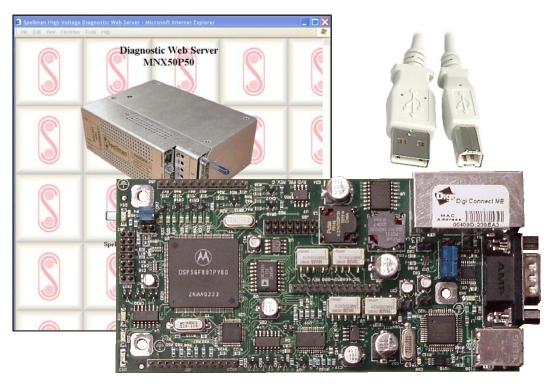


## **Standard Interface Control Option SIC Digital Interface:**

### **Ethernet** Serial - RS-232 **Universal Serial Bus - USB**



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USA EUROPE JAPAN MEXICO

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#### 1.0 SCOPE

This document applies to the communications interfaces on the Standard Interface Control Board (SIC) Option, assemblies 460059-XXX.

#### 2.0 FUNCTIONAL DESCRIPTION

The SIC option provides 3 different types of communications interfaces:

- RS-232 on JB1
- Ethernet (10-Base-T) on JB3
- Universal Serial Bus on JB4.

Data acquisition and control capabilities are provided by:

- 14 channels of 12-bit analog-to-digital converters
- 2 additional analog channels that monitor the house-keeping power supply and ambient temperature
- 5 digital output bits
- 8 digital inputs bits
- 3 relays/interlocks

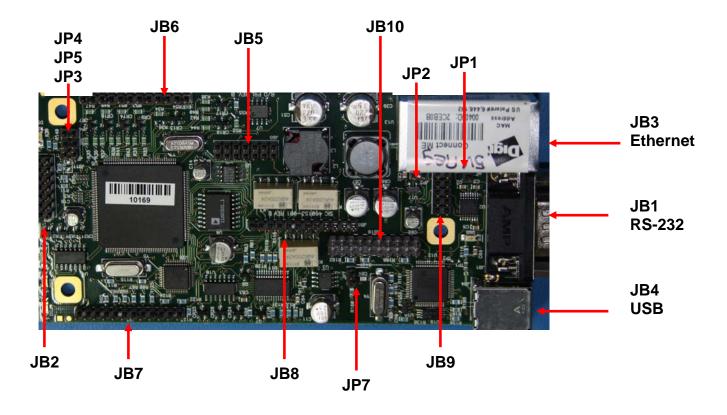


Figure 1A - SIC 460153-XXX Rev C Assembly

#### 3.0 GETTING STARTED – HARDWARE SETUP

The digital hardware includes a 40MIPS digital signal processor, a network processor, and a USB processor/controller. Serial port 0 of the DSP is jumper selectable to allow for firmware updating through either the RS-232 port or the Ethernet interface.

#### 3.1 HEADERS / JUMPER BLOCKS

ID	Revision	Description	Normal Connection	Factory Use Only
JB1	All	External RS-232, DB-9	-	-
JB2	All	DSP JTAG	-	Yes
JB3	All	External Ethernet	-	-
JB4	All	External USB, Type B	-	-
JB5	All	Analog, digital, interlock 1	-	-
JB6	All	Analog	-	-
JB7	All	Digital I/O	-	-
JB8	All	Digital I/O, Interlocks 2-3	-	-
JB9	All	Firmware update source	-	-
JB10	All	USB JTAG	-	Yes
JB11	All	DSP Reset	Open	Yes
JP1	All	RS-232 Idle Enable	Open	Yes
JP2	All	Ethernet to USB	Open	Yes
JP3	All	DSP JTAG Enable	Closed	Yes
JP4	B & up	ADC Calibration on ch. 9	Closed	Yes
JP5	B & up	ADC Calibration on ch. 8	Closed	Yes
JP7	C & up	USB Local F/W Update	Closed	Yes

#### 3.2 CONFIGURING THE HARDWARE

Normally, the end user will not need to configure the SIC board, as it will be pre-configured from the factory for the type of unit it is intended to interface with. However, the user may desire to change the setting of the Firmware Update Source via JB9.

#### 3.2.1 TO UPDATE VIA RS-232:

Set the JB9 jumpers as per Figure 2. 1-3, 2-4, 5-7, 6-8

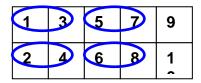


Figure 2 – Firmware Updates via RS-232

#### 3.2.2 TO UPDATE VIA ETHERNET:

Set the JB9 jumpers as per Figure 3. 3-5, 4-6, 7-9, 8-10

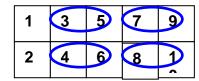


Figure 3 – Firmware Updates via Ethernet

#### 3.3 RS232 INTERFACE

The RS232C interface has the following attributes:

- 115K bits per second
- No Parity
- 8 Data Bits
- 1 Stop Bit
- No handshaking
- DB-9 connector as shown

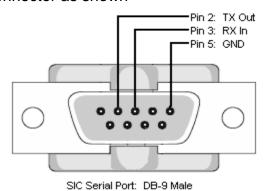


Figure 4 – JB1, RS-232 DB-9M pinout (front view)

PIN	DESCRIPTION
1	-
2	Tx Out
3	Rx In
4	-
5	Ground
6	-
7	-
8	-
9	-

#### 3.4 ETHERNET INTERFACE

The Ethernet interface has the following attributes:

- 10-Base-T (rev A-B), 10/100-Base-T (Rev E and higher)
- IP address can be set by the system integrator
- Network Mask can be set by the system integrator
- TCP Port Number can be set by the system integrator
- RJ-45 connector
- Network attachment via Crossover and Standard Ethernet cables.
- Supported Operating Systems: Windows 98 2ED, Windows 2000 (SP2), Windows NT (SP6), Windows XP Professional

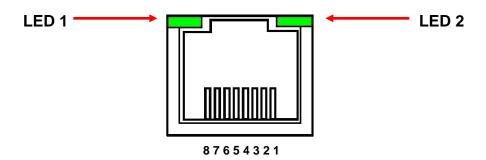


Figure 5 – JB3, Ethernet RJ45 Jack (front view)

PIN	DESCRIPTION
1	TX+
2	TX-
3	RX+
4	-
5	-
6	RX-
7	-
8	-

The Ethernet RJ-45 has two LED indicators, as shown in Figure 5. The left LED, LED1 indicates that the network processor has a valid network link. The right LED, LED2 indicates network activity.

#### 3.5 USB - UNIVERSAL SERIAL BUS INTERFACE

The USB interface has the following attributes:

- Compliant with USB 1.1 and USB 2.0 specifications
- Type B male connector
- Included driver can be communicated with via standard Windows serial communications methods



Figure 6 – JB4, USB Type B (front view)

PIN	DESCRIPTION
1	Vbus +5V
2	D-
3	D+
4	Ground

#### 3.6 **RS-232 CABLING**

A standard RS-232 cable where line 2 is connected straight through to pin 2 and 3 line is connected straight through to line 3. Please refer to the following chart.

PC to SIC Board Cable Details		
PC Connector (DB-9 Female) SIC Connector (DB-9 Male)		
Pin 2: TX Out	Pin 2: TX In	
Pin 3: RX In	Pin 3: RX Out	
Pin 5: Ground	Pin 5: Ground	

#### 3.7 ETHERNET CABLING

Category 5 (CAT5) Ethernet patch cables are used to connect the SIC to the host computer. There are two ways to connect to the SIC board via Ethernet: the first is to directly cable between the host and the SIC board, and the second is through the use of a switch, hub, or network.

A direct connection requires a **non**-standard cable **where the wires are not run straight through**. Please refer to the two cable ends shown below in figure 7.

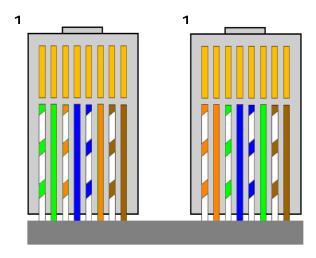


Figure 7 – Crossover Cable for Direct Connection

A standard connection through a hub, switch, or network uses a standard CAT5 patch cable. Please refer to the two cable ends shown below in figure 8.

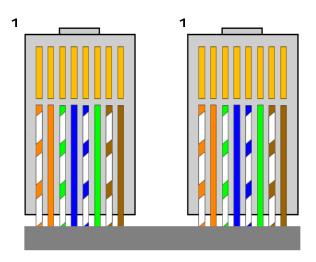


Figure 8 – Standard Straight Through Cable – Standard CAT5 Patch

#### 3.8 USB CABLING

A high-quality double shielded USB 2.0 Type A to B (host to slave) cable should be used in all applications. This type of cable is a standard PC to peripheral cable that utilizes full-size connectors.



Figure 9 – USB A-to-B cable

#### 3.8.1 HIGH EMI ENVIRONMENTS

If the SIC USB interface is being used in a high-EMI environment, ferrites should be added to the USB cable. Figure 10 illustrates the possible combinations of ferrites that can be used to achieve acceptable operation under these conditions.

The SIC should be controlled from a host interface which is compliant with Annex A of EN 61326-1. Proper attention to cable locations are the responsibility of the installer.

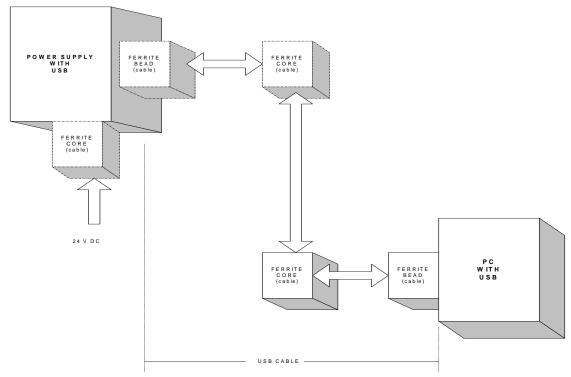


Figure 10 – Block Diagram of USB Cable Utilizing Ferrites

Ferrite beads should be attached to the USB cable next to the connectors – both sides should be installed. In extreme cases ferrite cores may be added where the cable is looped 3 or 4 times around the core as shown in figure 11. Cores of 1.5 to 2 inches should be used at both ends of the cable. In addition, a ferrite core may be required on the 24VDC input.



Figure 11 - Example of a USB Cable Using Ferrites

Please refer to the USB Interface Setup section, for an explanation of how USB works and why EMI may present a problem for this communications interface.

#### 4.0 GETTING STARTED - SOFTWARE

The following sections detail how to create software to interface to the SIC communications interfaces. In addition, please reference section 8 which lists commands used for specific Spellman power supplies.

#### 4.1 RS-232

The RS-232 interface makes use of a standard 'command/response' communications protocol. See section 6.0 for the syntax of the serial interface protocol. The programmer should also review section 4.3 for programming considerations for the USB interface as the code is nearly identical for the RS-232 interface.

All software that addresses the RS-232 interface must adhere to the following parameters:

- 115K bits per second
- No Parity
- 8 Data Bits
- 1 Stop Bit
- No handshaking

#### 4.1.1 Enabling Communications Objects in Visual Basic for RS-232

Communications in Microsoft Visual Basic 6.0 are directed to a control that abstracts the port. In the case of serial and USB we need Microsoft Comm Control 6.0. To enable this in your VB 6 project, go to:

#### **Project -> Components**

Then in the list make sure that Microsoft Comm Control 6.0 has a check next to it. The Comm Control Object should then appear in your toolbox. It will have an icon of a telephone and will be named: MSComm. This can be dragged and dropped into your application. You will then need to set the object's properties.

#### 4.1.2 Configuring Communications in Visual Basic for RS-232

In order to configure the MSComm Object, first you must initialize it in the Object properties:

Settings 115200,n,8,1 Handshaking 0 – comNone

The application can be set to either default to a specific COM Port or the End User can be allowed to choose one for the particular PC.

For the "Default" scenario, include the following commands in the Form\_Load() routine:

MSComm1.CommPort = portNumber MSComm1.PortOpen = True

For the "Choice" scenario, place the above two commands in a selectable menu item.

#### 4.2 ETHERNET

The SIC board contains an embedded diagnostic web server that can be accessed through any standard web browser by browsing to the SIC's IP address. The SIC is pre configured for the following IP address and or Port address:

IP= <u>http://192.168.1.4</u> Port Address = 50000

The Ethernet interface communicates using the following protocols:

- TCP/IP
- HTTP
- TFTP
- FTP

Revision A and B assemblies can communicate at 10Mb/s, while Revision C and higher assemblies can auto-switch between 10Mb/s and 100Mb/s.

#### 4.2.1 Diagnostic Web Server

The diagnostic web server can control and monitor an SIC equiped power supply from a web browser. It displays operating status of the Power Supply and allows the unit to be configured in real time. The application consists of three web pages; a page displaying contact information, a license agreement, and a monitoring and control applet that is at the heart of this application. The Web Server application for the MNX50P50 is presented as an example in the following pages. When prompted use the following User name and Password.

User Name = admin Password = SHV\_Applet

#### 4.2.2 Web Pages

#### 4.2.2.1 Web Page 1: Contact Information Page

Figure 12 displays a picture of the MNX50P50 and information on how to contact Spellman High Voltage Electronics Corporation. By clicking on the picture of the MNX50P50 or on the button labeled "Click Here to Monitor and Control" one can move on to the next screen, the license agreement.



Figure 12 - Web Page 1- Contact Information

#### 4.2.2.2 Web Page 2: License Agreement Page

Figure 13 displays the license agreement. Here the user can either agree or disagree with the Spellman license agreement. Click on "I Accept" to continue on to the applet.

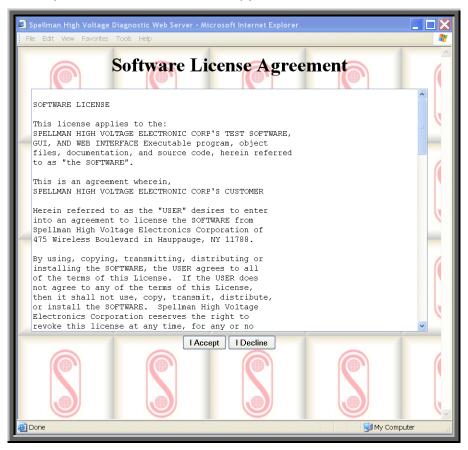


Figure 13 - Web Page 2 - License Agreement

#### 4.2.2.3 Web Page 3 - Monitor and Control Applet

#### 4.2.2.3.1 Requirements

The Monitor and Control Applet is a java "applet" ("small java application" specifically written to be embedded in a web page and invoked from a browser) that requires an Internet browser with an installed JVM (Java Virtual Machine). We have tested under Internet Explorer 5 and 6, Microsoft JVM 5 and Sun JVM versions 1.4.1 and 1.4.2.

#### 4.2.2.3.2 Description of Monitor and Control Applet

Figure 14 displays an example of an embedded monitor and control application.

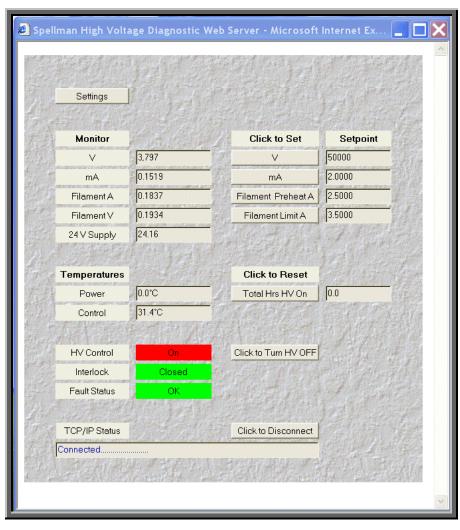


Figure 14 - Control and Monitor Applet

Broadly one can view the screen as a "left" and a "right" with the left half containing status values (read backs) read from the SIC and the right half containing the values that are configurable by the user. Notice that the top of the right half contains the label "Click to Set". For any configurable setting you click on the button to the left of the setting, which brings up the program set point screen. For example, click on the button labeled, 'V' to set the output voltage set point. Refer to figure 15.

