

# SC201 Lecture 2

## Define Model ( $h(\theta) = \theta x$ )

$$h(\theta) = \underline{\hspace{2cm}}$$


### Define Loss Function (L2 Loss)

loss = \_\_\_\_\_



## Define Cost Function J

J = \_\_\_\_\_



## Find the best parameter ( $\theta$ )

```
for i in range(iteration):
```

$$\theta = \theta - \alpha \frac{dJ}{d\theta}$$

$$\frac{dJ}{d\theta} = \frac{d}{d\theta} \left( \frac{\sum_{i=1}^m (\theta x_i - y_i)^2}{2m} \right)$$

$$\frac{dJ}{d\theta} = \frac{d}{d\theta} \left( \frac{\sum_{i=1}^m (y_i - \theta x_i)^2}{2m} \right)$$

**Fine the best parameter ( $\theta$ )**

→ Training

① Initialization

② if  $\frac{dJ(\theta)}{d\theta} > 0, \theta \downarrow$

elif  $\frac{dJ(\theta)}{d\theta} < 0, \theta \uparrow$

elif  $\frac{dJ(\theta)}{d\theta} == 0, \theta \text{ best}$

③ Gradient Descent

$$\theta = \theta - \alpha \frac{dJ}{d\theta}$$

④ Iteration

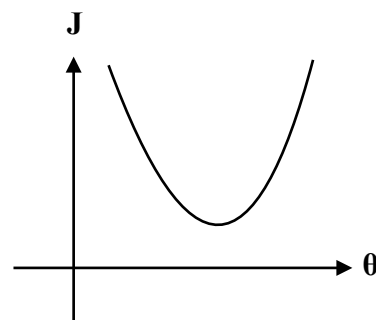
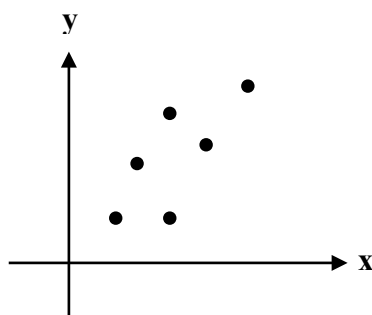
① <Step size (Learning Rate)  $\alpha$ >

usually \_\_\_\_\_

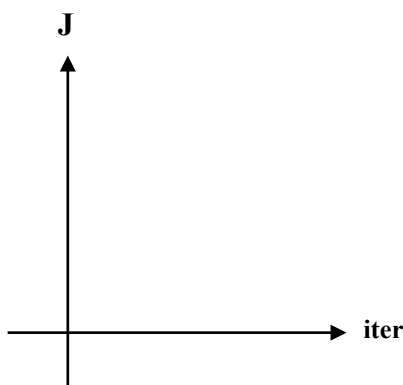
② <Iteration>

for i in range(iteration):

