

Improved Efficiency and Accuracy of the Magnetic Polarizability Tensor Spectral Signature Object Characterisation for Metal Detection

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Abstract

Keywords:

1. Introduction

1.1. Model Problem

$$\begin{aligned}\nabla \times \nabla \times \mathbf{E} - k^2 \mathbf{E} &= \mathbf{0} && \text{in } \Omega \\ \mathbf{n} \times \mathbf{E} &= \mathbf{n} \times \mathbf{E}^{(exact)} && \text{on } \Gamma = \partial\Omega\end{aligned}\tag{1}$$

with $\mathbf{E}^{(exact)} = e^{i\mathbf{k}\cdot\mathbf{x}}$ being the known solution for the electric field at position \mathbf{x} for perpendicular wavenumber $\mathbf{k} = [k_x, k_y, k_z]$. For the standard $\mathbf{H}(\text{curl})$ conforming finite element space [1] the weak form of this problem is: Find $\mathbf{u} \in \mathbf{H}_D(\text{curl})$ such that

$$\int_{\Omega} \tag{2}$$

2. Software

NGSolve (version 6.2.2302) and Netgen (version 6.2.2302) [3, 4, 2],

3. Conversion to Scipy Iterative Solvers

The iterative solvers available in NGSolve, notably CGSolver and GMRESSolver do not allow for the execution of arbitrary callback functions in the same way as many other solvers from other established python libraries. For this reason, it is difficult to retain the residual at each iteration of the NGSolve solvers. Furthermore, the GMRESSolver does not appear to have a restart option available to the API and is in general poorly documented. For this reason, the solving of the linear system used in static condensation is instead implemented using SciPy (version 1.10.1) and NumPy (version 1.24.2).

The following two code snippets are equivalent.

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```

1 # For assembled linear form f and bilinear form a for solution vector u.
2 r = f.vec.CreateVector()
3 r.data = f.vec - a.mat * u.vec
4 r.data += a.harmonic_extension_trans * r
5
6 # CGSolver(.) * r is equivalent to solving preconditioned Ax=r
7 u.vec.data += CGSolver(A.mat, P.mat, precision=1e-10) * r
8 u.vec.data += a.harmonic_extension * u.vec
9 u.vec.data += a.inner_solve * r

```

Listing 1: Static condensation using NGSolve

```

1 # For assembled linear form f and bilinear form a for solution vector u.
2 r = f.vec.CreateVector()
3 r.data = f.vec - a.mat * u.vec
4 r.data += a.harmonic_extension_trans * r
5
6 # The projector is used to remove non-local and non-Dirichlet degrees of freedom that
7   # should not participate in the solve
8 q = r.CreateVector()
9 pre = Projector(mask=fes.FreeDofs(coupling=True), range=True)
10
11 tmp1 = F.vec.CreateVector()
12 tmp2 = F.vec.CreateVector()
13
14 # A linear operator that returns Av for the sparse matrix A
15 def matvec(v):
16     tmp1.FV().NumPy()[:] = v
17     tmp2.data = A.mat * tmp1
18     tmp2.data = pre * tmp2
19     return tmp2.FV().NumPy()
20
21 r.data = pre * res
22 A_linop = sp.sparse.linalg.LinearOperator((A.mat.height, A.mat.width), matvec)
23
24 # Solve Ax = r
25 q.FV().NumPy()[:], OutputStatus = sp.sparse.linalg.gmres(A_linop, r.FV().NumPy(), tol=1e
26     -10, M=P.mat)
27 u.vec.data += q
28 u.vec.data += a.harmonic_extension * u.vec
29 u.vec.data += a.inner_solve * r

```

Listing 2: Static condensation using SciPy

4. GMRES Convergence

4.1. Choice of Preconditioner

5. Numerical Results

5.1. Non-Magnetic Sphere

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