#### 4.2.2.4 Program Set Point Screen

On the program set point screen (Reference figure 15) there are two fields: a top field labeld 'V' and a bottom field labeled 'DAC'.

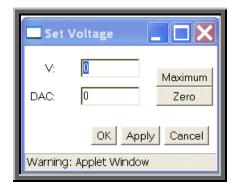


Figure 15 - Program Configurable Values Screen

The top field is the scaled value or real world value, which is the field the user is going to use most of the time. The bottom field is the raw digital-to-analog converter (DAC) value that is actually sent to the SIC. Enter either the desired set point level in the top field or the DAC value between 0 and 4095 in the bottom field.

The user can then click Apply to send the set point to the SIC and remain in the set point screen, or click OK to send the set point and close the set point entry window. The Maximum and Zero buttons will set both fields to the indicated end point value. The user may also click on Cancel to close the window without sending any changes.

#### 4.2.2.5 Java Warning Messages

You may notice a message at the bottom of all dialog windows that are displayed from the SIC Control and Monitor Applet. The wording may vary slightly depending on the JVM version but on some the message is "Warning: Applet Window". This message is letting you know that the dialog window was generated by an

applet. The design philosophy for the JVM was for secure computing so the origins of new windows are supposed to be as obvious as possible.

#### 4.2.2.6 Menu Item "Settings" on Applet

The user can view and set operating parameters of the applet or network configurations of the SIC or view firmware version information for both through the settings menu. Click on the button at the top of the Monitor and Control Applet that has the label "Settings". This displays the settings popup menu as shown in figure 16.



Figure 16 – Settings Pop up Menus

Notice that there are three choices. The first, "Network Settings" refers to the network settings for the network component of the SIC and not the Monitor and Control applet. The second option, "Poll Rate" affects refresh rate of the Monitor and Control Applet and will be discussed in the next section. In the "about" choice firmware version information is displayed, both for the Monitor and Control Applet and for the SIC hardware.

#### 4.2.2.7 Refresh rate for monitored values

The refresh rate for the applet display of the SIC is dependent upon the rate of placement of status requests in the internal send queue and how fast responses are sent back from the SIC in response to the requests. The default value for queuing responses is every 600ms and this is a configurable value in the

Settings->Poll rate screen. Please refer to figure 17.



Figure 17 - Configure Polling Rate Screen

Setting this value lower may make the screen refresh quicker. However, setting it too low may cause requests to queue up in the send queue. This may make controlling the SIC very slow, as control requests now must wait behind queued status requests. We recommend leaving the delay set at the default value.

#### 4.2.2.8 Version Information

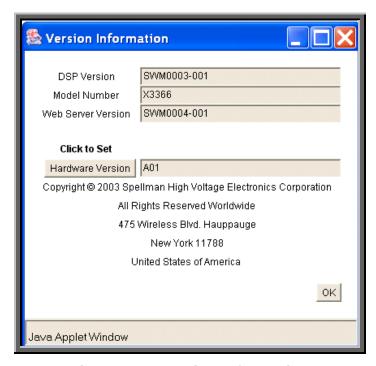


Figure 18 – Version Information

#### 4.2.2.9 Turning the SIC HVOn/Off and Connection Status

Please refer to Figure 14, the Monitor and Control Applet.

Setting Name	Range Values
HV	On/Off
Interlock	Open/Closed
Fault Status	OK/Fault

Connection Status Connected/No Data Received/Disconnected

Unlike the controls we previously discussed at the top of the screen which required a separate dialog screen to enter values, these are controlled by a button. For example, an On/Off button controls the HV. When HV is on, the Control is labeled "Click to Turn HV Off". When HV is off, the control is labeled "Click to Turn HV On". Thereby handling the two distinct states.

Notice that at the very bottom of the screen is a text field that displays the current connection status, which as mentioned above is one of three values. "Connected" is displayed when there exists a valid TCP/IP session connecting the SIC and the Applet and data is being received by the applet from the SIC. The next state is "No Data Received" which is when there is still a valid connection but no responses have been received from the SIC for 2 seconds. Lastly, the text field displays "Disconnected" when the TCP/IP session has been disconnected.

When the Applet is first started and anytime the "Click To Connect" button is clicked there is a 5 second delay as the Applet starts up the threads necessary for communication between it and the SIC.

#### 4.2.2 Direct Connection between the SIC and a Computer

A direct Ethernet connection between the SIC and the computer requires an RJ45 crossover cable. The end connectors will look identical to a "normal" RJ45 connector but the colors of some of the wires in the connectors will be "reversed". Hold up the two ends of the RJ45 cable and look at the color of the wires from left to right. They should differ on the two connectors.

When direct connecting the SIC to a computer using a crossover cable over Ethernet they are essentially participating in a private network. As such you need to pick two valid IP addresses, one for each device.

The table below illustrates that not all IP addresses are actually valid IP addresses. For example, IP addresses beginning with 127 are not valid.

Class	Address Range	
А	1.0.0.0-126.255.255.255	
В	128.0.0.0-191.255.255.255	
С	192.0.0.0-223.255.255.255	

## 4.2.2.1 Configuring the Computer for Direct Ethernet Connection

As mentioned above both the IP Address and Subnet Mask need to be configured. In our environment computers normally are assigned IP addresses dynamically, using DHCP. We need to change this and assign the IP Address statically to the one we have selected.

Here are the steps on Windows XP. On the desktop right click on "My Network Places" and select properties at the bottom of the menu.



Figure 19 – Right Click on Desktop



Figure 20 - Select Properties

After selecting properties you are brought up to the screen below (Figure 21). You must RIGHT CLICK and select Properties on Local Area Connection, and not double click which will display a window similar to figure 22.



Figure 21 – Here you must Right Click and Select Properties

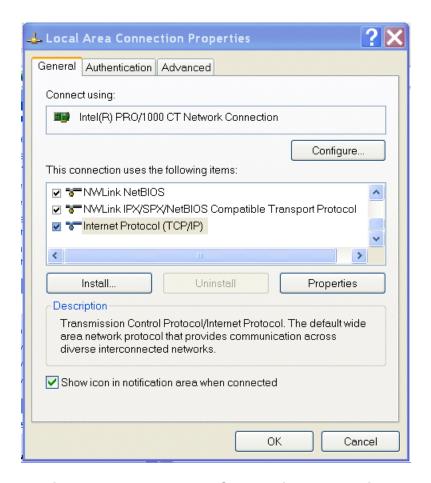


Figure 22 – Local Area Connection Properties

Now you must select "Internet Protocol (TCP/IP)" and click on the Properties button to be brought to figure 23. Lastly you must disable any firewall software you have running. If you are running a proxy server for Internet access, you must also disable the proxy client. Disabling this also requires a reboot.

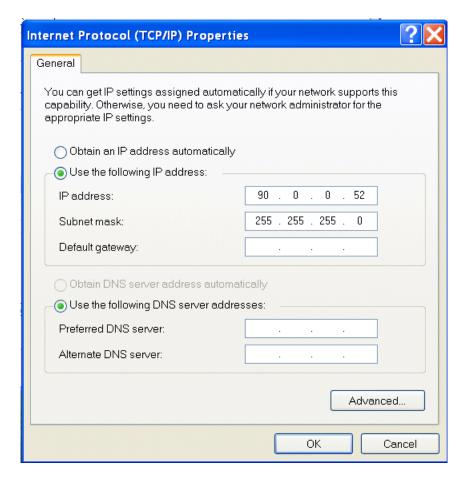


Figure 23 – TCP/IP Properties

#### 4.2.2.2 Testing a Direct Connection

You can use the program "Ping" to test a network connection between the computer and the SIC. "Ping" is a command line tool so we will need to bring up a command prompt. Under Windows NT, 2000 and XP the name of this command is "CMD". Under Windows 98 the name of this command is "Command".

To do this, click on Start->Run->Cmd

Then on the command line type

Ping <IP Address>

For example

Ping 192.168.1.2

If the SIC board is found at the specified IP address, the Ping command will respond with a report that is similar to:

Pinging 192.168.1.2 with 32 bytes of data:

Reply from 192.168.1.2: bytes=32 time<1ms TTL=64

Ping statistics for 192.168.1.1:

Packets: Sent = 4, Received = 4, Lost = 0 (0% loss),

Approximate round trip times in milli-seconds:

Minimum = 0ms, Maximum = 0ms, Average = 0ms

#### 4.2.3 Configuring the SIC For a Local Area Network (LAN)

If you have chosen to place the SIC onto your local area network you will need:

- A CAT5 network patch cable to physically connect the SIC to the LAN
- A static IP address to assign to the SIC.

Remember that even if the IP address you have selected is in general a valid IP address it needs to be valid for your LAN (local area network). Otherwise the device will not be accessible from an Internet browser or Ping.

# 4.2.3.1 Configuring the Network Settings from the Monitor and Configure Applet

The network settings are configurable from the Settings->Network Settings screen, refer to figure 24.

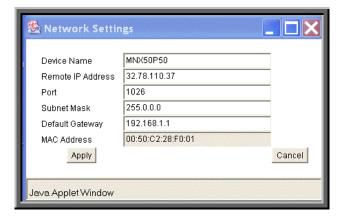


Figure 24 - Configure Network Settings

The settings that can be changed are the:

- Device Name
- IP Address
- TCP Port
- Subnet Mask
- Default Gateway

Once the Apply button is clicked on the network settings screen the network component of the SIC is configured, rebooted and the applet is disconnected from the SIC. You must type the NEW IP address into a web browser to bring up a new instance of the applet to monitor and control the SIC after reconfiguring it. This may also require reconfiguring the host computer with the correct host IP address, subnet mask, and TCP port.

The device name does not affect the operation of the SIC; it is simply a way for the user to differentiate multiple units on the same network.

Depending on the type of network you are attaching the SIC to, you may need to configure the host PC's IP address and subnet mask as shown in section 4.2.2.1. You can also test a network connection to the SIC by following the instructions listed in section 4.2.2.2.

## **4.2.4 Enabling Communications Objects in Visual Basic for Ethernet Communications**

For Ethernet communications, we need Microsoft Winsock Control 6.0 and SP5. To enable this in your VB 6 project, go to:

#### **Project -> Components**

Once selected in your toolbox you will have an icon of two computers linked together and it will be named: Winsock. This can be dragged and dropped into your application. Then set the object's properties.

#### 4.2.5 Configuring Communications in Visual Basic for Ethernet

In order to configure the Winsock Object, you must make the following initialization in the object's properties:

Protocol 0 – sckTCPProtocol

Then, in the application code, include the following commands:

```
tcpClient.RemoteHost = host
tcpClient.RemotePort = portNumber
tcpClient.Connect
```

For further information regarding the use of the above commands, please refer to your Visual Studio Help File.

#### 4.2.5.1 Data Output Example

MSComm1 is both the serial and USB port. TcpClient is the Ethernet port.

```
If (portType = "ethernet") Then tcpClient.SendData (str)

Else

MSComm1.InBufferCount = 0
On Error GoTo done
MSComm1.Output = str done:
tmrOpenClose.Enabled = True

End If
```

USA EUROPE JAPAN MEXICO

#### 4.2.5.2 Data Input Example

```
If (portType = "ethernet") Then
      Do
             DoEvents
             tcpClient.GetData temp$
             str = str + temp$
             Loop Until InStr(str, Chr(3)) Or Timer - t1 > 1
             On Error Resume Next
Else
      Do
             DoEvents
             If MSComm1.InBufferCount > 0 Then
                   str = str & MSComm1.Input
             End If
             Loop Until InStr(str, Chr(3)) Or Timer - t1 > 1
             If InStr(str, Chr(3)) > 0 Then
                   tmrOpenClose.Enabled = False
             End If
End If
```

#### 4.3 USB

The USB interface makes use of a standard 'command/response' communications protocol. See section 6.0 for the syntax of the serial interface protocol.

The USB interface is accessed through a Windows USB Human Interface Device driver

#### 4.3.1 USB Driver Installation

The Windows USB Human Interface Device (HID) driver is included with the windows operating system. There may be other HID devices connected to USB ports like an optical mouse or a keyboard.

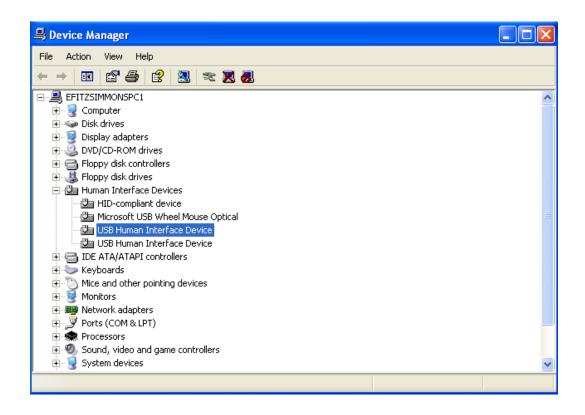


Figure 26 - Device Manager HID Driver

To determine which HID device is connected to the supply right click and select properties. Next to the Location: under the General tab "Spellman USB HID" should be seen.



Figure 26a: HID General Properties

For more details on the HID connection go to the Details tab of the properties window where the VID, PID and Serial number can be seen.

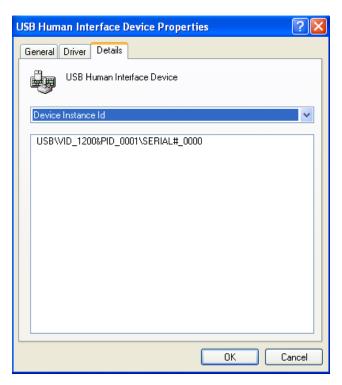


Figure 26b: HID Detail Properties

#### 4.3.2 USB and EMI

The USB protocol utilizes a heartbeat signal from each client device back to the host (PC). If the heartbeat is interrupted due to radiated or conducted transient noise, it is possible that the host may lose connection with the client. This can cause problems with data transfers over the USB cable.

The SIC revision C or higher assembly when used in combination with the HID Windows driver makes it possible for the host to re-numerate the client connection and reestablish communications. This is holds providing the

control application implements a method of timeout and retry.

#### NOTE:

The SIC should be controlled from a host interface which is compliant with Annex A of EN 61326-1. Proper attention to cable locations and grounding are the

responsibility of the installer.

#### 4.3.3 Using the USB HID Interface in Visual Basic

The dynamic link library USB\_dll.dll will be provided which needs to be added to the project. The library has three functions that can be called from the VB code.

The three functions are:

- FindTheHid finds the connection with the correct VID, PID and Serial Number
- WriteReport(str) Writes a string to the connected HID interface
- ReadReport() Returns a string from the connected HID interface

#### 4.3.4 Configuring Communications in Visual Basic for USB

To use the USB\_dll.dll in VB the following statement is needed.

Dim usb As usbDll Dim MyDeviceDetected As Boolean

Using this statement determines whether a connection is present.

MyDeviceDetected = usb.FindTheHid

If MyDeviceDetected is true then the connection is present.

#### 4.3.5 Software Considerations for USB Reconnection

The following Visual Basic code snippets are presented as a guideline for implementation with revision C and higher assemblies.

