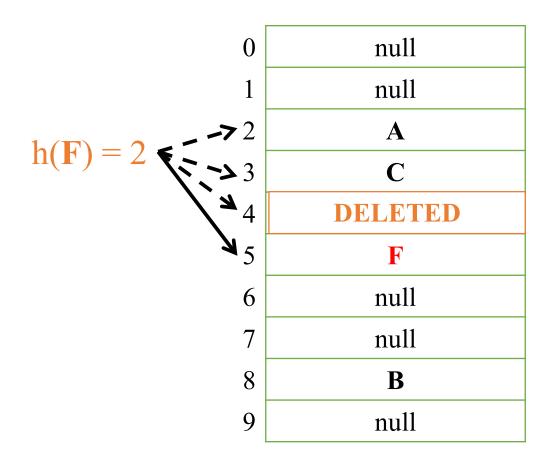
## Open Addressing with Probing

- Deletion:
  - Set the slot to be "DELETED"
- For Searching, we can use the previous algorithm
  - Note that we will stop searching when we met a "null" or we found the key ONLY
- How about insertion now?
  - We can replace an item on the slot of "DELETED"



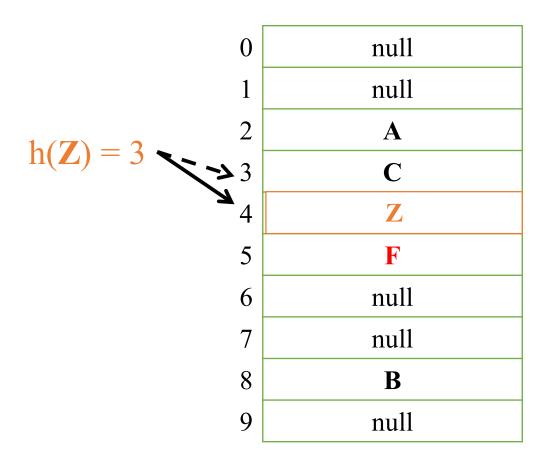
#### Deletion Example

- Assuming h(F,0) = 2
- Delete(D)
- Search for F
  - Same



#### Deletion Example

- Assuming h(F,0) = 2
- Delete(D)
- Search for F
  - Same
- Now insert Z for h(Z) = 3
  - Collided with C
  - Look for h(Z,1) = 4
    - Insert Z into slot 4



## Two Properties of Good Hashing Functions

- 1. h(key, i) must be able to reach all slots
  - For every bucket j, there is some i such that:

$$h(\text{key}, i) = j$$

- For linear probing: true!
- 2. Simple Uniform Hashing Assumption
  - Every key is equally likely to be mapped to every bucket, independently of every other key.
  - An "Art"
  - Could be either with good math or empirical proof

# Performance

#### Performance

• Under uniform hashing assumption, what is the expected time for insertion after we inserted m items into a table of size m?

- a) O(1)
- b) O(log n)
- c) O(n)
- d)  $O(n^2)$
- e) None of the above.

#### • Chaining:

- When m == n, we can still add new items to the hash table.
- We can still search efficiently.

#### Open addressing:

- When m == n, the table is full.
- We cannot insert any more items.
- We cannot search efficiently.

- Define:
  - Load:  $\alpha = n / m$
  - Assume  $\alpha < 1$ .
- Claim:
- For n items, in a table of size m, assuming uniform hashing, the expected cost of an operation is:

$$\leq \frac{1}{1-\alpha}$$

• Example: if ( $\alpha = 90\%$ ), then E[# probes] = 10

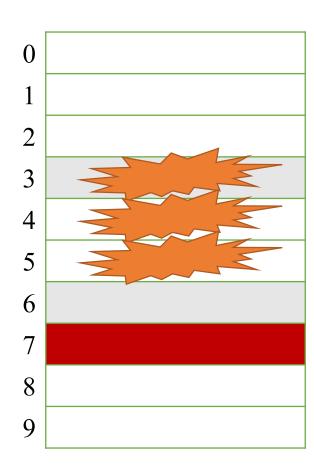
 First probe: probability that first bucket is full is:

