Lab 3 Jineidy Mak Secton 7F31

Pre-Lab Questions:

1. What is the advantage of mirroring the input and output ports to \$8000 - \$BFFF (also known as partial address decoding)? What would be necessary if you wanted to only place the ports at 0x8000 and no place else?

The CS0 would need the equation for that particular address space, It would require 16 inputs for one chip select. The advantage is that by mirroring the address we only need A15 and A14 as opposed to A15:0.

2. What is the complete range of external memory on the XMEGA?

16 mb of external memory according to chapter 4.

3. Write the address decode equation to put the input and output ports at addresses 0x4000 – 0xCFFF.

CE = /A15A14 or A15A14

4. The uPAD Proto Base is configured to use the EBI in SRAM ALE1 mode, which does not give us address bits A23:16. Which mode(s) can be used to access all of these higher address bits? Describe the change(s) necessary to use one of these modes. What additional hardware is needed, if any?

We could use SRAM 3Port ALE12 we would not need any additional hardware. We could also use SRAM 4Port ALE2 we would need additional latches.

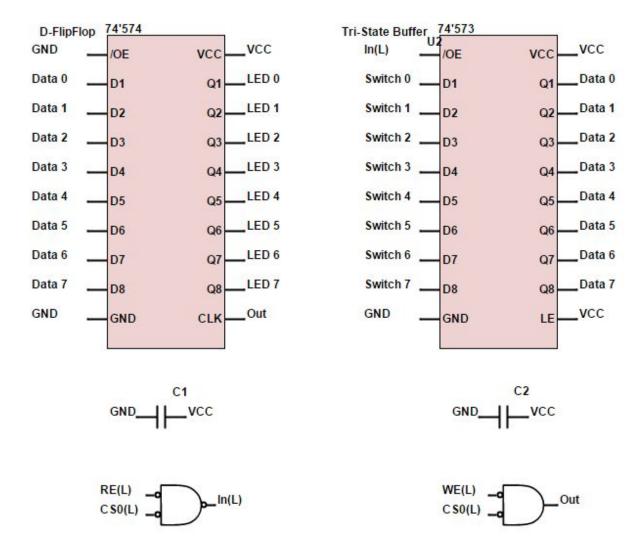
Problems Encountered:

The ROR and ROL instructions would not work as expected. They would not set or use the carry register.

Future Work/Applications:

Could use the EBI to expand memory to numerous devices, to write all the inputs to memory. Can be used to output to LCDs.

Schematics:



Decoding Logic:

```
library ieee;
use ieee.std_logic_1164.all;
entity lab3 is
 port (
  CS0_L : in std_logic;
  RE_L : in std_logic;
  WE_L : in std_logic;
  Out_H : out std_logic;
  In_L : out std_logic
  );
end lab3;
architecture BHV of lab3 is
begin
 In L <= RE L or CS0 L;
 Out_H <= WE_L nor CS0_L;
end BHV;
```

Pseudocode/Flowcharts:

Back to Shift Loop.

Configure Port H Configure Port J Configure Port K Set EBI to 3 Port ALE1 mode. Set CS0 data space to 16K SRAM mode. Initialize CS0 Base Address Initialize pointer to Base Address. Read Input. Write to LEDs. SHIFT LOOP: Shift Left. Delay. Dec Counter. Back to Shift Loop. If counter is zero. Shift Right. Delay. Dec Counter.