#### 4.3.5.1 Recognize partial, corrupt, or absent data

- 1: temp2\$ = inputInputString
- 2: If temp2\$ <> "" Then
- 3: btn UPDATEDATA. Value = False
- 4: CommStatusFlag = True
- 5: CommaPos = InStr(Start, temp2\$, Comma,
- vbTextCompare)
- 6: 'Channel 0
- 7: On Error GoTo endhere
- 8: AmbTemp = Mid(temp2\$, Start, (CommaPos Start))

Please note that even though we have guarded against no data, in line 2, we still need to guard against bad data, in this case no comma, on line 8. If there is no comma, we wind up passing a negative value to Mid, which is an error, that we should trap for.

#### 4.3.5.2 Retrieve data from USB

- 1: Do
- 2: DoEvents
- 3: stra = usb.ReadReport
- 4: str = str & stra
- 5: 'str = str & ReadReport
- 6: Loop Until InStr(str, Asc(3)) Or Timer t1 > 0.09

#### 4.3.5.3 Example Output Routine

- 1: Public Sub outputOutputString(outputString As String)
- 2: Dim str As String
- 3: str = ProcessOutputString(outputString)
- 4: StatusBar1.Panels(4).Text = "TX: " & str
- 5: 'StatusBar1.Panels(3).Text = "RX: Waiting"
- 6: If (portType = "ethernet") Then
- 7: tcpClient.SendData (str)
- 8: Elself (portType = "USB") Then
- 9: usb.WriteReport (str)
- 10: Else
- 11: MSComm1.InBufferCount = 0
- 12: MSComm1.Output = str
- 13: End If
- 14: End Sub

#### 4.3.5.4 Example Input Routine Example Input Routine

- 1: Private Function inputInputString() As String
- 2: Dim str As String
- 3: Dim t1 As Single
- 4: Dim stra As String
- 5: Dim stri(300) As String
- 6: Dim temp\$
- 7: Dim a As Integer
- 8: t1 = Timer
- 9: If (portType = "ethernet") Then
- 10: Do
- 11: DoEvents
- 12: tcpClient.GetData temp\$
- 13: str = str + temp\$
- 14: Loop Until InStr(str, Chr(3)) Or Timer t1 > 1
- 15: On Error Resume Next
- 16: Elself (portType = "USB") Then
- 17: Do
- 18: DoEvents

```
19:
         stra = usb.ReadReport
20:
         str = str & stra
21:
          'str = str & ReadReport
22:
       'Loop Until InStr(str, Chr(3)) Or Timer - t1 > 0.09
23:
       Loop Until InStr(str, Asc(3)) Or Timer - t1 > 0.09
24:
      Else
25:
       Do
26:
          DoEvents
27:
          str = str & MSComm1.Input
28:
        Loop Until InStr(str, Chr(3)) Or Timer - t1 > 1
29:
        str = str & MSComm1.Input
30:
       frm_EXTRAS.txt_MSCOMMBUFF.Text =
MSComm1.Input
31:
       tmr COMMWDT.Enabled = True
32:
       On Error Resume Next
33:
     End If
34: StatusBar1.Panels(3).Text = "RX: " & str
35: inputInputString = str
36: tmr RCVTIMER.Enabled = True
37: MSComm1.InBufferCount = 0
38: End Function
```

#### 4.3.5.5 Data Parsing Example

Here we have an example of a code that parses incoming data. Notice that it makes use of our generic input and output routines. The important consideration is to gracefully handle corrupted input data after a noise event. In this case we may get data, so a test against empty string returns false, but we may not get commas in the correct place. Notice that we register an error handler on line 26 so that the mid function, which would raise an error when given a negative number, is handled.

```
1: Private Sub btn_EMI_Click()
2: Dim temp2$
3: Dim Response1$
4: Dim Response2$
5: Dim number$
6: Dim Comma
7: Dim CommaPos
8: Dim Start
9: Dim ODATA$
10:
11: Comma = ","
12: Start = 5
13:
```

```
14: If
tmr_RCVTIMER.Enabled =
True Then
tmr RCVTIMER.Enabled =
False
15: If
tmr_NETRCVTMR.Enabled =
True Then
tmr_NETRCVTMR.Enabled =
False
16:
17: If AutoUpdate = True Then
18: tmr_UPDATE.Enabled = False
19: End If
20:
21: number$ = "15."
22: outputOutputString (number$)
23:
24: temp2$ = inputInputString
25: CommaPos = InStr(Start, temp2$, Comma,
vbTextCompare)
26: On Error GoTo endhere
27: Response1$ = Mid(temp2$, Start,
(CommaPos - Start))
28:
29: 'With a 5v reference:
30: ODATA$ = Format(str(Response1$ *
0.0004884), "0.##0")
31:
32: txt DACB.Text = ODATA$ + " mA"
33: frm RAWDATA.txt RAWDACB.Text =
str(Response1$)
34: txt DACB.BackColor = vbWhite
35: CommStatusFlag = True
36: endhere:
37:
38: If portType = "ethernet" Then
39: tmr NETRCVTMR.Enabled = True
40: Else
41: tmr_RCVTIMER.Enabled = True
42: End If
43:
44: If AutoUpdate = True Then
tmr UPDATE.Enabled = True
46: End Sub
```

# 4.3.5.6 Example Input Routine

Notice on line 18 we check for data first before extracting data from the input. Then if we have actual data we turn off the timer. Otherwise the timer routine toggles the port open/close.

```
1: Private Function inputInputString() As String
2: Dim str As String
3: Dim t1 As Single
4: Dim temp$
5: t1 = Timer
6:
7: If (portType = "ethernet") Then
8:
      Dο
          DoEvents
10:
11:
          tcpClient.GetData temp$
          str = str + temp$
12:
13:
       Loop Until InStr(str, Chr(3)) Or Timer - t1 > 1
14:
       On Error Resume Next
15:
     Else
16:
       Do
17:
          DoEvents
         If MSComm1.InBufferCount > 0 Then
18:
19:
            str = str & MSComm1.Input
20:
         End If
21:
       Loop Until InStr(str, Chr(3)) Or Timer - t1 > 1
22:
23:
       If InStr(str, Chr(3)) > 0 Then
          tmrOpenClose.Enabled = False
24:
25:
       Fnd If
26:
       frm EXTRAS.txt MSCOMMBUFF.Text = str
27:
28:
       tmr COMMWDT.Enabled = True
       On Error Resume Next
29:
30:
     End If
     StatusBar1.Panels(3).Text = "RX: " & str
31:
32: inputInputString = str
33: tmr RCVTIMER.Enabled = True
34: End Function
```

# 4.3.5.7 Example Timer Routine: Toggle Port State

This is the timer routine in which the open/closed state of the port is toggled. If communications are interrupted, the USB device will reregister itself with the OS (vendor term: renumeration). Once this happens, re-opening the port will enable communications. Until the

re-registration happens, open operations will fail. Notice line 5 where we register an error handler.

```
1:Private Sub tmrOpenClose_Timer()
2: If MSComm1.PortOpen = True Then
3:
4: MSComm1.PortOpen = False
5: On Error GoTo done
6: MSComm1.PortOpen = True
7: done:
8: tmrOpenClose.Enabled = False
9: End If
10:
11: End Sub
```

# 4.3.5.8 Example Timer Routine: Port Reconnection

This is another timer routine whose purpose is to turn the port on if it is off. Notice that in line 8 an error handler is called because if the device has not re-registered itself with the OS, an error will be raised.

```
1: Private Sub tmr COMMWDT Timer()
3: tmr_COMMWDT.Enabled = False
4:
5: If CommStatusFlag = True Then
6:
7:
   If MSComm1.PortOpen = False Then
      On Error GoTo done
8:
9:
      MSComm1.PortOpen = True
10: done:
11: End If
12:
13: Elself CommStatusFlag = False Then
14:
15:
     If MSComm1.PortOpen = False Then
16:
17:
       MSComm1.PortOpen = True
18:
19:
       MSComm1.PortOpen = False
20:
    End If
21:
22: End If
```

# 4.3.5.9 Data Parsing Example

Here we have an example of a code that parses incoming data. Notice that it makes use of our generic input and output routines. The important consideration is to gracefully handle corrupted input data after a noise event. In this case we may get data, so a test against empty string returns false, but we may not get commas in the correct place. Notice that we register an error handler on line 26 so that the mid function, which would raise an error when given a negative number, is handled.

```
1: Private Sub btn_EMI_Click()
2: Dim temp2$
3: Dim Response1$
4: Dim Response2$
5: Dim number$
6: Dim Comma
7: Dim CommaPos
8: Dim Start
9: Dim ODATA$
10:
11: Comma = "."
12: Start = 5
13:
14: If tmr RCVTIMER.Enabled = True Then
tmr_RCVTIMER.Enabled = False
15: If tmr_NETRCVTMR.Enabled = True Then
tmr NETRCVTMR.Enabled = False
16:
17: If AutoUpdate = True Then
18: tmr UPDATE.Enabled = False
19: End If
20:
21:
    number$ = "15,"
22:
    outputOutputString (number$)
23:
24:
    temp2$ = inputInputString
25:
     CommaPos = InStr(Start, temp2$, Comma, vbTextCompare)
26:
     On Error GoTo endhere
27:
     Response1$ = Mid(temp2$, Start, (CommaPos - Start))
28:
29:
     'With a 5v reference:
    ODATA$ = Format(str(Response1$ * 0.0004884), "0.##0")
30:
31:
32: txt DACB.Text = ODATA$ + " mA"
33: frm RAWDATA.txt RAWDACB.Text = str(Response1$)
34:
    txt DACB.BackColor = vbWhite
```

- 35: CommStatusFlag = True
- 36: endhere:
- 37:
- 38: If portType = "ethernet" Then
- 39: tmr\_NETRCVTMR.Enabled = True
- 40: Else
- 41: tmr\_RCVTIMER.Enabled = True
- 42: End If
- 43:
- 44: If AutoUpdate = True Then tmr\_UPDATE.Enabled = True
- 46: End Sub

# 5.0 ETHERNET COMMANDS

## 5.1 TCP/IP FORMAT

Each Ethernet command will consist of a TCP/IP header followed by the required data bytes. Figure 27 summarizes the TCP/IP header configuration. Please note that this functionality is provided by the software implementation of the Open Systems Interconnection (OSI) TCP/IP protocol stack, specifically the upper 4 layers.

Byte																						
0	Protoc Versio	_		eade engt		Type Of Service			Total Length													
4				Pac	ke	t ID					Flags Fragmentation Offset				et							
8	Time	e To	) Li	ive			Pr	oto	col				He	ead	er	ch	ec	ksı	un	n		
12								Sc	ourc	e A	Address											
16	Destination Address																					
20	Source Port					Destination Port																
24	Sequence Number																					
28	Acknowledgement Number																					
32	Data Offset	t	R	ese	rv	ed	C	Code	e Bi	ts	Window											
36	Checksum				Urgent Pointer																	
40	Data Byte 1 E		Data Byte 2		2	Data Byte 3			Dat	a	Ву	/te	N									

Figure 27: Network TCP/IP datagram header

The format of Data Bytes 1 through N are as follows:

Where:

<STX> = 1 ASCII 0x02 Start of Text character

<CMD> = 2 ASCII characters representing the command ID

<,> = 1 ASCII 0x2C character <ARG> = Command Argument <,> = 1 ASCII 0x2C character

<ETX> = 1 ASCII 0x03 End of Text character

#### 5.2 COMMAND ARGUMENTS

The format of the numbers is a variable length string. To represent the number 42, the string '42', '042', or '0042' can be used. This being the case, commands and responses that carry data are variable in length.

## 5.3 COMMAND OVERVIEW

Data Byte section of the TCP/IP Datagram								
Command Name	<cmd></cmd>	<arg></arg>	RANGE					
Program DAC	10	1-4 ASCII	0-4095					
Channel A								
Program DAC Channel B	11	1-4 ASCII	0-4095					
Program DAC	12	1-4 ASCII	0-4095					
Channel D	12	1 47.0011	0 4000					
Program DAC	13	1-4 ASCII	0-4095					
Channel C								
Request DAC A	14	None	-					
Setpoint								
Request DAC B	15	None	-					
Setpoint	4.0							
Request DAC D Setpoint	16	None	-					
Request DAC C	17	None	-					
Setpoint								
Request Analog	19	None	-					
Readbacks – J6								
Channels 7 - 15								
Request Analog	20	None	-					
Readbacks – J5 Channels 0 - 6								
Request HV On	21	None						
Hours Counter	21	NOTIE	-					

Request Status	22	None	-
Request Software Version	23	None	-
Request Hardware	24	None	-
Version	27	140110	
Request Web	25	None	-
Server Version			
Request Model	26	None	-
Number			
Reset HV On	30	None	-
Hours Counter			
Reset Faults	31	None	-
Request Network	50	None	-
Settings			
Program Network	51	6 ASCII	See
Settings			Description
Program Interlock	52	1 ASCII	0 or 1
1			
Program Interlock	53	1 ASCII	0 or 1
2			
Program Interlock	54	1 ASCII	0 or 1
3			
Read Interlock	55	None	-
Status			
Readback A/D	60	None	-
Channel 0 Data			
Readback A/D	61	None	-
Channel 1 Data			
Readback A/D	62	None	-
Channel 2 Data			
Readback A/D	63	None	-
Channel 3 Data			
Readback A/D	64	None	-
Channel 4 Data	0.7		
Readback A/D	65	None	-
Channel 5 Data			
Readback A/D	66	None	-
Channel 6 Data	0=		
Readback A/D	67	None	-
Channel 7 Data	00	Nierr	
Readback A/D	68	None	-
Channel 8 Data	00	Name	
Readback A/D	69	None	-
Channel 9 Data			

Deceloped: A/D	70	Mone	
Readback A/D	70	None	-
Channel 10 Data			
Readback A/D	71	None	-
Channel 11 Data			
Readback A/D	72	None	-
Channel 12 Data			
Readback A/D	73	None	-
Channel 13 Data			
Readback A/D	74	None	-
Channel 14 Data			
Readback A/D	75	None	-
Channel 15 Data			
Read Digital Inputs	76	None	-
Program Digital	84	1 ASCII	0 or 1
Output Channel 1			
Program Digital	85	1 ASCII	0 or 1
Output Channel 2			
Program Digital	86	1 ASCII	0 or 1
Output Channel 3			
Program Digital	87	1 ASCII	0 or 1
Output Channel 4			
Program Digital	88	1 ASCII	0 or 1
Output Channel 5			
Toggle Verbose	92	None	-
Mode			
Program High	99	1 ASCII	0 or 1
Voltage Status			
3			

# 5.4 RESPONSE OVERVIEW

The command responses will follow the same network TCP/IP header format as outlined above in section 5.1. This list is comprised of Commands with complex responses only. Commands using a simple response will use the <\$> character (ASCII 0x24) as a "Success" response or a single character error code. These will be seven ASCII characters in length.

