# **Heuristic Analysis**

COMP140 - Heuristic Analysis

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### 1 The Controller

The controller is based on the Nintendo nunchuck, this was chosen for marketable reasons. As there seems to ba a lack of PC controllers for use in one hand, it seemed appropriate to use this controller as a baseline. The idea for the controller was to create a one-handed device that could be used in conjunction with a game while being able to free up the other hand. The controller was build using and Arduino UNO and a MakeyMakey kit. As the Arduino UNO does not support HID, the MakeyMakey was used as a bridge between the PC and the Arduino. Two buttons and a joystick were applied to the controller.

# 2 Analysis

The controller was build for functionality over creativity, to that end everything worked as planned. Both buttons responded to being pressed and with some tinkering the joystick recognized both the X,Y axis. The LED light that was present ensured that the user would know that a button press was being recognized. As this was done through

the means of software and not hard-wired into the controller the responsiveness of the buttons was clearly seen.

#### 2.1 Aesthetics

From an aesthetic view, the controller its self was minimalistic, although the circuit boards attached to it made for an unpleasant addition. This was due to the two board having to be connected for the PC to recognize the controller as a HID. A suggestion for improvement here would be to minimise the need for the two circuit board. To do this an Arduino Micro would have been proficient, this Arduino has a built in HID driver and would have removed the need for any wires to be present outside of the controller. This also would have allowed the removal of the large box and improved usability and aesthetics.

## 2.2 Flexibility and Efficiency

The controller was efficient in what it was planned to do, as stated at the beginning, comfortable to hold and responsive. To use, the controller was straining on the hands as the two buttons were placed at the back. Although the lack of extra buttons limited its usability, a suggested improvement would be to increase this number. Also to improve the ergonomics of the controller would be an improvement for flexibility. This would be achieved by altering the position of the buttons at the back.