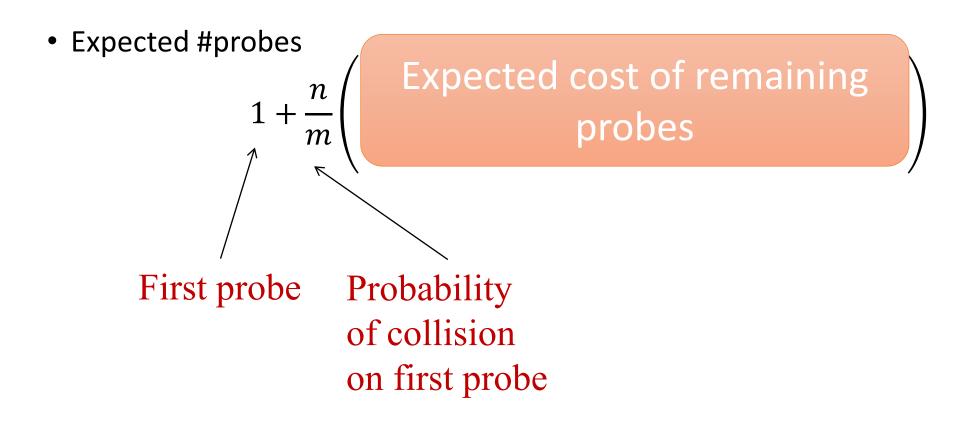
• Second probe: if first bucket is full, then the probability that the second bucket is also full:

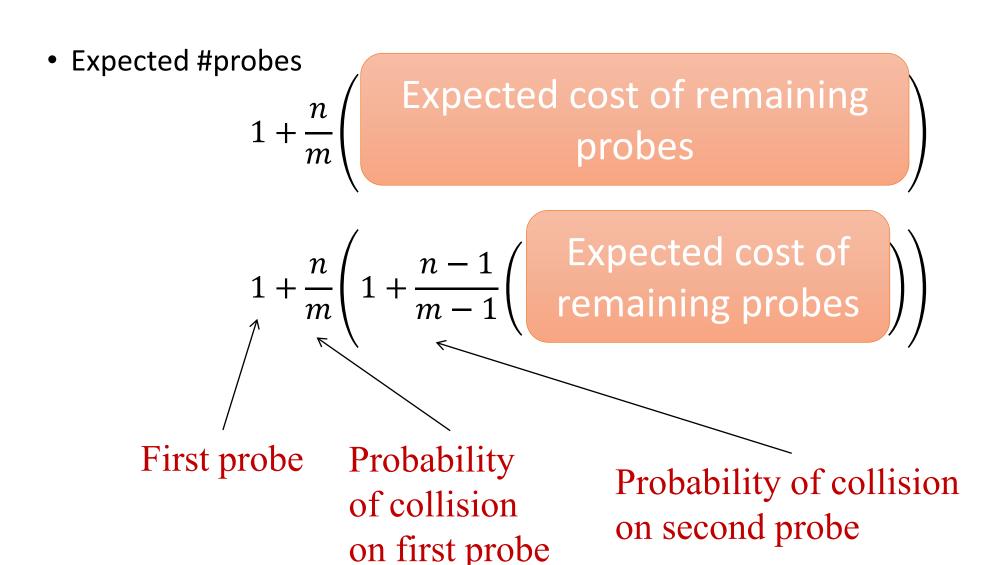
$$(n-1)/(m-1)$$

Third probe: probability is full:

$$(n-2)/(m-2)$$







Expected #probes

$$1 + \frac{n}{m} \left( 1 + \frac{n-1}{m-1} \left( 1 + \frac{n-2}{m-2} \left( 1 + \frac{n-3}{m-3} \right) (\dots) \right) \right)$$

Note that

$$\frac{n-i}{m-i} \le \frac{n}{m} \le \alpha$$

Expected #probes

$$1 + \frac{n}{m} \left( 1 + \frac{n-1}{m-1} \left( 1 + \frac{n-2}{m-2} \left( 1 + \frac{n-3}{m-3} \right) (\dots) \right) \right)$$

$$\leq 1 + \alpha \left(1 + \alpha \left(1 + \alpha \left(1 + \alpha\right) \left(\dots\right)\right)\right)$$

$$\leq 1 + \alpha + \alpha^2 + \alpha^3 + \alpha^4 + \cdots$$

$$\leq \frac{1}{1-\alpha}$$

- Define:
  - Load:  $\alpha = n / m$
  - Assume  $\alpha < 1$ .
- Claim:
- For n items, in a table of size m, assuming uniform hashing, the expected cost of an operation is:

$$\leq \frac{1}{1-\alpha}$$

• Example: if ( $\alpha = 90\%$ ), then E[# probes] = 10

#### Open Addressing Advantages

- Saves space
  - Empty slots vs. linked lists.
- Rarely allocate memory
  - No new list-node allocations.
- Better cache performance
  - Table all in one place in memory
  - Fewer accesses to bring table into cache.
  - Linked lists can wander all over the memory.

#### Open Addressing Disadvantages

- More sensitive to choice of hash functions.
  - Clustering is a common problem.
  - See issues with linear probing.
- More sensitive to load.
  - Performance degrades badly as  $\alpha \rightarrow 1$ .