Doonanaa Nama	<cmd></cmd>	Doopopoo
Response Name		Response
Request DAC A	14	10 ASCII
Setpoint	4-	10.1000
Request DAC B	15	10 ASCII
Setpoint		
Request DAC D	16	10 ASCII
Setpoint		10.100:
Request DAC C	17	10 ASCII
Setpoint	4.0	00 -0
Request Analog	19	23-50
Readbacks – J6		ASCII
Request Analog	20	19-40
Readbacks – J5	0.4	ASCII
Request Total	21	13 ASCII
Hours High		
Voltage On	00	44.000
Request Status	22	11 ASCII
Request DSP	23	17 ASCII
Software Version	0.4	0.4001
Request Hardware	24	9 ASCII
Version	0.5	47.40011
Request Web	25	17 ASCII
Server Version	00	44 40011
Request Model	26	11 ASCII
number	<b>5</b> 0	40.404
Request Network	50	48-104
Settings	FF	ASCII
Read Interlock	55	11 ASCII
Status	60	7.40
Readback A/D	60	7-10
Channel 0 Data	C4	ASCII
Readback A/D	61	7-10
Channel 1 Data	00	ASCII
Readback A/D	62	7-10
Channel 2 Data		ASCII

Readback A/D	63	7-10
Channel 3 Data		ASCII
Readback A/D	64	7-10
Channel 4 Data		ASCII
Readback A/D	65	7-10
Channel 5 Data		ASCII
Readback A/D	66	7-10
Channel 6 Data		ASCII
Readback A/D	67	7-10
Channel 7 Data		ASCII
Readback A/D	68	7-10
Channel 8 Data		ASCII
Readback A/D	69	7-10
Channel 9 Data		ASCII
Readback A/D	70	7-10
Channel 10 Data		ASCII
Readback A/D	71	7-10
Channel 11 Data		ASCII
Readback A/D	72	7-10
Channel 12 Data		ASCII
Readback A/D	73	7-10
Channel 13 Data		ASCII
Readback A/D	74	7-10
Channel 14 Data		ASCII
Readback A/D	75	7-10
Channel 15 Data		ASCII
Read Digital Inputs	76	8 ASCII
Read Digital	89	8 ASCII
Output Settings		
Program High	99	7 ASCII
Voltage Status		
_		

# 5.5 COMMAND STRUCTURE

# 5.5.1 Program DAC Channel A

# Description:

The host requests that the firmware change the setpoint of DAC Channel A.

# **Direction:**

Host to supply

## Syntax:

<STX><10><,><ARG><,><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>10,4095,<ETX>

## Response:

<STX><10><,><\$><,><ETX><<STX><10><,><ARG><,><ETX>

where <ARG> = error code

# 5.5.2 Program DAC Channel B

# **Description:**

The host requests that the firmware change the setpoint of DAC Channel B.

# Direction:

Host to supply

## Syntax:

<STX><11><,><ARG><,><ETX>

## Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>11,4095,<ETX>

## Response:

<STX><11><,><\$><,><ETX><<STX><11><,><ARG><,><ETX></STX>

where <ARG> = error code

# 5.5.3 Program DAC Channel D

# Description:

The host requests that the firmware change the setpoint of DAC Channel D.

# Direction:

Host to supply

# Syntax:

<STX><12><,><ARG><,><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>12,4095,<ETX>

## Response:

<STX><12><,><\$><,><ETX> <STX><12><,><ARG><,><ETX>

where <ARG> = error code

# 5.5.4 Program DAC Channel C

# **Description:**

The host requests that the firmware change the setpoint of DAC Channel C.

# Direction:

Host to supply

# Syntax:

<STX><13><,><ARG><,><ETX>

## Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>13,4095,<ETX>

## Response:

<STX><13><,><\$><,><ETX>< <STX><13><,><ARG><,><ETX>

where <ARG> = error code

# 5.5.5 Request DAC A Setpoint

# Description:

The host requests that the firmware report the DAC Channel A setpoint.

# Direction:

Host to supply

# Syntax:

<STX><14><,><ETX>

# Response:

<STX><14><,><ARG><,><ETX>

## Where:

 $\langle ARG \rangle = 0 - 4095$  in ASCII format

# Example:

<STX>14,4095,<ETX>

# 5.5.6 Request DAC B Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel B setpoint.

# Direction:

Host to supply

Syntax:

<STX><15><,><ETX>

Response:

<STX><15><,><ARG><,><ETX>

Where:

<ARG> = 0 - 4095 in ASCII format

Example:

<STX>15,4095,<ETX>

# 5.5.7 Request DAC D Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel D setpoint.

# Direction:

Host to supply

Syntax:

<STX><16><,><ETX>

Response:

<STX><16><,><ARG><,><ETX>

Where:

<ARG> = 0 - 4095 in ASCII format

Example:

<STX>16,4095,<ETX>

# 5.5.8 Request DAC C Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel C setpoint.

# Direction:

Host to supply

# Syntax:

<STX><17><,><ETX>

# Response:

<STX><17><,><ARG><,><ETX>

## Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>17,4095,<ETX>

# 5.5.9 Request Analog Readbacks – J6

# Description:

The host requests that the firmware transmit the present values of Analog Channels 7 through 15, which are available via connector J6.

# Direction:

Host to supply

# Syntax:

<STX><19><,><ETX>

#### Example:

<STX><19>,<ETX>

## Response:

<STX><19><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><ARG8><,><ARG9><,><ETX>

#### Where:

ARGx = 0 - 4095

## Example:

# 5.5.10 Request Analog Readbacks – J5

# Description:

The host requests that the firmware transmit the present values of Analog Channels 0 through 6, which are available via connector J5.

# Direction:

Host to supply

# Syntax:

<STX><20><,><ETX>

#### Example:

<STX>20,<ETX>

# Response:

<STX><20><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><ETX>

#### Where:

ARGx = 0 - 4095

## Example:

<STX>20,4095,4095,4095,4095,4095,4095,4095,<ETX>

# 5.5.11 Request Total Hours High Voltage On

# **Description:**

The host requests that the firmware sends the present value of the Total Hours High Voltage On.

# Direction:

Host to supply

# Syntax:

<STX><21><,><ETX>

## Example:

<STX>21,<ETX>

## Response:

<STX><21><,><ARG1>< ARG2>< ARG3><ARG4><ARG5><.><ARG6><,><ETX>

#### Where:

<.> = ASCII 0x2E

ARGx =0-9 in ASCII format

# Example:

<STX>21,99999.9,<ETX>

# 5.5.12 Request Status

# **Description:**

The host requests that the firmware sends the power supply status.

# **Direction:**

Host to supply

#### Syntax:

<STX><22><,><ETX>

#### Example:

<STX>22,<ETX>

## Response:

<\$TX><22><,><ARG1><,><ARG2><,><ARG3><,><ETX>

#### Where:

<ARG1> 1 = HvOn, 0 = HvOff

<ARG2> 1 = Interlock 1 Open, 0 = Interlock 1 Closed

<ARG3> 1 = Fault Condition, 0 = No Fault

#### Example:

<STX>22,1,1,0,<ETX>

NOTE: This response will also be sent in an unsolicited manner when a change of state is detected on the HvOn and Interlock 1 bits. This is providing that a valid handle has already been established with a host.

# 5.5.13 Request DSP Software Part Number/Version

# **Description:**

The host requests that the firmware sends the DSP firmware version.

# **Direction:**

Host to supply

## Syntax:

<STX><23><,><ETX>

## Example:

<STX>23,<STX>

## Response:

<STX><23><,>< ARG><,><ETX>

# Where:

<ARG> consists of eleven ASCII characters representing the current firmware part number/version. The format is SWM9999-999

#### Example:

<STX>23,SWM9999-999,<ETX>

# 5.5.14 Request Hardware Version

# Description:

The host requests that the firmware sends the hardware version.

# **Direction:**

Host to supply

# Syntax:

<STX><24><,><ETX>

## Example:

<STX>24,<ETX>

## Response:

<STX><24><,>< ARG><,><ETX>

#### Where:

<ARG> consists of 3 ASCII characters representing the hardware version.
The format is ANN, where A is an alpha character and N is a numeric character

# Example:

<STX>24,A01,<ETX>

# 5.5.15 Request Webserver Software Part Number/Version

# Description:

The host requests that the firmware sends the Web Server firmware part number/version.

# Direction:

Host to supply

# Syntax:

<STX><25><,><ETX>

#### Example:

<STX>25,<ETX>

## Response:

<STX><25><,><ARG><,><ETX>

#### Where:

<ARG> consists of eleven ASCII characters representing the current firmware part number/version. The format is SWM9999-999

# Example:

<STX>25,SWM9999-999,<ETX>

# 5.5.16 Request Model Number

## Description:

The host requests that the firmware sends the unit model number

# **Direction:**

Host to supply

## Syntax:

<STX><26><,><ETX>

## Example:

<STX>26,<ETX>

## Response:

<STX><26><,><ARG><,><ETX>

## Where:

<ARG> consists of five ASCII characters representing the model number. The format is XNNNN, where N is a numeric character.

#### Example:

<STX>25,X9999,<ETX>

# 5.5.17 Reset Run Hours

# **Description:**

The host requests that the firmware resets the run hour counter.

# **Direction:**

Host to supply

# Syntax:

<STX><30><,><ETX>

# Example:

<STX>30,<ETX>

# Response:

<STX><30><,><\$><,><ETX>

# 5.5.18 Reset Faults

# Description:

The host requests that the firmware resets all Fault messages and indicators.

# **Direction:**

Host to supply

# Syntax:

<STX><31><,><ETX>

# Example:

<STX>31,<ETX>

# Response:

<STX><31><,><\$><,><ETX>

# 5.5.19 Request Network Settings

# **Description:**

The host requests that the firmware transmits the network settings

# **Application:**

	ARG 1	ARG2	ARG3	ARG4	ARG5	ARG6
Function	Device	Remote	Remote	Subnet	Default	MAC
	Name	Address	Port	Mask	Gateway	Address

## rection:

Host to supply

## Syntax:

<STX><50><,><ETX>

#### Example:

<STX>50,<ETX>

# Response:

<STX><50><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ETX>

#### Arguments:

Device Name is limited to 20 characters or less. Remote address is a ip address in dotted notation. Remote port is a decimal number. Subnet Mask and Default Gateway are also dotted notation and MAC address is in MAC Address notation.

ARG1: Device Name	1 character minimum, up to 20 maximum
ARG2: IP Address	<nnn>&lt;.&gt;<nnn>&lt;.&gt;<nnn>, where</nnn></nnn></nnn>
	<nnn> represents a number from 0 to 255.</nnn>
ARG3: Remote Port	5001 or from 49152 to 65535.
ARG4: Subnet Mask	<xxx>&lt;.&gt;<xxx>&lt;.&gt;<xxx>, where</xxx></xxx></xxx>
	<xxx> represents a number from 0 to 255.</xxx>
ARG5: Default Gateway	<yyy>&lt;.&gt;<yyy>&lt;.&gt;<yyy>, where</yyy></yyy></yyy>
	<yyy> represents a number from 0 to 255.</yyy>
ARG6: MACAddress	<zzz>&lt;:&gt;<zzz>&lt;:&gt;<zzz></zzz></zzz></zzz>
	<:> <zzz> , where <zzz> represents a number</zzz></zzz>
	from 0 to 255.

## Example:

<STX>50,Spellman2.0,32.78.110.37,1026,255.0.0.0,192.168.1.1,0:100:33 :1:32:84,<ETX>

# 5.5.20 Program Network Settings

# **Description:**

The host requests that the firmware programs the network settings and then reboots.

# Application:

	ARG 1	ARG2	ARG3	ARG4	ARG5	ARG6
Function	Device	Remote	Remote	Subnet	Default	MAC
	Name	Address	Port	Mask	Gateway	Address

# **Direction:**

Host to supply

#### Syntax:

<STX><51><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ETX>

#### Arguments:

Device Name is limited to 20 characters or less. Remote address is a ip address in dotted notation. Remote port is a decimal number. Subnet Mask and Default Gateway are also dotted notation and MAC address is in MAC Address notation.

ARG1: Device Name ARG2: IP Address	1 character minimum, up to 20 maximum <nnn>&lt;.&gt;<nnn>&lt;.&gt;<nnn>, where <nnn> represents a number from 0 to 255.</nnn></nnn></nnn></nnn>
ARG3: Remote Port	5001 or from 49152 to 65535.
ARG4: Subnet Mask	<xxx>&lt;.&gt;<xxx>&lt;.&gt;<xxx>, where</xxx></xxx></xxx>
	<xxx> represents a number from 0 to 255.</xxx>
ARG5: Default Gateway	<yyy>&lt;.&gt;<yyy>&lt;.&gt;<yyy>, where</yyy></yyy></yyy>
	<yyy> represents a number from 0 to 255.</yyy>
ARG6: MACAddress	<zzz>&lt;:&gt;<zzz>&lt;:&gt;<zzz></zzz></zzz></zzz>
	<:> <zzz> , where <zzz> represents a number</zzz></zzz>
	from 0 to 255.

#### Example:

<\$TX>51,\$pellman2.0,32.78.110.37,1026,255.0.0.0,192.168.1.1,0:100:33 :1:32:84,<ETX>

#### Response:

None, as Embedded server reboots with new settings.

# 5.5.21 Program Interlock State

# **Description:**

The host requests that the firmware Program the state of a specific Interlock Channel.

# Direction:

Host to supply

## Syntax:

<STX><CH><,><ARG><,><ETX>

Where CH is the command for a specific Interlock Channel, and ARG is a 1 or a 0 to set or clear the interlock.

Channel Number	Command
Interlock 1:	52
Interlock 2:	53
Interlock 3:	54

## Response:

<STX><CH><,><\$><,><ETX>

# Example:

<STX>52,1,<ETX>

Where 1 signifies that interlock channel 1 has been energized.

# 5.5.22 Read Interlock Status

# **Description:**

The host requests that the firmware read the status of all interlock channels.

# Direction:

Host to supply

# Syntax:

<STX><55><,><ETX>

## Response:

<STX><55><,><ARG1><,><ARG2><,><ARG3><,><ETX> Where ARG1 through ARG3 are Interlocks 1 through 3. A 1 indicates that the Interlock is energized

# Example:

<STX>55,<ETX>

## 5.5.23 Readback A/D Channel Data

# Description:

The host requests that the firmware report data from a specific Analog Channel.

# Direction:

Host to supply

# Syntax:

<STX><CH><,><ETX>

Where CH is the command representing a specific A/D Channel:

Channel Number	Command	Channel Number	Command
Channel 0:	60	Channel 8:	68
Channel 1:	61	Channel 9:	69
Channel 2:	62	Channel 10:	70
Channel 3:	63	Channel 11:	71
Channel 4:	64	Channel 12:	72
Channel 5:	65	Channel 13:	73
Channel 6:	66	Channel 14:	74
Channel 7:	67	Channel 15:	75

# Response:

<STX><CH><,><ARG><,><ETX>

## Where:

<ARG>=0-4095 in ASCII format representing unscaled A/D Channel data.

## Example:

<STX>68,4095,<ETX>

## Note:

Channel 0 is the Ambient Temperature Monitor and Channel 1 is the S.I.C. Board Power Supply Monitor.

# 5.5.24 Read Digital Input Status

# **Description:**

The host requests that the firmware report the current status of the digital inputs.

# Direction:

Host to supply

# Syntax:

<STX><76><,><ETX>

#### Response:

<STX><76><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><ARG8><,><ETX>

## Where:

<ARGn> = ASCII Characters 1 or 0 (0x31 or 0x30) representing Digital Input Channel data. Digital Input Channel 1 is represented by ARG1.

# Example:

<STX>76,1,1,1,1,1,1,1,1,<ETX>

Where all input channels are detecting binary 1s.

# 5.5.25 Program a Digital Output Channel

# Description:

The host requests that the firmware SET or CLEAR a Digital Output Channel.

# Direction:

Host to supply

## Syntax:

<STX><CH><,><ARG><,><ETX>

Where CH is the command for a specific Digital Output Channel, and ARG is a 1 or a 0 to set or clear the output.

Channel Number	Command
Channel 1:	84
Channel 2:	85
Channel 3:	86
Channel 4:	87
Channel 5:	88

## Response:

<STX><CH><,><\$><,><ETX>

## Example:

<STX>86,1,<ETX>

The above command sets output channel 3 to 1.

# 5.5.26 Read Digital Output Settings

# Description:

The host requests that the firmware report the current status of the digital outputs.

# Direction:

Host to supply

#### Syntax:

<STX><89><,><ETX>

#### Response:

<STX><89><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5> <,><ETX>

#### Where:

<ARGn> = ASCII Characters 1 or 0 (0x31 or 0x30) representing Digital Input Channel data. Digital Output Channel 1 is represented by ARG1.

