Recorded at time: 1494551483.642 odom Broadcaster: /graft Average rate: 50.195 Hz Most recent transform: 1494551485.537 (-1.894 sec old) Buffer length: 4.941 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.200 Hz Average rate: 50.200 Hz Average rate: 25.306 Hz Average rate: 25.306 Hz Average rate: 25.306 Hz Average rate: 50.200 Hz Most recent transform: 1494551485.523 (-1.880 sec old) | Most recent transform: 1494551486.037 (-2.394 sec old) | Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551485.523 ( -1.880 sec old) Most recent transform: 1494551485.523 ( -1.880 sec old) Buffer length: 4.900 sec Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.900 sec Buffer length: 4.900 sec torso\_lift\_link l\_wheel\_link r\_wheel\_link estop\_link laser\_link torso\_fixed\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.200 Hz Average rate: 25.306 Hz Average rate: 25.306 Hz Average rate: 25.306 Hz Most recent transform: 1494551486.037 (-2.394 sec old) | Most recent transform: 1494551485.523 (-1.880 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.940 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec head\_pan\_link bellows\_link2 shoulder\_pan\_link bellows\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 25.306 Hz Average rate: 25.306 Hz Most recent transform: 1494551485.523 (-1.880 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec head\_tilt\_link shoulder\_lift\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 25.306 Hz Average rate: 50.200 Hz Most recent transform: 1494551486.037 ( -2.394 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.940 sec Buffer length: 4.900 sec upperarm\_roll\_link head\_camera\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.200 Hz Average rate: 25.306 Hz Average rate: 50.200 Hz Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551485.523 ( -1.880 sec old) Buffer length: 4.940 sec Buffer length: 4.900 sec Buffer length: 4.940 sec head\_camera\_rgb\_frame head\_camera\_depth\_frame elbow\_flex\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.200 Hz Average rate: 25.306 Hz Average rate: 50.200 Hz Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551486.037 (-2.394 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.900 sec forearm\_roll\_link head\_camera\_depth\_optical\_frame head\_camera\_rgb\_optical\_frame Broadcaster: /ar\_track\_alvar Broadcaster: /ar\_track\_alvar Broadcaster: /ar\_track\_alvar Broadcaster: /robot\_state\_publisher Average rate: 11.186 Hz Average rate: 11.186 Hz Average rate: 11.186 Hz Average rate: 25.306 Hz Most recent transform: 1494551485.269 (-1.627 sec old) Most recent transform: 1494551485.269 (-1.627 sec old) Most recent transform: 1494551485.269 (-1.627 sec old) Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.738 sec Buffer length: 4.738 sec Buffer length: 4.900 sec Buffer length: 4.738 sec ar\_marker\_0 ar\_marker\_2 wrist\_flex\_link ar\_marker\_1 Broadcaster: /robot\_state\_publisher Average rate: 25.306 Hz Most recent transform: 1494551485.523 (-1.880 sec old) Buffer length: 4.900 sec wrist\_roll\_link Broadcaster: /robot\_state\_publisher Average rate: 50.200 Hz Most recent transform: 1494551486.037 ( -2.394 sec old) Buffer length: 4.940 sec gripper\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 39.634 Hz Average rate: 39.634 Hz Most recent transform: 1494551485.526 (-1.883 sec old) Most recent transform: 1494551485.526 ( -1.883 sec old) Buffer length: 4.920 sec Buffer length: 4.920 sec r\_gripper\_finger\_link l\_gripper\_finger\_link

view\_frames Result