# James Wade

note2jwade@gmail.com | 817.888.2906 | http://www.linkedin.com/in/james-k-wade | Project Portfolio: https://tinyurl.com/5fwp549h

#### **OBJECTIVE**

Passionate 4<sup>th</sup>-year 4.0 GPA mechanical engineering major, with minors in computer science and mathematics, seeking a Summer 2025 internship in aerospace, defense, mechatronic systems, or computational analysis.

#### **EDUCATION**

#### BACHELOR OF MECHANICAL ENGINEERING, COMPUTER SCIENCE & MATH MINORS

April 2026

Brigham Young University – Ira A. Fulton College of Engineering, 4<sup>th</sup> year

**GPA**: 4.0 | **ACT**: 35 (99<sup>th</sup> percentile) | **SAT**: 1550 (99<sup>th</sup> percentile)

Awards & Honors: Highest-ranked student in engineering program; one of six national finalists in NASA

BIG Idea competition; President Russell M. Nelson Scholar (highest scholarship at BYU)

Technical Groups: Mars Rover Team, Rocketry club, Spacecraft club, Mechatronics club, Global Engineering Outreach

#### **WORK EXPERIENCE**

#### EMBEDDED SYSTEMS INTERN

May 2024 – present

# Lawrence Livermore National Laboratory (LLNL) - Livermore, CA

- Successfully prototyped an STM32 MCU-based remote control system to command a fleet of rafts designed for testing nuclear weapon functionality (<u>LIDSS program</u>)
- Utilized FreeRTOS for dynamic task management, and developed driver for LVGL-based UI
- Solely responsible for the mechanical, electrical, and software development of the entire project

# ROBOTICS RESEARCH ASSISTANT – Team Lead (One of Six National Finalists) Brigham Young University – Provo, UT

Aug 2023 – present

- Developing a redesign for a soft, inflatable octahedral robot for space application in NASA BIG Idea competition
- Developed a new radio structure for single parent-multiple children communication with error-checking
- Simulating the motion of the octahedral truss structure through inverse kinematics

#### MECHANICAL ENGINEER INTERN

*Mar* 2023 – Oct 2023

#### Ultradent Products, Inc. - South Jordan, UT

- Prototyped a medical syringe machine to assemble, fill, and cap a syringe in seven seconds
- Designed sheet metal shrouds for retaining chemicals and an offload system to reject deficient syringes
- Led Scrumban-style daily and monthly goal-setting meetings, and gave presentations to investors

# COMPLIANT MECHANISMS RESEARCH ASSISTANT

Jun 2023 – Aug 2023

### Mark Rober / Brigham Young University - Provo, UT

- Worked with Mark Rober and a team to create The World's Smallest Nerf Gun on five scales (>55 million views)
- Performed 100+ tests to analyze failure modes of the device and provided weekly reports to optimize the design

#### **OTHER PROJECTS**

#### Awarded top five finisher in line-following mechatronics competition

- Led the coding development in C, implementing closed-loop PID for navigation and sensors for task execution Serving as Payload Engineer for the BYU Rocketry Experimental High Power Competition Team
- Designing a water ballast for both our first-ever team competition and the first hybrid motor rocket at BYU **Created a custom 3D printer (individual project)**
- Fully upgraded an Ender 3; now designing a core-xy 3D printer, showcasing precision and engineering ingenuity **Built and modeled the behavior of a homemade DC motor (team lead)** 
  - Using Matlab, the dynamic behavior was measured and predicted for our custom-designed DC motor

#### Various individual coding projects in C/C++, Python, Matlab, and Java

#### RELEVANT COURSEWORK & SKILLS

**Relevant Coursework:** ROS2, Control Theory (PID, Full-State, Observers, MPC, LQR), Mechatronics, Deep Learning, SolidWorks, Ansys FEA, Kinematics, Dynamic System Modeling, Thermodynamics, Mechanical System Design, Electrical Circuit Design

Design: GD&T, Arduino, ESP32, STM32, Eagle, 3D Printing

Computer: C/C++ (advanced), Matlab (advanced), Python (advanced), Excel (intermediate), Java (intermediate), Git

**Certifications:** SolidWorks Professional Design, SolidWorks Sheet Metal

Leadership: Time Management, Adaptability, Conflict Resolution, Collaboration