# Example:

<STX>89,1,1,1,1,1,<ETX>

Where all output channels are set to 1s.

# 5.5.27 Toggle Verbose Mode

# Description:

The host requests that the firmware provide or cease continuous data updates via the current communications channel. Transmit this command to begin the transmission of data, transmit again to stop transmission.

### Direction:

Host to supply

# Syntax:

<STX><92><,><ETX>

#### Response:

<STX><92><,><\$><,><ETX>

# Example:

<STX>92,<ETX>

# 5.5.28 Program High Voltage On/Off

# Description:

The host requests that the firmware to turn on or off High Voltage.

# Direction:

Host to supply

# Syntax:

<STX><99><,><ARG><,><ETX>

#### Where:

<ARG> 1 = On, 0 = Off in ASCII format

# Example:

<STX>99,1,<ETX>

#### Response:

<STX><99><,><\$><,><ETX>< <STX><99><,><ARG><,><ETX>

where <ARG> = error code

Error Codes TBD,

1 = out of range

2 = Interlock 1 open, High Voltage Disabled

#### **6.0** SERIAL COMMANDS - RS-232 / USB SERIAL INTERFACE PROTOCOL 6.1

Serial communications will use the following protocol:

Where:

<STX> = 1 ASCII 0x02 Start of Text character

<CMD> = 2 ASCII characters representing the command ID

= 1 ASCII 0x2C character <,> <ARG> = Command Argument = 1 ASCII 0x2C character <.>

<CSUM> = Checksum (see section 6.3 for details) <ETX> = 1 ASCII 0x03 End of Text character

#### 6.2 **COMMAND ARGUMENTS**

The format of the numbers is a variable length string. To represent the number 42, the string '42', '042', or '0042' can be used. This being the case, commands and responses that carry data are variable in length.

#### 6.3 **CHECKSUMS**

The checksum is computed as follows:

- Add the <CMD>, <,>, and <ARG> bytes into a 16 bit (or larger) word. The bytes are added as unsigned integers.
- Take the 2's compliment (negate it).
- Truncate the result down to the eight least significant bits.
- Clear the most significant bit (bit 7) of the resultant byte, (bitwise AND with 0x7F).
- Set the next most significant bit (bit 6) of the resultant byte (bitwise OR with 0x40).

Using this method, the checksum is always a number between 0x40 and 0x7F. The checksum can never be confused with the <STX> or <ETX> control characters, since these have non-overlapping ASCII values.

If the DSP detects a checksum error, the received message is ignored – no acknowledge or data is sent back to the host. A timeout will act as an implied NACK.

The following is sample code, written in Visual Basic, for the generation of checksums:

Public Function ProcessOutputString(outputString As String) As String

```
Dim i As Integer
Dim CSb1 As Integer
Dim CSb2 As Integer
Dim CSb3 As Integer
Dim CSb$
Dim X
X = 0
For i = 1 To (Len(outputString))
                               'Starting with the CMD character
  X = X + Asc(Mid(outputString, i, 1)) 'adds ascii values together
Next i
CSb1 = 256 - X
                           'Twos Complement
CSb2 = 63 \text{ And } (CSb1)
                          'OR 0x40
CSb3 = 64 Or (CSb2)
CSb$ = Chr(Val("&H" & (Hex(CSb3))))
ProcessOutputString = Chr(2) & outputString & CSb$ & Chr(3)
```

**End Function** 

USA EUROPE JAPAN MEXICO

# 6.3 COMMAND OVERVIEW

Program DAC 10 1-4 ASCII 0-409 Channel A Program DAC 11 1-4 ASCII 0-409 Channel B Program DAC 12 1-4 ASCII 0-409 Channel D Program DAC 13 1-4 ASCII 0-409 Channel C	95 95
Program DAC 11 1-4 ASCII 0-409 Channel B Program DAC 12 1-4 ASCII 0-409 Channel D Program DAC 13 1-4 ASCII 0-409 Channel C	95
Channel B Program DAC Channel D Program DAC Channel C  12 1-4 ASCII 0-409 13 1-4 ASCII 0-409	95
Program DAC 12 1-4 ASCII 0-409 Channel D Program DAC 13 1-4 ASCII 0-409 Channel C	
Channel D Program DAC Channel C 13 1-4 ASCII 0-409	
Program DAC 13 1-4 ASCII 0-409 Channel C	95
Channel C	95
Request DAC A 14 None -	
Request DAC A 14 None - Setpoint	
Request DAC B 15 None -	
Setpoint	
Request DAC D 16 None -	
Setpoint	
Request DAC C 17 None -	
Setpoint	
Request Analog 19 None -	
Readbacks – J6	
Channels 7 – 15	
Request Analog 20 None -	
Readbacks – J5	
Channels 0 – 6	
Request HV On 21 None - Hours Counter -	
Request Status 22 None -	
Nequest Status 22 Notic -	
Request Software 23 None -	
Version	
Request Hardware 24 None -	
Version	
Request Web 25 None -	
Server Version	
Request Model 26 None -	
Number	
Reset HV On 30 None -	
Hours Counter	
Reset Faults 31 None -	1
Program Interlock 52 1 ASCII 0 or 1	1
Program Interlock 53 1 ASCII 0 or	1
2	

Program Interlock	54	1 ASCII	0 or 1
3			
Read Interlock	55	None	-
Status			
Readback A/D	60	None	-
Channel 0 Data			
Readback A/D	61	None	-
Channel 1 Data			
Readback A/D	62	None	-
Channel 2 Data			
Readback A/D	63	None	-
Channel 3 Data			
Readback A/D	64	None	-
Channel 4 Data			
Readback A/D	65	None	-
Channel 5 Data			
Readback A/D	66	None	-
Channel 6 Data			
Readback A/D	67	None	-
Channel 7 Data			
Readback A/D	68	None	-
Channel 8 Data			
Readback A/D	69	None	-
Channel 9 Data			
Readback A/D	70	None	-
Channel 10 Data			
Readback A/D	71	None	-
Channel 11 Data			
Readback A/D	72	None	-
Channel 12 Data			
Readback A/D	73	None	-
Channel 13 Data			
Readback A/D	74	None	-
Channel 14 Data			
Readback A/D	75	None	-
Channel 15 Data			
Read Digital Inputs	76	None	-
Program Digital	84	1 ASCII	0 or 1
Output Channel 1			
Program Digital	85	1 ASCII	0 or 1
Output Channel 2			
Program Digital	86	1 ASCII	0 or 1
Output Channel 3			
Program Digital	87	1 ASCII	0 or 1

Output Channel 4			
Program Digital	88	1 ASCII	0 or 1
Output Channel 5			
Toggle Verbose	92	None	-
Mode			
Program High	99	1 ASCII	0 or 1
Voltage Status			

#### 6.5 RESPONSE OVERVIEW

The command responses will follow the same format as outlined above in section 6.1. This list is comprised of Commands with complex responses only. Commands using a simple response will use the <\$> character (ASCII 0x24) as a "Success" response or a single character error code. These responses will be eight ASCII characters in length.

Response Name	<cmd></cmd>	Response
Request DAC A Setpoint	14	11 ASCII
Request DAC B Setpoint	15	11 ASCII
Request DAC D Setpoint	16	11 ASCII
Request DAC C Setpoint	17	11 ASCII
Request Analog Readbacks – J6	19	24-51 ASCII
Request Analog Readbacks – J5	20	20-41 ASCII
Request Total Hours High Voltage On	21	14 ASCII
Request Status	22	12 ASCII
Request DSP Software Version	23	18 ASCII
Request Hardware Version	24	10 ASCII
Request Web Server Version	25	18 ASCII
Request Model number	26	12 ASCII
Read Interlock Status	55	12 ASCII

Readback A/D	60	8-11
Channel 0 Data		ASCII
Readback A/D	61	8-11
Channel 1 Data		ASCII
Readback A/D	62	8-11
Channel 2 Data		ASCII
Readback A/D	63	8-11
Channel 3 Data	0.4	ASCII
Readback A/D	64	8-11
Channel 4 Data	0=	ASCII
Readback A/D	65	8-11
Channel 5 Data	00	ASCII
Readback A/D	66	8-11
Channel 6 Data	0=	ASCII
Readback A/D	67	8-11
Channel 7 Data	00	ASCII
Readback A/D	68	8-11
Channel 8 Data	00	ASCII
Readback A/D	69	8-11
Channel 9 Data	70	ASCII
Readback A/D	70	8-11
Channel 10 Data	74	ASCII
Readback A/D	71	8-11
Channel 11 Data	70	ASCII
Readback A/D	72	8-11
Channel 12 Data	70	ASCII
Readback A/D	73	8-11 ACCII
Channel 13 Data	74	ASCII
Readback A/D	74	8-11 ACCII
Channel 14 Data	75	ASCII
Readback A/D	75	8-11
Channel 15 Data	70	ASCII
Read Digital Inputs	76	9 ASCII
Read Digital	89	9 ASCII
Output Settings		
Program High	99	8 ASCII
Voltage Status		
-		

#### 6.6 COMMAND STRUCTURE

# 6.6.1 Program DAC Channel A

### **Description:**

The host requests that the firmware change the setpoint of DAC Channel A.

# **Direction:**

Host to supply

#### Syntax:

<STX><10><,><ARG><,><CSUM><ETX>

#### Where:

 $\langle ARG \rangle = 0 - 4095$  in ASCII format

# Example:

<STX>10,4095,<CSUM><ETX>

#### Response:

<STX><10><,><\$><,><CSUM><ETX>< <STX><10><,><ARG><,><CSUM><ETX>

where <ARG> = error code

Error Codes TBD, 1=out of range

# 6.6.2 Program DAC Channel B

# **Description:**

The host requests that the firmware change the setpoint of DAC Channel B.

# Direction:

Host to supply

#### Syntax:

<STX><11><,><ARG><,><CSUM><ETX>

### Where:

<ARG> = 0 - 4095 in ASCII format

#### Example:

<STX>11,4095,<CSUM><ETX>

#### Response:

<STX><11><,><\$><,><CSUM><ETX><STX><11><,><ARG><,><CSUM><ETX>

where <ARG> = error code

Error Codes TBD, 1=out of range

# 6.6.3 Program DAC Channel D

# **Description:**

The host requests that the firmware change the setpoint of DAC Channel D.

# Direction:

Host to supply

# Syntax:

<STX><12><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

#### Example:

<STX>12,4095,<CSUM><ETX>

#### Response:

<STX><12><,><\$><,><CSUM><ETX><STX><12><,><ARG><,><CSUM><ETX>

where <ARG> = error code

Error Codes TBD, 1 = out of range

# 6.6.4 Program DAC Channel C

# **Description:**

The host requests that the firmware change the setpoint of DAC Channel C.

# Direction:

Host to supply

### Syntax:

<STX><13><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

#### Example:

<STX>13,4095,<CSUM><ETX>

#### Response:

<STX><13><,><\$><,><CSUM><ETX><STX><13><,><ARG><,><CSUM><ETX>

where <ARG> = error code

Error Codes TBD, 1 = out of range

# 6.6.5 Request DAC A Setpoint

# **Description:**

The host requests that the firmware report the DAC Channel A setpoint.

# Direction:

Host to supply

# Syntax:

<STX><14><,><CSUM><ETX>

# Response:

<STX><14><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>14,4095,<CSUM><ETX>

# 6.6.6 Request DAC B Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel B setpoint.

# Direction:

Host to supply

# Syntax:

<STX><15><,><CSUM><ETX>

# Response:

<STX><15><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>15,4095,<CSUM><ETX>

# 6.6.7 Request DAC D Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel D setpoint.

# Direction:

Host to supply

# Syntax:

<STX><16><,><CSUM><ETX>

# Response:

<STX><16><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>16,4095,<CSUM><ETX>

# 6.6.8 Request DAC C Setpoint

# **Description:**

The host requests that the firmware report the current DAC Channel C setpoint.

# Direction:

Host to supply

# Syntax:

<STX><17><,><CSUM><ETX>

# Response:

<STX><17><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> = 0 - 4095 in ASCII format

# Example:

<STX>17,4095,<CSUM><ETX>

# 6.6.9 Request Analog Readbacks – J6

# Description:

The host requests that the firmware transmit the present values of Analog Channels 7 through 15, which are available via connector J6.

# Direction:

Host to supply

#### Syntax:

<STX><19><,><CSUM><ETX>

#### Example:

<STX>19,<CSUM><ETX>

#### Response:

<STX><19><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><ARG8><,><ARG9><,><CSUM><ET X>

# Where:

ARGx = 0 - 4095

# Example:

<STX>19,4095,4095,4095,4095,4095,4095,4095, 4095, 4095, <CSUM><ETX>

# 6.6.10 Request Analog Readbacks - J5

# **Description:**

The host requests that the firmware transmit the present values of Analog Channels 0 through 6, which are available via connector J5.

# Direction:

Host to supply

# Syntax:

<STX><20><,><CSUM><ETX>

#### Example:

<STX>20,<CSUM><ETX>

# Response:

<STX><20><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><CSUM><ETX>

#### Where:

ARGx = 0 - 4095

#### Example:

<STX>20,4095,4095,4095,4095,4095,4095,4095,<CSUM><ETX>

# 6.6.11 Request Total Hours High Voltage On

# **Description:**

The host requests that the firmware sends the present value of the Total Hours High Voltage On.

### Direction:

Host to supply

# Syntax:

<STX><21><,><CSUM><ETX>

#### Example:

<STX>21,<CSUM><ETX>

#### Response:

<STX><21><,><ARG1>< ARG2>< ARG3><ARG4><ARG5><.><ARG6><,><CSUM><ETX>

#### Where:

<.> = ASCII 0x2E ARGx = 0 - 9 in ASCII format

# Example:

<STX>21,99999.9,<CSUM><ETX>

# 6.6.12 Request Status

#### Description:

The host requests that the firmware sends the power supply status.

### **Direction:**

Host to supply

#### Syntax:

<STX><22><,><CSUM><ETX>

#### Example:

<STX>22,<CSUM><ETX>

#### Response:

<STX><22><,><ARG1><,><ARG2><,><ARG3><,><CSUM><ETX>

#### Where:

<ARG1> 1 = HvOn, 0 = HvOff

<ARG2> 1 = Interlock 1 Open, 0 = Interlock 1 Closed

<ARG3> 1 = Fault Condition, 0 = No Fault

#### Example:

<STX>22,1,1,<CSUM><ETX>

NOTE: This response will also be sent in an unsolicited manner when a change of state is detected on the HvOn and Interlock 1 bits.

# 6.6.13 Request DSP Software Part Number/Version

# Description:

The host requests that the firmware sends the DSP firmware version.

# **Direction:**

Host to supply

#### Syntax:

<STX><23><,><CSUM><ETX>

### Example:

<STX>23,<CSUM><STX>

#### Response:

<STX><23><,>< ARG><,><CSUM><ETX>

# Where:

<ARG> consists of eleven ASCII characters representing the current firmware part number/version. The format is SWM9999-999

### Example:

<STX>23,SWM9999-999,<CSUM><ETX>

# 6.6.14 Request Hardware Version

# Description:

The host requests that the firmware sends the hardware version.

# **Direction:**

Host to supply

# Syntax:

<STX><24><,><CSUM><ETX>

#### Example:

<STX>24,<CSUM><ETX>

#### Response:

<STX><24><,>< ARG><,><CSUM><ETX>

#### Where:

<ARG> consists of 3 ASCII characters representing the hardware version.
The format is ANN, where A is an alpha character and N is a numeric character

# Example:

<STX>24,A01,<CSUM><ETX>

# 6.6.15 Request Webserver Software Part Number/Version

# **Description:**

The host requests that the firmware sends the Web Server firmware part number/version.