$$\theta = \theta - \alpha \frac{dJ}{d\theta}$$

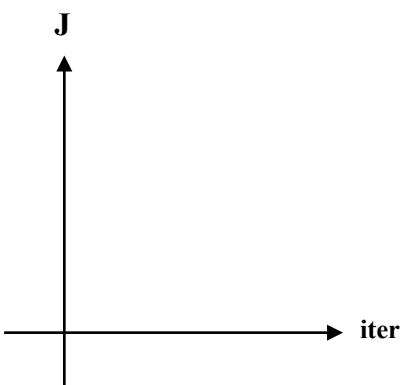


③ <Cost v.s. Iteration Plateau>



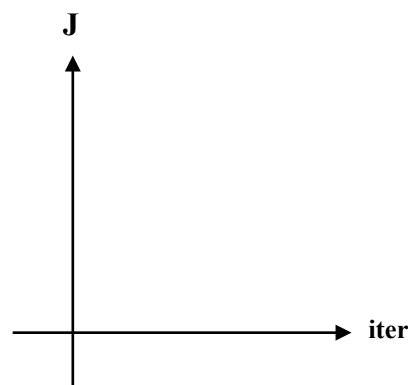
iter \_\_\_\_\_

$\alpha$  \_\_\_\_\_



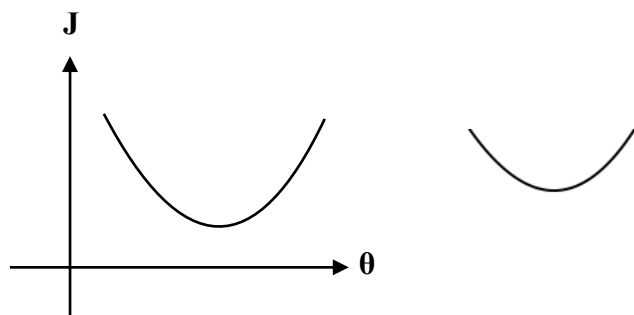
iter \_\_\_\_\_

$\alpha$  \_\_\_\_\_



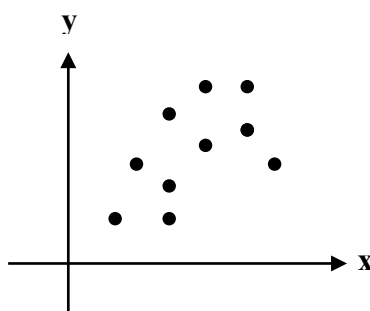
$\alpha$  \_\_\_\_\_

如果for i in range (100) 會超過最小值嗎？



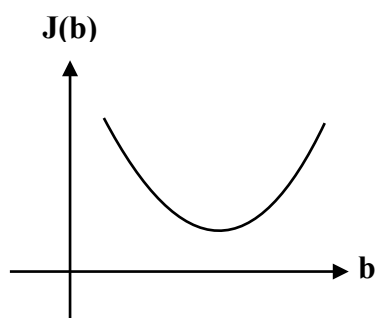
如果Model不一定過(0,0)?

new\_model  $\Rightarrow$  \_\_\_\_\_



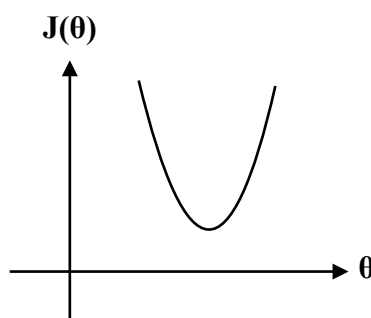
\_\_\_\_\_也是\_\_\_\_\_的函數！

< When  $\theta$  is fixed >



$b =$  \_\_\_\_\_

< When  $b$  is fixed >



$\theta =$  \_\_\_\_\_

<  $dJ_{db}$  >

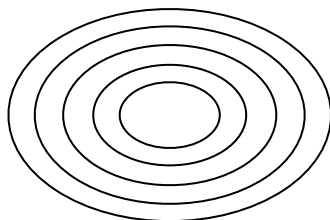
<  $dJ_{d\theta}$  >

## Non-Steepest Descent

for i in range(iter):

$\theta =$  \_\_\_\_\_

$b =$  \_\_\_\_\_



- \_\_\_\_\_ update
- \_\_\_\_\_ to converge

## Steepest Descent

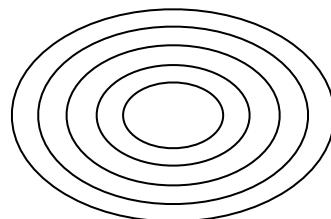
for i in range(iter):

$\theta\_temp =$  \_\_\_\_\_

$b\_temp =$  \_\_\_\_\_

$\theta =$  \_\_\_\_\_

$b =$  \_\_\_\_\_



- \_\_\_\_\_ update
- \_\_\_\_\_ to converge

## Polynomial Features

- raising existing features to an exponent

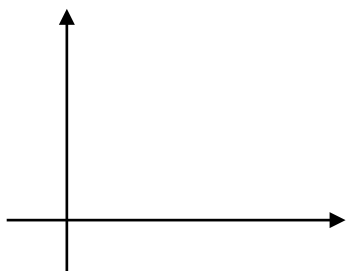
<degree1>

**linear function**

$$h(\theta, b) = \theta x + b$$



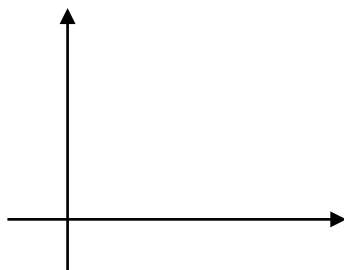
(Model we chose)



<degree2>

**quadratic function**

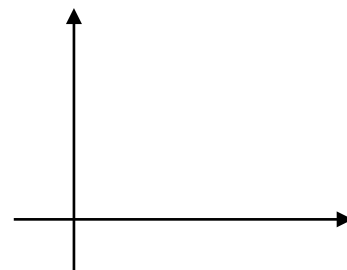
$$h(\theta', \theta, b) = \theta' x^2 + \theta x + b$$



<degree3>

**cubic function**

$$h(\theta'', \theta', \theta, b) = \theta'' x^3 + \theta' x^2 + \theta x + b$$



$$J = \frac{1}{2m} \sum_{i=1}^m (\theta' x_i^2 + \theta x_i + b - y_i)^2$$

<dJ\_dθ'>

<dJ\_dθ>

<dJ\_db>

**Normalization**

X' = \_\_\_\_\_