

To What Degree can an AI Built With Expert Strategies be Effective Against Competition AI?

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Abstract—Effective macro-management (the ability to create armies and expand bases), is essential to obtaining victory in Real-Time Strategy (RTS), in the research community many Artificial Intelligence's (AI's) have been created to handle this. One method is to use a design approach to create what is known as a build order, many of these build orders take from expert strategies used by real people in high ranking tournaments. Build orders can be ridged during games leaving little room for adaptation to the opponents strategy. In this work a collection of build orders will be used to create an AI capable of interchanging these build orders to effectively counter several strategies. An assumption is made here that the AI will only be effective in the early stages of the game and will be outmanoeuvred in late-game stages. The effectiveness of this AI will be measured its time survived, and winning state. Upon successful completion of this work the AI will be submitted to one of three competitions.

I. INTRODUCTION

ARTIFICIAL Intelligence can be defined as anything that gives the illusion of intelligence to an appropriate level [1]. In games, AI has been used in both single and multi-player environments to help create a more immersive, challenging and fun experience. One such area which AI is prominent is in the Real-Time Strategy (RTS) genre and since the call for more research to be made for AI in RTS games by Michael Buro in 2004 [2], research in this area has exploded, with hundreds of papers being written [3]. This has given rise to the creation of many AI's in RTS games, from AI's that are built with pre-defined build orders [4] to deep Neural Networks [5] that can learn from game-play replays, which will be covered in more detail later on in the paper.

RTS is a great test bed in AI research for its complex systems, involving many areas of interest in planning, dealing with uncertainty, domain knowledge exploitation, task decomposition, spatial reasoning, and machine learning [6]. Unlike turn based strategy, RTS requires real-time decision making with imperfect information, the information is limited through the use of fog of war. Unless the AI scouts the map and sees what the opponent is doing, then the AI will have no access to any strategic knowledge. This along with the non-deterministic nature of RTS, meaning it may not exhibit the same behaviour on each run, makes RTS one of the most challenging environments in which to create an AI [7].

Since the release of StarCraft Brood War API it has been easier for Academics to research AI in StarCraft, this has also given rise to an educational value as part of AI related subjects. From this three yearly competitions have been created to

compete students AI's, the first of which was hosted by the University of California, Santa Cruz in 2010 as part of the AAAI Artificial Intelligence and Interactive Digital Entertainment (AIIDE) conference program [8]. Another hosted at the IEEE Computational Intelligence in Games (CIG) conference [9], and the last one which is an ongoing stand-alone event is the Student StarCraft AI Tournament (SSCAIT) [6]. Upon successful completion of this work the AI will be submitted to one of these three competitions.

This paper is organised as follows, first StarCraft and what it is will be presented, followed by a review on the current methods being utilised by the research community in the development of StarCraft AI's. With a description on the research that this work will be using, this is proceeded by the method and tools that will be used to create the AI as well the metrics used to measure its effectiveness finishing with the hypothesis.

II. STARCRAFT

StarCraft the most popular RTS game of all time [7] is an RTS game developed by Blizzard Entertainment [10][11], and released in 1998. Later that year StarCraft: Brood War was released and took hold in the e-sports community and is still popular today. StarCraft 2: Wings of Liberty was released much later in 2010, with most of the game mechanics the same other than balance changes, and the user interface (UI) were kept the same just with a visual overhaul. The premise of StarCraft is to gather resources, build a base, and build an army to then use to destroy an enemies base and army, during playtime there are also many upgrades available for these units to give them the edge over an enemy who did not spend the time acquiring them. There are many ways of doing this each player with a different order of building their armies/bases commonly referred to as their "Build Order" [12]. Build orders refer to a players macro-management, whereas in StarCraft Micro-management is a huge part of the game, as those with greater control over individual units can better outmanoeuvre their opponent, and thus defeat them.

III. RELATED WORK

In RTS, strategy selection is perhaps the most important choice any player or AI can make, as this will dictate the actions and reactions which they take during playtime. Though a human player can be proficient at choosing their strategy

by simply scouting the map, finding the enemy and seeing what they are building. The human player can then counter accordingly, and if they countered incorrectly the human player can simply change their strategy to accommodate. Creating an AI to do the same though can be a huge and complex task [13][14][15], one way to achieve this result without a huge effort is to create a library of expert strategies, and allow the AI to select the appropriate one throughout the game. This can be achieved using tools such as Advanced Behaviour Oriented Design Environment (ABODE) and Parallel-rooted Ordered Slip-stack Hierarchical (POSH) reactive plans [16], which will also be covered later in the paper. These tools allow for an iterative design approach for AI's in games and in this work will be focusing on the macro-management with a particular focus on build orders and the selection of strategies rather than micro-management.

In the StarCraft research community there are many different methods of AI creation. Some focus on micro-management like S. Liu et al [17] that uses a Genetic Algorithm (GA) and others that focus on macro-management looking at the build order like N. Justesen et al [14]. Many of these research methods are cross depended and utilise more than one method for example, D. Churchill et al [18] created the UAlbertaBot, which was intended to automate both build order planning and unit control. There are also AI's that only use one strategy that has won several times in competitions like the ZZZKBot [19][20], which only uses a 3pool build and built that uses a rush tactic. This rush tactic involves creating many weak inexpensive units and sending them to the enemy base within 5 minutes of starting the game. And many AI's struggle to counter this strategy, hence why this type of AI tends to win.