#### Direction:

Host to supply

# Syntax:

<STX><25><,><CSUM><ETX>

#### Example:

<STX>25,<CSUM><ETX>

#### Response:

<STX><25><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> consists of eleven ASCII characters representing the current firmware part number/version. The format is SWM9999-999

#### Example:

<STX>25,SWM9999-999,<CSUM><ETX>

# 6.6.16 Request Model Number

### Description:

The host requests that the firmware sends the unit model number

# **Direction:**

Host to supply

#### Syntax:

<STX><26><,><CSUM><ETX>

### Example:

<STX>26,<CSUM><ETX>

#### Response:

<STX><26><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> consists of five ASCII characters representing the model number. The format is XNNNN, where N is a numeric character.

### Example:

<STX>25,X9999,<CSUM><ETX>

# 6.6.17 Reset Run Hours

# **Description:**

The host requests that the firmware resets the run hour counter.

# **Direction:**

Host to supply

# Syntax:

<STX><30><,><CSUM><ETX>

# Example:

<STX>30,<CSUM><ETX>

# Response:

<STX><30><,><\$><,><CSUM><ETX>

# 6.6.18 Reset Faults

# **Description:**

The host requests that the firmware resets all Fault messages and indicators.

# Direction:

Host to supply

# Syntax:

<STX><31><,><CSUM><ETX>

# Example:

<STX>31,<CSUM><ETX>

# Response:

<STX><31><,><\$><,><CSUM><ETX>

# 6.6.19 Program Interlock State

# **Description:**

The host requests that the firmware Program the state of a specific Interlock Channel.

# Direction:

Host to supply

# Syntax:

<STX><CH><,><ARG><,><CSUM><ETX>

Where CH is the command for a specific Interlock Channel, and ARG is a 1 or a 0 to set or clear the interlock.

Channel Number	Command
Interlock 1:	52
Interlock 2:	53
Interlock 3:	54

#### Response:

<STX><CH><,><\$><,><CSUM><ETX>

# Example:

<STX>52,1,<CSUM><ETX>

Where 1 signifies that interlock channel 1 has been energized.

#### 6.6.20 Read Interlock Status

# **Description:**

The host requests that the firmware read the status of all interlock channels.

### Direction:

Host to supply

# Syntax:

<STX><55><,><CSUM><ETX>

#### Response:

<STX><55><,><ARG1><,><ARG2><,><ARG3><,><CSUM><ETX>Where ARG1 through ARG3 are Interlocks 1 through 3. A 1 indicates that the Interlock is energized

# Example:

<STX>55,<CSUM><ETX>

#### 6.6.21 Readback A/D Channel Data

# **Description:**

The host requests that the firmware report data from a specific Analog Channel.

# Direction:

Host to supply

#### Syntax:

<STX><CH><,><CSUM><ETX>

Where CH is the command representing a specific A/D Channel:

Channel Number	Command	Channel Number	Command
Channel 0:	60	Channel 8:	68
Channel 1:	61	Channel 9:	69
Channel 2:	62	Channel 10:	70
Channel 3:	63	Channel 11:	71
Channel 4:	64	Channel 12:	72
Channel 5:	65	Channel 13:	73
Channel 6:	66	Channel 14:	74
Channel 7:	67	Channel 15:	75

# Response:

<STX><CH><,><ARG><,><CSUM><ETX>

#### Where:

<ARG>=0-4095 in ASCII format representing unscaled A/D Channel data.

# Example:

<STX>68,4095,<CSUM><ETX>

#### Note:

Channel 0 is the Ambient Temperature Monitor and Channel 1 is the S.I.C. Board Power Supply Monitor.

# 6.6.22 Read Digital Input Status

# **Description:**

The host requests that the firmware report the current status of the digital inputs.

### Direction:

Host to supply

#### Syntax:

<STX><76><,><CSUM><ETX>

#### Response:

<STX><76><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><ARG6><,><ARG7><,><ARG8><,><CSUM><ETX>

#### Where:

<ARGn> = ASCII Characters 1 or 0 (0x31 or 0x30) representing Digital Input Channel data. Digital Input Channel 1 is represented by ARG1

# Example:

<STX>76,1,1,1,1,1,1,1,<CSUM><ETX>

Where all input channels are detecting binary 1s.

# 6.6.23 Program a Digital Output Channel

# Description:

The host requests that the firmware SET or CLEAR a Digital Output Channel.

### Direction:

Host to supply

#### Syntax:

<STX><CH><,><ARG><,><CSUM><ETX>

Where CH is the command for a specific Digital Output Channel, and ARG is a 1 or a 0 to set or clear the output.

Channel Number	Command
Channel 1:	84
Channel 2:	85
Channel 3:	86
Channel 4:	87
Channel 5:	88

#### Response:

<STX><CH><,><\$><,><CSUM><ETX>

#### Example:

<STX>86,1,<CSUM><ETX>

The above command sets output channel 3 to 1.

# 6.6.24 Read Digital Output Settings

# **Description:**

The host requests that the firmware report the current status of the digital outputs.

# Direction:

Host to supply

# Syntax:

<STX><89><,><CSUM><ETX>

# Response:

<STX><89><,><ARG1><,><ARG2><,><ARG3><,><ARG4><,><ARG5><,><CSUM><ETX>

#### Where:

<ARGn> = ASCII Characters 1 or 0 (0x31 or 0x30) representing Digital Input Channel data. Digital Output Channel 1 is represented by ARG1.

# Example:

<STX>89,1,1,1,1,1,<CSUM><ETX> Where all output channels are set to 1s.

# 6.6.25 Toggle Verbose Mode

# **Description:**

The host requests that the firmware provide or cease continuous data updates via the current communications channel. Transmit this command to begin the transmission of data, transmit again to stop transmission.

#### Direction:

Host to supply

# Syntax:

<STX><92><,><CSUM><ETX>

#### Response:

<STX><92><,><\$><,><CSUM><ETX>

# Example:

<STX>92,<CSUM><ETX>

# 6.6.26 Program High Voltage On/Off

### **Description:**

The host requests that the firmware to turn on or off High Voltage.

#### Direction:

Host to supply

# Syntax:

<STX><99><,><ARG><,><CSUM><ETX>

#### Where:

<ARG> 1 = On, 0 = Off in ASCII format

#### Example:

<STX>99,1,<CSUM><ETX>

#### Response:

<STX><99><,><\$><,><CSUM><ETX><STX><99><,><ARG><,><CSUM><ETX>

where <ARG> = error code

Error Codes TBD.

- 1 = out of range
- 2 = Interlock 1 open, High Voltage Disabled
- 3 = Mode mismatch, eg. User command remote mode but hardware is still in local mode control.

#### 6.7 SPELLMAN TEST COMMANDS

- Program Hardware Version (Hardware setup)
- Set USB Mode (Program USB)
- Set USB Page Address (Program USB)
- Send USB Page Data (Program USB)
- Toggle Passthrough Mode (Diagnostics)
- Store A/D Calibration Value (Hardware setup)

Contact Spellman High Voltage for details and the syntax of these commands.

#### 6.8 SERIAL COMMAND HANDLING

#### 6.8.1 Command Time Out

The host computer should set a serial time out at approximately 100mS. This allows the DSP to process the incoming message, and transmit a response. The DSP will initiate a reply to incoming messages in approximately 1-2mS, with a worst case of 5mS.

### 6.8.2 Buffer Flushing

The DSP will flush the incoming serial data buffer every time an STX is received. This provides a mechanism to clear the receive buffer of partial or corrupt messages.

#### 6.8.3 Handshaking

The only handshaking implemented on the host interface, is built in to the implementation of this protocol. That is, the host must initiate all communications. If the supply receives a program command, an acknowledge message is sent back to the host via the "\$" message. If the host does not receive an acknowledge within the time out window, the host should consider the message lost or the device off-line.

Similarly, if the supply receives a request command, the requested data is sent back to the host. If the host does not receive the requested data within the time out window, the host should consider the message lost or the device off-line.

This essentially uses the full-duplex channel in a half-duplex communication mode.

#### 7.0 S.I.C. Board Resource Utilization Table (SL Product Line Only)

The following table is "generally" how the SIC's resources are applied to various projects and may not specifically address your model. Refer to section 8.0 for specific models.

A/DC Channel	Header	Scaling (LSB	Project Signal Name
	Location	Multiplier)	N/A OLO T
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	Unit KV max/4095	KV Monitor
ANA 3	JB5-8	(Unit mA	mA Monitor
		max/4095)*1000	
ANA 4	JB5-12		N/U
ANA 5	JB5-10		N/U
ANA 6	JB5-2		N/U
ANA 7	JB6-1		N/U
ANA 8	JB6-3		N/U
ANA 9	JB6-2		N/U
ANA 10	JB6-5		N/U
ANA 11	JB6-4		N/U
ANA 12	JB6-7		N/U
ANA 13	JB6-6		N/U
ANA 14	JB6-9		N/U
ANA 15	JB6-8		N/U

Digital to Analog Converter Resources

#### Digital to Analog Converter Resources

DAC Channel	Header	Scaling (LSB	Project Signal Name
	Location	Multiplier)	
Channel A	JB5-1	Unit KV max/4095	KV Program
Channel B	JB5-5	(Unit mA	mA Program
		max/4095)*1000	
Channel C	JB5-3		N/U
Channel D	JB5-4		N/U

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

## Digital Output Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		N/U
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		N/U
OUT 4	JB7-10		N/U
OUT 5	JB7-9		N/U

#### Interlock Resources

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11		RESET
Interlock 1 - NO	JB5-13		
Interlock 1 – COM	JB5-14	Open (Not Engergized)	RESET
Interlock 1 - AUX	JB8-10		
Interlock 2 - NC	JB8-8		HV On 1
Interlock 2 – NO	JB8-6		
Interlock 2 – COM	JB8-7	Open (Not Energized)	HV On 2
Interlock 2 - AUX	JB8-9		
Interlock 3 - NC	JB8-4		HV Off1
Interlock 3 - NO	JB8-2		HV Off2
Interlock 3 - COM	JB8-3	Open (Not Energized)	
Interlock 3 - AUX	JB8-5		

USA EUROPE JAPAN MEXICO

Commands to Send	Generic Command	Comments
Program Voltage	Program DAC Channel A	Command 10
Setpoint		
Program Current Setpoint	Program DAC Channel B	Command 11
Program Filament Current	Not Used	
Setpoint		
Request Voltage	Request Dac A Setpoint	Command 14
Setpoint		
Request Current Setpoint	Request Dac B Setpoint	Command 15
Request Filament Current Setpoint	Not Used	
Request Analog Readbacks	Request Analog Channels – J5	Command 20 Arg1 = Ambient Temp Inside PS Arg2 = internal LVPS 24V Arg3 = KV Mon Arg4 = mA Mon Arg5 = N/U Arg6 = N/U Arg7 = N/U Note* These are raw bit values, which must be scaled.
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State Interlock 1	Command 31
HV ON	Program Interlock State Interlock 2	Command 99,1
HV OFF	Program Interlock State Interlock 3	Command 99,0
Read Digital Input Status		Command 76 Arg1 0 = N/A Arg2 0 = N/A Arg3 1 = Local remote Arg4 0 = Over Voltage Fault Arg5 0 = Over Current Fault Arg6 0 = REG Error Arg7 0 = ARC Error Arg8 0 = Temp Error
Request System Status		Command 22 Arg1 1= HV On Arg2 1= Interlock Open Arg3 1= PS Fault

#### 7.1 Writing a custom Application-

The following is an example of which commands can be sent to the supply, other commands are permissible however this is what Spellman sends via its own Graphical User Interface (GUI).

- Command 85,1 = Enter Remote Mode\*
- Command 20 = Request analog inputs
- Command 22 = Request System Status
- Command 76 = Request Digital Input Status

Note\*- For SL product lines only.

#### 8.0 Product Specific Usage

Note: Commands that differ in nomenclature from the specification will be cross-referenced to their equivalent. Commands that do not differ will simply be listed.

#### 8.1 MNX50P50

Note: Tabular information applies to the Standard Model with the 10 Volt DAC Reference and the X3366 Model with the 5 Volt Reference except as noted.

#### Analog to Digital Converter Resources

A/DC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
ANA 0	N/A	0.0732 V/°C	SIC Temperature Sensor: 10 mV/ Degree C
ANA 1	N/A	10.5 mV	SIC + 24 volt Monitor
ANA 2	JB5-6	12.21 V	$HV_MONITOR: 0-5V = 0-50kV$
ANA 3	JB5-8	586.1 uA	BEAM_CURRENT: 0-5V = 0-2.4
			mA
ANA 4	JB5-12	879 uA	FIL_CURRENT: 1V = 1A
ANA 5	JB5-10	1.343 mV	FIL_VOLTAGE: 5V / 3A
ANA 6	JB5-2	0.0732 V/°C	MULT_TEMP: 10 mV/ Degree C

#### Digital to Analog Converter Resources: 10 Volt Reference (5 Volt Reference)

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	12.21 V	KV_PROG
Channel B	JB5-5	488 uA	MA_PROG
Channel C	JB5-3	2.442 mA (1.221	FIL_LIMIT_PROG
		mA)	
Channel D	JB5-4	2.442 mA (1.221	FIL_PREHEAT
		mA)	

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11		
Interlock 1 - NO	JB5-13		INTRLK_RTN
Interlock 1 – COM	JB5-14	Off	INTRLK
Interlock 1 - AUX	JB8-10		

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 12.21v
Setpoint	-	
Program Emission Current	Program DAC Channel B	LSB = 488 uA
Setpoint		
Program Filament Pre-heat	Program DAC Channel D	LSB = 1.221 mA (Vref= 5 v)
Setpoint		LSB = 2.442 mA (Vref=10v)
Program Filament Current	Program DAC Channel C	LSB = 1.221 mA (Vref= 5 v)
Limit		LSB = 2.442 mA (Vref=10v)
Request Voltage	Request DAC A Setpoint	LSB = 12.21 v
Setpoint		
Request Emission Current	Request DAC B Setpoint	LSB = 488 uA
Setpoint		
Request Filament Pre-heat	Request DAC D Setpoint	LSB = 1.221 mA (Vref= 5 v)
Setpoint		LSB = 2.442 mA (Vref=10v)
Request Filament Current	Request DAC C Setpoint	LSB = 1.221 mA (Vref= 5 v)
Limit		LSB = 2.442 mA (Vref=10v)
Request Analog Readbacks	Request Analog Channels	Ch 2: LSB = 12.21 V
	– J5	Ch 3: LSB = 586.1 uA
		Ch 4: LSB = 879 uA
		Ch 5: LSB = 1.343mV
	_	Ch 6: LSB = 0.0732°
	Request "HV On" Hours	
	Counter	
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server	
	Version	
	Request Model Number	
	Reset "HV On" Hours	
	Counter	
	Request Network Settings	
	Program Network Settings	
	Program High Voltage	
	Status	

## 8.2 SL80PN1200 (X3442)

## Analog to Digital Converter Resources

A/DC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	39.072 V	HV Monitor
ANA 3	JB5-8	2.44 mA	Emission Current Monitor
ANA 6	JB5-2	0.0732 V/°C	Multiplier Temperature

# Digital to Analog Converter Resources: 10 Volt Reference

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	39.072 V	KV_PROG
Channel B	JB5-5	2.44 mA	MA_PROG
Channel C	JB5-3	.0016 mA	FIL_PRE-HEAT_PROG