Program Code:

: lab3.asm ; Created: 6/13/2016 6:28:22 PM ; Author : James Mak .include "ATxmega128A1Udef.inc" .set Port_Start = 0x8000 ;Base address of our expansion port. .set Port_End = 0xBFFF ;Ending address of our expansion port. .equ stack_init = 0x2FFF ;Initialize stack pointer. .org 0x0000 rjmp MAIN ;Jump to the start of our main program. .org 0x0200 MAIN: Idi YL, low(stack_init) ;Initialize low byte of stack pointer. out CPU_SPL, YL Idi YL, high(stack init) ;Initialize high byte of stack pointer. out CPU_SPH, YL ;We can use the same register YL for both high and low. ldi R16, 0b10111 ;Bit 4 = CS0(L), Bit 2 = ALE1(H), Bit 1 = RE(L), Bit 0 = WE(L)sts PORTH_DIRSET, R16 ;Configure PortH setting bits 4,2,1,0 as output bits. ldi R16, 0b10011 ;The manual says that active low pins should be set to 1 and that active high pins should be set to 0. sts PORTH_OUTSET, R16 ;Output 1 at bits 4,1,0 (active low pins). ldi R16, 0xFF ;Bit configurations for port K. (A15-A0) sts PORTK DIRSET, R16 ;Set all Port K pins to output pins. ldi R16, 0xFF ;Bit configurations for port J. (D7-D0) sts PORTJ DIRSET, R16 ;Set all Port J pins to output pins. Idi R16, 0x01 ;Configuration bits for EBI mode. sts EBI_CTRL, R16 ;Set IFMODE (EBI mode) to 3-Port Configuration.

ldi ZL, low(EBI_CS0_BASEADDR)

Idi ZH, high(EBI_CS0_BASEADDR) ;Point High bytes of Z register to point to base

;Point Low bytes of Z register to point to base

address register for CS0.

address register for CS0.

;Load the second byte of Starting address 0x8000, Byte 2 = Idi R16, byte2(Port_Start) 0x80. st Z+, R16 ;Store Byte 2 into base address register. Idi R16, byte3(Port Start) ;Load the third byte of the starting address. st Z. R16 ;Store Byte 3 into base address register. ldi R16, 0x19 ;16K chip select space 0x8000 - 0xBFFF. SRAM mode. sts EBI_CS0_CTRLA, R16 Idi R16, byte3(Port Start) ;Load the third byte of Starting address to R16. sts CPU RAMPX, R16 Idi XH, high(Port_Start) ;Point X register to high bytes of starting address. Idi XL, Iow(Port_start) ;Point X register to low bytes of starting address. TEST: Id R16, X ;Test input port to R16. non st X, R16 ;Output to LED. Idi R17, 0x08 ;Load counter value 8 to R19. SHIFT LEFT: sbrc R16, 7 ;If the most significant bit of r16 is a 1 then set the carry to one. sec rol R16 :Rotate R16 left. rcall DELAY ;Wait .25 seconds. rcall DELAY ;Wait .25 seconds. st X. R16 ;Display shifted number to LFDs dec R17 ;Decrement the counter. cpi R17, 0x00 :Is the counter zero? brne SHIFT_LEFT ;Do the shift 8 times. ldi R17, 0x08 ;Reset counter. SHIFT RIGHT: sbrc R16, 0 ;If bit 0 is a 0 skip next instruction. sec ror R16 ;Rotate R16 right. rcall DELAY ;Wait .25 seconds. st X, R16 ;Display shifted number to LEDs. dec R17 ;Decrement the counter. cpi R17, 0x00 :Is the counter zero?

brne SHIFT_RIGHT

;Do the shift 8 times.

rjmp TEST ;Repeat after 8

times.

DELAY: ;500 us delay

divided by two for 50% duty cycle.

ldi R18, 125 ;125 cycles for .25ms of Delay. 125 x

500 for .5s of Delay.

ldi R19, 250 ;250x125 for .25s of Delay.

delay_250:

dec R19 ;Decrement R19.

cpi R19, 0x00 ;Compare R19 with zero.

brne delay_125 ;If not equal to zero,loop.

ret

delay_125:

dec R18 ;Decrement R18.

cpi R18, 0x00 ;Compare R18 with zero.

brne delay_125 ;If not equal to zero loop.

rjmp delay_250

Appendix:

Waveform .5s Delay