A. Datasets

A Dataset can be a collection of any data, for game AI a dataset can consist of thousands of replays with millions of game frames, and player actions[21]. This information can then put together to create a full game-state which allows for machine learning tasks [22]. In AI research, datasets can be used in many approaches of development, one such use is to recreate game-states and evaluate them for prediction in realistic conditions [23].

B. Bayesian Approaches

Bayesian approaches are based on Bayes' Theorem, a calculation of probability or also known as a probabilistic model [24]. In papers by G. Synnaeve et al [25][23] they create an AI that controls units individually, they do this by using uncertainty which instead of asking where a unit might be, it makes rough estimations and acts upon that. Another use for the Bayesian approach is to predict strategies, by creating a probabilistic model that after learning from replays can predict an opponents strategy and adapt accordingly [26]. A major downfall of Bayesian Approaches is that it can be computationally intense to calculate.

C. Micro-Management

Micro management is a fundamental side of StarCraft game-play and many papers have their own approach to this aspect of RTS [27][17][28][29][23][25]. Many of these approaches use either Genetic Algorithms (GA) or Evolutionary Algorithms (EA) [27][17][28], while others observe replays and apply a Monte-Carlo method to create data for practice use [29]. But most of these methods have one thing in common, they all use a version of machine learning [3].

D. Prediction

On a higher strategic level the prediction of the opponents strategy is a prominent approach used in research [30][26][31][32]. This type of research relies on the use of replays and machine learning to help the AI accurately predict a strategy, these do rely on the quantity and quality of replays used for the learning process[30][26][32]. Another method for prediction is scouting alongside machine learning, this eliminates the need for replay observation and allows for a more real-time prediction [31]. Though this method does still require several games to be played before the AI can begin to have an accurate prediction.

E. Full Game Play

Many papers try to create an AI capable of handling all aspects of an RTS [18][33][34][35]. These AI's tend to take several methods that have been created in other research and combining them to form a new AI [18]. Another use for the full game play AI is to try and create a "Human-Like" AI, which can mimic the play-style of an expert human player though the current AI's are limited in this as players reported that the AI's used unusual unit movements or building placement [36].

F. Neural Networks

Neural Networking are computational models loosely based on the functioning of biological brains [5]. Given an input it computes an output by using a large number of neural units, in StarCraft it can be used to predict strategies or in the case of StarCraft 2 with its new architecture it can be used for full game-play. Using a neural network would be impractical for the purpose of this work as it would take many months to train, and even then would not have a great chance of doing well against other AI's.

G. Planning

Planning in StarCraft usually deals with the build order that the AI will use usually only dealing with macro-management. There are several different ways to use a build order, some will use a static build order that will not change throughout the game [4], and the more popular route is to allow the AI to jump between build orders during play-time, another term is Reactive Planning [13][14][15]. there has been some work on creating the build orders on the fly by finding out that most optimal method of gathering resource and building units [12].

Planning is perhaps the most optimal approach to creating an AI as there is little real-time calculations to make. Through the use of POSH tools [16], you can iteratively design AI prototypes and deploy quickly [4].

From looking at the research in the field there are many methods that can be used to create an AI. The use of replays to train an AI to counter strategies can be effective [26], they lack the greater control of the game, the ability to macro-management as there are too many variables to consider. This lack of large scale control is usually due to the heavy computational requirements of controlling each individual component of the game. Due to this slow process, it is quite impractical to use when there is already a library of knowledge that can be to exploited [37]. Though there are AI's out there with planned strategies already programmed into them [19][13], their limitation is that they only use a small number of strategies, though these work it can leave a lot of room for the opponent to manoeuvre. A logical step here is to program a larger pool of expert knowledge into the AI, it will then select one and follow it through, with the ability to jump between strategies at key points in-case a counter is detected.

H. StarCraft AI's

In the StarCraft AI community there are many AI's that have been created to compete against each other, and in this work a competition AI is defined as an AI that has been entered to the AI for Interactive Digital Entertainment conference (AAIDE) StarCraft AI Competition. A yearly competition hosted by David Churchill and sponsored by AIIDE. AI's of this grade include:

- ZZZKBot Winner of the 2017 AIIDE StarCraft AI Competition [19]
- Iron Winner of the 2016 AIIDE StarCraft AI Competition [38]
- UAlbertaBot Winner of the 2013/2011 AIIDE StarCraft AI Competition [39]
- Skynet Winner of the 2012 AIIDE StarCraft AI Competition [40]

These AI's use several strategies along with different factions, and were chosen as they have all previously won the AIIDE StarCraft AI competition [20].