## Digital Output Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1	CLEAR	FAULT_RESET

Product Specific Command	Generic Command	Comments
Program Voltage Setpoint	Program DAC Channel A	LSB = 39.072 V
Program Emission Current Setpoint	Program DAC Channel B	LSB = 2.44 mA
Program Filament Pre-heat Setpoint	Program DAC Channel C	LSB = .0016 mA (Vref=10v)
Request Voltage Setpoint	Request DAC A Setpoint	LSB = 39.072 V
Request Emission Current Setpoint	Request DAC B Setpoint	LSB = 2.44 mA
Request Analog Readbacks	Request Analog Channels  – J5	Ch 2: LSB = 39.072 V Ch 3: LSB = 2.44 mA Ch 6: LSB = 0.0732°
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Product Specific Command	Generic Command	Comments
Reset Faults	Program Digital Output	SET = Reset
	Channel 1	CLEAR = Normal
	Request Network Settings	
	Program Network Settings	
	Program High Voltage Status	

## 8.3 XLG130P1200 X3459

## Analog to Digital Converter Resources

A/DC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	31.746 V	HV Monitor
ANA 3	JB5-8	2.44 mA	Emission Current Monitor

## Digital to Analog Converter Resources: 10 Volt Reference

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	31.746 V	KV_PROG
Channel B	JB5-5	2.44 mA	MA_PROG

#### **Digital Input Resources**

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
IN 1	JB7-1	NA	FAULT_N
			(0 = fault)
IN 2	JB7-2	NA	INTERLOCK
			(0 = closed)
IN 3	JB7-3	NA	FILAMENT
			(15V = small, 0 = large)

#### **Digital Ouput Resources**

- 19.10 11			
Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1	CLEAR	FILAMENT SELECT

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 -	JB5-11	State	
Interlock 1 - NO	JB5-13		Ground
Interlock 1 – COM	JB5-14	OPEN (not energized)	RESET FAULT
Interlock 1 - AUX	JB8-10	-	
Interlock 2 – NC	JB8-8		
Interlock 2 – NO	JB8-6		HV ON 2
Interlock 2 – COM	JB8-7	OPEN (not energized)	HV ON 1
Interlock 2 - AUX	JB8-9		
Interlock 3 – NC	JB8-4		HV OFF 2
Interlock 3 – NO	JB8-2		
Interlock 3 – COM	JB8-3	OPEN (not energized)	HV OFF 1
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage Setpoint	Program DAC Channel A	LSB = 31.746 V
Program Emission Current Setpoint	Program DAC Channel B	LSB = 2.44 mA
Request Voltage Setpoint	Request DAC A Setpoint	LSB = 31.746 V
Request Emission Current Setpoint	Request DAC B Setpoint	LSB = 2.44 mA
Request Analog Readbacks	Request Analog Channels  – J5	Ch 2: LSB = 31.746 V Ch 3: LSB = 2.44 mA Ch 6: LSB = 0.0732°
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament Select	Program Digital Output	SET = Small
	Channel 1	CLEAR = Large
	Request Network Settings	
	Program Network Settings	
	Program High Voltage Status	
Reset Fault	Program Interlock State Interlock 1	Pulse Activated (> 1 ms) SET = reset CLEAR = not reset
HV ON	Program Interlock State Interlock 2	Pulse Activated (> 1 ms) SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Request Filament Status	Read Digital Input Status	<arg1> = FAULT <arg2> = INTERLOCK_N <arg3> = FILAMENT_N all other arguments are NA</arg3></arg2></arg1>

## 8.4 XLG80P800 X3461

#### Analog to Digital Converter Resources

A/DC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	19.536 V	HV Monitor
ANA 3	JB5-8	2.44 mA	Emission Current Monitor

## Digital to Analog Converter Resources: 10 Volt Reference

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	19.536 V	KV_PROG
Channel B	JB5-5	2.44 mA	MA_PROG

#### **Digital Input Resources**

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
IN 1	JB7-1	NA	FAULT_N
			(0 = fault)
IN 2	JB7-2	NA	INTERLOCK
			(0 = closed)
IN 3	JB7-3	NA	FILAMENT
			(15V = small, 0 = large)

#### **Digital Ouput Resources**

- 19.10 11			
Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1	CLEAR	FILAMENT SELECT

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11	State	
Interlock 1 - NO	JB5-13		Ground
Interlock 1 – COM	JB5-14	OPEN (not energized)	RESET FAULT
Interlock 1 - AUX	JB8-10		
Interlock 2 – NC	JB8-8		
Interlock 2 – NO	JB8-6		HV ON 2
Interlock 2 – COM	JB8-7	OPEN (not energized)	HV ON 1
Interlock 2 - AUX	JB8-9		
Interlock 3 – NC	JB8-4		HV OFF 2
Interlock 3 – NO	JB8-2		
Interlock 3 – COM	JB8-3	OPEN (not energized)	HV OFF 1
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage Setpoint	Program DAC Channel A	LSB = 19.536 V
Program Emission Current Setpoint	Program DAC Channel B	LSB = 2.44 mA
Request Voltage Setpoint	Request DAC A Setpoint	LSB = 19.536 V
Request Emission Current Setpoint	Request DAC B Setpoint	LSB = 2.44 mA
Request Analog Readbacks	Request Analog Channels  – J5	Ch 2: LSB = 19.536 V Ch 3: LSB = 2.44 mA Ch 6: LSB = 0.0732°
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament Select	Program Digital Output	SET = Small
	Channel 1	CLEAR = Large
	Request Network Settings	
	Program Network Settings	
	Program High Voltage Status	
Reset Fault	Program Interlock State Interlock 1	Pulse Activated (> 1 ms) SET = reset CLEAR = not reset
HV ON	Program Interlock State Interlock 2	Pulse Activated (> 1 ms) SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Request Filament Status	Read Digital Input Status	<arg1> = FAULT <arg2> = INTERLOCK_N <arg3> = FILAMENT_N all other arguments are NA</arg3></arg2></arg1>

## 8.5 SL6PN1200 X3496

#### Analog to Digital Converter Resources

A/DC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	1.4625 V	HV Monitor
ANA 3	JB5-8	0.0488 mA	Emission Current Monitor
ANA 8	JP5-1,JP5-2	0.806 mV	Constant 1.981 Volts
ANA 9	JP4-1,JP4-2	0.806 mV	Constant 0.824 Volts

## Digital to Analog Converter Resources: 10 Volt Reference

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	1.4625 V	KV_PROG
Channel B	JB5-5	0.04884 mA	MA_PROG

#### **Digital Input Resources**

Input Channel	Header Location	Initial Power Up State	Project Signal Name
IN 1	JB7-1	NA	FAULT_N
			(0 = fault @ input to U11)
IN 2	JB7-2	NA	INTERLOCK
			(0 = closed @ input to U11)
IN 3	JB7-3	NA	
IN 4	JB7-4	NA	OVER VOLTAGE
			(1 = Voltage Mode @ input to
			U11)
IN 5	JB7-5	NA	OVER CURRENT
			(0 = HV is On @ input to U11)
IN 6	JB7-6	NA	REG ERROR
			(1 = PS is On @ input to U11)
IN 7	JB7-7	NA	ARC
IN 8	JB7-8	NA	TEMP

## Digital Ouput Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1	CLEAR	NA
OUT 2	JB7-12	CLEAR	LOCAL/REMOTE

Interlock	Header	Initial Power Up	Project Signal Name
Block	Location	State	
Interlock 1 - NC	JB5-11		
Interlock 1 - NO	JB5-13		GROUND
Interlock 1 – COM	JB5-14	OPEN (not energized & connected to JB5- 11 thru relay contact)	RESET_N
Interlock 1 - AUX	JB8-10	,	
Interlock 2 – NC	JB8-8		
Interlock 2 – NO	JB8-6		HV ON 2
Interlock 2 – COM	JB8-7	OPEN (not energized)	HV ON 1
Interlock 2 - AUX	JB8-9		
Interlock 3 – NC	JB8-4		HV OFF 2
Interlock 3 – NO	JB8-2		
Interlock 3 – COM	JB8-3	OPEN (not energized)	HV OFF 1
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage Setpoint	Program DAC Channel A	LSB = 1.4652 V
Program Emission Current Setpoint	Program DAC Channel B	LSB = 0.04884 mA
Request Voltage Setpoint	Request DAC A Setpoint	LSB = 1.4652 V
Request Emission Current Setpoint	Request DAC B Setpoint	LSB = 0.04884 mA
Request Analog Readbacks	Request Analog Channels – J5	Ch 2: LSB = 1.4652 V Ch 3: LSB = 0.04884 mA Ch 6: LSB = 0.0732°
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web	
	Server Version	
	Request Model	
	Number	
	Program Digital Output Channel 1	
Local/Remote Select	Program Digital	SET = Remote
	Output Channel 2	CLEAR = Local
	Request Network Settings	
	Program Network Settings	
	Program High Voltage Status	
Reset Fault	Program Interlock	Pulse Activated (> 1 ms)
	State	SET = reset
10/00/	Interlock 1	CLEAR = not reset
HV ON	Program Interlock	Pulse Activated (> 1 ms)
	State	SET then CLEAR
	Interlock 2	

HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Request Digital Status	Read Digital Input Status	<pre><arg1> = FAULT</arg1></pre>

## 8.6 SR60N6.6 X3480

## Analog to Digital Converter Resources

A/DC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	16.117 V	HV Monitor
ANA 3	JB5-8	0.03223 mA	Emission Current Monitor
ANA 4	JB5-12	0.004029 mA	Filament Current
ANA 8	JP5-1,JP5-2	0.806 mV	Constant 1.981 Volts
ANA 9	JP4-1,JP4-2	0.806 mV	Constant 0.824 Volts

# Digital to Analog Converter Resources: 10 Volt Reference

DAC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
Channel A	JB5-1	14.652 V	KV_PROG
Channel B	JB5-5	0.0293 mA	MA_PROG
Channel C	JB5-3	3.663 mA	FIL_PROG

#### **Digital Input Resources**

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
IN 1	JB7-1	NA	FAULT_N
			(0 = fault @ input to U11)
IN 2	JB7-2	NA	INTERLOCK
			(0 = closed @ input to U11)
IN 3	JB7-3	NA	Current Mode
			(1 = Current Mode @ input to
			U11)
IN 4	JB7-4	NA	Voltage Mode
			(1 = Voltage Mode @ input to
			U11)
IN 5	JB7-5	NA	HV ON
			(0 = HV is On @ input to U11)
IN 6	JB7-6	NA	Power Supply ON
			(1 = PS is On @ input to U11)

# Digital Ouput Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1	CLEAR	FILAMENT_ON
OUT 2	JB7-12	CLEAR	GRID_ON

Interlock	Header	Initial Dower Up	Project Signal Name
		Initial Power Up	Project Signal Name
Block	Location	State	T-5.4
Interlock 1 -	JB5-11		TB1
NC			
Interlock 1 -	JB5-13		PWR_ON1
NO			
Interlock 1 –	JB5-14	OPEN	PWR_ON2
COM		(not energized &	
		connected to JB5-	
		11 thru relay	
		contact)	
Interlock 1 -	JB8-10		
AUX	020 10		
Interlock 2 –	JB8-8		
NC	300-0		
Interlock 2 –	JB8-6		HV ON 2
NO	JD0-0		I TV OIN 2
	IDO 7	ODEN	LIV/ONLA
Interlock 2 –	JB8-7	OPEN	HV ON 1
COM		(not energized)	
Interlock 2 -	JB8-9		
AUX			
Interlock 3 –	JB8-4		HV OFF 2
NC			
Interlock 3 –	JB8-2		
NO			
Interlock 3 –	JB8-3	OPEN	HV OFF 1
COM		(not energized)	
Interlock 3 -	JB8-5	(	
AUX			
AUA			

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 14.652 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = 0.0293 mA
Setpoint		
Program Filament Current	Program DAC Channel C	LSB = 3.663 mA
Setpoint		
Request Voltage	Request DAC A Setpoint	LSB = 14.652 V
Setpoint		
Request Emission Current	Request DAC B Setpoint	LSB = 0.0293 mA
Setpoint		
Request Filament Current	Request DAC C Setpoint	LSB = 3.663 mA
Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = 16.117 V
	J5	Ch 3: LSB = 0.03223 mA
		Ch 4: LSB = 0.004029 mA
		Ch 6: LSB = 0.0732°
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off	Program Digital Output	SET = Filament ON
	Channel 1	CLEAR = Filament OFF
Grid On/Off	Program Digital Output	SET = Grid ON
	Channel 2	CLEAR = Grid OFF
	Request Network Settings	
	Program Network Settings	
	Program High Voltage Status	
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
		CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
		Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = sys fault</arg1>
		<arg2> 1 = interlock open</arg2>
		<arg3> 1 = IMODE</arg3>
		<arg4> 1 = VMODE</arg4>
		<ARG5 $> 0 =$ HV on
		<arg6> 1 = PS on</arg6>
		all other arguments are NA

#### 8.7 **SR80**

A/DC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	, ,
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	19.536	HV Monitor
ANA 3	JB5-8	.01831	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

## Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	19.536	KV Program
Channel B	JB5-5	.01831	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

# Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Current mode (0= Current Mode)
IN 4 – LS, IRQ	JB7-4	Voltage mode (0= Voltage mode)
IN 5 – LS, IRQ	JB7-5	High Voltage On (1= HV On)
IN 6 – LS, IRQ	JB7-6	Power Supply On (0= Power Supply On)
IN 7 – LS, IRQ	JB7-7	Not Used
IN 8 - IRQ	JB7-8	Not Used

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

# **Digital Output Resources**

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12		Not used
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11		
Interlock 1 - NO	JB5-13		Power Supply On
Interlock 1 – COM	JB5-14	Open (Not Engergized)	Power Supply On
Interlock 1 - AUX	JB8-10		
Interlock 2 - NC	JB8-8		
Interlock 2 – NO	JB8-6		HV On 2
Interlock 2 – COM	JB8-7	Open (Not Energized)	HV On 1
Interlock 2 - AUX	JB8-9		
Interlock 3 - NC	JB8-4		
Interlock 3 - NO	JB8-2		HV Off 2
Interlock 3 - COM	JB8-3	Open (Not Energized)	HV Off1
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 19.536 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .018315 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current		
Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = 19.536 V
	J5	Ch 3: LSB = .01831 mA
		Ch 4:
	De avec et Otetere	Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
Filomony On /Off	Request Model Number	Net Head
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
Reset Fault	Interlock 1	SET = reset
	IIILETIOCK I	CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
110 010	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
	criook o	Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = sys fault</arg1>
1 12 4000 2 191181 3 14140		<arg2> 1 = interlock open</arg2>
		<arg3> 1 = IMODE</arg3>
		<arg4> 1 = VMODE</arg4>
		<ARG5 $> 0 = HV on$
		<arg6> 1 = PS on</arg6>
		all other arguments are NA

#### 8.8 SL10PN300

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	2.4420024	HV Monitor
ANA 3	JB5-8	.0007326	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

## Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	2.4420024	KV Program
Channel B	JB5-5	.0007326	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

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# Digital Output Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock	Header	Initial Power Up	Project Signal Name
Block	Location	State	-
Interlock 1 - NC	JB5-11		RESET
Interlock 1 - NO	JB5-13		
Interlock 1 – COM	JB5-14	Open (Not Engergized)	RESET
Interlock 1 - AUX	JB8-10		
Interlock 2 -	JB8-8		
Interlock 2 – NO	JB8-6	Open (Not Energized)	HV On 2
Interlock 2 – COM	JB8-7		HV On 1
Interlock 2 - AUX	JB8-9		
Interlock 3 -	JB8-4		HV Off1
Interlock 3 - NO	JB8-2		
Interlock 3 - COM	JB8-3	Open (Not Energized)	HV Off 2
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 2.4420024 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .0007326 mA
Setpoint	-	
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels – J5	Ch 2: LSB = 2.4420024 V Ch 3: LSB = .0007326 mA Ch 4: Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off	·	Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State Interlock 1	Pulse Activated (> 1 ms) SET = reset CLEAR = not reset
HV ON	Program Interlock State Interlock 2	Pulse Activated (> 1 ms) SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = PS Fault <arg2> 1 = Interlock <arg3> 1 = Auto Remote <arg4> 1 = Over Voltage <arg5> 1 = Over Current <arg6> 1 = REG Error <arg7> 1 = ARC Error <arg8> 1 = OVER TEMP</arg8></arg7></arg6></arg5></arg4></arg3></arg2></arg1>

#### 8.9 **SL50PN30**

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	12.210012	HV Monitor
ANA 3	JB5-8	.00014652	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

# Digital to Analog Converter Resources

DAC Channel	Header	Scaling (LSB	Project Signal Name
	Location	Multiplier)	
Channel A	JB5-1	12.210012	KV Program
Channel B	JB5-5	.00014652	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

# Digital Output Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

I	1	T T
	-	Project Signal Name
Location	State	
JB5-11		RESET
JB5-13		
JB5-14	Open (Not	RESET
	Engergized)	
JB8-10		
JB8-8		
JB8-6	Open (Not	HV On 2
	Energized)	
JB8-7		HV On 1
JB8-9		
JB8-4		HV Off1
JB8-2		
JB8-3	Open (Not	HV Off 2
	Energized)	
JB8-5		
	JB5-11  JB5-13  JB5-14  JB8-10  JB8-8  JB8-6  JB8-7  JB8-9  JB8-9  JB8-4  JB8-2  JB8-3	Location         State           JB5-11         JB5-13           JB5-14         Open (Not Engergized)           JB8-10         Open (Not Energized)           JB8-8         Open (Not Energized)           JB8-7         JB8-9           JB8-9         Open (Not Energized)           JB8-3         Open (Not Energized)

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 12.210012 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .00014652 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels – J5	Ch 2: LSB = 12.210012 V Ch 3: LSB = .00014652 mA Ch 4: Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off	·	Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State Interlock 1	Pulse Activated (> 1 ms) SET = reset CLEAR = not reset
HV ON	Program Interlock State Interlock 2	Pulse Activated (> 1 ms) SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = PS Fault <arg2> 1 = Interlock <arg3> 1 = Auto Remote <arg4> 1 = Over Voltage <arg5> 1 = Over Current <arg6> 1 = REG Error <arg7> 1 = ARC Error <arg8> 1 = OVER TEMP</arg8></arg7></arg6></arg5></arg4></arg3></arg2></arg1>

#### 8.10 SL100P300

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	.02442	HV Monitor
ANA 3	JB5-8	.0007326	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

## Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	.02442	KV Program
Channel B	JB5-5	.0007326	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

# Digital Output Resources

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock	Header	Initial Power Up	Project Signal Name
Block	Location	State	-
Interlock 1 - NC	JB5-11		RESET
Interlock 1 - NO	JB5-13		
Interlock 1 – COM	JB5-14	Open (Not Engergized)	RESET
Interlock 1 - AUX	JB8-10		
Interlock 2 -	JB8-8		
Interlock 2 – NO	JB8-6	Open (Not Energized)	HV On 2
Interlock 2 – COM	JB8-7		HV On 1
Interlock 2 - AUX	JB8-9		
Interlock 3 -	JB8-4		HV Off1
Interlock 3 - NO	JB8-2		
Interlock 3 - COM	JB8-3	Open (Not Energized)	HV Off 2
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = .02442 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .0007326 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = .02442 V
	J5	Ch 3: LSB = .0007326 mA
		Ch 4:
		Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
F"	Request Model Number	N. d. I.
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
LIV ON	Don one or late de als Otata	CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
LIV OFF	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR
	Interiock 3	Note: HV ON must be in
Request Digital Status	Read Digital Input Status	CLEAR state <arg1> 0 = PS Fault</arg1>
Nequest Digital Status	Nead Digital Input Status	<arg1> 0 = P3 Fault <arg2> 1 = Interlock</arg2></arg1>
		<arg2> 1 = Interlock <arg3> 1 = Auto Remote</arg3></arg2>
		<arg3> 1 = Auto Remote <arg4> 1 = Over Voltage</arg4></arg3>
		<arg5> 1 = Over Voltage</arg5>
		<arg6> 1 = Over Current</arg6>
		<arg7> 1 = ARC Error</arg7>
		<arg8> 1 = OVER TEMP</arg8>
		ANOUS I - OVER TEIVIE

#### 8.11 SL30P60

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	7.3260073	HV Monitor
ANA 3	JB5-8	.0004884	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

#### Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	7.3260073	KV Program
Channel B	JB5-5	.0004884	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

USA EUROPE JAPAN MEXICO

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock	Header	Initial Power Up	Project Signal Name
Block	Location	State	
Interlock 1 -	JB5-11		
NC			
Interlock 1 -	JB5-13		
NO			
Interlock 1 –	JB5-14	Open (Not	RESET
COM		Engergized)	
Interlock 1 -	JB8-10		
AUX			
Interlock 2 -	JB8-8		
NC			
Interlock 2 –	JB8-6	Open (Not	HV On 2
NO		Energized)	
Interlock 2 –	JB8-7		HV On 1
COM			
Interlock 2 -	JB8-9		
AUX			
Interlock 3 -	JB8-4		HV Off1
NC			
Interlock 3 -	JB8-2		
NO			
Interlock 3 -	JB8-3	Open (Not	HV Off 2
COM		Energized)	
Interlock 3 -	JB8-5	,	
AUX			

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 7.3260073 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .0004884 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = 7.3260073 V
Troquest Analog Treadbacks	J5	Ch 3: LSB = .0004884 mA
		Ch 4:
		Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
		CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
		Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = PS Fault</arg1>
		<arg2> 1 = Interlock</arg2>
		<arg3> 1 = Auto Remote</arg3>
		<arg4> 1 = Over Voltage</arg4>
		<arg5> 1 = Over Current</arg5>
		<arg6> 1 = REG Error</arg6>
		<pre><arg7> 1 = ARC Error </arg7></pre>
		<arg8> 1 = OVER TEMP</arg8>

#### 8.12 SL50N1200 X3715

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	, ,
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	12.210012	HV Monitor
ANA 3	JB5-8	.00586081	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

## Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	12.210012	KV Program
Channel B	JB5-5	.00586081	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

USA EUROPE JAPAN MEXICO

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	-
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Header	Initial Power Up	Project Signal Name
Location	State	
JB5-11		
JB5-13		
JB5-14	Open (Not	RESET
	• `	
JB8-10	<b>J J</b> ,	
JB8-8		
JB8-6	Open (Not	HV On 2
	Energized)	
JB8-7		HV On 1
JB8-9		
JB8-4		HV Off1
JB8-2		
JB8-3	Open (Not	HV Off 2
	Energized)	
JB8-5		
	Location JB5-11 JB5-13 JB5-14 JB8-10 JB8-8 JB8-6 JB8-7 JB8-9 JB8-4 JB8-2 JB8-3	State   Stat

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 12.210012 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .00586081 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current		
Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = 12.210012 V
	J5	Ch 3: LSB = .0058608 mA
		Ch 4:
		Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
		CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
		Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = PS Fault</arg1>
		<arg2> 1 = Interlock</arg2>
		<arg3> 1 = Auto Remote</arg3>
		<arg4> 1 = Over Voltage</arg4>
		<arg5> 1 = Over Current</arg5>
		<arg6> 1 = REG Error</arg6>
		<pre><arg7> 1 = ARC Error</arg7></pre>
		<arg8> 1 = OVER TEMP</arg8>

#### 8.13 SL50P1200X3714

ADC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	, ,
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	12.210012	HV Monitor
ANA 3	JB5-8	.00586081	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

#### Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	12.210012	KV Program
Channel B	JB5-5	.00586081	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 – IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

USA EUROPE JAPAN MEXICO

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock	Header	Initial Power Up	Project Signal Name
Block	Location	State	
Interlock 1 -	JB5-11		
NC			
Interlock 1 -	JB5-13		
NO			
Interlock 1 –	JB5-14	Open (Not	RESET
COM		Engergized)	
Interlock 1 -	JB8-10		
AUX			
Interlock 2 -	JB8-8		
NC			
Interlock 2 –	JB8-6	Open (Not	HV On 2
NO		Energized)	
Interlock 2 –	JB8-7		HV On 1
COM			
Interlock 2 -	JB8-9		
AUX			
Interlock 3 -	JB8-4		HV Off1
NC			
Interlock 3 -	JB8-2		
NO			
Interlock 3 -	JB8-3	Open (Not	HV Off 2
COM		Energized)	
Interlock 3 -	JB8-5	,	
AUX			

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = 12.210012 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .00586081 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = 12.210012 V
	J5	Ch 3: LSB = .0058608 mA
		Ch 4:
		Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
		CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
		Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<arg1> 0 = PS Fault</arg1>
		<arg2> 1 = Interlock</arg2>
		<arg3> 1 = Auto Remote</arg3>
		<arg4> 1 = Over Voltage</arg4>
		<arg5> 1 = Over Current</arg5>
		<arg6> 1 = REG Error</arg6>
		<arg7> 1 = ARC Error</arg7>
		<arg8> 1 = OVER TEMP</arg8>

#### 8.14 SL1N300X3638

A/DC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	.2442	HV Monitor
ANA 3	JB5-8	.07326	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

### Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	.2442	KV Program
Channel B	JB5-5	.07326	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11		RESET
Interlock 1 - NO	JB5-13		
Interlock 1 – COM	JB5-14	Open (Not Engergized)	RESET
Interlock 1 - AUX	JB8-10		
Interlock 2 -	JB8-8		HV On 1
Interlock 2 – NO	JB8-6		
Interlock 2 – COM	JB8-7	Open (Not Energized)	HV On 2
Interlock 2 - AUX	JB8-9		
Interlock 3 - NC	JB8-4		HV Off1
Interlock 3 - NO	JB8-2		HV Off 2
Interlock 3 - COM	JB8-3	Open (Not Energized)	
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage	Program DAC Channel A	LSB = .2442 V
Setpoint		
Program Emission Current	Program DAC Channel B	LSB = .07326 mA
Setpoint		
Program Filament Current		
Setpoint		
Request Voltage		
Setpoint		
Request Emission Current		
Setpoint		
Request Filament Current		
Setpoint		
Request Analog Readbacks	Request Analog Channels –	Ch 2: LSB = .2442 V
	J5	Ch 3: LSB = .07326 mA
		Ch 4:
		Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 1	SET = reset
		CLEAR = not reset
HV ON	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 2	SET then CLEAR
HV OFF	Program Interlock State	Pulse Activated (> 1 ms)
	Interlock 3	SET then CLEAR
		Note: HV ON must be in
		CLEAR state
Request Digital Status	Read Digital Input Status	<ARG1 $> 0 = N/A$
		<arg2> 1 = Local remote</arg2>
		<arg3> 1 = Over Voltage</arg3>
		<arg4> 1 = Over Current</arg4>
		<arg5> 0 = REG Error</arg5>
		<arg6> 1 = ARC Error</arg6>
		<arg7> 1 = Temp Error</arg7>

#### 8.15 SL1P1200X3639

A/DC	Header	Scaling (LSB	Project Signal Name
Channel	Location	Multiplier)	
ANA 0	N/A	0.0732 V/°C	N/A: SIC Temperature Sensor
ANA 1	N/A	10.5 mV	N/A: SIC + 24 volt Monitor
ANA 2	JB5-6	.2442	HV Monitor
ANA 3	JB5-8	.3663	Emmisions Current Monitor
ANA 4	JB5-12		
ANA 5	JB5-10		
ANA 6	JB5-2		
ANA 7	JB6-1		
ANA 8	JB6-3		
ANA 9	JB6-2		
ANA 10	JB6-5		
ANA 11	JB6-4		
ANA 12	JB6-7		
ANA 13	JB6-6		
ANA 14	JB6-9		
ANA 15	JB6-8		

## Digital to Analog Converter Resources

DAC Channel	Header Location	Scaling (LSB Multiplier)	Project Signal Name
Channel A	JB5-1	.2442	KV Program
Channel B	JB5-5	.3663	mA Program
Channel C	JB5-3		
Channel D	JB5-4		

## Digital Input Resources

Input Channel	Header Location	Project Signal Name
IN 1 – LS, IRQ	JB7-1	System Fault (1= System Fault)
IN 2 – LS, IRQ	JB7-2	Interlock Status (1= Interlock closed)
IN 3 – LS, IRQ	JB7-3	Auto Remote Monitor (1= Remote)
IN 4 – LS, IRQ	JB7-4	High Voltage On (1= HV On)
IN 5 – LS, IRQ	JB7-5	High Current On (1= mA On)
IN 6 – LS, IRQ	JB7-6	Regulation Error (1= Reg Error)
IN 7 – LS, IRQ	JB7-7	ARC (1= ARC Occurred)
IN 8 - IRQ	JB7-8	Over Temp (1= Over Temp)

LS = Level Sensitive. IRQ = Able to send an Interrupt to the DSP

USA EUROPE JAPAN MEXICO

Output	Header Location	Initial Power Up	Project Signal Name
Channel		State	
OUT 1	JB8-1		Not used
OUT 2	JB7-12	Local Mode	Auto local Remote Mode
OUT 3	JB7-11		Not used
OUT 4	JB7-10		Not used
OUT 5	JB7-9		Not used

Interlock Block	Header Location	Initial Power Up State	Project Signal Name
Interlock 1 - NC	JB5-11		RESET
Interlock 1 - NO	JB5-13		
Interlock 1 – COM	JB5-14	Open (Not Engergized)	RESET
Interlock 1 - AUX	JB8-10		
Interlock 2 - NC	JB8-8		HV On 1
Interlock 2 – NO	JB8-6		
Interlock 2 – COM	JB8-7	Open (Not Energized)	HV On 2
Interlock 2 - AUX	JB8-9		
Interlock 3 -	JB8-4		HV Off1
Interlock 3 - NO	JB8-2		HV Off 2
Interlock 3 - COM	JB8-3	Open (Not Energized)	
Interlock 3 - AUX	JB8-5		

Product Specific Command	Generic Command	Comments
Program Voltage Setpoint	Program DAC Channel A	LSB = .2442
Program Emission Current Setpoint	Program DAC Channel B	LSB = .3663 mA
Program Filament Current Setpoint		
Request Voltage Setpoint		
Request Emission Current Setpoint		
Request Filament Current Setpoint		
Request Analog Readbacks	Request Analog Channels  – J5	Ch 2: LSB = .2442 V Ch 3: LSB = .3663 mA Ch 4: Ch 6:
	Request Status	
	Request Software Version	
	Request Hardware Version	
	Request Web Server Version	
	Request Model Number	
Filament On/Off		Not Used
Grid On/Off		Not Used
Reset Fault	Program Interlock State Interlock 1	Pulse Activated (> 1 ms) SET = reset CLEAR = not reset
HV ON	Program Interlock State Interlock 2	Pulse Activated (> 1 ms) SET then CLEAR
HV OFF	Program Interlock State Interlock 3	Pulse Activated (> 1 ms) SET then CLEAR Note: HV ON must be in CLEAR state
Democrat Birdt I Ot 1	Dead Birital	I ADO4 0 N/A
Request Digital Status	Read Digital Input Status	<arg1> 0 = N/A <arg2> 1 = Local remote <arg3> 1 = Over Voltage <arg4> 1 = Over Current <arg5> 1 = REG Error <arg6> 1 = ARC Error</arg6></arg5></arg4></arg3></arg2></arg1>
		<arg7> 1 = ARC Entire   <arg7> 1 = Temp Error</arg7></arg7>