IV. METHOD

This work will be focusing on the implementation of an AI with pre-built build orders and their counters taken from Liquipedia [37], a website dedicated to StarCraft, on there they have a collection of strategies that are free to use in any capacity. Building upon these build orders the experiment will also include a method for swapping between the orders at any point, to know when to do this, the AI will scout the map in search of the opponent and compare their current building to its stored build orders and find an appropriate counter. The issue with this method is that in late game the AI will struggle to decide which build order to continue.

A. Tools

There are several tools that will be using in this experiment, these include The Brood War Application Programming Interface (BWAPI), POSH tools, specifically POSH Sharp which is an interface that uses c# instead of C++, and the ABODE editing software which uses POSH plans to create Behaviour Oriented Design's for AI's.



Fig. 1: POSH plan for the Three Hatch Hydra build plan inside the ABODE editor.

- **Brood War Application Programming Interface** [41] is a open source software that creates an interface for a custom AI to use to communicate with the game. BWAPI deliberately does not give access to all the games information [16], limiting the AI to only be able to have information on the enemy if there is no Fog-of-War currently covering them, as well as the size of the map and base locations. This prevents custom AI's from cheating and ensures a fair game, though this could be considered a plus as it means that the developers of these AI's do not need to worry about using information that could cause their AI to cheat. Though this does mean that all the AI's must work in an imperfect environment which forces the AI to have to scout for information.
- **POSH** plans can be created in the ABODE Environment as seen in Figure 1, these are a visual planning tool that allows for hierarchy of actions with associated triggers. Each plan can be split into three parts, Drive-Collections, Competences and Action patterns, these three determine when an action is to be triggered. POSH plans use a behaviour library created in the native language of the problem space, see Fig 2.

B. Process

The first thing that will be chosen in the creation of this AI is to pick a faction, in StarCraft there are three, Zerg, Protoss and Terran, each with their own unique play style. Zerg is a rushing faction, with their units being relatively weak and cheap usually focus on overwhelming their enemy with numbers. Protoss are strong but expensive, relying on smaller numbers and taking longer to produce anything means they can be weak at rushing and defending from a rush. Terran are a balance of the two, being able to produce strong and expensive

units as well as cheap weak ones, they can effectively rush and defend from a rush.

In this work Protoss will be chosen, so the second logical step is to implement an anti rush strategy as an opening strategy. From there more aggressive strategies will be implemented and executed at the appropriate times. The challenge here is that it is difficult for Protoss to counter a Zerg rush but if successful it will leave the Zerg open for attack.

At each implementation a test will be made on the AI to show its effectiveness and influence the next iteration of strategy implementation. These tests will consist of 10 games against the in game AI until it has an relatively high win rate, at which point it will be tested against one fo the competition AI's.

C. Metrics

In this work the StarCraft AI will be measured on its success using two factors:

Time Survived
End game Condition

Through these factors the effectiveness of the AI will be determined, as the average time of a StarCraft game can last between 10-20 minutes if the AI survives pas the upper limit of this time or wins the game it will support a greater effectiveness. Though if the AI does not survive past the lower limit of that time or looses it will negate the effectiveness. To begin with the AI will be pitted against the inbuilt AI as a test-bed, if it should have a high effectiveness it will then be put against an open source competition grade AI, and measured from there.

D. Hypothesis

- **Null Hypothesis** The AI will not be at all effective even when faced against the in built StarCraft AI even with the use of expert strategies.
- **Hypothesis 1** The AI will be effective in its abilities to survive and defeat the in built AI but not the competition AI.
- **Hypothesis 2** The AI will be effective in its abilities to survive and defeat the in built AI as well as the competition AI, as long as the Rush tactic can be countered.

```

1 [ExecutableAction("SelectExtractorLocation")]
2 public bool SelectExtractorLocation()
3 {
4     // enough resources available?
5     if (!CanMorphUnit(bwapi.
6         UnitTypes_Zerg_Extractor) || !Interface
7         ().baseLocations.ContainsKey((int)
8         Interface().currentBuildSite))
9         return false;
10
11     TilePosition buildPosition = Interface().
12         baseLocations[(int)Interface().
13         currentBuildSite];
14
15     // are there any geysers available/visible?
16     IEnumerable<Unit> geysers = Interface()
17         .GetGeysers().Where(geyser => geyser.
18         getResources() > 0);
19
20     if (geysers.Count() < 1)
21         return false;
22
23
24
25
26
27
28
29
30
31

```

```

15 // sort by closest path for ground units
16 // from selected build base
17 TilePosition closest = geysers
18     .OrderBy(geyser => geyser.getDistance(
19         new Position(buildPosition)))
20     .First().getTilePosition();
21
22 // if there is a close geysers we are done
23 if (closest is TilePosition)
24 {
25     this.buildLocation = closest;
26     builder = Interface().GetBuilder(
27         buildPosition);
28     //move(new Position(closest), builder);
29     // if (builder.getDistance(new Position(
30         closest)) < DELTADISTANCE)
31     // return true;
32     return true;
33 }
34
35 return false;
36 }

```

Fig. 2: c# behaviour code snippet for selecting an extractor location for the Zerg, these behaviours are referred to by the POSH plan which determines when they are executed.

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